# A comonadic view of simulation and quantum resources

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#### Overview of the talk

- Crash course on contextuality
- What are we trying to formalize?
- Free operations on empirical models. Free transformations.
- Simulations.
- Equivalence of the viewpoints
- No-cloning
- Further topics

#### Measurement scenarios

A measurement scenario  $\mathbf{X} = \langle X, \Sigma, O \rangle$ :

► X a finite set of measurements

Σ is a simplicial complex on X, whose faces are called the measurement contexts.

O = (O<sub>x</sub>)<sub>x∈X</sub> specifies for each measurement x ∈ X a finite non-empty set of possible outcomes O<sub>x</sub>;

Note: X and each  $O_x$  finite.

#### Events and distributions

Let  $\langle X, \Sigma, O \rangle$  be a scenario. For any  $U \subseteq X$ , we write

$$\mathcal{E}_O(U) := \prod_{x \in U} O_x$$

for the set of assignments of outcomes to each measurement in the set U. When U is a valid context, this is be the set of possible joint outcomes for the measurements UFor any set Y, let D(Y) denote the set of finitely supported probability distributions over Y

#### Empirical models

An empirical model e: (X, Σ, O) is a family (e<sub>σ</sub>)<sub>σ∈Σ</sub> where e<sub>σ</sub> is a distribution over the available joint outcomes, i.e.

$$e_{\sigma} \in \mathsf{D} \circ \mathcal{E}_{\mathcal{O}}(\sigma) = \mathsf{D}\left(\prod_{x \in \sigma} \mathcal{O}_{x}\right)$$

We assume (generalized) no-signalling, i.e. that marginal distributions are well-defined: for any σ, τ ∈ Σ with τ ⊆ σ, it holds that

$$e_{ au}=e_{\sigma}|_{ au}={\sf D}\circ {\mathcal E}( au\subseteq \sigma)(e_{\sigma})$$
 ;

concretely, for any  $t\in \mathcal{E}( au)$ ,

$$e_{\tau}(t) = \sum_{s \in \mathcal{E}(\sigma), s|_{ au} = t} e_{\sigma}(s) \; .$$

#### Contextuality

• Contextuality: Is there a joint distribution d on  $\mathcal{E}_O(X)$  such that  $d|_{\sigma} = e_{\sigma}$  for each  $\sigma \in \Sigma$ ?

Strong contextuality: Is there a joint outcome s ∈ C<sub>O</sub>(X) consistent with e?

Non-contextual fraction NCF(e) ∈ [0, 1]: what fraction of e is non-contextual? CF(e) = 1 − NCF(e)

## Examples

Bell:

	(0,0)	(0,1)	(1,0)	(1, 1)
$(x_0, y_0)$	1/2	0	0	1/2
$(x_0, y_1)$	3/8	1/8	1/8	3/8
$(x_1, y_0)$	3/8	1/8	1/8	3/8
$(x_1, y_1)$	1/8	3/8	3/8	1/8

## Examples

#### PR box:

	(0,0)	(0, 1)	(1,0)	(1,1)
$(x_0, y_0)$	1/2	0	0	1/2
$(x_0, y_1)$	1/2	0	0	1/2
$(x_1, y_0)$	1/2	0	0	1/2
$(x_1, y_1)$	0	1/2	1/2	0

#### Towards morphisms

A bunch of mathematical objects has been defined, but what are the morphisms?

Given e: (X, Σ, O) and d: (Y, Θ, P), a morphism d → e is a way of transforming d to e using free operations.

► Alternatively: a morphism d → e is a way of simulating e using d.

#### Examples from the literature

 Any two-outcome bipartite box can be simulated with PR boxes (Barrett-Pironio).

An explicit two-outcome three-partite box that cannot be simulated with PR boxes (Barrett-Pironio).

 No finite set of bipartite boxes can simulate all of them (Dupuis et al).

#### Free operations

We have

Zero model z: the unique empirical model on the empty measurement scenario

$$\langle \emptyset, \Delta_0 = \{\emptyset\}, () 
angle$$
 .

Singleton model u: the unique empirical model on the one-outcome one measurement scenario

$$\langle \mathbf{1} = \{\star\}, \Delta_1 = \{\emptyset, \mathbf{1}\}, (\mathcal{O}_{\star} = \mathbf{1}) 
angle$$
 .

Probabilistic mixing: Given empirical models e and d in ⟨X,Σ, O⟩ and λ ∈ [0,1], the model e +<sub>λ</sub> d : ⟨X,Σ, O⟩ is given by the mixture λe + (1 − λ)d

#### Free operations

Tensor: Let e : (X, Σ, O) and d : (Y, Θ, P) be empirical models. Then

$$e \otimes d : \langle X \sqcup Y, \Sigma * \Theta, (O_x)_{x \in X} \cup (P_y)_{y \in Y} \rangle$$

represents running *e* and *d* independently and in parallel. Here  $\Sigma * \Theta := \{ \sigma \cup \theta | \sigma \in \Sigma, \theta \in \Theta \}.$ 

Coarse-graining: given e : (X, Σ, O) and a family of functions h = (h<sub>x</sub>: O<sub>x</sub> → O'<sub>x</sub>)<sub>x∈X</sub>, get a coarse-grained model

$$e/h:\langle X,\Sigma,O'\rangle$$

Measurement translation: given e : (X, Σ, O) and a simplicial map f: Σ' → Σ, the model f\*e : (X', Σ', O) is defined by pulling e back along the map f.

#### Free operations

Given a simplicial complex  $\Sigma$  and a face  $\sigma \in \Sigma$ , the link of  $\sigma$  in  $\Sigma$  is the subcomplex of  $\Sigma$  whose faces are

$$\mathsf{lk}_{\sigma}\Sigma := \{\tau \in \Sigma \mid \sigma \cap \tau = \emptyset, \sigma \cup \tau \in \Sigma\} \ .$$

Conditioning on a measurement: Give e : (X, Σ, O), x ∈ X and a family of measurements (y<sub>o</sub>)<sub>o∈Ox</sub> with y<sub>o</sub> ∈ Vert(lk<sub>x</sub>Σ). Consider a new measurement x?(y<sub>o</sub>)<sub>o∈Ox</sub>, abbreviated x?y. Get

$$e[x?y]: \langle X \cup \{x?y\}, \Sigma[x?y], O[x?y \mapsto O_{x?y}] \rangle$$

that results from adding x?y to e.

## Summary of operations

The operations generate terms

$$\mathsf{Terms} \ni t := a \in \mathsf{Var} \mid z \mid u \mid f^*t \mid t/h$$
$$\mid t +_{\lambda} t \mid t \otimes t \mid t[x?y]$$

typed by measurement scenarios.

## Morphisms as free transformations

#### Proposition

A term without variables always represents a noncontextual empirical model. Conversely, every noncontextual empirical model can be represented by a term without variables.

Can *d* be transformed to *e*?

Formally: is there a typed term  $a : \mathbf{Y} \vdash t : \mathbf{X}$  such that t[d/a] = e?

#### Morphisms as simulations

- Think of a measurement scenario as a concrete experimental setup, where for each measurement there is a grad student responsible for it.
- The grad student responsible for measuring x ∈ X, should have instructions which measurement π(x) ∈ Y to use instead.
- Given a result for those measurements, should be able to determine the outcome to output.
- The outcome statistics should be identical to those of e.

Dependencies on multiple measurements and stochastic processing added as a comonadic effect.

## Deterministic morphisms

#### Definition

Let  $\mathbf{X} = \langle X, \Sigma, O \rangle$  and  $\mathbf{Y} = \langle Y, \Theta, P \rangle$  be measurement scenarios. A *deterministic morphism*  $\langle \pi, h \rangle \colon \mathbf{Y} \longrightarrow \mathbf{X}$  consists of:

- a simplicial map  $\pi \colon \Sigma \longrightarrow \Theta$ ;
- ► a natural transformation  $h: \mathcal{E}_P \circ \pi \longrightarrow \mathcal{E}_O$ ; equivalently, a family of maps  $h_x: P_{\pi(x)} \longrightarrow O_x$  for each  $x \in X$ .

Let  $e: \mathbf{X}$  and  $d: \mathbf{Y}$  be empirical models. A *deterministic simulation*  $\langle \pi, h \rangle: d \longrightarrow e$  is a deterministic morphism  $\langle \pi, h \rangle: \mathbf{Y} \longrightarrow \mathbf{X}$  that takes d to e.

#### Example simulation

If 
$$h = (h_x \colon O_x \longrightarrow O'_x)_{x \in X}$$
, can coarse-grain  $e$  to get  $e/h$ .

There is a deterministic simulation  $e \rightarrow e/h$ :

If you need to measure  $x \in X$  for e/h, just measure  $x \in X$  in the experiment *e* and apply *h* to the outcome.

## Beyond deterministic maps

 Deterministic morphisms aren't enough: a deterministic model can't simulate (deterministically) a coinflip

Need classical (shared) correlations

Moreover, to simulate x ∈ X one might want to run a whole measurement protocol on ⟨Y, Θ, P⟩.

#### Definition

Let  $\mathbf{X} = \langle X, \Sigma, O \rangle$  be a measurement scenario. We define recursively the *measurement protocol completion* MP(X) of X by

$$\mathsf{MP}(\mathbf{X}) ::= \emptyset \mid (x, f)$$

where  $x \in X$  and  $f: O_x \to MP(Ik_x\Sigma)$ .

 $MP(\mathbf{X})$  can be given the structure of a measurement scenario, and if  $e: \langle X, \Sigma, O \rangle$ , can extend it to  $MP(e): MP(\mathbf{X})$ 

## General simulations

#### Definition

Given empirical models e and d, a simulation of e by d is a deterministic simulation  $MP(d \otimes c) \rightarrow e$  for some noncontextual model c.

We denote the existence of a simulation of e by d as  $d \rightsquigarrow e$ , read "d simulates e".

#### Theorem

MP defines a comonoidal comonad on the category of empirical models.

Roughly: comultiplication MP(X)  $\rightarrow$  MP<sup>2</sup>(X) by "flattening", unit MP(X)  $\rightarrow$  X, and MP( $X \otimes Y$ )  $\rightarrow$  MP(X)  $\otimes$  MP(Y)

#### Theorem

Let  $e : \mathbf{X}$  and  $d : \mathbf{Y}$  be empirical models. Then  $d \rightsquigarrow e$  if and only if there is a typed term  $a : \mathbf{Y} \vdash t : \mathbf{X}$  such that  $t[d/a] \simeq e$ .

#### Proof.

(Sketch) If  $d \rightsquigarrow e$ , then e can be obtained from MP( $d \otimes x$ ) by a combination of a coarse-graining and a measurement translation. There is a term representing x and MP can be built by repeated controlled measurements.

For the other direction, build a simulation  $d \rightarrow t[d/a]$  inductively on the structure of t.

## No-cloning

## Theorem (No-cloning)

 $e \rightsquigarrow e \otimes e$  if and only if e is noncontextual.

#### Further questions

- Study the preorder induced by  $d \rightsquigarrow e$ .
- ▶ What can you simulate with arbitrarily many copies of *d*?
- The same for possibilistic empirical models. Connections to CSPs.
- Changing the free class of "free" models allows for more general simulations. What can be said about e.g. quantum simulations? Does the no-cloning result generalize?
- Comparison with other approaches to contextuality.

## Further questions 2

Multipartite non-locality

Graded structure on the comonad?

MBQC?

Generating all empirical models?



## Summary

Intraconversions of contextual resources formalized in terms of

free operations



These viewpoints agree and capture known examples

► A no-cloning result

Several avenues for further work