

Computation of emotions in man and machines

Journal:	<i>Philosophical Transactions B</i>
Manuscript ID:	RSTB-2009-0198
Article Type:	Introduction
Date Submitted by the Author:	28-Jul-2009
Complete List of Authors:	Robinson, Peter; University of Cambridge, Computer Laboratory el Kaliouby, Rana; MIT, Media Laboratory
Issue Code: Click http://rstb.royalsocietypublishing.org/site/misc/issue-codes.xhtml to find the code for your issue.:	EMOTIONS
Subject:	Behaviour < BIOLOGY, Cognition < BIOLOGY
Keywords:	Psychology, Emotions, Human-computer interactions, Affective computing

COMPUTATION OF EMOTIONS IN MAN AND MACHINES

PETER ROBINSON¹
RANA EL KALIOUBY²

The importance of emotional expression as part of human communication has been understood since Aristotle, and the subject has been explored scientifically since Charles Darwin and others in the nineteenth century. Advances in computer technology now allow machines to recognise and express emotions, paving the way for improved human-computer and human-human communications.

Recent advances in psychology have greatly improved our understanding of the role of affect in communication, perception, decision-making, attention and memory. At the same time, advances in technology mean that it is becoming possible for machines to sense, analyse and express emotions. We can now consider how these advances relate to each other and how they can be brought together to influence future research in perception, attention, learning, memory, communication, decision-making and other applications.

The computation of emotions includes both recognition and synthesis, using channels such as facial expressions, non-verbal aspects of speech, posture, gestures, physiology, brain imaging and general behaviour. The combination of new results in psychology with new techniques of computation is leading to new technologies with applications in commerce, education, entertainment, security, therapy and everyday life. However, there are important issues of privacy and personal expression that must also be considered.

INTRODUCTION

2009 marks the bicentenary of Charles Darwin's birth. We remember him today for the publication of *On the origin of species* in 1859 and, perhaps rather less, for *The descent of man* in 1871 and *The expression of the emotions in man and animals* a year later. The last of these (Darwin 1872) was a remarkable book, selling over 5000 copies on the day of publication, and another 4000 in the following four months. More importantly, it remains completely relevant today. In the book, Darwin explores the expression of emotions not only by humans but also by cats, dogs, horses and many other animals. He observes that the expressions within a species are similar, but differ between species, and considers the question of whether this expression is learned or innate.

It is only much more recently, perhaps in the last 40 years, that Darwin's theories of universality have been scientifically tested and our understanding of the importance of emotions in human communication developed. Paul Ekman provided strong evidence for universality in a book published to mark the centenary of *Expression* (Ekman 1973). 25 years later Rosalind Picard observed that the latest scientific findings indicated that emotions play an essential role in rational decision making, perception, learning and a variety of other cognitive emotions (Picard 1997). She went on to argue that effective communication with computers also requires emotional intelligence – computers must have the ability to recognize and express emotions.

¹ University of Cambridge, Computer Laboratory, William Gates Building, 15 JJ Thomson Avenue, Cambridge CB3 0FD, UK. <http://www.cl.cam.ac.uk/~pr/>.

² MIT Media Lab, 20 Ames Street, Cambridge, MA 02139, USA. <http://web.media.mit.edu/~kaliouby/>.

1 Computation of emotions in man and machines

2
3 The study of affective computing has subsequently blossomed, with research groups around the world
4 investigating different aspects of the field. This paper presents a summary of the achievements and challenges
5 involved in affective computing.
6

7
8 This special issue of the *Philosophical Transactions* follows a two day Discussion Meeting on the *Computation*
9 *of emotions in man and machines* held at the Royal Society in April 2009. The speakers represented a wide
10 spectrum of academic disciplines from psychology through computer science to design, and their papers
11 present recent advances in theories of emotion and affect, their embodiment in computational systems, the
12 implications for general communications, and broader applications.
13

14 Four interlinked themes will be discussed in the following four sections:

- 15 • Underlying theories from psychology that provide the basis for studying emotions.
- 16
- 17 • Recognising emotions expressed by humans through facial expressions, gestures and body posture.
- 18
- 19 • Expressing emotions through the same channels in animated cartoons and by robots.
- 20
- 21 • Bringing these technologies to bear on practical applications.
- 22
- 23
- 24

25 A common observation across all four themes of the meeting was that affect- measuring technologies are
26 becoming robust and reliable. It is now realistic to use the models and sensors in other experiments, allowing
27 real-world testing of theories about the mechanisms that underpin affect, social cognition, developmental
28 trajectories and modes of derailed development such as autism spectrum disorders. Previously unanswered
29 questions across a number of disciplines can now be addressed systematically. This is a very exciting prospect.
30

31
32 These new tools range from automated facial expression analysis and mobile biosensors to avatars, robots and
33 immersive environments, which can be precisely manipulated, allowing human-machine and human-human
34 interactions to be examined in controlled, yet naturalistic experimental settings. For example, Baylor (2009)
35 and Pelachaud (2009) manipulate appearance and abilities of embodied conversational agents to test theories
36 of persuasion and trust.
37

38
39 Cohn (Boker, et al. 2009) describes a novel experimental paradigm that allows for the systematic testing of
40 dyadic interactions, an area that was previously hard to undertake because of the range of parameters
41 involved. Frith (2009) shows how the brain's responses to robots are fundamentally different from those to
42 humans and puts challenges us to develop robots that can produce an affective imprint in humans. Slater's
43 immersive environments (Slater 2009) and Breazeal's social robots (Breazeal 2009) shed some light on the rôle
44 of embodiment in social cognition. Robots can also be used to explore different aspects of human
45 development and are already being used to test theories such as mentalizing and mirroring.
46

47
48 Affect-measurement technologies are particularly exciting because they enable studies of affect to move from
49 the laboratory to the real- world. Baron-Cohen (Baron-Cohen, Golan and Ashwin 2009) considers affect-
50 comprehension abilities in children with autism spectrum disorders in everyday social situations. Picard (2009)
51 presents simple, wearable sensors that can be used to study physiological indicators in large populations over
52 extended periods, enabling detailed examination of the interaction between everyday experiences and
53 physiology.
54

55
56 We conclude by presenting some observations that arose during discussions at the meeting, which set an
57 agenda for future research in the field.
58

UNDERSTANDING EMOTION

The first theme explores the grounding in psychology for studying human emotions.

Paul Ekman (2009) starts this special issue with a highlight of Darwin's contributions to the study of emotion and facial expression, ranging from the theory of discrete emotions through the importance of facial expressions to the universality of emotions. Ekman emphasizes Darwin's methodological contributions that shaped the field of psychology as we know it today. Darwin introduced the concept of a judgment study that remains the most widely used method in studying facial expression; he also had excellent observational skills, which are especially important even as we move toward technology that is capable of doing some or all of the processing and analysis. Ekman points out several areas that Darwin did not consider in his research; in some of these areas substantial progress has been made, such as in the study of the dynamics of facial expressions and the study of deception; others areas remain unanswered, e.g., we do not yet have a clear mapping from facial expressions to emotion, nor do we have a clear understanding between indicators and communicative signals. Throughout, Ekman reminds us that, all scientific endeavours are ultimately about people and relationships.

Chris Frith (2009) looks more closely at the role of facial expressions in social interactions, demonstrating how a behaviour such as facial movement can evolve into a complex and rich communication system. Frith covers topics such as imitation and emotional contagion to mental state attribution and empathy, as well as human-human communication and human-robot communication. While Darwin's methods and his followers are deeply rooted in psychology and observation, Frith borrows methods from neuroscience and brain imaging. Frith describes two parallel processes through which sensory signals, facial expressions included, are converted into behaviour; one is associated with consciousness while the other is not. Frith gives numerous examples where the unconscious processing of facial expressions and eye-gaze direction plays an important role in social interactions, including trust and friendliness. In the conscious route, senders and receivers are cognizant of their signals, and can voluntarily control the exchange of signals.

Klaus Scherer (2009) draws on extensive empirical evidence from psychology and neuroscience to demonstrate that emotions are emergent processes, best described using a dynamic computational architecture. In his "component process model of emotion", emotion is a cultural and psychobiological adaptation mechanism that is built on emotion-antecedent appraisal on different levels of processing to empower individuals to react flexibly and dynamically to internal and external events. Scherer proposes the emergent computational modelling of emotion using nonlinear dynamic systems.

Following these two papers focussed primarily on the face, Beatrice de Gelder (2009) challenges the dominance of the face in emotion research and presents twelve reasons for including bodily expression in affective neuroscience. De Gelder surveys an emerging body of research that demonstrates how bodily expressions are recognized as reliably as facial expressions even under conditions of limited attention and awareness.

De Gelder also reviews differences between the two channels of emotional expression and discusses why they are both important. De Gelder highlights the importance of a multi-modal approach – a theme that recurs throughout this special issue. One important reason for studying bodily expressions is that it provides an excellent opportunity to validate human emotion theories, the majority of which are currently built on studies of facial expressions. Multi-modal studies will determine whether existing theories generalize beyond the face to other affective signals.

1 Computation of emotions in man and machines
2
3

4 AUTOMATIC RECOGNITION OF EMOTIONS 5

6 The second area of discussion covers machine sensing and recognition of emotions. Humans communicate a
7 wide range of affective states through a rich and varied collection of nonverbal channels, including the face,
8 voice, gestures and body posture. This area of research draws on many disciplines including machine learning,
9 pattern recognition, signal processing, machine vision, cognitive science and psychology.
10

11 Jeffrey Cohn (Boker, et al. 2009) presents an experiment that shows how people adapt their head movements
12 and facial expressions in response to their partners in a social exchange to maintain equilibrium throughout
13 the interaction. The experiment uses real-time automatic face tracking to drive a synthetic facial avatar in real
14 time for communication in one direction and straightforward video conferencing for the return channel.
15 Attenuating the avatar's head movements led to greater head movement by the conversational partner, and
16 attenuated facial expressions led to increased head nodding in both naive participants and confederates.
17 These results show that the dynamics of head movements in dyadic conversation are adapted to maintain
18 symmetry.
19

20 This novel experimental paradigm is very promising and enables researches to study dyadic and small group
21 interactions in a controlled way that was not previously possible, enabling the manipulation of real-time
22 appearance of real-time appearance of facial structure and expression as well as head movements.
23
24

25 Ursula Hess (Hess, Adams and Kleck 2009) reviews a growing body of research that demonstrates that the face
26 is not simply an empty canvas, but that facial appearance interacts with facial movements to modify the
27 perception of emotion expressions. Facial appearance communicates important information such as sex, age,
28 ethnicity, personality and other characteristics which can define a person and the social group to which he or
29 she belongs. Through a systematic manipulation of each of these parameters, Hess shows this information
30 affects the perception of emotion expressions because it shapes the expectations of the person on the
31 decoding or receiving end and biases their inference and attribution.
32
33

34 Hess' work is important because it argues while facial expression researchers often remove context to control
35 for its effect, this is almost impossible to do with facial appearance. Her work has implications on how videos
36 are labelled for emotional content and by whom, since social beliefs about individuals inform how and what
37 we read in faces.
38
39

40 Maja Pantic (2009) reviews progress with machine analysis of facial expressions over the past 10 years. Most
41 of the work so far has focused on the automatic detection of units in Ekman's Facial Action Coding System
42 (Ekman and Friesen 1978) or the detection of prototypic expressions of the basic emotions.
43
44

45 Pantic highlights several challenges that researchers in this area have begun to address. The majority of
46 methods published to date are not applicable to real-life situations where changes in facial expressions are
47 subtle, fleeting and certainly non-prototypic. As more interest builds in the potential applications of
48 automated facial analysis, the focus of the research in the field is shifting to automatic recognition of
49 spontaneous facial movements. Another challenge is that of dynamic modelling of facial expressions. Pantic
50 cites the growing body of literature in cognitive science that demonstrates the importance of temporal
51 information in facial expression, and presents trends in dynamic modelling of facial expressions. Finally, Pantic
52 poses one of the prominent challenges in this area of research: the availability of publicly available datasets
53 that are labelled for facial action units and emotional expressions.
54
55

56 Roddy Cowie (2009) challenges many current assumptions in emotion research, focusing on the perception of
57 emotion. He argues that affective computing and machine-based methods for detection of emotion has
58 shifted the emphasis from analysing a single stimulus (often a static image or a short audio clip) to a more
59 realistic, immersive approach to the study of emotion. He reminds us of how emotions continuously,
60

1
2
3 consciously and more often sub-consciously influence the way we see the world and interact with others. He
4 reviews the state of the research field representing emotion in speech, facial expressions, gestures and body
5 postures. Cowie also highlights the importance of considering the context of the particular task at hand when
6 inferring emotions
7

8 9 EXPRESSION OF EMOTIONS

10
11 The third area of discussion explores the possibility of emotional expression by computer-controlled robots
12 and by computer-generated cartoon avatars. The main question to be considered is how people react to these
13 synthetic expressions. Can a computer generated expression of emotion elicit the same empathic response in
14 a person? What minimal set of displays is required to elicit the response? Is there any effect analogous to the
15 "uncanny valley" in computer animation (Mori 1970) that just makes the displays seem frightening rather than
16 empathic?
17

18
19 Cynthia Breazeal (2009) presents her work on robots as social learners. Her central thesis is that people are
20 social, so robots should also be social; physical robots should interact with people in terms of their interests,
21 beliefs and desires. Within this framework, cognition (understanding what is being displayed) is less important
22 than emotion (its immediate effects the other participant in a conversation). Social learning in humans is
23 based on imitation, so Breazeal has taken the interaction of a carer with a child as a model for interactions
24 between people and robots. Her robots, notably Kismet (Breazeal 2002), look and act like babies to encourage
25 exaggerated expressions of emotion in people which can easily be interpreted and imitated. As a
26 consequence, many of the machine learning problems associated with more analytical approaches are
27 avoided. In effect the human and the robot collaborate in a process of teaching and learning.
28
29

30
31 This approach presents four main challenges. The overall goal is to establish a framework in which the social
32 and communicative skills of the robot can be aligned with those of the human participant. Collaborating as a
33 learner and a teacher establishes a mutually agreeable level of complexity in the communication. The second
34 problem is to filter the salient data out of the stream of information made available by physical sensors.
35 Thirdly, the robot has to plan appropriate actions in response to its stimuli. Finally, the robot has to evaluate
36 the effects of its responses to diagnose errors and improve performance.
37

38
39 Catherine Pelachaud (2009) presents her work on modelling multimodal expression of emotion in a virtual
40 agent. Embodied conversational agents express emotions through facial expressions, gaze, body movement
41 and gesture, and voice. The focus of her paper is the expression of emotion in the face and gestures of a
42 computer-generated cartoon avatar. This expression is dynamic, evolving in three ways: a spatial extent
43 controlling the magnitude of the movement, a temporal extent controlling the durations of its onset, apex and
44 offset, and power controlling the acceleration of the movement. The main challenge is that emotions in
45 human-computer interaction are rarely discrete and rarely limited to the six basic emotions. A dimensional
46 representation with interpolation between reference expressions is more appropriate.
47
48

49
50 There are three practical complications. These blends must still be calculated even when the component
51 expressions are contradictory. One solution is to divide the face into eight areas and blend expressions
52 separately in each area. While doing this, the dynamics of the expressions must be controlled to give realism
53 and interest. This can not be achieved by deterministic finite state machine controls; a degree of random
54 variation is necessary. Finally, the expressions must be appropriate for the social context. This involves
55 modelling social conventions and personalities. The relative social standing and politeness of the participants
56 will affect their expressions. Embodied conversational agents implementing these ideas to exhibit a
57 vocabulary of nine emotions achieve recognition rates between 37% and 93%.
58
59

60
Mel Slater (2009) presents his work on place illusion and plausibility in immersive virtual environments.
Immersive virtual reality systems present users with a 360° projected image, viewed through shutter glasses so

1 Computation of emotions in man and machines

2
3 that the left and right eyes receive different views allowing simulation of depth in the pictures. This can be a
4 compelling experience, with a strong sense of presence allowing initial disbelief to be suspended. It can also
5 be trite and risible. What influences the different experiences? Indeed, how can a user's response be
6 measured?
7

8
9 Slater's approach is to seek a "response as if real" in terms of physiological, behavioural and cognitive
10 responses. He identifies two separate factors that must both be present if the user's response is to be as real.
11 First, the virtual environment must provide a *place illusion* (π), the sense of being in a real place. Secondly, the
12 environment must provide a *plausibility illusion* (ψ), the sense that the scenario being presented is actually
13 happening. These two factors are independent, and absence of either will result in the user's response not
14 being as if real. Place illusion depends on the degree to which the sensory motor contingencies afforded by
15 the virtual reality system permit perception by using the participant's whole body much as they would in
16 reality. For example, head tracking enables them to bend down and look underneath things, and events in
17 peripheral vision lead to automatic head turns. Plausibility illusion depends on the extent to which the system
18 can produce events that directly relate to the participant, and the overall credibility of the scenario being
19 depicted in comparison with expectations. These are subjective concepts and can only be measured through
20 indirect assessments such as physiological measures, behavioural responses and questionnaires. Interestingly,
21 both can be achieved when the virtual reality only modestly approximates to physical reality.
22
23
24

25 Amy Baylor (2009) presents her work on visual presence and appearance in virtual agents. She investigates
26 what makes a virtual agent (such as an anthropomorphic interface agent or even a simple pop-up window
27 containing text) persuasive. The result is to influence the empathy and receptiveness of a human viewer more
28 strongly, leading to more significant responses in terms of interest, attitudes and beliefs. Key factors include
29 the agent's visibility, gender, race, age and even attractiveness and 'coolness'.
30
31

32 Initial studies show that a visible agent is more persuasive than a spoken message, which in turn is more
33 persuasive than a simple textual message or voice alone. This effect is even significant when a computer
34 program is delivering an error message. A message spoken by a visible agent was much more positively
35 received than a text message; participants tended to blame themselves when a text box popped up, but
36 blamed the computer when the error message was deliver by the visible agent. As with communications
37 between people, the appearance of virtual agents is also important. Users receive a message more readily
38 from an avatar of their own gender and ethnicity. However, these general rules break down in specific
39 contexts. Middle-school students (male and female) were significantly more persuaded to consider
40 Engineering as a subject for further study when persuaded by a female (as opposed to male) agent. In a
41 broader experimental study, avatars with young, 'cool' appearances were more effective in persuading
42 university freshmen to study Engineering (especially when attractive and female), again suggesting a peer
43 group effect. However, older, 'uncool' avatars were almost as effective, suggesting that old stereotypes of
44 engineers persist.
45
46
47
48

49 APPLICATIONS

50
51 The final theme considers a range of emerging application areas for affective computing. First, affect-sensing
52 and affect-expressing technologies can enhance people's ability to make sense of and communicate with
53 others, especially those individuals who have difficulties understanding, communication and regulating their
54 affective systems, such as those with autism spectrum disorders, affective mood disorders, anxiety, nonverbal
55 learning disorders, visually impaired individuals and others. Secondly, affect-sensing and affect-expressing
56 technologies can advance social-emotional intelligence in machines including conversational agents and
57 sociable robots to improve people's experience with technology. Finally, as affect-measurement technologies
58 continue to mature, researchers will be able to build technologies and models that facilitate real-world testing
59 of contending theories of the mechanisms that underpin social cognition, developmental trajectories and
60

1
2
3 modes of derailed development such as autism. This is particularly exciting because it means that studies of
4 affect can be transferred from the laboratory to real-world situations.
5

6
7 Simon Baron-Cohen (Baron-Cohen, Golan and Ashwin 2009) brings a clinical perspective to the role of
8 emotional intelligence in everyday social interactions and communication by highlighting the difficulties that
9 individuals on the autism spectrum face. Individuals with autism spectrum conditions (ASCs) have major
10 difficulties in recognizing and responding to emotional and mental states in others' facial expressions. Baron-
11 Cohen starts with an operational definition of empathy, specifics two components of empathy, emphasizes
12 how such difficulties underlie the social and communication difficulties that form a core of the diagnosis of
13 autism spectrum conditions, and argues that at least one of these component are amenable to teaching.
14

15
16 Baron-Cohen has developed a series of short animated films designed to enhance emotion comprehension in
17 children with ASCs, and describes a study that evaluates the efficacy of the animated series in improving
18 emotion vocabulary and recognition in clinical trials. The results are very promising, with three levels of
19 generalization including both similar stimuli and substantially different video-based stimuli. Baron-Cohen
20 concludes with a discussion on the importance of designing for these populations, and putting into
21 consideration specific strengths (e.g., hyper-systemizing and attention to detail) as well as sensitivities (e.g.,
22 atypical sensory processing).
23

24
25 Rosalind Picard (2009) continues on the theme of technology that helps people sense, regulate and
26 communicate affect, focusing particularly on autonomic nervous system (ANS) arousal. Picard starts with a
27 case study of people who have difficulty expressing their emotions, appearing to be calm and relaxed, yet
28 experiencing extreme overload as measured by ANS activation. Affect-sensing technology can change this, by
29 enabling people with such difficulties to visualize and share emotional information with others. Preliminary
30 trials show that the technology helps conversational partners understand the difficulties experienced by
31 people with ASCs, even when those difficulties can not be articulated clearly.
32

33
34 Picard also highlights an especially important application of these technologies – enabling researchers to
35 validate contending theories of affect and social cognition. She presents a new methodological paradigm
36 where very large sets of individualized data are processed using dynamic pattern analysis that looks across
37 many variables. This enables researchers to conduct real-world measurements in the field that were previously
38 restricted to the laboratory.
39

40
41 Kristina Höök (2009) presents affective applications as affective loop experiences. She emphasizes that
42 emotions are processes, part and parcel of the interaction, and covering everyday bodily, cognitive and social
43 experiences. Within this context she presents several prototypes that are built around this theme with the goal
44 to pull the user into the interaction and engage the user at the affective, cognitive and social level. Users of the
45 system are active participants of the interaction and can choose to drive and shape in ways that are
46 meaningful to them.
47

48
49 Finally, Bill Gaver (2009) brings a design perspective to affective computing. His observations raise difficult
50 questions, criticise bland assumptions by technologists, and introduce a healthy note of scepticism. Gaver
51 challenges the use of computational approaches to emotion particularly in design, drawing on a range of
52 technical, cultural and aesthetic reasons. Gaver describes a prototype that they built that uses sensor-based
53 inferences to comment on domestic "well-being" and shares how this prototype was a failure. As an
54 alternative, Gaver advocates a broader view of interaction design in which open-ended designs serve as
55 resources for individual appropriation, and suggests that emotional experiences become one of several
56 outcomes of engaging with them.
57

58
59 Numerous challenges emerged from this final theme. How far are our technologies from really working in the
60 field, under limited control? How close are our models in terms of modelling the complexity and uncertainty

1 Computation of emotions in man and machines
2

3 inherent in emotional and social interactions? In the case where this technology is presented as assistive or
4 augmentative, generalization is an important concern. How well do the acquired skills generalize to new
5 settings?
6
7

8 DISCUSSION 9

10 Each of these four sessions was followed by a discussion which explored the broader issues raised in the
11 formal presentations. These provide a useful framework for future research.
12

13 From considering the way in which people understand emotions, it was apparent that a richer classification
14 than the six basic emotions would be required. There are arguments for both multi-dimensional continua and
15 larger taxonomies of discrete emotions. In either case, the simultaneous expression of several emotions must
16 be accommodated in both analysis and synthesis. Similarly, it is apparent that still pictures can not convey a
17 full range of emotions; the dynamics of expression are also important.
18
19

20 More subtly, it is necessary to distinguish emotions from moods. Emotions are relatively transient external
21 expressions, but moods are sustained aspects of an individual's personality. For example, anger is an emotion,
22 but hatred is a mood. Most of the work presented was considering emotions, but there is perhaps a need to
23 understand the underlying moods.
24
25

26 Any analysis of mental states can not take sensor readings in isolation, but must consider their context.
27 Interpretation depends on culture, the activity being undertaken and even the time of day. There is also the
28 question of personal variation, not only in amplitude of expression, but also in personal displays such as
29 blushing or dilation of pupils.
30
31

32 Many of the analytical systems presented relied on machine learning techniques, and there was considerable
33 discussion of what forms of training data were appropriate. There was a strong preference for naturalistic
34 data, evoked by a real task. However, labelling the resulting data is difficult and time consuming. In any case,
35 the difference between a real and acted is smile is mostly a matter of degree rather than a discrete choice.
36 There is a case for using acted training data, especially if performed by professionally trained method actors.
37
38

39 It is hard to identify the minimal set of competences required in a system that is to express emotions. An
40 animated avatar is more persuasive than text, but the quality of animation does not appear to be significant.
41 Simply knowing that a robot is not human influences our own perceptions and expectations. Speech is
42 valuable and prosody is important but, again, high fidelity does not appear to be significant. People are aware
43 of their own moods and use this to control their emotional displays; in the same way, displays by avatars and
44 robots must be appropriate to the context and audience. A degree of ambiguity in the synthesised displays
45 may add to their interest and realism.
46
47

48 If there is one lesson to be learned from the development of popular computer applications over the past 25
49 years, it is that the most successful emerged by accident. So it seems futile to try to predict future applications
50 of affective computing. It is clear that emotional intelligence is of some value, so applications should not be
51 completely decoupled from their users' feelings. On the other hand, measurement of a person's mental state
52 is unlikely to be exact. After all, even people find it hard. There will be some intermediate point where a
53 degree of emotional intelligence will give hints to a system rather than precise guidance, but there is no
54 obvious application waiting to occupy the sweet spot.
55
56

57 Perhaps surprisingly, participants in the discussion were generally relaxed about the social implications of
58 computer systems that monitor and manipulate people's emotions. However, we were reminded of Brian
59 Aldiss' novel, *The primal urge* (Aldiss 1961). The premise is the invention of an emotion register, a small disc
60 on an individual's forehead wired through to its wearer's hypothalamus, so that that the disc glows red when

1
2
3 its wearer is attracted to another person. After some initial ructions, these prove acceptable and even
4 popular. However, the closing paragraph of the novel reveals the possibility of a second disc that glows when
5 its wearer lies... We are still some way from creating such a simple technology that gives such a clear signal of
6 emotions, but there are still ethical questions to be addressed.
7
8

9 CONCLUSION

10
11 The remaining papers in this special issue of the *Philosophical Transactions* record the presentations made
12 over the two days of the meeting. The computation of emotions draws on insights from a wide variety of
13 disciplines, and these papers span the whole range from the underlying psychology through computer science
14 and machine learning to practical applications. The authors represent the leading authorities in their fields
15 and their work is setting the agenda for future research across the whole breadth of the subject. We hope
16 that this compilation sets forth a research agenda for inter and multi-disciplinary research in emotion research.
17
18

19
20 From the discussion meeting, several challenges emerged. The first challenge is to develop applications that
21 address the wide range of affective states that people experience, communicate and attribute to each other.
22 This entails continuing to push affect-sensing technologies and models that can identify subtle nuances and
23 intensities of a wide range of affective states, which consider the rich spectrum of modalities that humans
24 employ to express themselves, and which consider the dynamics of these channels. Models should represent
25 emotions as emergent processes, which change with internal and external contextual cues, including a
26 person's past experiences, appraisal of current events, and relationship with the interaction partner.
27
28

29
30 The second challenge is brought about by adopting an embodied approach to sensing people's state, where
31 systems are not just passive sensors but are instrumental in driving human-computer and human-human
32 interactions. Besides the challenges brought about by sensing people "in the wild", there are challenges in
33 implementing real-time, dynamic mechanisms and novel applications that learn with their users rather than
34 simply being trained in advance. With the increasing use of robots and agents that will interact with people,
35 there is growing interest in enabling machines to learn better by learning from people in a more natural,
36 collaborative manner, not just from people who program the computer or robot.
37
38

39
40 The third grand challenge we propose is moving towards new methodologies that enable not only large-scale
41 sensing of people's individual affect-related data, but also networks of data, such as face-to-face interactions
42 of groups of people, or physiological sensing of large audiences. Within this framework, every instance of an
43 interaction can be considered as an opportunity to learn about that person's specific knowledge and
44 experiences.
45

46 REFERENCES

- 47
48 Aldiss, Brian W. *The primal urge*. Ballantine Books, 1961.
49
50 Baron-Cohen, Simon, Ofer Golan, and Emma Ashwin. "Can emotion recognition be taught to children with
51 autism spectrum conditions?" *Phil. Trans. R. Soc. B*, 2009.
52
53 Baylor, Amy L. "Promoting motivation with anthropomorphic interface agents: the importance of agent
54 presence and appearance." *Phil. Trans. R. Soc. B*, 2009.
55
56 Boker, Steven M, Jeffrey F Cohn, Barry-John Theobald, Iain Matthews, Timothy R Brick, and Jeffrey R Spies.
57 "Effect of damping head movement and facial expression in dyadic conversation using real-time facial
58 expression tracking and synthesized avatars." *Phil. Trans. R. Soc. B*, 2009.
59
60 Breazeal, Cynthia. *Designing sociable robots*. Cambridge: MIT Press, 2002.

1 Computation of emotions in man and machines

2
3 Breazeal, Cynthia. "The role of expressive behavior for robots that learn from people." *Phil. Trans. R. Soc. B*,
4 2009.

5
6
7 Cowie, Roddy. "Perceiving emotion: towards a realistic understanding of the task." *Phil. Trans. R. Soc. B*, 2009.

8
9 Darwin, Charles. *The expression of the emotions in man and animals*. London: John Murray, 1872.

10
11 de Gelder, Beatrice. "Why bodies? Twelve reasons for including bodily expressions in affective neuroscience."
12 *Phil. Trans. R. Soc. B*, 2009.

13
14 Ekman, Paul. *Darwin and facial expression*. Academic Press, 1973.

15
16 Ekman, Paul. "Darwin's contributions to our understanding of emotional expressions." *Phil. Trans. R. Soc. B*,
17 2009.

18
19 Ekman, Paul, and W.V. Friesen. *Facial action coding system: a technique for the measurement of facial*
20 *movement*. Palo Alto: Consulting Psychologists Press, 1978.

21
22 Frith, Chris. "The role of facial expressions in social interactions." *Phil. Trans. R. Soc. B*, 2009.

23
24 Gaver, William. "Designing for emotion (among other things)." *Phil. Trans. R. Soc. B*, 2009.

25
26 Hess, Ursula, Reginald B Adams, and Robert E Kleck. "The face is not an empty canvas; How facial expressions
27 interact with facial appearance." *Phil. Trans. R. Soc. B*, 2009.

28
29 Höök, Kristina. "Affective loop experiences: designing for interactional embodiment." *Phil. Trans. R. Soc. B*,
30 2009.

31
32 Mori, Masahiro. "The uncanny valley." *Energy* 7, no. 4 (1970): 33-35.

33
34 Pantic, Maja. "Machine analysis of facial behaviour: naturalistic and dynamic behaviour." *Phil. Trans. R. Soc. B*,
35 2009.

36
37 Pelachaud, Catherine. "Modelling multimodal expression of emotion in a virtual agent." *Phil. Trans. R. Soc. B*,
38 2009.

39
40 Picard, Rosalind W. *Affective computing*. Cambridge: MIT Press, 1997.

41
42 Picard, Rosalind W. "Future affective technology for autism and emotion communication." *Phil. Trans. R. Soc.*
43 *B*, 2009.

44
45 Scherer, Klaus R. "Emotions are emergent processes: they require a dynamic computational architecture." *Phil.*
46 *Trans. R. Soc. B*, 2009.

47
48 Slater, Mel. "Place illusion and plausibility can lead to realistic behaviour in immersive virtual environments."
49 *Phil. Trans. R. Soc. B*, 2009.