

Linear Temporal Logic (LTL)

- ▶ Grammar of *well formed formulae* (wff) ϕ

$\phi ::= p$	(Atomic formula: $p \in AP$)
$\neg\phi$	(Negation)
$\phi_1 \vee \phi_2$	(Disjunction)
$X\phi$	(successor)
$F\phi$	(sometimes)
$G\phi$	(always)
$[\phi_1 \mathbf{U} \phi_2]$	(Until)

- ▶ Details differ from Prior's tense logic – but similar ideas
- ▶ Semantics define when ϕ true in model M
 - ▶ where $M = (S, S_0, R, L)$ – a Kripke structure
 - ▶ notation: $M \models \phi$ means ϕ true in model M
 - ▶ model checking algorithms compute this (when decidable)

$M \models \phi$ means “wff ϕ is true in model M ”

- ▶ If $M = (S, S_0, R, L)$ then

π is an M -path starting from s iff $\text{Path } R s \pi$

- ▶ If $M = (S, S_0, R, L)$ then we define $M \models \phi$ to mean:

ϕ is true on all M -paths starting from a member of S_0

- ▶ We will define $\llbracket \phi \rrbracket_M(\pi)$ to mean

ϕ is true on the M -path π

- ▶ Thus $M \models \phi$ will be formally defined by:

$M \models \phi \Leftrightarrow \forall \pi s. s \in S_0 \wedge \text{Path } R s \pi \Rightarrow \llbracket \phi \rrbracket_M(\pi)$

- ▶ It remains to actually define $\llbracket \phi \rrbracket_M$ for all wffs ϕ

Definition of $\llbracket \phi \rrbracket_M(\pi)$

- ▶ $\llbracket \phi \rrbracket_M(\pi)$ is the application of function $\llbracket \phi \rrbracket_M$ to path π
 - ▶ thus $\llbracket \phi \rrbracket_M : (\mathbb{N} \rightarrow \mathcal{S}) \rightarrow \mathbb{B}$

- ▶ Let $M = (\mathcal{S}, \mathcal{S}_0, R, L)$

$\llbracket \phi \rrbracket_M$ is defined by structural induction on ϕ

$$\llbracket p \rrbracket_M(\pi) = p \in L(\pi 0)$$

$$\llbracket \neg \phi \rrbracket_M(\pi) = \neg(\llbracket \phi \rrbracket_M(\pi))$$

$$\llbracket \phi_1 \vee \phi_2 \rrbracket_M(\pi) = \llbracket \phi_1 \rrbracket_M(\pi) \vee \llbracket \phi_2 \rrbracket_M(\pi)$$

$$\llbracket \mathbf{X}\phi \rrbracket_M(\pi) = \llbracket \phi \rrbracket_M(\pi \downarrow 1)$$

$$\llbracket \mathbf{F}\phi \rrbracket_M(\pi) = \exists i. \llbracket \phi \rrbracket_M(\pi \downarrow i)$$

$$\llbracket \mathbf{G}\phi \rrbracket_M(\pi) = \forall i. \llbracket \phi \rrbracket_M(\pi \downarrow i)$$

$$\llbracket \phi_1 \mathbf{U} \phi_2 \rrbracket_M(\pi) = \exists i. \llbracket \phi_2 \rrbracket_M(\pi \downarrow i) \wedge \forall j. j < i \Rightarrow \llbracket \phi_1 \rrbracket_M(\pi \downarrow j)$$

- ▶ We look at each of these semantic equations in turn

$$\llbracket p \rrbracket_M(\pi) = p(\pi 0)$$

- ▶ Assume $M = (S, S_0, R, L)$
- ▶ We have: $\llbracket p \rrbracket_M(\pi) = p \in L(\pi 0)$
 - ▶ p is an atomic property, i.e. $p \in AP$
 - ▶ $\pi : \mathbb{N} \rightarrow S$ so $\pi 0 \in S$
 - ▶ $\pi 0$ is the first state in path π
 - ▶ $p \in L(\pi 0)$ is *true* iff atomic property p holds of state $\pi 0$
- ▶ $\llbracket p \rrbracket_M(\pi)$ means p holds of the first state in path π
- ▶ $\top, \text{F} \in AP$ with $\top \in L(s)$ and $\text{F} \notin L(s)$ for all $s \in S$
 - ▶ $\llbracket \top \rrbracket_M(\pi)$ is always true
 - ▶ $\llbracket \text{F} \rrbracket_M(\pi)$ is always false

$$\llbracket \neg \phi \rrbracket_M(\pi) = \neg(\llbracket \phi \rrbracket_M(\pi))$$

$$\llbracket \phi_1 \vee \phi_2 \rrbracket_M(\pi) = \llbracket \phi_1 \rrbracket_M(\pi) \vee \llbracket \phi_2 \rrbracket_M(\pi)$$

▶ $\llbracket \neg \phi \rrbracket_M(\pi) = \neg(\llbracket \phi \rrbracket_M(\pi))$

▶ $\llbracket \neg \phi \rrbracket_M(\pi)$ true iff $\llbracket \phi \rrbracket_M(\pi)$ is not true

▶ $\llbracket \phi_1 \vee \phi_2 \rrbracket_M(\pi) = \llbracket \phi_1 \rrbracket_M(\pi) \vee \llbracket \phi_2 \rrbracket_M(\pi)$

▶ $\llbracket \phi_1 \vee \phi_2 \rrbracket_M(\pi)$ true iff $\llbracket \phi_1 \rrbracket_M(\pi)$ is true or $\llbracket \phi_2 \rrbracket_M(\pi)$ is true

$$\llbracket \mathbf{X}\phi \rrbracket_M(\pi) = \llbracket \phi \rrbracket_M(\pi \downarrow 1)$$

▶ $\llbracket \mathbf{X}\phi \rrbracket_M(\pi) = \llbracket \phi \rrbracket_M(\pi \downarrow 1)$

▶ $\pi \downarrow 1$ is π with the first state chopped off

$$\pi \downarrow 1(0) = \pi(1 + 0) = \pi(1)$$

$$\pi \downarrow 1(1) = \pi(1 + 1) = \pi(2)$$

$$\pi \downarrow 1(2) = \pi(1 + 2) = \pi(3)$$

⋮

▶ $\llbracket \mathbf{X}\phi \rrbracket_M(\pi)$ true iff $\llbracket \phi \rrbracket_M$ true starting at *the second state* of π

$$\llbracket \mathbf{F}\phi \rrbracket_M(\pi) = \exists i. \llbracket \phi \rrbracket_M(\pi \downarrow i)$$

- ▶ $\llbracket \mathbf{F}\phi \rrbracket_M(\pi) = \exists i. \llbracket \phi \rrbracket_M(\pi \downarrow i)$
 - ▶ $\pi \downarrow i$ is π with the first i states chopped off
$$\begin{aligned}\pi \downarrow i(0) &= \pi(i+0) = \pi(i) \\ \pi \downarrow i(1) &= \pi(i+1) \\ \pi \downarrow i(2) &= \pi(i+2) \\ &\vdots\end{aligned}$$
 - ▶ $\llbracket \phi \rrbracket_M(\pi \downarrow i)$ true iff $\llbracket \phi \rrbracket_M$ true *starting i states along π*
- ▶ $\llbracket \mathbf{F}\phi \rrbracket_M(\pi)$ true iff $\llbracket \phi \rrbracket_M$ true *starting somewhere along π*
- ▶ “ $\mathbf{F}\phi$ ” is read as “sometimes ϕ ”

$$\llbracket \mathbf{G}\phi \rrbracket_M(\pi) = \forall i. \llbracket \phi \rrbracket_M(\pi \downarrow i)$$

- ▶ $\llbracket \mathbf{G}\phi \rrbracket_M(\pi) = \forall i. \llbracket \phi \rrbracket_M(\pi \downarrow i)$
 - ▶ $\pi \downarrow i$ is π with the first i states chopped off
 - ▶ $\llbracket \phi \rrbracket_M(\pi \downarrow i)$ true iff $\llbracket \phi \rrbracket_M$ true *starting i states along π*
- ▶ $\llbracket \mathbf{G}\phi \rrbracket_M(\pi)$ true iff $\llbracket \phi \rrbracket_M$ true *starting anywhere along π*
- ▶ “ $\mathbf{G}\phi$ ” is read as “always ϕ ” or “globally ϕ ”
- ▶ $M \models \mathbf{AG}p$ defined earlier: $M \models \mathbf{AG}p \Leftrightarrow M \models \mathbf{G}(p)$
- ▶ \mathbf{G} is definable in terms of \mathbf{F} and \neg : $\mathbf{G}\phi = \neg(\mathbf{F}(\neg\phi))$

$$\begin{aligned} \llbracket \neg(\mathbf{F}(\neg\phi)) \rrbracket_M(\pi) &= \neg(\llbracket \mathbf{F}(\neg\phi) \rrbracket_M(\pi)) \\ &= \neg(\exists i. \llbracket \neg\phi \rrbracket_M(\pi \downarrow i)) \\ &= \neg(\exists i. \neg(\llbracket \phi \rrbracket_M(\pi \downarrow i))) \\ &= \forall i. \llbracket \phi \rrbracket_M(\pi \downarrow i) \\ &= \llbracket \mathbf{G}\phi \rrbracket_M(\pi) \end{aligned}$$

$$\llbracket [\phi_1 \mathbf{U} \phi_2] \rrbracket_M(\pi) = \exists i. \llbracket \phi_2 \rrbracket_M(\pi \downarrow i) \wedge \forall j. j < i \Rightarrow \llbracket \phi_1 \rrbracket_M(\pi \downarrow j)$$

- ▶ $\llbracket [\phi_1 \mathbf{U} \phi_2] \rrbracket_M(\pi) = \exists i. \llbracket \phi_2 \rrbracket_M(\pi \downarrow i) \wedge \forall j. j < i \Rightarrow \llbracket \phi_1 \rrbracket_M(\pi \downarrow j)$
 - ▶ $\llbracket \phi_2 \rrbracket_M(\pi \downarrow i)$ true iff $\llbracket \phi_2 \rrbracket_M$ true *starting i states along π*
 - ▶ $\llbracket \phi_1 \rrbracket_M(\pi \downarrow j)$ true iff $\llbracket \phi_1 \rrbracket_M$ true *starting j states along π*

- ▶ $\llbracket [\phi_1 \mathbf{U} \phi_2] \rrbracket_M(\pi)$ is true iff

$\llbracket \phi_2 \rrbracket_M$ is true **somewhere** along π and **up to then** $\llbracket \phi_1 \rrbracket_M$ is true

- ▶ “[$\phi_1 \mathbf{U} \phi_2$]” is read as “ ϕ_1 until ϕ_2 ”

- ▶ **F** is definable in terms of [$- \mathbf{U} -$]: $\mathbf{F}\phi = [\mathbf{T} \mathbf{U} \phi]$

$$\begin{aligned} & \llbracket [\mathbf{T} \mathbf{U} \phi] \rrbracket_M(\pi) \\ &= \exists i. \llbracket \phi \rrbracket_M(\pi \downarrow i) \wedge \forall j. j < i \Rightarrow \llbracket \mathbf{T} \rrbracket_M(\pi \downarrow j) \\ &= \exists i. \llbracket \phi \rrbracket_M(\pi \downarrow i) \wedge \forall j. j < i \Rightarrow \mathbf{true} \\ &= \exists i. \llbracket \phi \rrbracket_M(\pi \downarrow i) \wedge \mathbf{true} \\ &= \exists i. \llbracket \phi \rrbracket_M(\pi \downarrow i) \\ &= \llbracket \mathbf{F}\phi \rrbracket_M(\pi) \end{aligned}$$

Review of Linear Temporal Logic (LTL)

- ▶ Grammar of *well formed formulae* (wff) ϕ

$\phi ::= p$	(Atomic formula: $p \in AP$)
$\neg\phi$	(Negation)
$\phi_1 \vee \phi_2$	(Disjunction)
$X\phi$	(successor)
$F\phi$	(sometimes)
$G\phi$	(always)
$[\phi_1 \mathbf{U} \phi_2]$	(Until)

- ▶ $M \models \phi$ means ϕ holds on all M -paths

- ▶ $M = (S, S_0, R, L)$
- ▶ $\llbracket \phi \rrbracket_M(\pi)$ means ϕ is true on the M -path π
- ▶ $M \models \phi \Leftrightarrow \forall \pi \text{ s. } s \in S_0 \wedge \text{Path } R \text{ s } \pi \Rightarrow \llbracket \phi \rrbracket_M(\pi)$

LTL examples

- ▶ “DeviceEnabled holds infinitely often along every path”

$\mathbf{G}(\mathbf{F} \text{ DeviceEnabled})$

- ▶ “Eventually the state becomes permanently Done”

$\mathbf{F}(\mathbf{G} \text{ Done})$

- ▶ “Every Req is followed by an Ack”

$\mathbf{G}(\text{Req} \Rightarrow \mathbf{F} \text{ Ack})$

Number of Req and Ack may differ - no counting

- ▶ “If Enabled infinitely often then Running infinitely often”

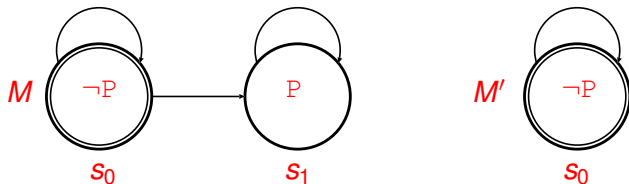
$\mathbf{G}(\mathbf{F} \text{ Enabled}) \Rightarrow \mathbf{G}(\mathbf{F} \text{ Running})$

- ▶ “An upward going lift at the second floor keeps going up if a passenger requests the fifth floor”

$\mathbf{G}(\text{AtFloor2} \wedge \text{DirectionUp} \wedge \text{RequestFloor5} \Rightarrow [\text{DirectionUp} \mathbf{U} \text{AtFloor5}])$

A property not expressible in LTL

- ▶ Let $AP = \{P\}$ and consider models M and M' below



$$M = (\{s_0, s_1\}, \{s_0\}, \{(s_0, s_0), (s_0, s_1), (s_1, s_1)\}, L)$$

$$M' = (\{s_0\}, \{s_0\}, \{(s_0, s_0)\}, L)$$

where: $L = \lambda s. \text{if } s = s_0 \text{ then } \{\} \text{ else } \{P\}$

- ▶ Every M' -path is also an M -path
- ▶ So if ϕ true on every M -path then ϕ true on every M' -path
- ▶ Hence in LTL for any ϕ if $M \models \phi$ then $M' \models \phi$
- ▶ Consider $\phi_P \Leftrightarrow$ “can always reach a state satisfying P ”
 - ▶ ϕ_P holds in M but not in M'
 - ▶ but in LTL can't have $M \models \phi_P$ and not $M' \models \phi_P$
- ▶ hence ϕ_P not expressible in LTL

LTL expressibility

“can always reach a state satisfying P ”

- ▶ In LTL $M \models \phi$ says ϕ holds of all paths of M
- ▶ LTL formulae ϕ are evaluated on paths ... path formulae
- ▶ Want to say that from any state there exists a path to some state satisfying p
 - ▶ $\forall s. \exists \pi. \text{Path } R s \pi \wedge \exists i. p \in L(\pi(i))$
 - ▶ but this isn't expressible in LTL (see slide 57)
- ▶ CTL properties are evaluated at a state ... state formulae
 - ▶ they can talk about both some or all paths
 - ▶ starting from the state they are evaluated at

Computation Tree Logic (CTL)

- ▶ LTL formulae ϕ are evaluated on paths ... path formulae
 - ▶ CTL formulae ψ are evaluated on states .. state formulae
-

- ▶ Syntax of CTL well-formed formulae:

$\psi ::= p$	(Atomic formula $p \in AP$)
$\neg\psi$	(Negation)
$\psi_1 \wedge \psi_2$	(Conjunction)
$\psi_1 \vee \psi_2$	(Disjunction)
$\psi_1 \Rightarrow \psi_2$	(Implication)
AX ψ	(All successors)
EX ψ	(Some successors)
A [ψ_1 U ψ_2]	(Until – along all paths)
E [ψ_1 U ψ_2]	(Until – along some path)

Semantics of CTL

- Assume $M = (S, S_0, R, L)$ and then define:

$$\llbracket p \rrbracket_M(s) = p \in L(s)$$

$$\llbracket \neg\psi \rrbracket_M(s) = \neg(\llbracket \psi \rrbracket_M(s))$$

$$\llbracket \psi_1 \wedge \psi_2 \rrbracket_M(s) = \llbracket \psi_1 \rrbracket_M(s) \wedge \llbracket \psi_2 \rrbracket_M(s)$$

$$\llbracket \psi_1 \vee \psi_2 \rrbracket_M(s) = \llbracket \psi_1 \rrbracket_M(s) \vee \llbracket \psi_2 \rrbracket_M(s)$$

$$\llbracket \psi_1 \Rightarrow \psi_2 \rrbracket_M(s) = \llbracket \psi_1 \rrbracket_M(s) \Rightarrow \llbracket \psi_2 \rrbracket_M(s)$$

$$\llbracket \mathbf{AX}\psi \rrbracket_M(s) = \forall s'. R s s' \Rightarrow \llbracket \psi \rrbracket_M(s')$$

$$\llbracket \mathbf{EX}\psi \rrbracket_M(s) = \exists s'. R s s' \wedge \llbracket \psi \rrbracket_M(s')$$

$$\begin{aligned} \llbracket \mathbf{A}[\psi_1 \mathbf{U} \psi_2] \rrbracket_M(s) &= \forall \pi. \text{Path } R s \pi \\ &\Rightarrow \exists i. \llbracket \psi_2 \rrbracket_M(\pi(i)) \\ &\quad \wedge \\ &\quad \forall j. j < i \Rightarrow \llbracket \psi_1 \rrbracket_M(\pi(j)) \end{aligned}$$

$$\begin{aligned} \llbracket \mathbf{E}[\psi_1 \mathbf{U} \psi_2] \rrbracket_M(s) &= \exists \pi. \text{Path } R s \pi \\ &\quad \wedge \exists i. \llbracket \psi_2 \rrbracket_M(\pi(i)) \\ &\quad \wedge \\ &\quad \forall j. j < i \Rightarrow \llbracket \psi_1 \rrbracket_M(\pi(j)) \end{aligned}$$

The defined operator **AF**

- ▶ Define **AF** $\psi = \mathbf{A}[\mathbf{T} \mathbf{U} \psi]$
- ▶ **AF** ψ true at s iff ψ true somewhere on every R -path from s

$$\begin{aligned} \llbracket \mathbf{AF}\psi \rrbracket_M(s) &= \llbracket \mathbf{A}[\mathbf{T} \mathbf{U} \psi] \rrbracket_M(s) \\ &= \forall \pi. \text{Path } R \text{ } s \pi \\ &\quad \Rightarrow \\ &\quad \exists i. \llbracket \psi \rrbracket_M(\pi(i)) \wedge \forall j. j < i \Rightarrow \llbracket \mathbf{T} \rrbracket_M(\pi(j)) \\ &= \forall \pi. \text{Path } R \text{ } s \pi \\ &\quad \Rightarrow \\ &\quad \exists i. \llbracket \psi \rrbracket_M(\pi(i)) \wedge \forall j. j < i \Rightarrow \text{true} \\ &= \forall \pi. \text{Path } R \text{ } s \pi \Rightarrow \exists i. \llbracket \psi \rrbracket_M(\pi(i)) \end{aligned}$$

The defined operator **EF**

- ▶ Define **EF** $\psi = \mathbf{E}[\mathbf{T} \mathbf{U} \psi]$
- ▶ **EF** ψ true at s iff ψ true somewhere on some R -path from s

$$\begin{aligned} \llbracket \mathbf{EF}\psi \rrbracket_M(s) &= \llbracket \mathbf{E}[\mathbf{T} \mathbf{U} \psi] \rrbracket_M(s) \\ &= \exists \pi. \text{Path } R \text{ } s \pi \\ &\quad \wedge \\ &\quad \exists i. \llbracket \psi \rrbracket_M(\pi(i)) \wedge \forall j. j < i \Rightarrow \llbracket \mathbf{T} \rrbracket_M(\pi(j)) \\ &= \exists \pi. \text{Path } R \text{ } s \pi \\ &\quad \wedge \\ &\quad \exists i. \llbracket \psi \rrbracket_M(\pi(i)) \wedge \forall j. j < i \Rightarrow \text{true} \\ &= \exists \pi. \text{Path } R \text{ } s \pi \wedge \exists i. \llbracket \psi \rrbracket_M(\pi(i)) \end{aligned}$$

- ▶ “can reach a state satisfying ρ ” is **EF** ρ

The defined operator **AG**

- ▶ Define **AG** $\psi = \neg\mathbf{EF}(\neg\psi)$
- ▶ **AG** ψ true at s iff ψ true **everywhere** on **every** R -path from s

$$\begin{aligned} \llbracket \mathbf{AG}\psi \rrbracket_M(s) &= \llbracket \neg\mathbf{EF}(\neg\psi) \rrbracket_M(s) \\ &= \neg(\llbracket \mathbf{EF}(\neg\psi) \rrbracket_M(s)) \\ &= \neg(\exists\pi. \text{Path } R \text{ } s \text{ } \pi \wedge \exists i. \llbracket \neg\psi \rrbracket_M(\pi(i))) \\ &= \neg(\exists\pi. \text{Path } R \text{ } s \text{ } \pi \wedge \exists i. \neg\llbracket \psi \rrbracket_M(\pi(i))) \\ &= \forall\pi. \neg(\text{Path } R \text{ } s \text{ } \pi \wedge \exists i. \neg\llbracket \psi \rrbracket_M(\pi(i))) \\ &= \forall\pi. \neg\text{Path } R \text{ } s \text{ } \pi \vee \neg(\exists i. \neg\llbracket \psi \rrbracket_M(\pi(i))) \\ &= \forall\pi. \neg\text{Path } R \text{ } s \text{ } \pi \vee \forall i. \neg\neg\llbracket \psi \rrbracket_M(\pi(i)) \\ &= \forall\pi. \neg\text{Path } R \text{ } s \text{ } \pi \vee \forall i. \llbracket \psi \rrbracket_M(\pi(i)) \\ &= \forall\pi. \text{Path } R \text{ } s \text{ } \pi \Rightarrow \forall i. \llbracket \psi \rrbracket_M(\pi(i)) \end{aligned}$$

- ▶ **AG** ψ means ψ true at all reachable states
- ▶ $\llbracket \mathbf{AG}(p) \rrbracket_M(s) \equiv \forall s'. R^* s s' \Rightarrow p \in L(s')$
- ▶ “can always reach a state satisfying p ” is **AG**(**EF** p)

The defined operator **EG**

- ▶ Define **EG** $\psi = \neg\mathbf{AF}(\neg\psi)$
- ▶ **EG** ψ true at s iff ψ true **everywhere** on **some** R -path from s

$$\begin{aligned} \llbracket \mathbf{EG}\psi \rrbracket_M(s) &= \llbracket \neg\mathbf{AF}(\neg\psi) \rrbracket_M(s) \\ &= \neg(\llbracket \mathbf{AF}(\neg\psi) \rrbracket_M(s)) \\ &= \neg(\forall\pi. \text{Path } R \text{ } s \text{ } \pi \Rightarrow \exists i. \llbracket \neg\psi \rrbracket_M(\pi(i))) \\ &= \neg(\forall\pi. \text{Path } R \text{ } s \text{ } \pi \Rightarrow \exists i. \neg\llbracket \psi \rrbracket_M(\pi(i))) \\ &= \exists\pi. \neg(\text{Path } R \text{ } s \text{ } \pi \Rightarrow \exists i. \neg\llbracket \psi \rrbracket_M(\pi(i))) \\ &= \exists\pi. \text{Path } R \text{ } s \text{ } \pi \wedge \neg(\exists i. \neg\llbracket \psi \rrbracket_M(\pi(i))) \\ &= \exists\pi. \text{Path } R \text{ } s \text{ } \pi \wedge \forall i. \neg\neg\llbracket \psi \rrbracket_M(\pi(i)) \\ &= \exists\pi. \text{Path } R \text{ } s \text{ } \pi \wedge \forall i. \llbracket \psi \rrbracket_M(\pi(i)) \end{aligned}$$

The defined operator $\mathbf{A}[\psi_1 \mathbf{W} \psi_2]$

- ▶ $\mathbf{A}[\psi_1 \mathbf{W} \psi_2]$ is a ‘partial correctness’ version of $\mathbf{A}[\psi_1 \mathbf{U} \psi_2]$
- ▶ It is true at s if along all R -paths from s :
 - ▶ ψ_1 always holds on the path, or
 - ▶ ψ_2 holds sometime on the path, and until it does ψ_1 holds

▶ Define

$$\begin{aligned} & \llbracket \mathbf{A}[\psi_1 \mathbf{W} \psi_2] \rrbracket_M(s) \\ &= \llbracket \neg \mathbf{E}[(\psi_1 \wedge \neg \psi_2) \mathbf{U} (\neg \psi_1 \wedge \neg \psi_2)] \rrbracket_M(s) \\ &= \neg \llbracket \mathbf{E}[(\psi_1 \wedge \neg \psi_2) \mathbf{U} (\neg \psi_1 \wedge \neg \psi_2)] \rrbracket_M(s) \\ &= \neg(\exists \pi. \text{Path } R \text{ } s \ \pi \\ & \quad \wedge \\ & \quad \exists i. \llbracket \neg \psi_1 \wedge \neg \psi_2 \rrbracket_M(\pi(i)) \\ & \quad \wedge \\ & \quad \forall j. j < i \Rightarrow \llbracket \psi_1 \wedge \neg \psi_2 \rrbracket_M(\pi(j))) \end{aligned}$$

- ▶ Exercise: understand the next two slides!

A[ψ_1 W ψ_2] continued (1)

► Continuing:

$$\neg(\exists \pi. \text{Path } R \text{ s } \pi \\ \wedge \\ \exists i. [\neg\psi_1 \wedge \neg\psi_2]_M(\pi(i)) \wedge \forall j. j < i \Rightarrow [\psi_1 \wedge \neg\psi_2]_M(\pi(j)))$$

$$= \forall \pi. \neg(\text{Path } R \text{ s } \pi \\ \wedge \\ \exists i. [\neg\psi_1 \wedge \neg\psi_2]_M(\pi(i)) \wedge \forall j. j < i \Rightarrow [\psi_1 \wedge \neg\psi_2]_M(\pi(j)))$$

$$= \forall \pi. \text{Path } R \text{ s } \pi \\ \Rightarrow \\ \neg(\exists i. [\neg\psi_1 \wedge \neg\psi_2]_M(\pi(i)) \wedge \forall j. j < i \Rightarrow [\psi_1 \wedge \neg\psi_2]_M(\pi(j)))$$

$$= \forall \pi. \text{Path } R \text{ s } \pi \\ \Rightarrow \\ \forall i. \neg[\neg\psi_1 \wedge \neg\psi_2]_M(\pi(i)) \vee \neg(\forall j. j < i \Rightarrow [\psi_1 \wedge \neg\psi_2]_M(\pi(j)))$$

$\mathbf{A}[\psi_1 \mathbf{W} \psi_2]$ continued (2)

► Continuing:

$$= \forall \pi. \text{Path } R \text{ s } \pi$$

\Rightarrow

$$\forall i. \neg[\neg\psi_1 \wedge \neg\psi_2]_M(\pi(i)) \vee \neg(\forall j. j < i \Rightarrow [\psi_1 \wedge \neg\psi_2]_M(\pi(j)))$$

$$= \forall \pi. \text{Path } R \text{ s } \pi$$

\Rightarrow

$$\forall i. \neg(\forall j. j < i \Rightarrow [\psi_1 \wedge \neg\psi_2]_M(\pi(j))) \vee \neg[\neg\psi_1 \wedge \neg\psi_2]_M(\pi(i))$$

$$= \forall \pi. \text{Path } R \text{ s } \pi$$

\Rightarrow

$$\forall i. (\forall j. j < i \Rightarrow [\psi_1 \wedge \neg\psi_2]_M(\pi(j))) \Rightarrow [\psi_1 \vee \psi_2]_M(\pi(i))$$

► Exercise: explain why this is $[\mathbf{A}[\psi_1 \mathbf{W} \psi_2]]_M(s)$?

- this exercise illustrates the subtlety of writing CTL!

Sanity check: $\mathbf{A}[\psi \mathbf{W} \mathbf{F}] = \mathbf{AG} \psi$

- ▶ From last slide:

$$\begin{aligned} & \llbracket \mathbf{A}[\psi_1 \mathbf{W} \psi_2] \rrbracket_M(s) \\ &= \forall \pi. \text{Path } R \text{ s } \pi \\ &\quad \Rightarrow \forall i. (\forall j. j < i \Rightarrow \llbracket \psi_1 \wedge \neg \psi_2 \rrbracket_M(\pi(j))) \Rightarrow \llbracket \psi_1 \vee \psi_2 \rrbracket_M(\pi(i)) \end{aligned}$$

- ▶ Set ψ_1 to ψ and ψ_2 to \mathbf{F} :

$$\begin{aligned} & \llbracket \mathbf{A}[\psi \mathbf{W} \mathbf{F}] \rrbracket_M(s) \\ &= \forall \pi. \text{Path } R \text{ s } \pi \\ &\quad \Rightarrow \forall i. (\forall j. j < i \Rightarrow \llbracket \psi \wedge \neg \mathbf{F} \rrbracket_M(\pi(j))) \Rightarrow \llbracket \psi \vee \mathbf{F} \rrbracket_M(\pi(i)) \end{aligned}$$

- ▶ Simplify:

$$\begin{aligned} & \llbracket \mathbf{A}[\psi \mathbf{W} \mathbf{F}] \rrbracket_M(s) \\ &= \forall \pi. \text{Path } R \text{ s } \pi \Rightarrow \forall i. (\forall j. j < i \Rightarrow \llbracket \psi \rrbracket_M(\pi(j))) \Rightarrow \llbracket \psi \rrbracket_M(\pi(i)) \end{aligned}$$

- ▶ By induction on i :

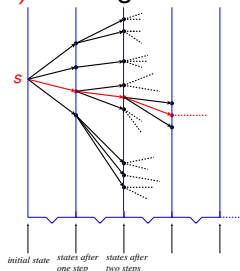
$$\llbracket \mathbf{A}[\psi \mathbf{W} \mathbf{F}] \rrbracket_M(s) = \forall \pi. \text{Path } R \text{ s } \pi \Rightarrow \forall i. \llbracket \psi \rrbracket_M(\pi(i))$$

-
- ▶ Exercises

1. Describe the property: $\mathbf{A}[\mathbf{T} \mathbf{W} \psi]$.
2. Describe the property: $\neg \mathbf{E}[\neg \psi_2 \mathbf{U} \neg(\psi_1 \vee \psi_2)]$.
3. Define $\mathbf{E}[\psi_1 \mathbf{W} \psi_2] = \mathbf{E}[\psi_1 \mathbf{U} \psi_2] \vee \mathbf{EG}\psi_1$.
Describe the property: $\mathbf{E}[\psi_1 \mathbf{W} \psi_2]$?

Recall model behaviour computation tree

- ▶ Atomic properties are true or false of individual states
- ▶ General properties are true or false of whole behaviour
- ▶ Behaviour of (S, R) starting from $s \in S$ as a tree:



- ▶ A path is shown in red
- ▶ Properties may look at all paths, or just a single path
 - ▶ CTL: Computation Tree Logic (all paths from a state)
 - ▶ LTL: Linear Temporal Logic (a single path)

Summary of CTL operators (primitive + defined)

► CTL formulae:

p	(Atomic formula - $p \in AP$)
$\neg\psi$	(Negation)
$\psi_1 \wedge \psi_2$	(Conjunction)
$\psi_1 \vee \psi_2$	(Disjunction)
$\psi_1 \Rightarrow \psi_2$	(Implication)
AX ψ	(All successors)
EX ψ	(Some successors)
AF ψ	(Somewhere – along all paths)
EF ψ	(Somewhere – along some path)
AG ψ	(Everywhere – along all paths)
EG ψ	(Everywhere – along some path)
A $[\psi_1 \mathbf{U} \psi_2]$	(Until – along all paths)
E $[\psi_1 \mathbf{U} \psi_2]$	(Until – along some path)
A $[\psi_1 \mathbf{W} \psi_2]$	(Unless – along all paths)
E $[\psi_1 \mathbf{W} \psi_2]$	(Unless – along some path)

Example CTL formulae

- ▶ **EF**(*Started* \wedge \neg *Ready*)

*It is possible to get to a state where **Started** holds but **Ready** does not hold*

- ▶ **AG**(*Req* \Rightarrow **AF***Ack*)

*If a request **Req** occurs, then it will eventually be acknowledged by **Ack***

- ▶ **AG**(**AF***DeviceEnabled*)

***DeviceEnabled** is always true somewhere along every path starting anywhere: i.e. **DeviceEnabled** holds infinitely often along every path*

- ▶ **AG**(**EF***Restart*)

*From any state it is possible to get to a state for which **Restart** holds*

Can't be expressed in LTL!

More CTL examples (1)

- ▶ **AG**(*Req* \Rightarrow **A**[*Req* **U** *Ack*])
If a request Req occurs, then it continues to hold, until it is eventually acknowledged
- ▶ **AG**(*Req* \Rightarrow **AX**(**A**[\neg *Req* **U** *Ack*]))
Whenever Req is true either it must become false on the next cycle and remains false until Ack, or Ack must become true on the next cycle
Exercise: is the **AX** necessary?
- ▶ **AG**(*Req* \Rightarrow (\neg *Ack* \Rightarrow **AX**(**A**[*Req* **U** *Ack*]))))
Whenever Req is true and Ack is false then Ack will eventually become true and until it does Req will remain true
Exercise: is the **AX** necessary?

More CTL examples (2)

- ▶ **AG**(*Enabled* \Rightarrow **AG**(*Start* \Rightarrow **A**[\neg *Waiting* **U** *Ack*]))
If Enabled is ever true then if Start is true in any subsequent state then Ack will eventually become true, and until it does Waiting will be false
- ▶ **AG**(\neg *Req*₁ \wedge \neg *Req*₂ \Rightarrow **A**[\neg *Req*₁ \wedge \neg *Req*₂ **U** (*Start* \wedge \neg *Req*₂)]))
Whenever Req₁ and Req₂ are false, they remain false until Start becomes true with Req₂ still false
- ▶ **AG**(*Req* \Rightarrow **AX**(*Ack* \Rightarrow **AF** \neg *Req*))
If Req is true and Ack becomes true one cycle later, then eventually Req will become false

Some abbreviations

- ▶ $\mathbf{AX}_i \psi \equiv \underbrace{\mathbf{AX}(\mathbf{AX}(\dots(\mathbf{AX} \psi)\dots))}_{i \text{ instances of } \mathbf{AX}}$
 ψ is true on all paths i units of time later
- ▶ $\mathbf{ABF}_{i..j} \psi \equiv \underbrace{\mathbf{AX}_i(\psi \vee \mathbf{AX}(\psi \vee \dots \mathbf{AX}(\psi \vee \mathbf{AX} \psi)\dots))}_{j - i \text{ instances of } \mathbf{AX}}$
 ψ is true on all paths sometime between i units of time later and j units of time later
- ▶ $\mathbf{AG}(\mathit{Req} \Rightarrow \mathbf{AX}(\mathit{Ack}_1 \wedge \mathbf{ABF}_{1..6}(\mathit{Ack}_2 \wedge \mathbf{A}[\mathit{Wait} \mathbf{U} \mathit{Reply}])))$
One cycle after Req , Ack_1 should become true, and then Ack_2 becomes true 1 to 6 cycles later and then eventually Reply becomes true, but until it does Wait holds from the time of Ack_2
- ▶ More abbreviations in 'Industry Standard' language PSL