

LiteLab: Efficient Large-scale Network Experiments

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Motivation - Challenges

- Deploying network systems in developing regions is a very difficult task, even for those mature and well-tested systems.
- There are both technical and non-technical barriers such as
 - extreme environment,
 - inefficient transportation,
 - lack of local technicians,
 - limited equipment,
 - poor infrastructure,
 - and many other socio-economical challenges.

Motivation - Requirements

- "Trial and error" method will simply fail in the rural context due to its high cost. To reduce both investment risk and maintenance overhead, we need to obtain a comprehensive understanding of the system.
- Due to the large parameter space, researchers usually need to run thousands of experiments with different parameter combinations.
 - Replayability is critical in modern network experiments.
 - Flexibility in the platform: easy to configure and extend.
 - Take advantage of the computation and storage resources in the cluster.
 - Reduce the experiment complexity and speeds up experiment life-cycle.
 - Provide satisfying accuracy.

Background – Multiple Options

- There are generally two methodologies to evaluate a system: model-based evaluation and experiment-based evaluation.
- Model-based: apply analytical models, mathematically tractable; but the complexity may explode as a system becomes more complicated.
- Experiment-based: take advantage of the ever-growing computation power to explore the problem space; suitable for large and complex systems; simulation, emulation, and real testbed.

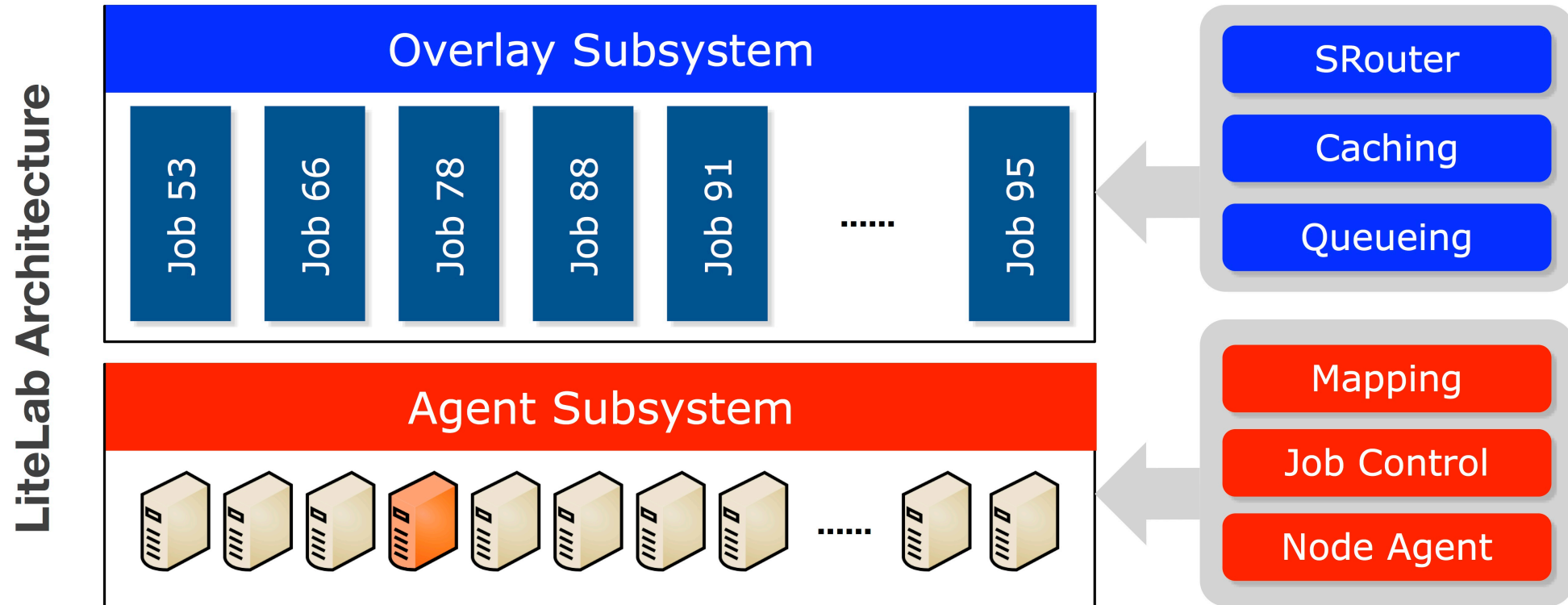
Three Exemplars

- Simulators: NS2 and NS3
 - one of the most famous among general purpose simulators;
 - has many tunable parameters to allow more realistic settings;
- Emulator: Emulab
 - tries to integrate simulation, emulation and live network into a common framework; the configuration and setup can be quite complicated.
- Internet: PlanetLab
 - a platform for live network experiments. The traffic goes through the real Internet and is subject to real-life dynamics.
- Many others, specialised in different.

LiteLab Architecture

- LiteLab consists of two subsystems: *Agent Subsystem* and *Overlay Subsystem*.
- All experiments are *jobs* in LiteLab and are defined by a job description archive provided by a user.
- A user submits the job to LiteLab which processes the job description archive, determines needed resources and allocates necessary physical nodes from the available nodes.
- LiteLab informs the selected nodes and deploys an instance of the Overlay Subsystem on them.
- LiteLab starts the experiment, and the logs are saved.

LiteLab Architecture



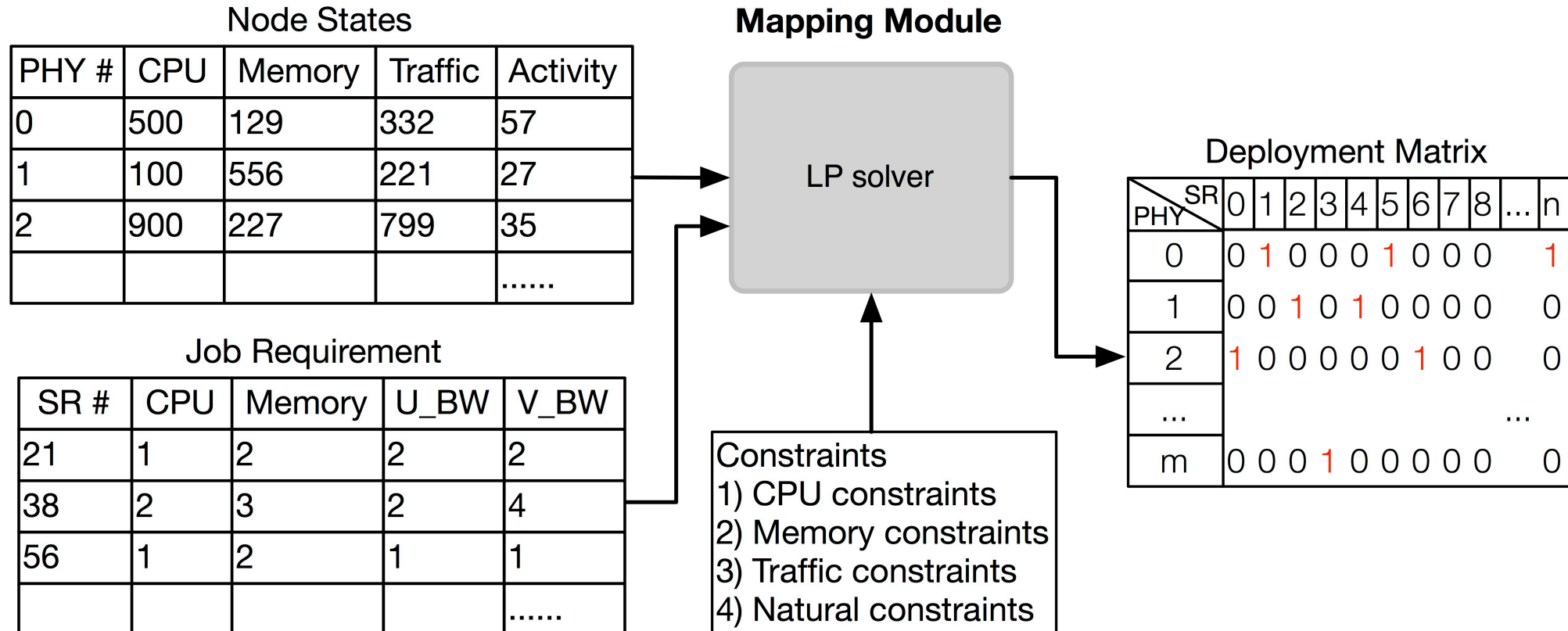
Agent Subsystem

- The Agent Subsystem provides a stable and uniform experiment infrastructure. It hides the communication complexity, resource failures and other underlying details from the Overlay Subsystem.
- There are three main components in Agent Subsystem:
 - **NodeAgent** represents a physical node;
 - **JobControl** manages all the submitted jobs in LiteLab;
 - **Mapping** maps virtual resources to physical resources;

Resource Allocation – Static Mapping

- Resource allocation focuses on the mapping between virtual nodes and physical nodes, and it is the key to platform scalability.
- The mapping maximises the resource utilisation, guarantee there is no violation of physical capacity.
- Four metrics are taken into account as the constraints: CPU load, network traffic, memory usage and use of pseudo-terminal devices.
- The mapping is formulated as an optimisation problem.

Static Mapping – Inputs and Outputs



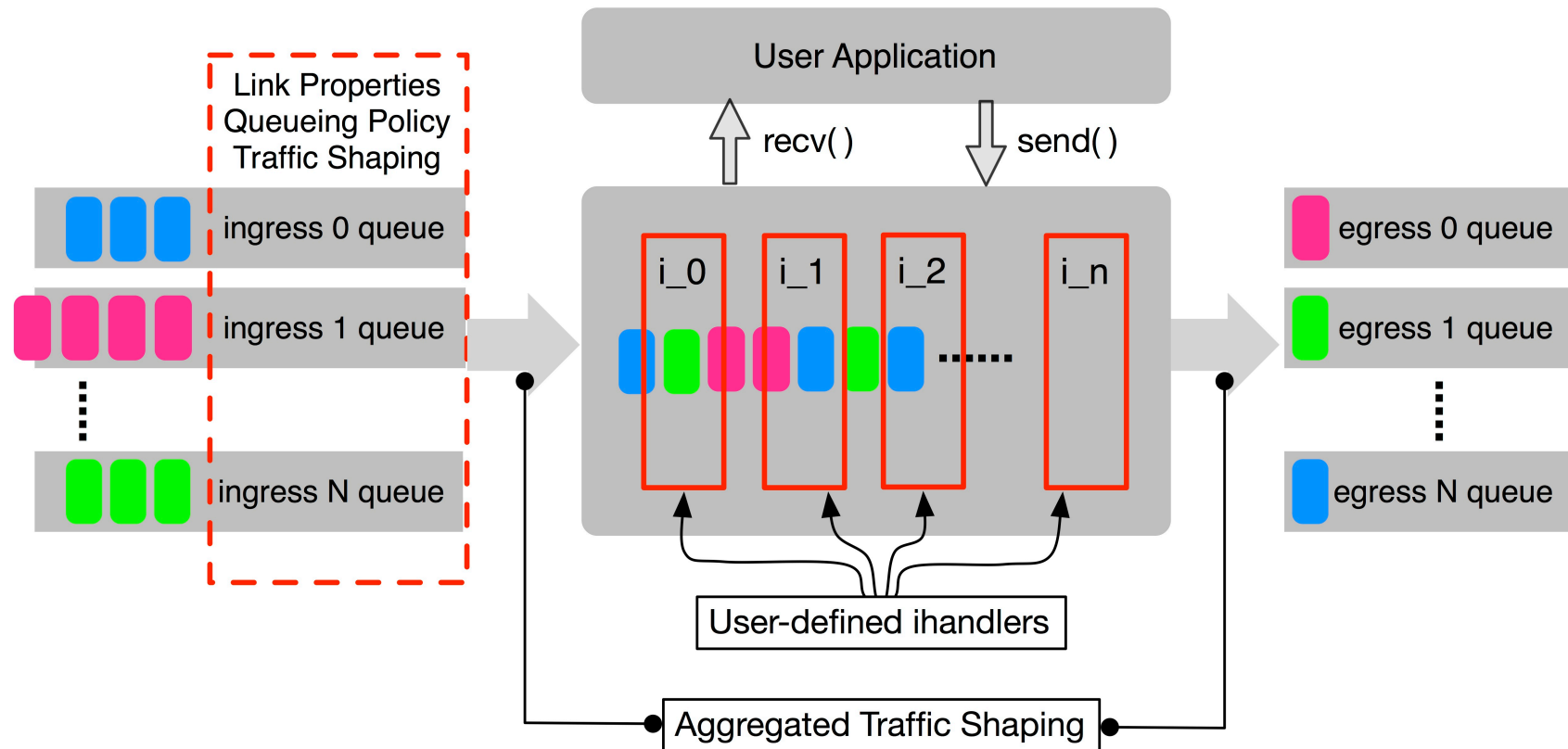
Resource Allocation – Dynamic Migration

- The static mapping cannot efficiently handle the dynamics during an experiment. An overloaded node may impact the experiment results.
- Dynamic migration is implemented as a sub-module in NodeAgent. It keeps monitoring the on its host.
- If NodeAgent detects a node is overloaded, some tasks will be moved onto other machines without restarting the experiments.
- Migration is not able to completely mask the effects from other users, but can alleviate the worst problems.

Overlay Subsystem

- Overlay Subsystem constructs an experiment overlay by using the resources from Agent Subsystem.
- One overlay instance corresponds to a job, therefore LiteLab can have multiple overlay instances running in parallel at the same time.
- The most critical component in Overlay Subsystem is SRouter, which is a software abstraction of a realistic router.

Innards of SRouter



Flexible Configurations

- Users can configure many parameters of SRouters, e.g., link properties (delay, loss rate, bandwidth), queue size, queueing policy(Droptail, RED), and so on.
 - Queues: `iqueue`, `equeue`, `cqueue`;
 - Processing Chain: similar concept as the chains of rules in *iptables*;
 - VID: a logical ID (VID) to identify a Srouter, neutral to any naming scheme;
 - Routing: is based on VID, can plug in different routing algorithms;
 - User Application: `ihandler` provides a passive way to interact with SRouters.

Evaluation - Accuracy

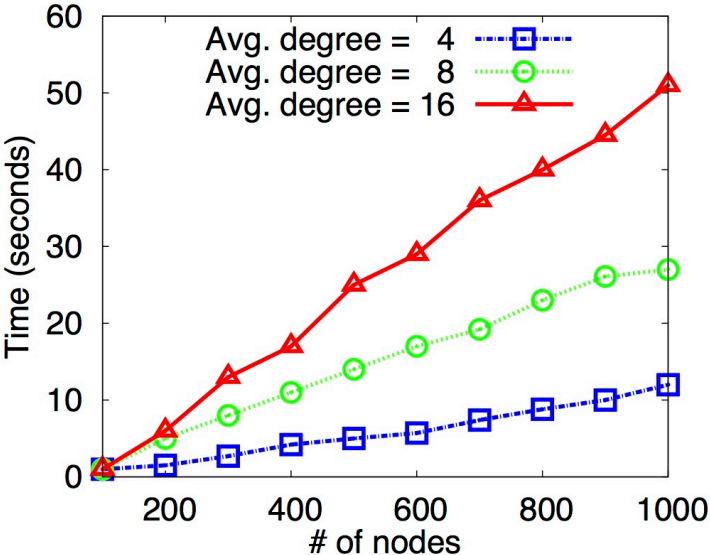
TABLE I: Accuracy of SRouter's bandwidth control as a function of link bandwidth and packet size.

Bandwidth (Kbps)	Packet Size	Observed Value	
		bw (Kbps)	% err
56	64	55.77	0.41
	1518	57.62	2.89
384	64	382.56	0.37
	1518	387.96	1.03
1544	64	1539.23	0.31
	1518	1546.32	0.15
10000	1518	9988	0.12
45000	1518	44947	0.12

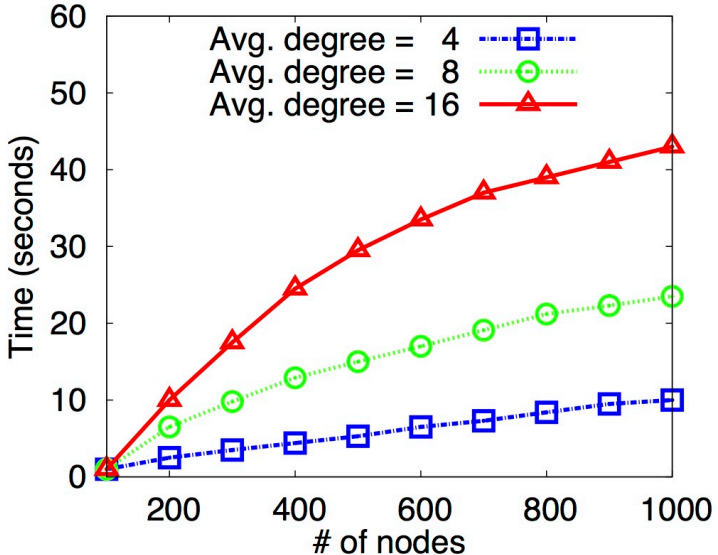
TABLE II: Accuracy of SRouter's delay at maximum packet rate as a function of 1-way link delay and packet size.

OW Delay (ms)	Packet Size	Observed Value		
		RTT	stdev	% err
0	64	0.190	0.004	N/A
	1518	0.221	0.007	N/A
5	64	10.200	0.035	2.00
	1518	10.230	0.009	2.30
10	64	20.212	0.057	1.06
	1518	20.185	0.015	0.92
50	64	100.209	0.060	0.21
	1518	100.218	0.031	0.22
300	64	600.189	0.083	0.03
	1518	600.273	0.034	0.04

Evaluation - Scalability



(a) Random (Erdős-Rényi)



(b) Scale-free (Barabási-Albert)

Fig. 4: Time to construct synthetic networks of different type.

Figure 4 shows that the time to construct network increases linearly as the number of nodes increases in random networks. However, the growth of time is slower in scale-free networks because the nodes with high degree dominate the construction time.

Heuristic in Resource Allocation

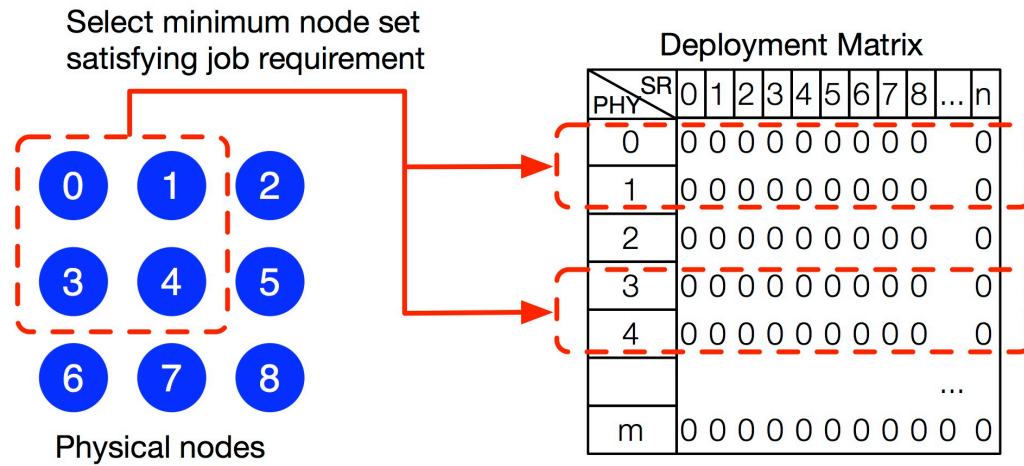


Fig. 5: Reduce deployment matrix size by selecting minimum physical node set that satisfies the job requirement.

Input: job requirements \mathbf{R} , physical nodes \mathbf{L}

Output: minimum physical node set \mathbf{S}

Calculate overall job requirement \mathbf{R}

Order nodes from lightest to heaviest load into \mathbf{L}

foreach *node N* in \mathbf{L} **do**

 Add \mathbf{N} to \mathbf{S}

 Calculate capacity of \mathbf{S} : \mathbf{C}

if $\mathbf{R} < \mathbf{C}$ **then**

 Solve LP

if *optimal solution exists* **then** break

 ;

else $\mathbf{R} \leftarrow 2 \times \mathbf{R}$;

end

end

Algorithm 1: Heuristic to improve mapping efficiency

Discussion

- LiteLab aims at a flexible, easy-to-deploy experiment platform and in this goal, it makes tradeoffs between accuracy and performance.
- LiteLab cannot completely eliminate external effects from other processes running on the test platform.
- SRouter's processing power is another limitation as it can only process about 10000 packets per second. Adding more user-defined modules will further slow down SRouter.

Conclusion

- LiteLab which aims to reduce the deployment risk by providing a light-weight platform for both network scientists and practitioners to efficiently evaluate their novel system designs.
- LiteLab combines the benefits from both emulation and simulation: ease of use, high accuracy, no complicated hardware settings, easy to extend and interface with user applications, etc.
- LiteLab is open sourced and is available for download for others.

Thank you!

Questions?