## Ligra: A Lightweight Graph Processing Framework for Shared Memory

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# What is Ligra?

Ligra is a lightweight and efficient framework for graph processing in shared memory. It was designed to make it easier for developers to implement graph algorithms that can run efficiently on multi-core machines

• Well suited for graph traversal problems

## Implementations

### Algorithm 1 EDGEMAP

1: procedure EDGEMAP(G, U, F, C)

- if (|U| + sum of out-degrees of U > threshold) then 2:
- return EDGEMAPDENSE(G, U, F, C)3:
- 4: else return EDGEMAPSPARSE(G, U, F, C)

### Algorithm 2 EDGEMAPSPARSE

1: procedure EDGEMAPSPARSE(G, U, F, C)

- 2:  $Out = \{\}$
- parfor each  $v \in U$  do 3:
- 4: parfor ngh  $\in N^+(v)$  do
- 5: if (C(ngh) == 1 and F(v, ngh) == 1) then 6:
  - Add ngh to Out
- Remove duplicates from Out 7:
- 8: return Out

#### Algorithm 3 EDGEMAPDENSE

```
1: procedure EDGEMAPDENSE(G, U, F, C)
      Out = \{\}
2:
      parfor i \in \{0, ..., |V| - 1\} do
3:
          if (C(i) == 1) then
4:
5:
             for ngh \in N^-(i) do
                 if (ngh \in U \text{ and } F(ngh, i) == 1) then
6:
7:
                    Add i to Out
                 if (C(i) == 0) then break
8:
9:
      return Out
```

### Algorithm 4 VERTEXMAP

1: procedure VERTEX MAP(U, F)

- 2:  $Out = \{\}$
- 3: parfor  $u \in U$  do
- 4: if (F(u) == 1) then Add u to Out
- return Out 5:

## **Application (Breadth-First Search)**

```
1: Parents = \{-1, \ldots, -1\}
                                                       \triangleright initialized to all -1's
2:
3: procedure UPDATE(s, d)
        return (CAS(&Parents[d], -1, s))
4:
 5:
    procedure COND(i)
6:
7:
        return (Parents[i] == -1)
8:
9:
   procedure BFS(G, r)
                                                                \triangleright r is the root
10:
        Parents[r] = r
11:
                                \triangleright vertexSubset initialized to contain only r
        Frontier = \{r\}
12:
        while (SIZE(Frontier) \neq 0) do
            Frontier = EDGEMAP(G, Frontier, UPDATE, COND)
13:
```

**Figure 1.** Pseudocode for Breadth-First Search in our framework. The compare-and-swap function CAS(*loc*,*oldV*,*newV*) atomically checks if the value at location *loc* is equal to *oldV* and if so it updates *loc* with *newV* and returns *true*. Otherwise it leaves *loc* unmodified and returns *false*.

```
Algorithm 6 Betweenness Centrality
1: NumPaths = \{0, ..., 0\}
                                                    ▷ initialized to all 0
2: Visited = \{0, \dots, 0\}
                                                    ▷ initialized to all 0
3: NumPaths[r] = 1
 4: Visited[r] = 1
 5: currLevel = 0
 6: Levels = []
7: Dependencies = \{0.0, \dots, 0.0\}
                                                  ▷ initialized to all 0.0
 8:
 9: procedure VISIT(i)
10:
       Visited[i] = 1
11:
        return 1
12:
13: procedure PATHSUPDATE(s, d)
14:
       repeat
15:
           oldV = NumPaths[d]
16:
           newV = oldV + NumPaths[s]
       until (CAS(&NumPaths[d], oldV, newV) == 1)
17:
       return (old\dot{V} == 0)
18:
19:
20: procedure DEPUPDATE(s, d)
21:
       repeat
22:
           oldV = Dependencies[d]
           newV = oldV + \frac{NumPaths[d]}{NumPaths[s]} \times (1 + Dependencies[s])
23:
       until (CAS(&Dependencies[d], oldV, newV) == 1)
24:
25:
       return (old\dot{V} == 0.0)
26:
27: procedure COND(i)
28:
       return (Visited[i] == 0)
29:
30: procedure BC(G, r)
                             ▷ vertexSubset initialized to contain only r
31:
       Frontier = \{r\}
       while (SIZE(Frontier) \neq 0) do
32:
                                                             Phase 1
           Frontier = EDGEMAP(G, Frontier, PATHSUPDATE, COND)
33:
34:
           Levels[currLevel] = Frontier
           Frontier = VERTEXMAP(Frontier, VISIT)
35:
36:
           currLevel = currLevel + 1
37:
       Visited = \{0, ..., 0\}
38:
                                                   ▷ reinitialize to all 0
39:
       currLevel = currLevel - 1
40:
       TRANSPOSE(G)
                                                     transpose graph
41:
       while (currLevel \ge 0) do
42:
                                                             ▷ Phase 2
43:
           Frontier = Levels[currLevel]
44:
           VERTEX MAP(Frontier, VISIT)
           EDGEMAP(G, Frontier, DEPUPDATE, COND)
45:
           currLevel = currLevel - 1
46:
47:
       return Dependencies
```

### Application (Betweenness Centrality)

## Application (Radii Estimation)

1: \	$isited = \{0,, 0\}$	▷ initialized to all 0
	$VextVisited = \{0, \dots, 0\}$	▷ initialized to all 0
	$adii = \{\infty, \dots, \infty\}$	▷ initialized to all ∞
4: r	ound = 0	
5:		
6: J	rocedure RADIIUPDATE(s, d)	
7:	if (Visited $[d] \neq$ Visited $[s]$ ) then	
8:	ATOMICOR(&NextVisited[d])	Visited[d]   Visited[s])
9:	oldRadii = Radii[d]	
10:	if (Radii[d] $\neq$ round) then	
11:	return CAS(&Radii[d], o	ldRadii, round)
12:	return 0	
13:		
14: 1	procedure ORCOPY(i)	
15:	NextVisited[i] = NextVisited[i]	Visited[i]
16:	return 1	
17:		
18: 1	procedure RADII(G)	
19:	Sample K vertices and for each or	e set a unique bit in Visited to 1
20:	Initialize Frontier to contain the K	sampled vertices
21:	Set the Radii entries of the sample	d vertices to 0
22:	while $(SIZE(Frontier) \neq 0)$ do	
23:	round = round + 1	
24:	Frontier = EDGEMAP(G, Fro	
25:	Frontier = VERTEXMAP(From	ntier, ORCOPY)
26:	SWAP(Visited, NextVisited)	switch roles of bit-vectors
27:	return Radii	

## **Application (Connected Components)**

```
Algorithm 8 Connected Components
 1: IDs = \{0, \dots, |V| - 1\}
                                          \triangleright initialized such that IDs[i] = i
2: prevIDs = \{0, ..., |V| - 1\}
3:
                                      \triangleright initialized such that prevIDs[i] = i
 4:
    procedure CCUPDATE(s, d)
       origID = IDs[d]
 5:
       if (WRITEMIN(&IDs[d], IDs[s])) then
 6:
 7:
           return (origID == prevIDs[d])
 8:
        return 0
 \mathbf{Q}_{1}
10: procedure COPY(i)
11:
        prevIDs[i] = IDs[i]
12:
        return 1
13:
14: procedure CC(G)
        Frontier = \{0, ..., |V| - 1\}
15:
                                            \triangleright vertexSubset initialized to V
16:
        while (SIZE(Frontier) \neq 0) do
17:
            Frontier = VERTEXMAP(Frontier, COPY)
18:
            Frontier = EDGEMAP(G, Frontier, CCUPDATE, C_{true})
        return IDs
19:
```

## Application (PageRank)

Algorithm 9 PageRank 1:  $p_{curr} = \{\frac{1}{|V|}, \dots, \frac{1}{|V|}\}$  $\triangleright$  initialized to all  $\frac{1}{|V|}$ 2:  $p_{next} = \{0.0, \dots, 0.0\}$ initialized to all 0.0 3: diff =  $\{\}$ array to store differences 4: 5: procedure PRUPDATE(s, d) ATOMICINCREMENT  $(\& p_{next}[d], \frac{p_{curr}[s]}{deg^+(s)})$ 6: 7: return 1 8: 9: procedure PRLOCALCOMPUTE(i)  $p_{next}[i] = (\gamma \times p_{next}[i]) + \frac{1-\gamma}{|V|}$ 10:  $\operatorname{diff}[i] = \left| p_{next}[i] - p_{curr}[i] \right|$ 11: 12: $p_{curr}[i] = 0.0$ 13: return 1 14: 15: procedure PAGERANK( $G, \gamma, \epsilon$ ) 16: Frontier =  $\{0, ..., |V| - 1\}$ vertexSubset initialized to V 17:  $error = \infty$ 18: while (error  $> \epsilon$ ) do 19: Frontier = EDGEMAP(G, Frontier, PRUPDATE,  $C_{true}$ ) 20:Frontier = VERTEXMAP(Frontier, PRLOCALCOMPUTE) 21:error = sum of diff entries 22:SWAP(pcurr, pnext) 23:return p<sub>curr</sub>

# Application (Bellman-Ford)

Algorithm 10 Bellman-Ford

```
1: SP = \{\infty, \ldots, \infty\}
                                                     \triangleright initialized to all \infty
 2: Visited = \{0, \dots, 0\}
                                                       initialized to all 0
 3:
 4:
   procedure BFUPDATE(s, d, edgeWeight)
       if (WRITEMIN(&SP[d], SP[s] + edgeWeight)) then
 5:
           return CAS(&Visited[d], 0, 1)
 6:
 7:
       else return 0
 8:
    procedure BFRESET(i)
 9:
10:
        Visited[i] = 0
11:
        return 1
12:
13: procedure BELLMAN-FORD(G, r)
14:
        SP[r] = 0
15:
        Frontier = \{r\}
                                vertexSubset initialized to contain just r
16:
        round = 0
17:
        while (SIZE(Frontier) \neq 0 \text{ and } round < |V|) do
18:
           round = round + 1
19:
           Frontier = EDGEMAP(G, Frontier, BF-UPDATE, C_{true})
20:
           Frontier = VERTEXMAP(Frontier, BF-RESET)
21:
        if (round == |V|) then return "negative-weight cycle"
        else return SP
22:
```

# **Running Times**

Application	3D-grid		random-local		rMat24			rMat27			Twitter			Yahoo				
	(1)	(40h)	(SU)	(1)	(40h)	(SU)	(1)	(40h)	(SU)	(1)	(40h)	(SU)	(1)	(40h)	(SU)	(1)	(40h)	(SU)
Breadth-First Search	2.9	0.28	10.4	2.11	0.073	28.9	2.83	0.104	27.2	11.8	0.423	27.9	6.92	0.321	21.6	173	8.58	20.2
Betweenness Centrality	9.15	0.765	12.0	8.53	0.265	32.2	11.3	0.37	30.5	113	4.07	27.8	47.8	2.64	18.1	634	23.1	27.4
Graph Radii	351	10.0	35.1	25.6	0.734	34.9	39.7	1.21	32.8	337	12.0	28.1	171	7.39	23.1	1280	39.6	32.3
Connected Components	51.5	1.71	30.1	14.8	0.399	37.1	14.1	0.527	26.8	204	10.2	20.0	78.7	3.86	20.4	609	29.7	20.5
PageRank (1 iteration)	4.29	0.145	29.6	6.55	0.224	29.2	8.93	0.25	35.7	243	6.13	39.6	72.9	2.91	25.1	465	15.2	30.6
Bellman-Ford	63.4	2.39	26.5	18.8	0.677	27.8	17.8	0.694	25.6	116	4.03	28.8	75.1	2.66	28.2	255	14.2	18.0

Table 2. Running times (in seconds) of algorithms over various inputs on a 40-core machine (with hyper-threading). (SU) indicates the speedup of the application (single-thread time divided by 40-core time).

# Setup of Experiments



All experiments were performed on:



- 40-core Intel machine (with hyper-threading), 4x2:4GHz Intel



10-core E7-8870 Xeon processors, a 1066MHz bus, (256GB) main memory



- icpc compiler (version
12.1.0) using CilkPlus with
the -O3 flag

# Conclusion

- Designed for shared-memory machines.
- Implementations using Ligra:
- Efficient and scalable
- Often outperform other graph libraries/systems
- Potential uses for other algorithms:
- Maximum flow
- Biconnected components
- Belief propagation
- Markov clustering
- Current Limitations:
- Doesn't support algorithms that modify the input graph
- Future Directions:
- Extend Ligra to support graph modifications
- Explore adaptability for GPU systems