Rlgraph: Modular Computation Graphs For Deep Reinforcement Learning

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Reinforcement Learning

- Has its origins with Markovian Decision Processes (Bellman, 1957)
- Q value vs Q learning
- Deep Q-Network Deepmind (Volodymyr Mnih et al, 2013)
- DNQ Issues: Forgetfulness / Volitility; Enormous state-space
- Algorithmic Progress: Dueling DNS (Ziyu Wang, 2015), IMPALA
- Environment Standardisation: OpenAl gym
- Reinforcement Learning Frameworks...

Challenges of Reinforcement Learning

- No Supervision, Feedback is Delayed (Credit Assignment Problem)
- Data observed is causally effected by agents' actions.
 - Therefore, Actor / Environment feedback loop is sequential
 - Parallelisation (Especially if environment not simulated)
- Non-determinism of environment and stochastic nature of many approximations cause issues with testing and reproducibility.
- Large Search Space -> Computational Power:
 - Seeking to benefit from distributed approach

RL Frameworks

- OpenAl gym Baselines for testing, Environments (Atari, 3D, ...)
 - Tool for environments, libraries favour conciseness over extensibility
- TensorForce TensorFlow library for Deep RL
 - Declarative API
 - Modular Components (not decomposable)
 - Algorithm and Application Separation
- Ray RLib RL Library for Ray Distributed Execution Engine
 - Distributed RL Library. Native to Ray with Central Command Framework

Rlgraph Overview

- This paper outlines a new, unifying Framework with the aim to improve:
- Incremental Building Testing
 - To improve the speed of prototyping and robustness of production models.
- Distributed Execution
 - By focusing on modularisation, RLgraph aims to separate the concerns of design and execution.
- Extensibility
 - By separating "logical component composition, backend graph definition and distributed execution," components are interchangeable and well defined.

Rlgraph Components

- The Rlgraph framework is primarily a Component graph.
- A Component class can encapsulate arbitrary computations.
- A Component contains internal methods, API methods, variables, and associated sub-components.
- This graph structure is an abstraction that can be executed across platforms.

	API, Component configuration	Prebuilt models, inference
5.	RLgraph component graph	Model design, dataflow composition
	TensorFlow PyTorch	Local backends variables/operations
	Distributed TF Horovod Ray	Distributed execution engine
	Hardware: CPU, GPU, TPU, FPGAs	Execution, orchestration

Framework Design

- Separating algorithms and execution
 - RL algorithms require complex control flow to coordinate distributed system and sample collection.
 - Agents' policies require internal training logic.
 - Components separate concerns.
- Reusable components with strict interfaces.
 - Interchangeable components, not dissimilar to NN layers in Keras for example.
 - Components interact only via strict, declared APIs. Static analysis
- Incremental sub-graph testing.
 - Components in Rlgraph may be individually built and tested.

Identified Failings of Existing Frameworks

- TensorForce TensorFlow library for Deep RL
 - Modular, but lack Modular, Separated Build Process for Testing
 - Unnecessary context switching between TF runtime and Python interpreter
- Ray RLib RL Library for Ray Distributed Execution Engine
 - Lacks portability due to Ray nativity
 - Restricted Control Flow inherited from Ray

Results

- Build overhead: Sub 1 second for both TF and PT
- Worker Performance Baseline: No overhead on TF, Slight overhead PT
- Distributed execution on Ray:
 - Outperformed Rlib in Ray environment



Follow on

- This paper was 2019
- RL Algorithms: Multi Agent & Semi Supervised
- Frameworks: Acme (Deepmind June 2020)

