RLgraph: Flexible Computation Graphs for Deep Reinforcement Learning

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Background

Standardization of high-level graph frameworks is a big driving force behind the success of ML.

Yet, it is happening very slowly for reinforcement learning settings.

Examples include: ≻OpenAl ≻TensorForce ≻Ray RLlib

What is reinforcement learning?

Instead of a supervised setting, where all the training data is available in advance,

Reinforcement learning revolves around defining a reward system for an agent and letting it freely produce strategies.

Separation of Concerns

>Managing trial runs in the testing environment

>Managing execution environment

- Distributed coordination
- Device strategies e.g. GPU utilization
- Driving the learning models
 - ► Logical component composition
 - Backend graph definition for specific frameworks

What does separation of logic achieve?

Encourage code reuse

Speed up iterative development

Allow for sub-component testing

>Allow for a higher-level reasoning about the components

>Allow for identification of optimizations

Major contribution

Meta-graph.

This provides an abstraction that allows to compose various components of the reinforcement learning procedure and re-compose them in different ways.



Figure 9. TensorBoard visualization of RLgraph's IMPALA learner. As all operations and variables are organized in components under separate scopes, dataflow between components is clear.

How is the meta graph created?

Three stages:

- Composing the components
- Traversing all the call paths to provide a skeleton of the metagraph
- Building the backend-specific implementation, by allocating required data-structures and defining operations

PrioritizedReplay	
Scope/name: prioritizedreplay Device: CPU Backend: TensorFlow	
SegmentTree (sub component) graph_fn API	Variables: buffers & indices
graph_fn TensorFlow operations	insert_records (API)
graph_fn	get_records (API)
graph_fn	update (API)

Figure 2. Example memory component with three API methods.

* The framework also supports a define-by-run execution mode, where the third phase isn't pre-build, instead dynamically created according to the shape of data passed around.

Conveniences provided

>Ability to test only parts of the meta-graph

Convenient nesting, merging, splitting and folding of data passed around

Shape and type checking

Backend independence



Figure 3. RLgraph execution stack.

Benchmarks

1s of build overhead. 1.00175000 TF meta **RLLib** 150000 TF build RLgraph 0.75 S 125000 June 100000 Runtime (s) PT meta PT build 100000 Deepmind IMPALA Environment Euvironment frames/s 15000 10000 5000 RLgraph IMPALA 75000 0.25 50000 25000 0.00 Prioritized replay DQN 16 32 64 128 256 Architecture Number of workers 16 32 64 128 Build overheads. Figure 5. Distributed sample throughput on Pong. (a) Number of workers

Performance wasn't sacrificed in maintaining abstraction.

Figure 8. IMPALA throughput comparison on seekavoid_arena_01

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Critique

Misleading to advertise a 180% speed-up on the front page compared to RLlib that is an optimization that could be incorporated into RLlib too.

No comparison to other frameworks when driving multiple GPUs.

No data to back up the claim that "overhead [in excessive call graph traversal while using PyTorch] becomes negligible as batch size increases and runtime is dominated by the network forward passes".

Nor is there any data presented on the "edge-contractions" which is the proposed mitigation of said issue.

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