A Tautology Checker loosely related to Stålmarck's Algorithm

by

#### Martin Richards

mr@cl.cam.ac.uk

http://www.cl.cam.ac.uk/users/mr/

University Computer Laboratory New Museum Site Pembroke Street Cambridge, CB2 3QG









### **Inference Rules**

The terms are modified and possibly eliminated by the application of inference rules which sometimes yield variable mapping information.

Mapping information

Variable mapping information is a set of items of the form:

x = 0 x = 1 x = yor  $x = \overline{y}$ where x and y are variables.



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Mapping:

 $t_4 = \bar{t}_3, \quad t_3 = t_1, \quad t_5 = t_2,$  $t_2 = 0, \quad t_1 = 1, \quad c = 0, \quad a = b$ 

There are now no terms left. An inconsistency has not been found, so the original expression was not a tautology.

These direct derivations can be done in linear time.

# Unfortunately

We cannot, in general, expect direct derivations to solve the problem, (since tautology checking has exponential cost).

If we apply the technique to:

 $((a \land b) \lor (\neg a \land b) \to \neg (\neg a \land \neg b)$ 

we obtain:





has no solution since

first term implies: second term implies: third term implies: fourth term implies:

| ab = |     | 01, | 10, | 11 |
|------|-----|-----|-----|----|
| ab = | 00, | 01, |     | 11 |
| ab = | 00, |     | 10, | 11 |
| ab = | 00, | 01, | 10  |    |

## The Dilemma Rule

- 1. Select a variable,  $v_i$ , say, that has not yet been assigned a value.
- 2. Set it to 0 and 1 in turn and apply the direct inferences until convergence, yielding variable mappings  $M_0$  and  $M_1$ , respectively.
- 3. If both settings lead to inconsistencies then the terms cannot be satisfied.
- 4. If just one setting leads to an inconsistency, return the other mapping.
- 5. If neither setting leads to an inconsistency, return the intesection of  $M_0$  and  $M_1$ , i.e. the set of mapping items that occur in both  $M_0$ and  $M_1$ .
- 6. Repeat for all other variables.

- 7. Repeat the process using pairs of variables,  $v_i v_j$ , setting them to all possible values (00, 01, 10 and 11), taking the intersection of the four mappings produced.
- 8. Repeat similarly with all sets of  $3, 4, \ldots n$ variables until either no terms remain or an inconsistency is found.

When the algorithm is considering k variables, it is said to be at recursion depth k.

Hopefully, the problem will be solved before the recursion depth gets too large.

The problem will certainly be solved at recursion depth n, if not before.

Any strategy to reduce the recursion depth is valuable.

#### Mapping Intersection

Suppose  $M_0 = \{v_1 = 0, v_2 = 1, v_2 = \bar{v}_4, v_5 = v_6\}$ and  $M_1 = \{v_1 = 0, v_2 = 0, v_3 = v_5, v_5 = v_6\}$ then the intersection is  $\{v_1 = 0, v_5 = v_6\}$ 

## **Using Triadic Relations**

The terms so far considered represent the relation between the operands and result of dyadic Boolean operators. For example,



says that the only valid settings of xyz are: 000, 001, 010 or 111

There are just 16 dyadic Boolean operators, but there are 256 relations over 3 Boolean variables.

We extend Ståmarck's Algorithm to use such relations in the term set.

## **Eight Bit Representation**

The relation R(x, y, z) can be represented using a bit pattern of length 8, as follows:



## **New Inferences**

Many more inference rules are now available. We can, for instance, combine R00101101(0, a, b) and R10000111(0, a, b) to yield R00000101(0, a, b).

| Relation  | Triplets |     |     |     |     |     |
|-----------|----------|-----|-----|-----|-----|-----|
| R00101101 |          | 101 | 011 | 010 |     | 000 |
| R10000111 | 111      |     |     | 010 | 001 | 000 |
| R00000101 |          |     |     | 010 |     | 000 |
|           | -        |     |     |     |     |     |

## Derivation

The terms in the previous example are: R00011110(0, a, b)

 $egin{aligned} R01001011(0,a,b)\ R00101101(0,a,b)\ R10000111(0,a,b) \end{aligned}$ 

Combining terms 3 and 4 gives: R00011110(0, a, b) R01001011(0, a, b)R00000101(0, a, b)

Combining terms 2 and 3 gives:  $\begin{array}{c} R00011110(0,a,b) \\ R0000001(0,a,b) \end{array}$ 

Combining these two terms gives: R0000000(0, a, b)

This is a term that cannot be satisfied, so an inconsistency has been found.

## Observations

Having 256 relations may seem to be a disadvantage, but there are compensations.

- As we have seen, the recursion depth may be reduced.
- Terms can be put into canonical form to allow easy elimination of equivalent terms.
- Many more inferences are possible.
- Inferences can be done by table lookup or by simple bit pattern operations.

### Canonicalisation

A term can be put into canonical form by the following steps:

- Replace R(x, y, z) by R'(0, y, z), if the relation does not depend on x. For example, replace R10111011(x, y, z) by R00001011(0, y, z), since the upper and lower 4 bits of R are equal.
- 2. Replace R(x, y, y) by the equivalent R'(x, y, 0). For example, replace R00110101(x, y, y) by R00010001(x, y, 0), i.e. mask R with R10011001.
- 3. Replace R(1, y, z) by the equivalent R'(0, y, z). For example, replace R00110101(1, y, z) by R00000011(0, y, z), i.e. right shift by 4.

- 4. Replace R(0, y, z) by the equivalent R'(0, y, z). For example, replace R00110101(0, y, z) by R00000101(0, y, z), i.e. mask R with R00001111.
- 5. Do the above transformations for all permutations of (x, y, z).
- 6. Return R(x, y, z) with the variables (x, y, z) in dictionary order.

The resulting canonical term will have one of the following forms:

Rabcdefgh(x, y, z)R0000abcd(0, y, z)R000000ab(0, 0, z)R000000a(0, 0, 0)

#### **Deducing Mappings**

Given a term Rabcdefgh(x, y, z), we may be able to deduce new mapping information. For instance, if abcd = 0000 then x = 0.

By similar means, we can deduce whether x = 1, x = y or  $x = \overline{y}$ .

| Term                | Deduction     |
|---------------------|---------------|
| R0000 efgh(x, y, z) | x = 0         |
| Rabcd0000(x,y,z)    | x = 1         |
| Ra00de00h(x,y,z)    | x = y         |
| R0bc00fg0(x,y,z)    | $x = \bar{y}$ |

There are 12 such mappings.

They can be deduced by simple masking operations or by table lookup.

#### **Pairwise Inferences**

As we have already seen, if we have two terms R(x, y, z) and S(x, y, z) referring to the same variables, then they can be replaced by the single term  $(R \wedge S)(x, y, z)$ .

#### **Pairwise Inferences**

If we have two terms R(a, x, y) and S(b, x, y) with two variables in common then we can sometimes simplify R and/or S, and we can sometimes deduce a relation between a and b. For example,

| Term               | Triplets |     |     |     |  |
|--------------------|----------|-----|-----|-----|--|
| R01010011(a, x, y) | 110      | 100 | 001 | 000 |  |
| R10101100(b, x, y) | 111      | 101 | 011 | 010 |  |

The first disallows the pattern xy = 11 and the second disallows xy = 00, so, taken together we can deduce:

 $egin{array}{rll} R01000010(a,x,y) & 110 & 001 \ R00100100(b,x,y) & 101 & 010 \end{array}$ 

#### **Pairwise Inferences**

 $\begin{array}{cccc} R01000010(a,x,y) & 110 & 001 \\ R00100100(b,x,y) & 101 & 010 \end{array}$ 

From these we can deduce information about ab, namely  $a = \overline{b}$ , and taken separately the terms allow us to deduce new information about axy, (namely:  $a = x = \overline{y}$ ), and bxy (namely:  $b = \overline{x} = \overline{y}$ ).

All these deductions can be made easily by means of bitwise operations on the relation bit patterns.

Another inference rule applies to a pair of terms of the form R(x, 0, z) and S(0, y, z), replacing them by T(x, y, z). Again, the bit pattern representation of T is easily calculated from Rand S.

#### **Using Larger Relations**

We have seen how the mechanism works with relations over three Boolean variables.

What about relations over  $4, 5, \ldots n$  variables?

The length of the relation bit pattern is  $2^n$  and the number of variable mapping items is n(n+1).

When n = 4, 16-bits are required to represent the relation and there are 20 mapping items.

When n = 8, the relation takes eight 32-bit word to represent, which is typically equal to the space require to represent the eight variables. Such a term can thus be represented in 16 32-bit words.

A term over 6 variables would require 8 words.

n = 8 is probably a good compromise.

## Notation

We will use Rn to denote the set of terms containing general relations over n variables.

A typical element of Rn is  $R(v_1, \ldots v_n)$ .

BinOp is the subset of R3 in which all terms are restricted to relations corresponding to the 16 dyadic Boolean operators.

Ståmarck's variable mapping can be thought of as the subset (EqNe) of R2, restricted to 12 of the 16 possible relations over 2 Booleans. The four that are omitted involve implication, possibly combined with negation. We will call this subset of R2: Imp.

# R2 Relations

| Relation |    | xy I | Pairs |    | Condition                |
|----------|----|------|-------|----|--------------------------|
|          |    |      |       |    |                          |
| R0000    |    |      |       |    | False                    |
| R0001    |    |      |       | 00 | x = 0 $y = 0$            |
| R0010    |    |      | 01    |    | x = 0  y = 1             |
| R0011    |    |      | 01    | 00 | x = 0                    |
| R0100    |    | 10   |       |    | x = 1 $y = 0$            |
| R0101    |    | 10   |       | 00 | y = 0                    |
| R0110    |    | 10   | 01    |    | $x = \bar{y}$            |
| R0111    |    | 10   | 01    | 00 | $x  ightarrow ar{y}$     |
| R1000    | 11 |      |       |    | x = 1 $y = 1$            |
| R1001    | 11 |      |       | 00 | x = y                    |
| R1010    | 11 |      | 01    |    | y = 1                    |
| R1011    | 11 |      | 01    | 00 | x  ightarrow y           |
| R1100    | 11 | 10   |       |    | x = 1                    |
| R1101    | 11 | 10   |       | 00 | $ar{x}  ightarrow ar{y}$ |
| R1110    | 11 | 10   | 01    |    | $ar{x}  ightarrow y$     |
| R1111    | 11 | 10   | 01    | 00 | True                     |
|          |    |      |       |    |                          |



If a circular chain of implications can be found in  $R^2$  then either all the variable in the chain are equal or an inconsistency is present. For example:

Such deductions should be made as soon as they are detectable.

Elements of EqNe correspond to renaming, and can be removed as soon as the renaming is done. We are thus left with an R2 structure containing only terms from Imp that contain no cycles and we need an efficient algorithm to detect cycles when new items are added (to either Imp or EqNe). It is well known that R2 can be "solved" in linear time.



$$R(v_1, v_1, v_3, \dots, v_n)$$
 $\Rightarrow$  $R'(v_1, 0, v_3, \dots, v_n)$ Example $R10110110(x, x, y)$  $111$  $101$  $010$  $\Rightarrow$  $R00100010(x, 0, y)$  $101$  $001$ By combining PERM and UNDUP, all repeated variables in a term can be removed.












$$s(a,b)$$

$$R(v_1, v_2, \dots, v_n) \implies$$

$$R'(v_1, v_2, \dots, v_n)$$

$$R(v_1, v_2, \dots, v_n)$$
$$S(w_1, w_2, \dots, w_n)$$
$$\Longrightarrow$$
$$T(v_i, w_j)$$

| R01101011(a, y, z) | 111 | 110  | 011 | 001 | 000 |
|--------------------|-----|------|-----|-----|-----|
| R01110011(b, y, z) | 110 | 101  | 100 | 001 | 000 |
| $\implies$         |     |      |     |     |     |
| R1011(a,b)         | 11  | 01 0 | 0   |     |     |

$$R(v_1, v_2, \dots, v_n)$$

$$S(w_1, w_2, \dots, w_n)$$

$$\Longrightarrow$$

$$R'(v_1, v_2, \dots, v_n)$$

$$S'(w_1, w_2, \dots, w_n)$$

| R01101011(a, y, z) | 111 | 110 | 011 | 001 | 000 |
|--------------------|-----|-----|-----|-----|-----|
| R01110011(b,y,z)   | 110 | 101 | 100 | 001 | 000 |
| $\implies$         |     |     |     |     |     |
| R01101011(a,y,z)   | 110 | 001 | 000 |     |     |
| R01110011(b, y, z) | 110 | 101 | 100 | 001 | 000 |

$$R(v_1, 0, \dots, v_n)$$
$$S(0, v_2, \dots, v_n)$$
$$\Longrightarrow$$
$$T(v_1, v_2, \dots, v_n)$$

| R000011000001010(a, 0, y, z) | 1011 | 1010 | 0011 |
|------------------------------|------|------|------|
|                              | 0001 |      |      |
| R000000011100001(0, b, y, z) | 0111 | 0110 | 0101 |
|                              | 0000 |      |      |
| $\Longrightarrow$            |      |      |      |
| R110000000101000(a, b, y, z) | 1111 | 1110 | 0101 |
|                              | 0011 |      |      |
|                              |      |      |      |
|                              |      |      |      |

# FACTOR

 $R(v_1, \dots, v_i, v_{i+1}, \dots, v_n) \implies$  $\implies$  $S(0, \dots, 0, v_0, \dots, v_i)$  $T(0, \dots, 0, v_{i+1}, \dots, v_n)$ 

if the given relation can be partitioned into two relations over independent sets of variables.

This is only useful when n > 5.

It increases the applicability of PAIRCOMB.

# **Final Remarks**

- This approach reduces the number of terms, the number of variables, and the depth and fanout of the recursion.
- This approach increases the number of inference rules and simplifies their application.
- Multi-variate relations allow the representation of higher level properties of a circuit.
- Another form of dilemma rule is possible. Pick a "random" relation over n variables R11011100(x, y, z), say, and its complement R00100011(x, y, z), and use these as the alternatives in the dilemma rule. This is more useful when n > 3.



