



Mobile and Sensor Systems

Lecture 4: Wireless LAN and Bluetooth

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In this Lecture



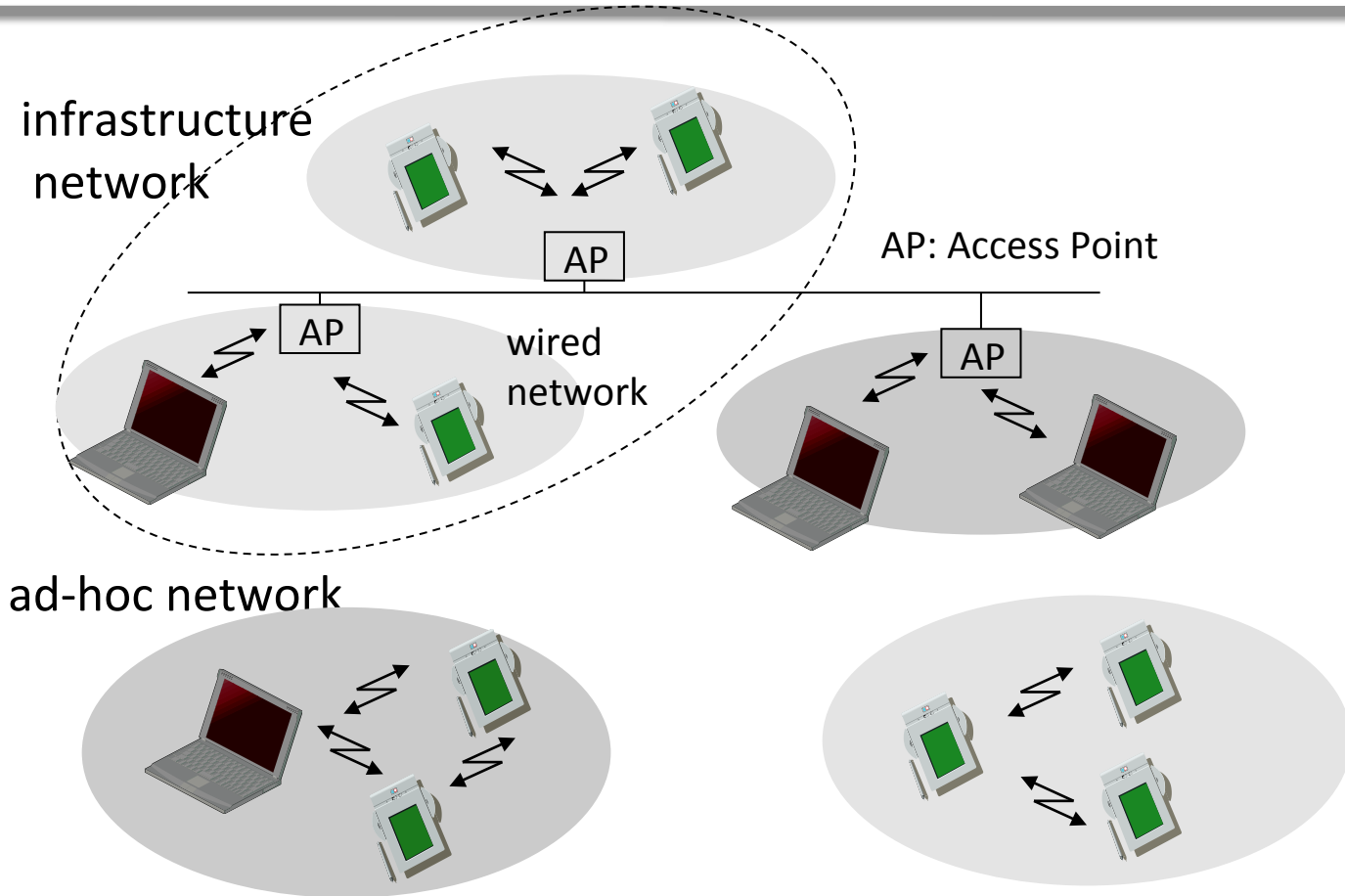
- We will describe
 - The Wireless LAN standard
 - The Bluetooth standard
- We will introduce the concept of ad hoc networking

The Wireless LAN Standard

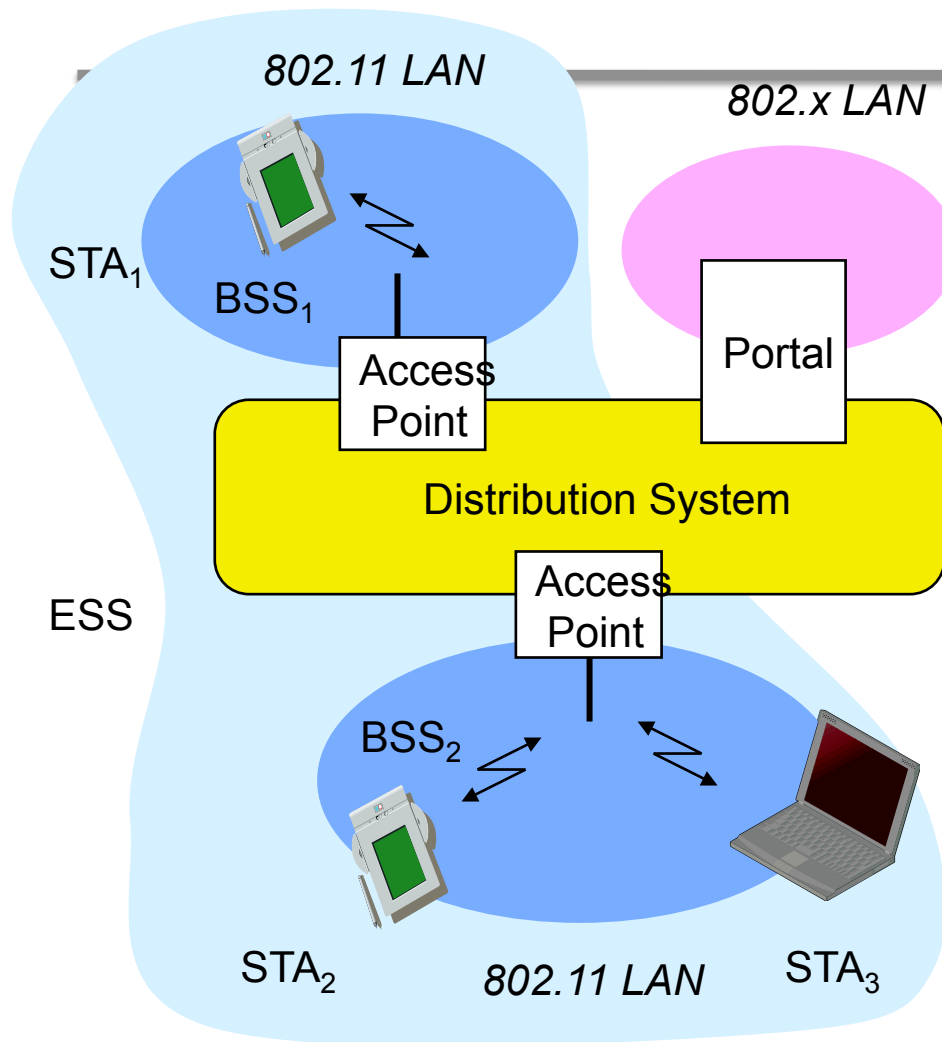


- The Mobile technology standard for LAN is called 802... and defined by the IEEE
- 802.3 is Ethernet
- Various examples of it exist:
 - 802.11 is the wireless LAN standard
 - 802.15 is wireless PAN (personal area network)
 - Zigbee is 802.15.4
 - Bluetooth is 802.15.1
 - 802.16 is WIMAX
 - 802.11 uses 2.4 and 5 GHz frequency bands (802.11g operates at 54Mbit/s with 22Mbit/s in average)
- Wireless LAN operates in 2 modes: infrastructured and ad hoc

Comparison: infrastructure vs. ad-hoc networks

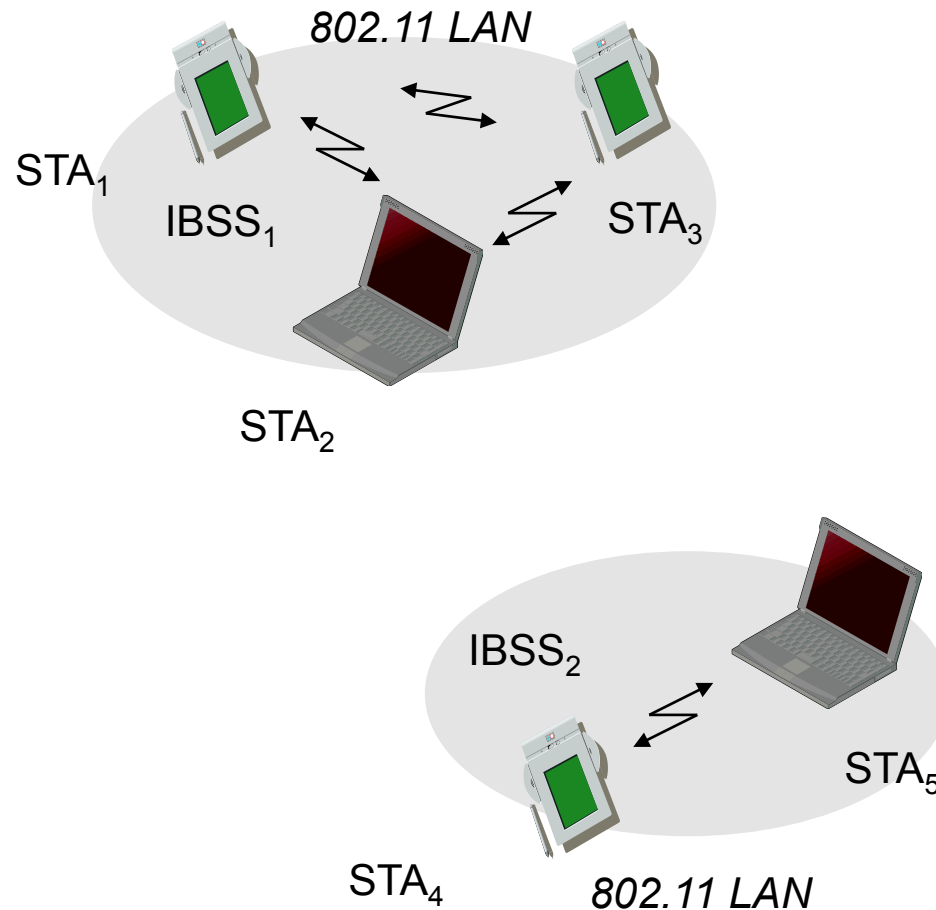


802.11 - Architecture of an infrastructure network



- Station (STA)
 - terminal with access mechanisms to the wireless medium & radio contact to AP
- Basic Service Set (BSS)
 - group of stations using the same radio frequency
- Access Point
 - station integrated into the wireless LAN and the distribution system
- Portal
 - bridge to other (wired) networks
- Distribution System
 - interconnection network to form one logical network (Extended Service Set with id ESSID) based on several BSS

802.11 - Architecture of an ad-hoc network

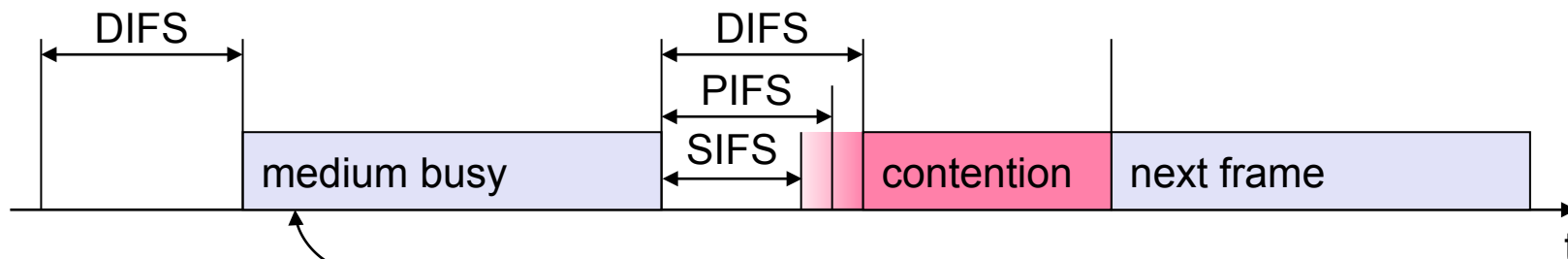


- Direct communication within a limited range
 - Station (STA): terminal with access mechanisms to the wireless medium
 - Independent Basic Service Set (IBSS): group of stations using the same radio frequency

802.11 - MAC layer (recap)



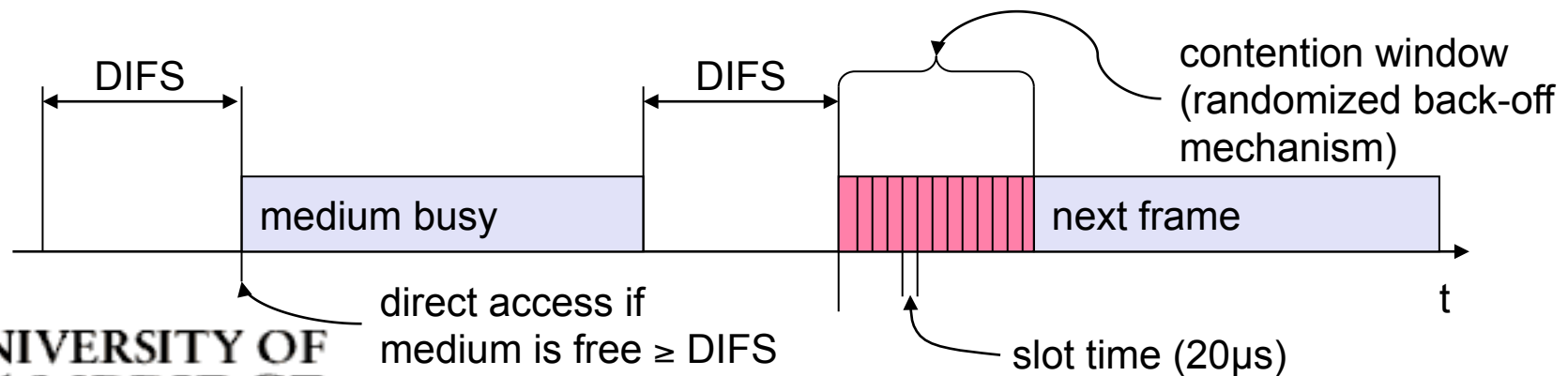
- Priorities
 - defined through different inter frame spaces
 - no guaranteed, hard priorities
 - SIFS (Short Inter Frame Spacing)
 - highest priority, for ACK, CTS, polling response
 - PIFS (PCF IFS)
 - medium priority, for time-bounded service using PCF
 - DIFS (DCF, Distributed Coordination Function IFS)
 - lowest priority, for asynchronous data service



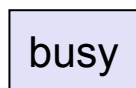
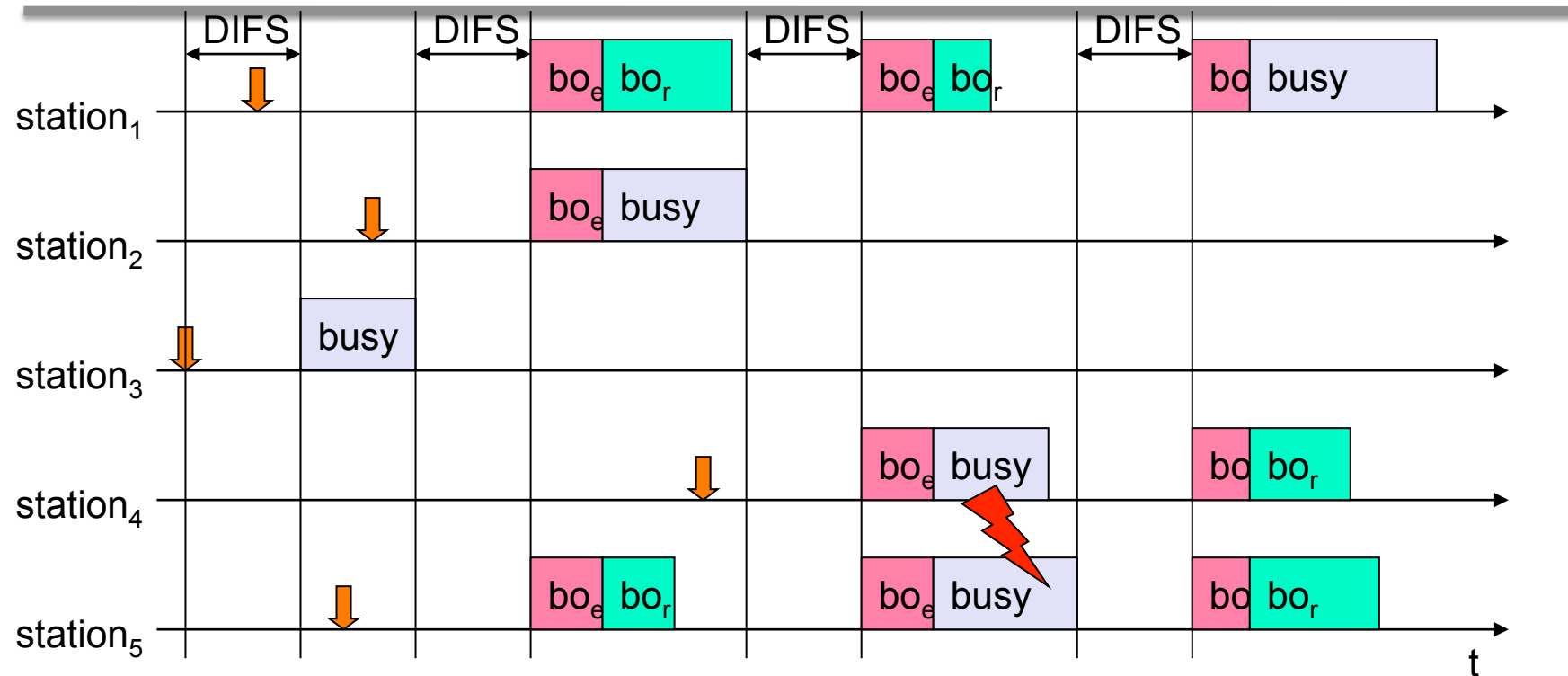
802.11 – CSMA/CA access method I



- station ready to send starts sensing the medium
- if the medium is free for the duration of an Inter-Frame Space (IFS), the station can start sending (IFS depends on service type)
- if the medium is busy, the station has to wait for a free IFS, then the station must additionally wait a random back-off time (collision avoidance, multiple of slot-time)
- if another station occupies the medium during the back-off time of the station, the back-off timer stops (fairness)



802.11 – competing stations



medium not idle (frame, ack etc.)



elapsed backoff time



packet arrival at MAC

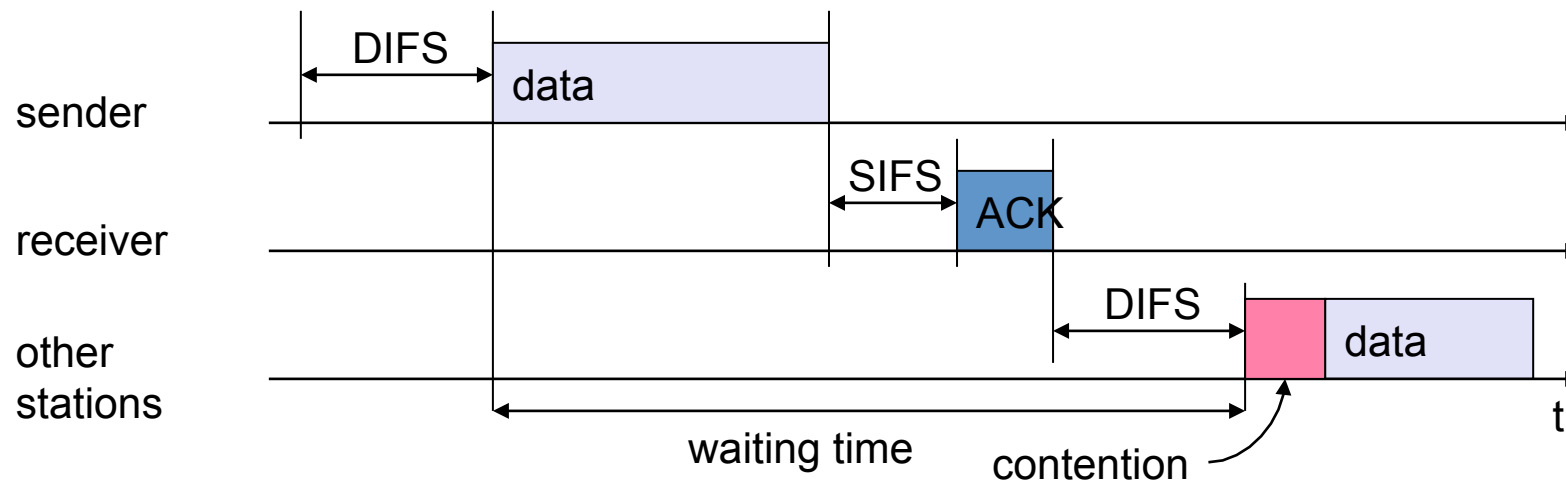


residual backoff time

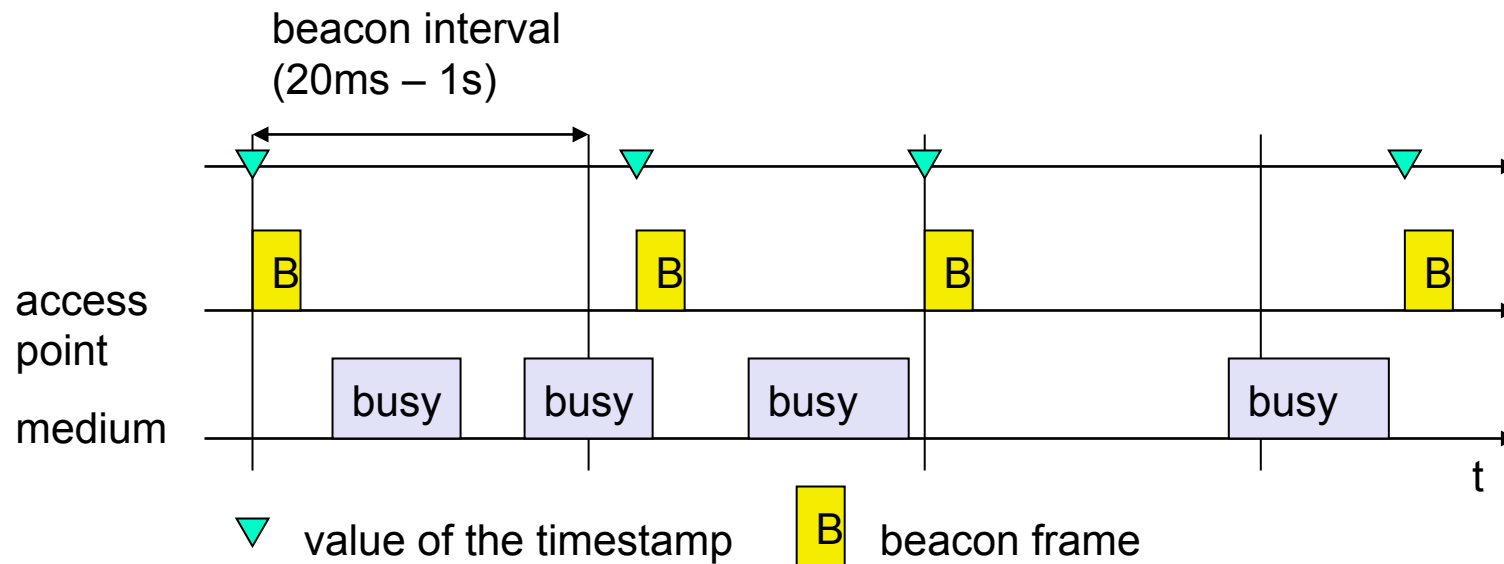
802.11 – Unicast/Ack



- Sending unicast packets
 - station has to wait for DIFS before sending data
 - receivers acknowledge at once (after waiting for SIFS) if the packet was received correctly (CRC)
 - automatic retransmission of data packets in case of transmission errors

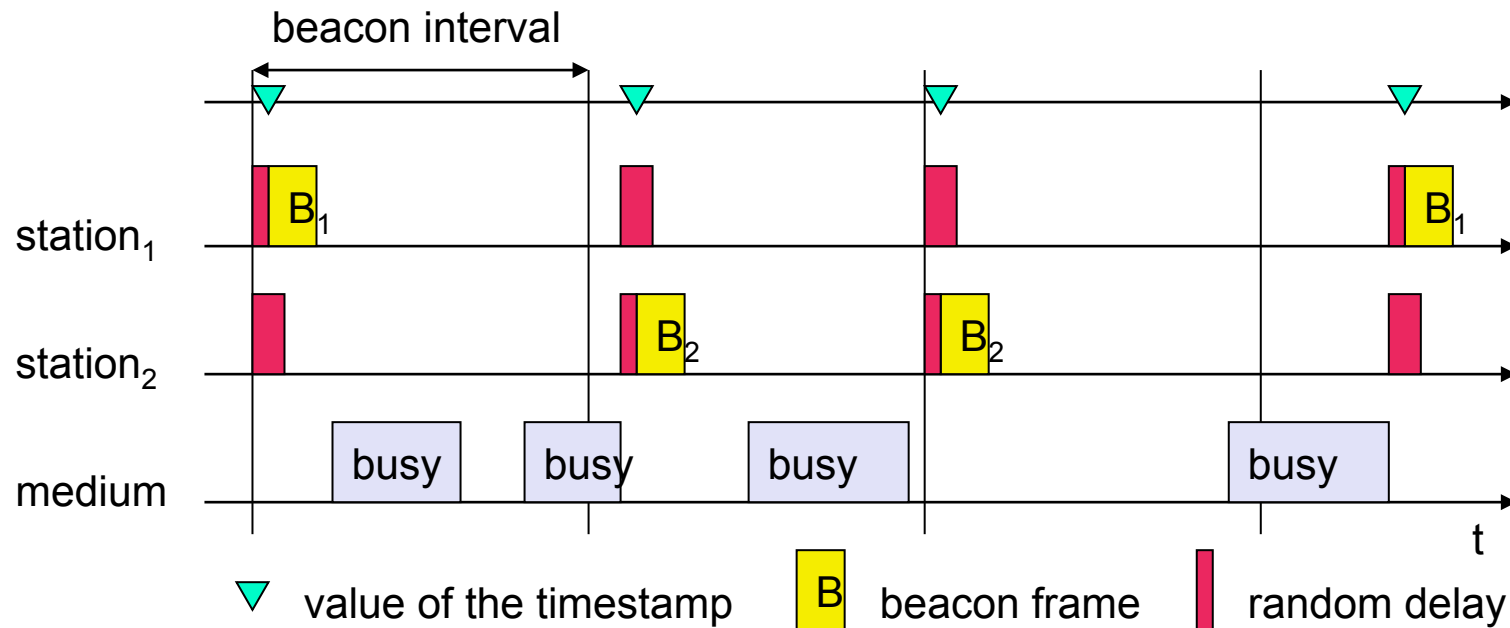


Synchronization using a Beacon (infrastructure)



- Nodes need to keep a tight synchronized clock with the access point: this is useful for power management and coordination of frequency hopping or contention slots.
- Beacons are sent semi-periodically [ei when the medium is not busy]

Synchronization using a Beacon (ad-hoc)



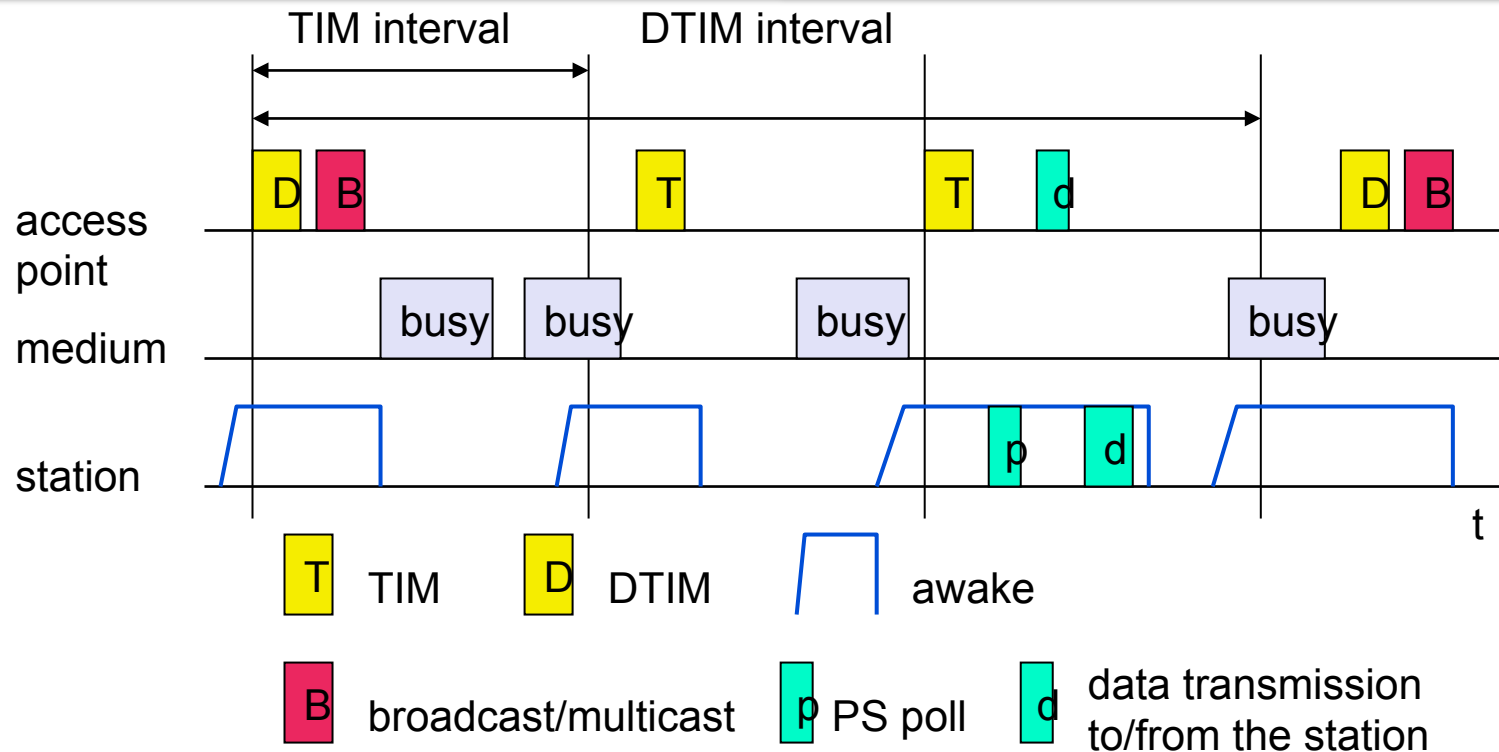
- In ad hoc mode each station transmits a beacon after the beacon interval [semi periodic again]
- Random backoffs are applied to beacons too: all station adjust clock to beacons received and suppress their beacon for the beacon interval

Power Management



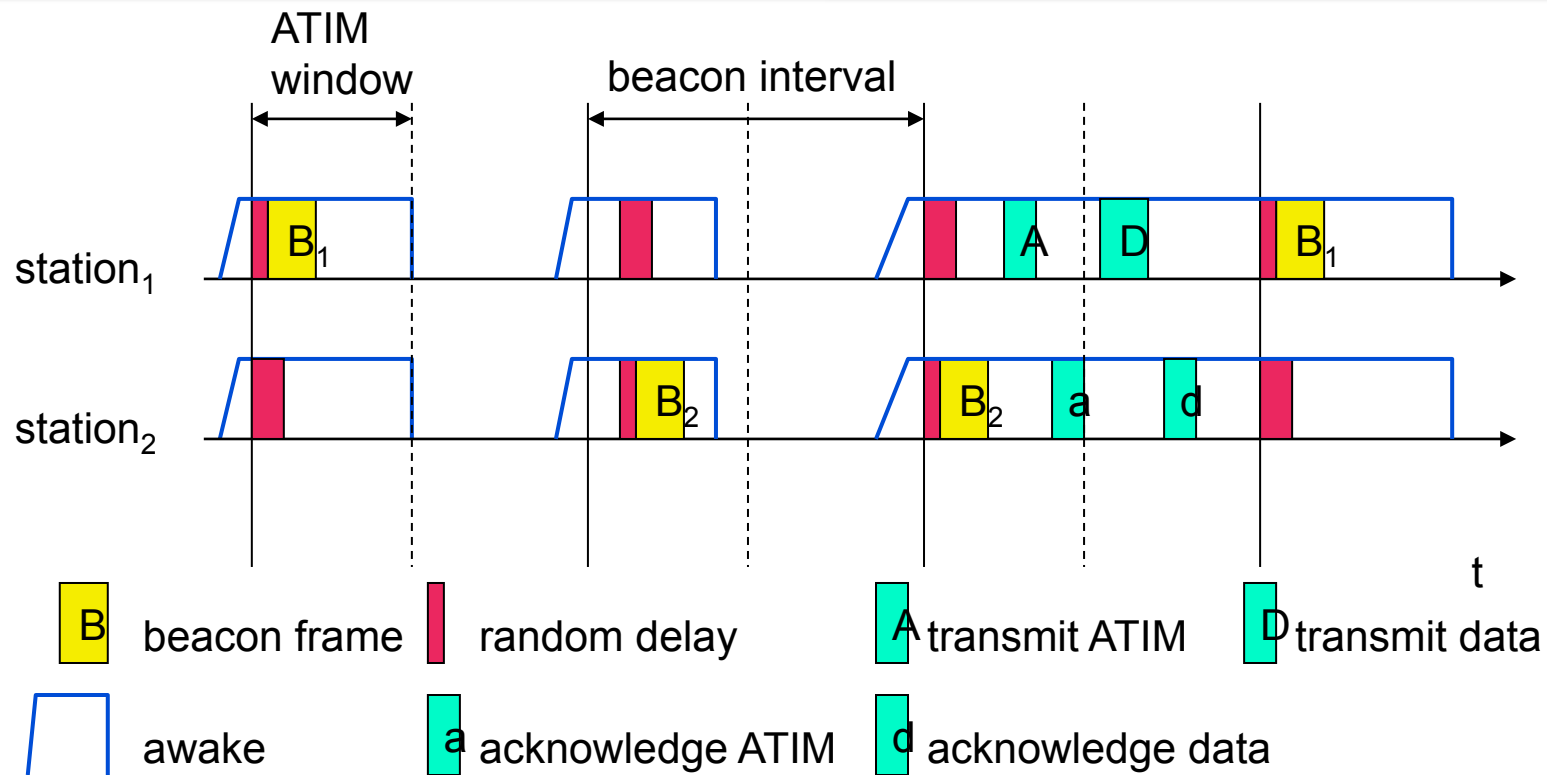
- Staying awake and transmitting is expensive for mobile stations as listening to the radio interface consumes power.
- Strategies have been devised to minimize awake times of mobile terminals while guaranteeing communication.

Power saving with wake-up patterns (infrastructure)



TIM: list of stations for which there will be data in the slot
 DTIM Interval indicates the delivery traffic indication map: for broadcast and multicast frames. It's a multiple of TIM

Power saving with wake-up patterns (ad-hoc)

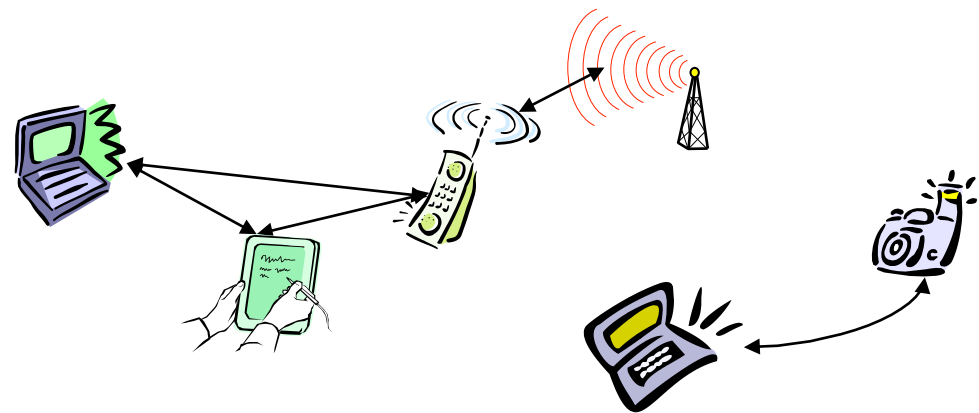
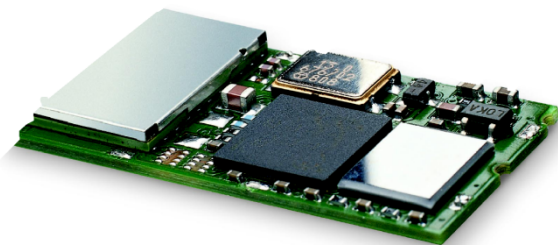


ATIM is the transmission map for ad hoc traffic: all stations stay awake for this slot

Bluetooth



- Standard is 802.15.1
- Basic idea
 - Universal radio interface for ad-hoc wireless connectivity
 - Interconnecting computer and peripherals, handheld devices, PDAs, mobile phones
 - Short range (10 m), low power consumption, license-free 2.45 GHz ISM
 - Voice and data transmission, approx. 1-3 Mbit/s gross data rate ((V3 offers 24Mbits)



History of Bluetooth



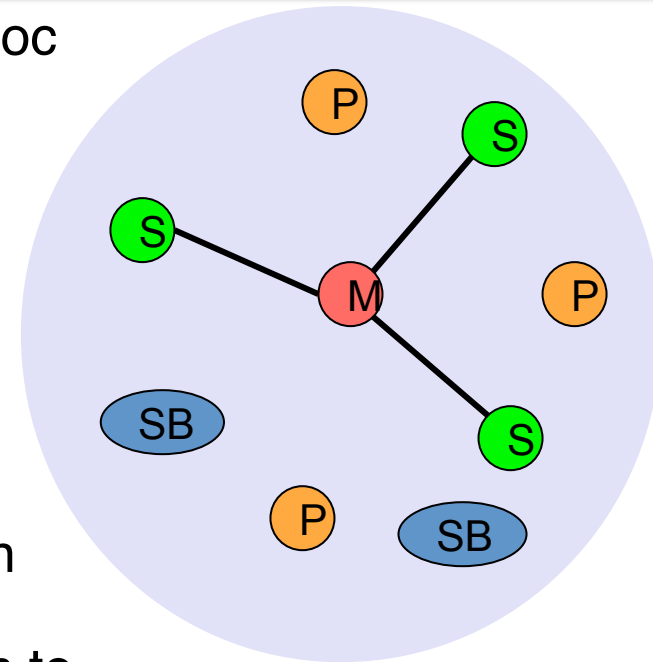
- History
 - 1994: Ericsson (Mattison/Haartsen), “MC-link” project
 - Renaming of the project: Bluetooth after Harald “Blåtand” Gormsen [son of Gorm], King of Denmark in the 10th century
 - 1998: foundation of Bluetooth SIG, www.bluetooth.org
 - 1999: erection of a rune stone at Ericsson/Lund ;-)
 - 2001: first consumer products for mass market, spec. version 1.1 released
 - 2005: 5 million chips/week
- Special Interest Group
 - Original founding members: Ericsson, Intel, IBM, Nokia, Toshiba
 - Added promoters: 3Com, Agere (was: Lucent), Microsoft, Motorola
 - > 10000 members
 - Common specification and certification of products



Piconet



- Collection of devices connected in an ad hoc fashion
- One unit acts as master and the others as slaves for the lifetime of the piconet
- Master determines frequency hopping pattern, slaves have to synchronize
- Each piconet has a unique hopping pattern
- Participation in a piconet = synchronization to hopping sequence
- Each piconet has **one master** and up to 7 simultaneous slaves (> 200 could be parked)



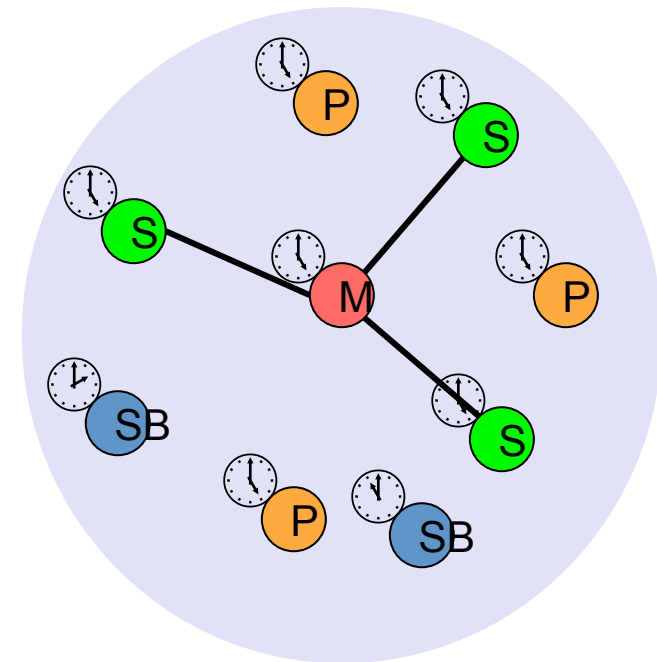
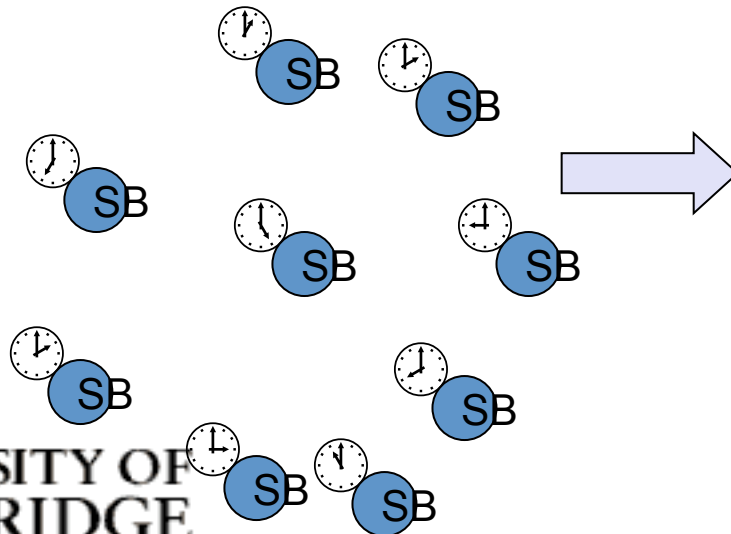
M=Master
S=Slave

P=Parked
SB=Standby

Forming a piconet



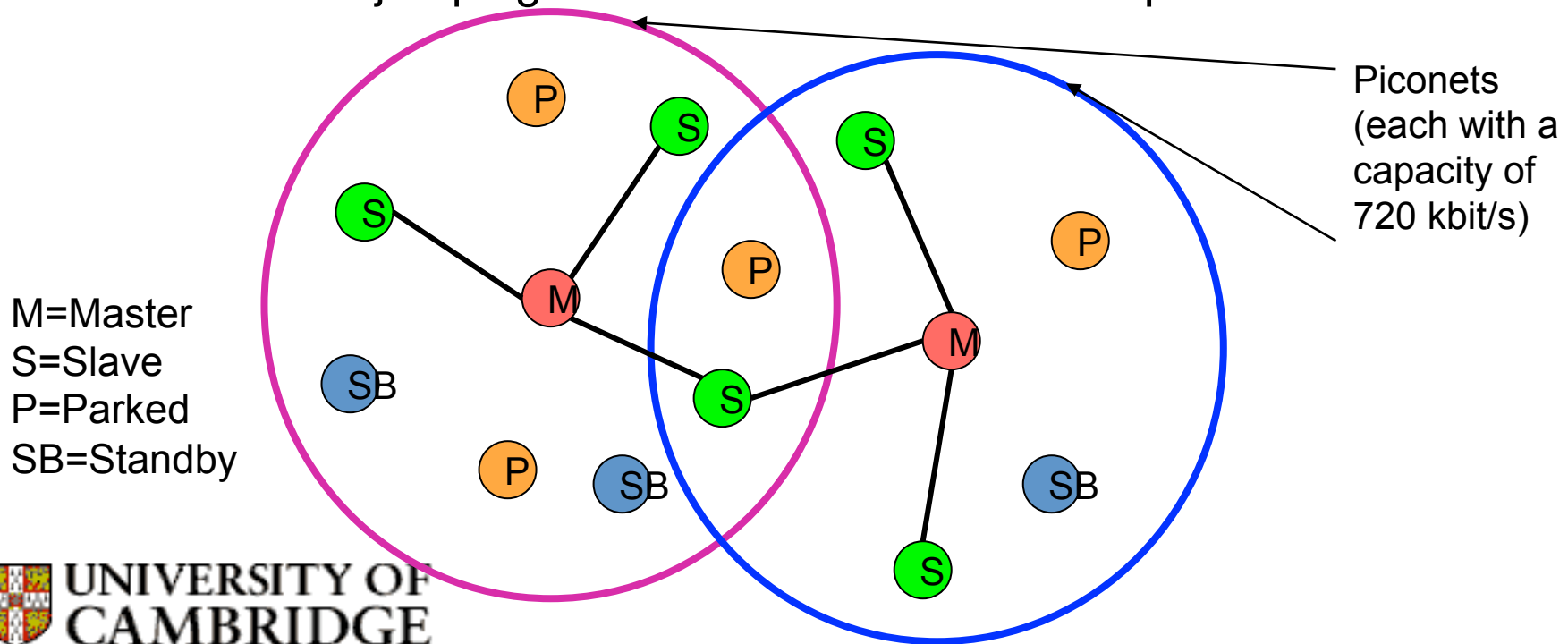
- All devices in a piconet hop together
 - Master gives slaves its clock and device ID
 - Hopping pattern: determined by device ID (48 bit, unique worldwide)
 - Phase in hopping pattern determined by clock
- Addressing
 - Active Member Address (AMA, 3 bit)
 - Parked Member Address (PMA, 8 bit)



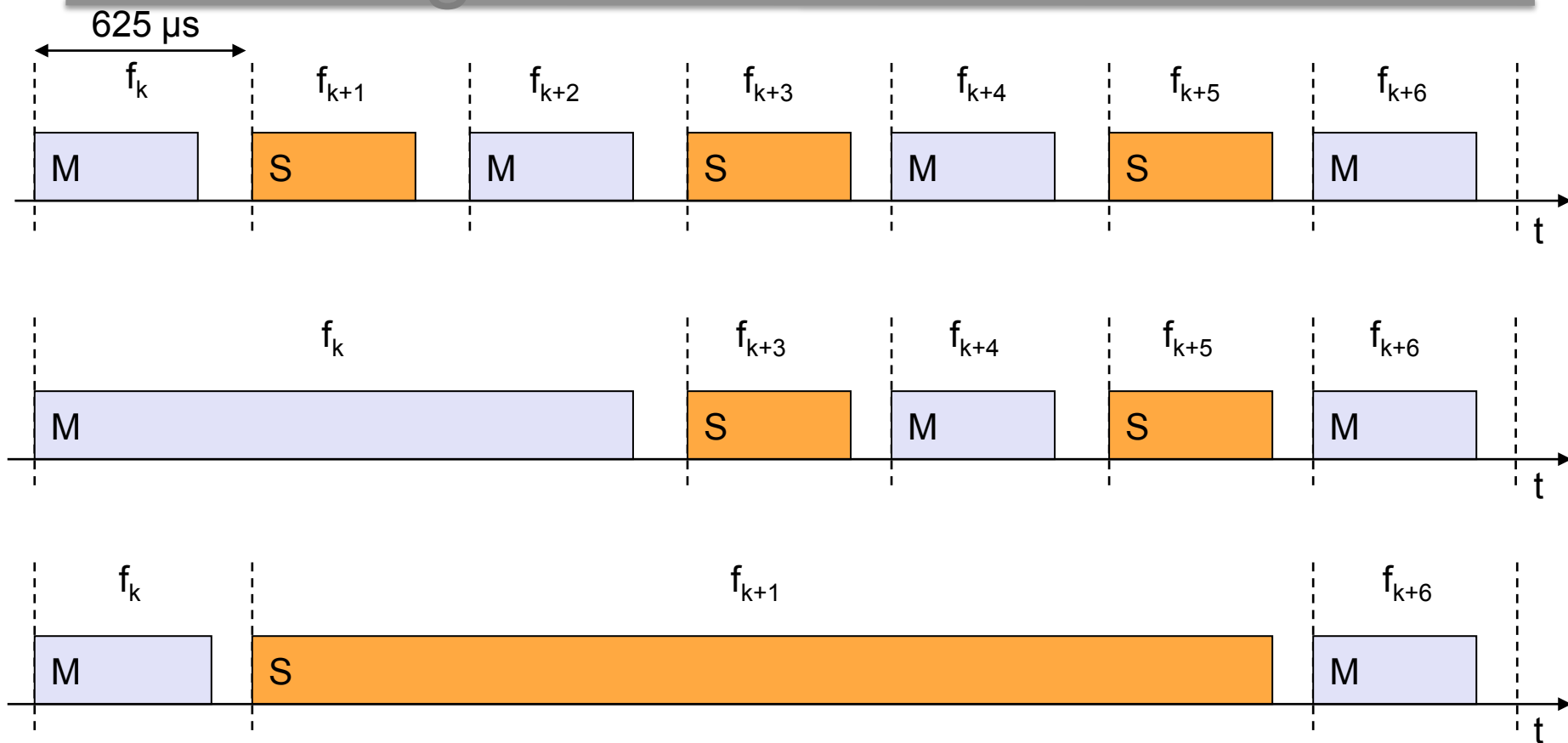
Scatternet



- Linking of multiple co-located piconets through the sharing of common master or slave devices
 - Devices can be slave in one piconet and master of another
- Communication between piconets
 - Devices jumping back and forth between the piconets



Frequency selection during data transmission

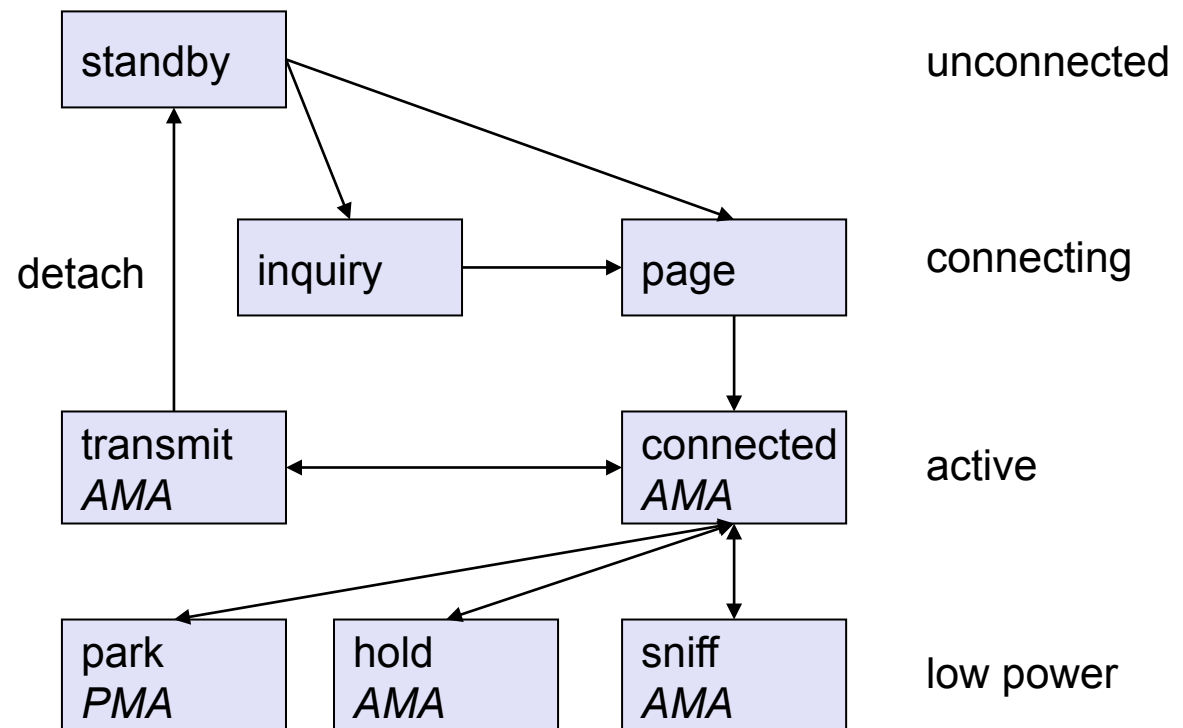


How to establish a piconet



- A device M starts an inquiry by sending an inquiry access code (IAC)
- Stand by devices listen periodically. When inquiry detected return packet containing its device address and timing information. The device is then a slave and enters the page mode
- After finding the required devices M sets up the piconet (hopping sequence, IDs). Slaves synch with M's clock.
- M can continue to page more devices
- Connection state:
 - Active state: transmit, receive and listening
 - All devices have AMA (active member address)
 - Passive state:
 - Sniff: listen at reduce rate but AMA kept
 - Hold: AMA kept but stop transmission
 - Park: release AMA and use PMA (parked). Still synched

Baseband states of a Bluetooth device



Standby: do nothing

Inquire: search for other devices

Page: connect to a specific device

Connected: participate in a piconet

Park: release AMA, get PMA

Sniff: listen periodically, not each slot

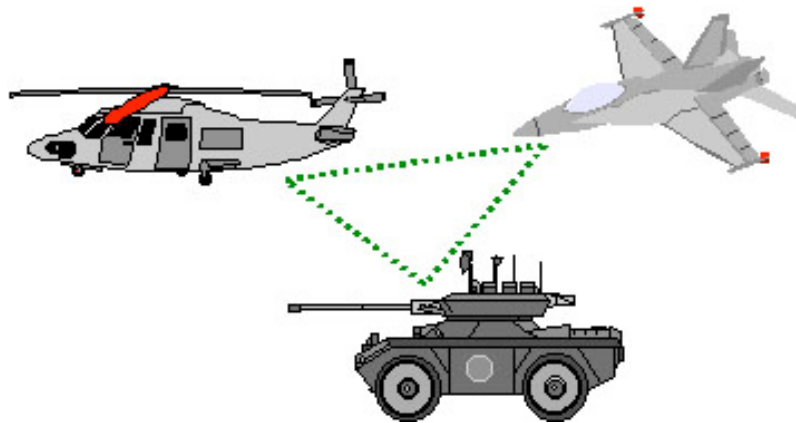
Hold: stop ACL, SCO still possible, possibly participate in another piconet

Ad Hoc Networking



- We have seen connectivity between wireless devices and fixed basestations through
 - WIFI
 - Cellular
- WIFI and Bluetooth provide [also] ad hoc connectivity modes where there is no infrastructure supporting the communication

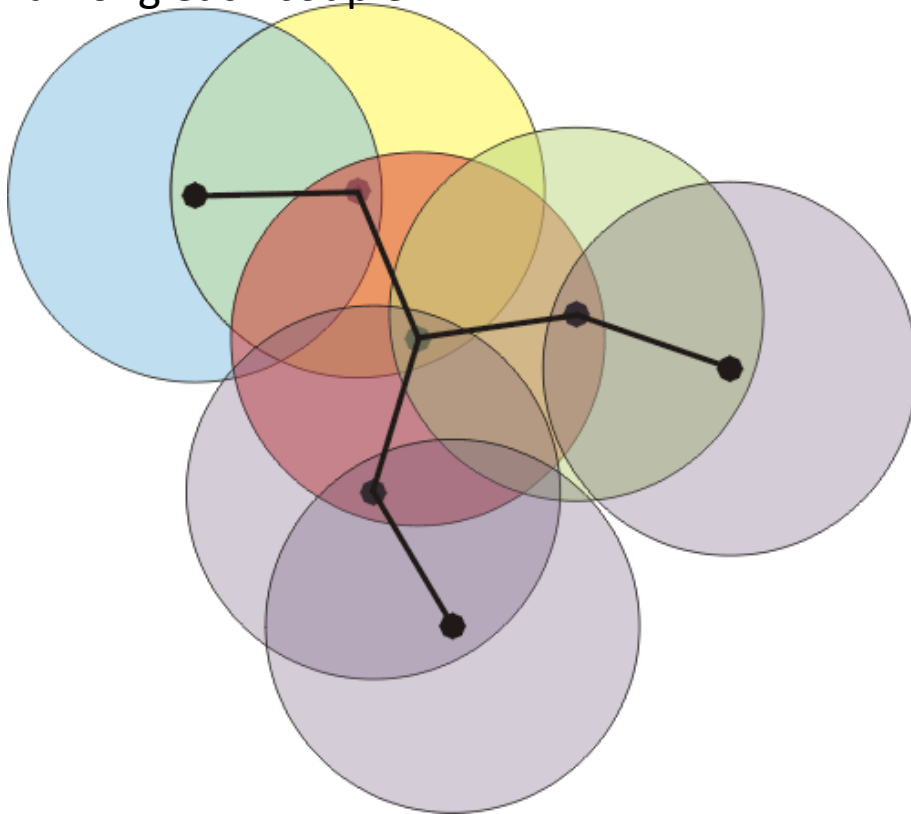
Examples of Multi-hop Ad hoc Networks



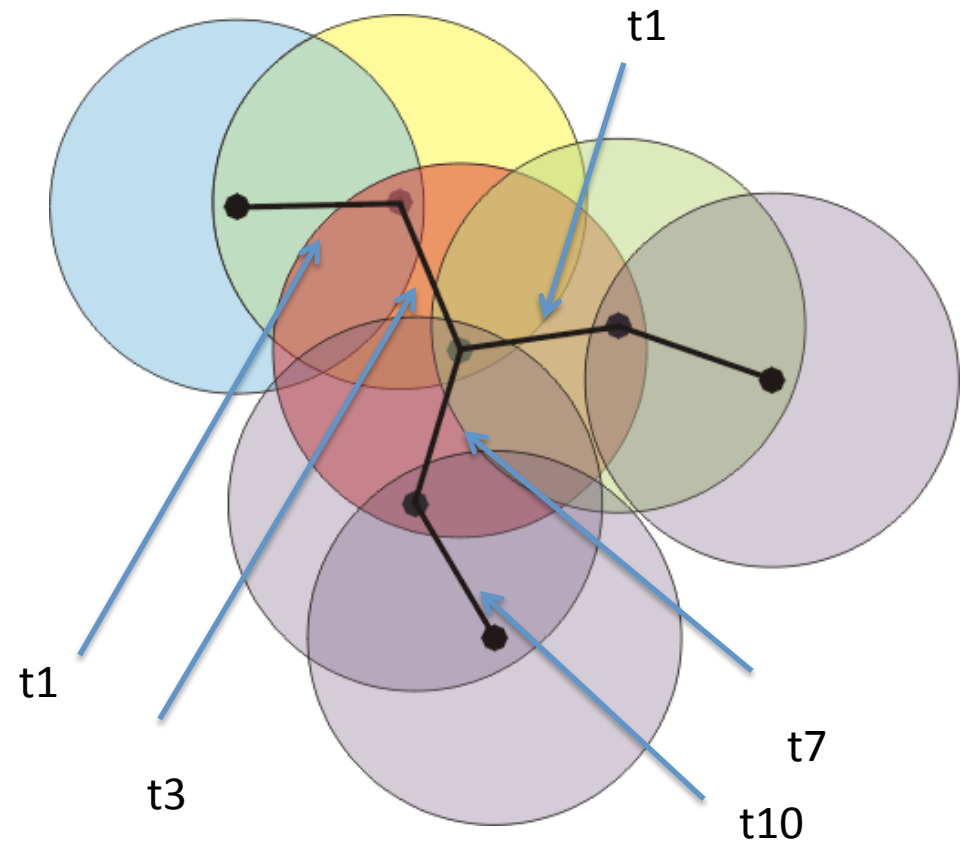
Connected vs Disconnected Ad Hoc Networks



Connected: there is a connected path among each couple



Disconnected: there is no connected path, just sometimes some temporal ones



Summary



- In this lecture we have introduced the Wireless LAN and Bluetooth standard and we have started to describe concepts related to ad hoc networking