## COMPUTER SCIENCE TRIPOS Part II – 2018 – Paper 9

## 4 Computer Vision (JGD)

- (a) Consider an object's surface reflectance map  $\phi(i, e, g)$  specifying the amount of incident light reflected towards a camera from each point on the surface, where the angle of the illuminant (a point source) relative to the local surface normal N is i, the angle relative to N of a ray of light re-emitted from the surface is e, and the angle between the emitted ray and the illuminant is g.
  - (i) For what kind of surface is the reflectance map simply  $\phi(i, e, g) = \cos(i)$ ? Name this type of surface and describe its key properties. [4 marks]
  - (*ii*) For what kind of surface does the reflectance map simplify to  $\phi(i, e, g) = 1$ if i = e and both i and e are coplanar with the surface normal N, and  $\phi(i, e, g) = 0$  otherwise? Name this type of surface and describe its key properties. [4 marks]
  - (*iii*) For what kind of surface does the reflectance map depend only on the ratio of the cosines of the angles of incidence and emission,  $\cos(i)/\cos(e)$ , but not upon their relative angle g nor upon the surface normal N? Give an example of such an object, and explain the consequence of this special reflectance map for the object's appearance. [4 marks]
- (b) The binary pixel array on the left below was convolved with what operator ? to produce the result on the right? Specify the operator by numbers within an array, and identify what task this convolution accomplishes in computer vision.

| 0           | 0           | 0           | 0           | 0           | 0           | 0           | 0           | 0           | 0           |                     | 0           | 0             | 0           | 0           | 0           | 0           | 0             | 0           |
|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|---------------------|-------------|---------------|-------------|-------------|-------------|-------------|---------------|-------------|
| 0           | 0           | 0           | 0           | 0           | 0           | 0           | 0           | 0           | 0           | -                   | 0           | 0             | 0           | 0           | 0           | 0           | 0             | 0           |
| 0           | 0           | 0           | 1           | 1           | 1           | 1           | 0           | 0           | 0           |                     | 0           | -1            | 1           | 0           | 0           | 1           | -1            | 0           |
| 0           | 0           | 0           | 1           | 1           | 1           | 1           | 0           | 0           | 0           |                     | 0           | -1            | 1           | 0           | 0           | 1           | -1            | 0           |
|             |             |             |             |             |             |             |             |             |             |                     |             |               |             |             |             |             |               |             |
| 0           | 0           | 0           | 1           | 1           | 1           | 1           | 0           | 0           | 0           | $*$ ? $\Rightarrow$ | 0           | -1            | 1           | 0           | 0           | 1           | -1            | 0           |
| 0           | 0<br>0      | 0           | 1<br>1      | 1           | 1<br>1      | 1<br>1      | 0           | 0           | 0           | * [?] ⇒             | 0           | -1<br>-1      | 1<br>1      | 0           | 0           | 1<br>1      | -1<br>-1      | 0           |
| 0<br>0<br>0 | 0<br>0<br>0 | 0<br>0<br>0 | 1<br>1<br>0 | 1<br>1<br>0 | 1<br>1<br>0 | 1<br>1<br>0 | 0<br>0<br>0 | 0<br>0<br>0 | 0<br>0<br>0 | * ? ⇒               | 0<br>0<br>0 | -1<br>-1<br>0 | 1<br>1<br>0 | 0<br>0<br>0 | 0<br>0<br>0 | 1<br>1<br>0 | -1<br>-1<br>0 | 0<br>0<br>0 |

[4 marks]

(c) When visually inferring a 3D representation of a face, it is useful to extract separately both a shape model, and a texture model. Explain the purposes of these steps, their use in morphable models for pose-invariant face recognition, and how the shape and texture models are extracted and later re-combined.

[4 marks]