## 1999 Paper 4 Question 8

## Continuous Mathematics

Suppose we need to solve a linear second-order differential equation with constant coefficients $A$ and $B$ in which the combined derivatives of the solution we seek, $f(x)$, are only known to be related to another function, $g(x)$ :

$$
A \frac{d^{2} f(x)}{d x^{2}}+B \frac{d f(x)}{d x}=g(x)
$$

We know the function $g(x)$, and we can compute its Fourier Transform $G(\mu)$.
How can we use the properties of the Fourier Transform and its inverse in order to compute the solution $f(x)$ of this differential equation? Provide an expression for $F(\mu)$, the Fourier Transform of $f(x)$, in terms of $G(\mu)$, frequency variable $\mu$, and the coefficients in the differential equation.

What final step is now required in order to compute the actual solution $f(x)$ of the differential equation, given your expression for $F(\mu)$ ? [2 marks]

In numerical computing, differential operators must always be represented by finite differences. Assume that a function has been sampled at uniform, closely spaced, intervals. How many consecutive sample points are necessary in order to compute the $N^{t h}$ derivative of the function at some point?

To compute the third derivative in a local region of a function, what set of weights would you use to multiply consecutive samples of the function?

What is the principal computational advantage of using orthogonal functions, over non-orthogonal ones, when representing a set of data as a linear combination of a universal set of basis functions?
[2 marks]
If $\Psi_{k}(x)$ belongs to a set of orthonormal basis functions, and $f(x)$ is a function or a set of data that we wish to represent in terms of these basis functions, what is the basic computational operation we need to perform involving $\Psi_{k}(x)$ and $f(x)$ ?
[3 marks]

