## 1998 Paper 10 Question 5

## Data Structures and Algorithms

Describe
(a) how to determine whether or not a point is inside a simple plane closed polygon, paying proper attention to awkward cases;
(b) how, with luck, to exclude large numbers of points from the convex hull of a set of points in the plane, with due consideration of what can go wrong;
(c) how to compute economically the convex hull of the points that are left after the measures you have described in $(b)$ above.

