## COMPUTER SCIENCE TRIPOS Part IB - 2022 - Paper 6

## 1 Artificial Intelligence (sbh11)

You are solving a planning problem using the GraphPlan algorithm. The problem has the following actions:

$$\neg A(S), H(M)$$
 $\neg A(B)$ 
 $\neg H(M), A(B)$ 
 $\neg H(C), H(M), A(S)$ 

$$\boxed{a_1(S)}$$
 $\boxed{a_1(B)}$ 
 $\boxed{a_2(M)}$ 
 $\boxed{a_2(S)}$ 

$$A(S)$$
 $A(B)$ 
 $H(M)$ 
 $H(C), \neg H(M)$ 

The start state is  $\neg H(M), \neg H(C), \neg A(S), \neg A(B)$  and the goal is H(C).

- (a) Draw the state levels  $S_i$  and action levels  $A_i$  of the planning graph up to and including  $S_2$ . Do not add any mutexes at this stage. [3 marks]
- (b) Explain why it is not possible at this stage to attempt to extract a plan. [1 mark]
- (c) What is the smallest i for which it might make sense to try to extract a plan, starting from  $S_i$ . Explain your answer. [2 marks]
- (d) For the value of i identified in Part (c), draw levels  $S_{i-1}$ ,  $A_{i-1}$  and  $S_i$  of the planning graph. [4 marks]
- (e) On the diagram you have produced for Part (d), mark four mutexes, each of which arises for a different reason. In each case explain what kind of mutex you have included.

  [6 marks]
- (f) Give a general description of how the extraction of a plan from a planning graph can be addressed as a heuristic search problem. [4 marks]