

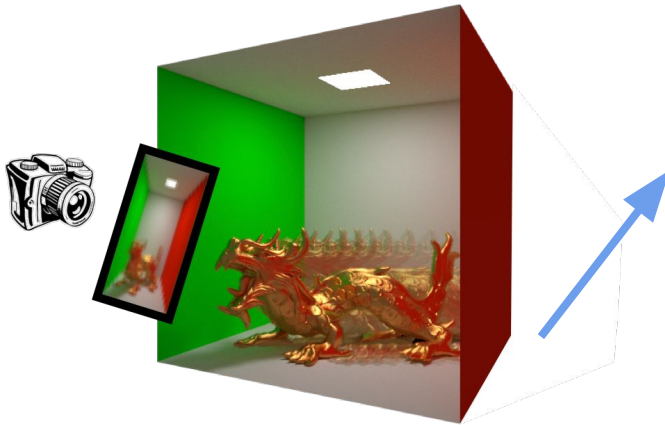
Differentiable Methods for Visual Computing

Dr Fangcheng Zhong



Inverse Problems in Machine Perception

Observation
(e.g. images, Lidar, etc.)



Causal factors
(camera and scene parameters,
e.g. geometry, lighting,
materials, motion, etc.)



Geometry Representations

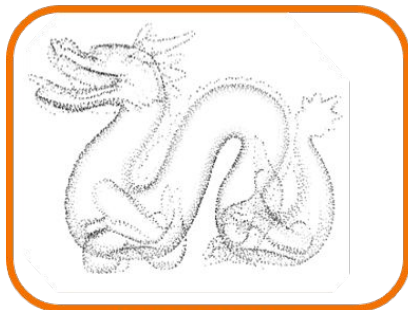
Surface Representations



Mesh



Parametric surface

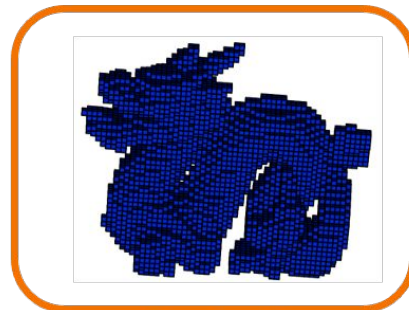


Point clouds

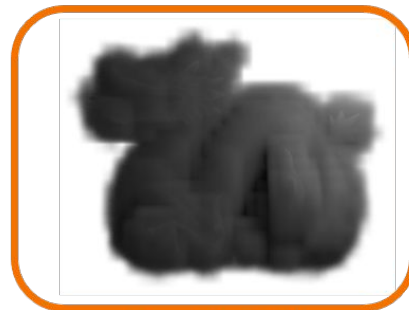


Signed distance function

Volume Representations



Voxel grids

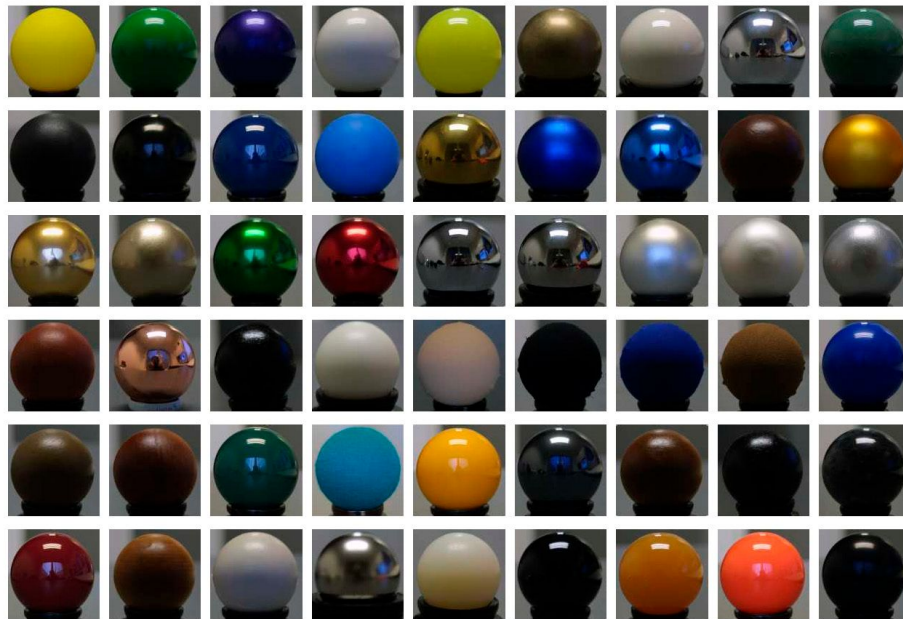


Density fields

Material Representations

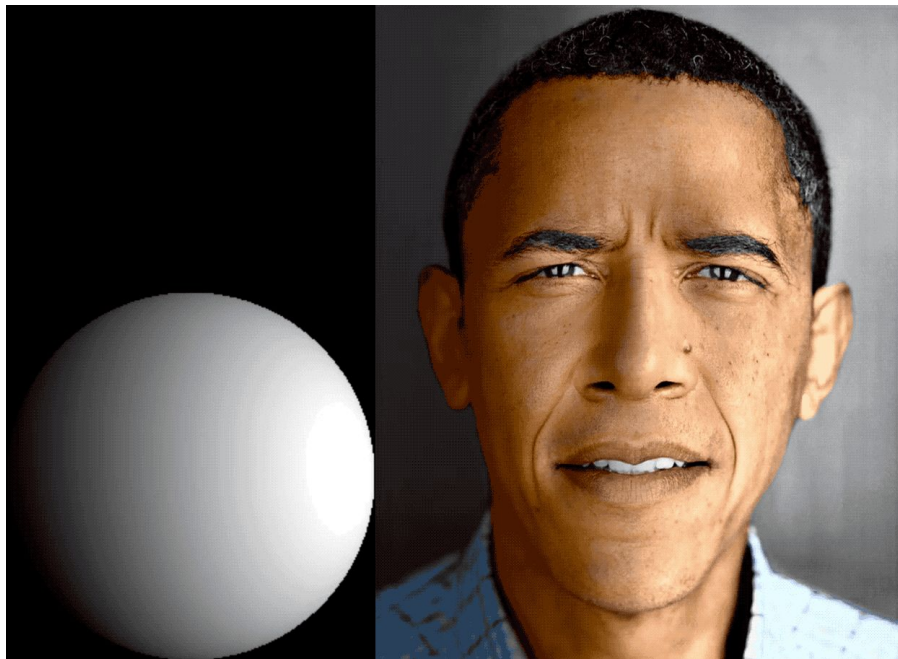


Textures

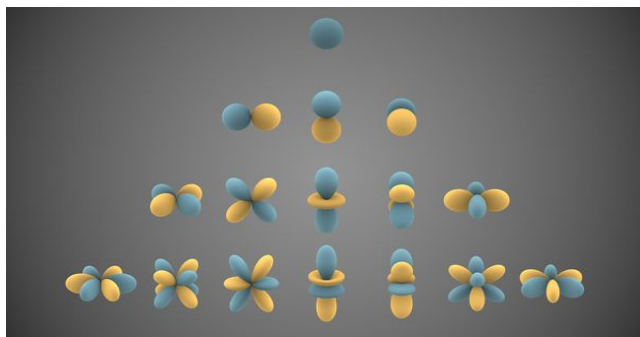


BRDFs

Light Representations



Lightmap
Images



Spherical
harmonics

Data-Driven Inference



2D Image



3D Point Cloud

(a) Possible Inputs

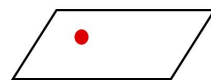


(b) Output Mesh for 2D Image

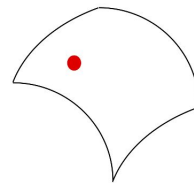
Latent shape representation



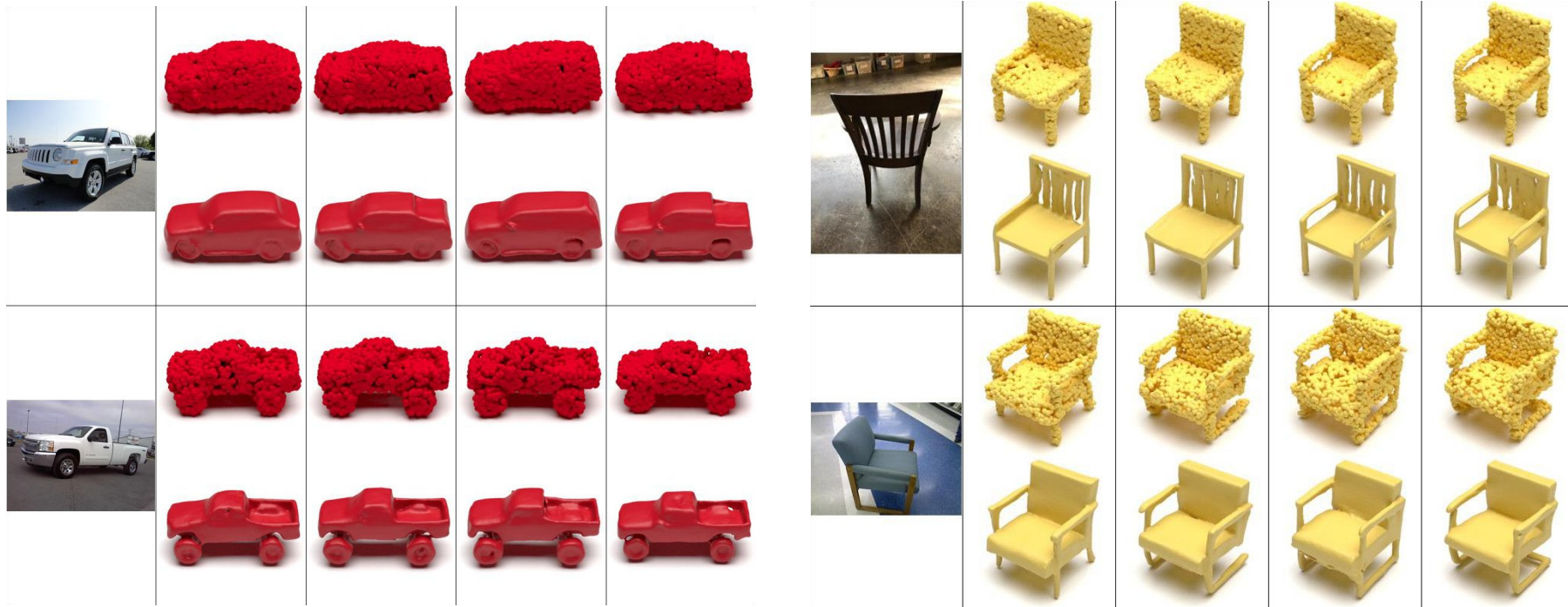
Sampled 2D point



Generated 3D point

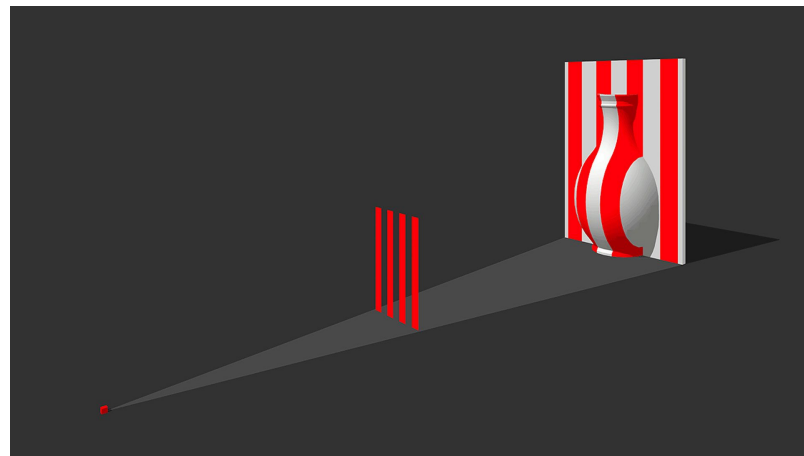
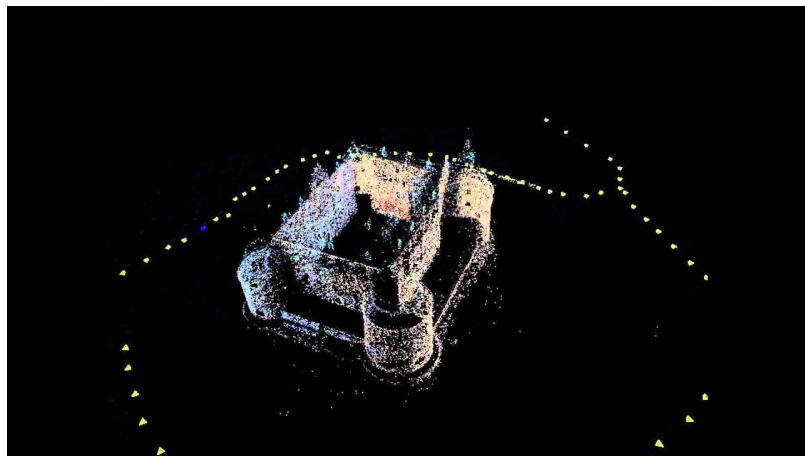


Generative Methods



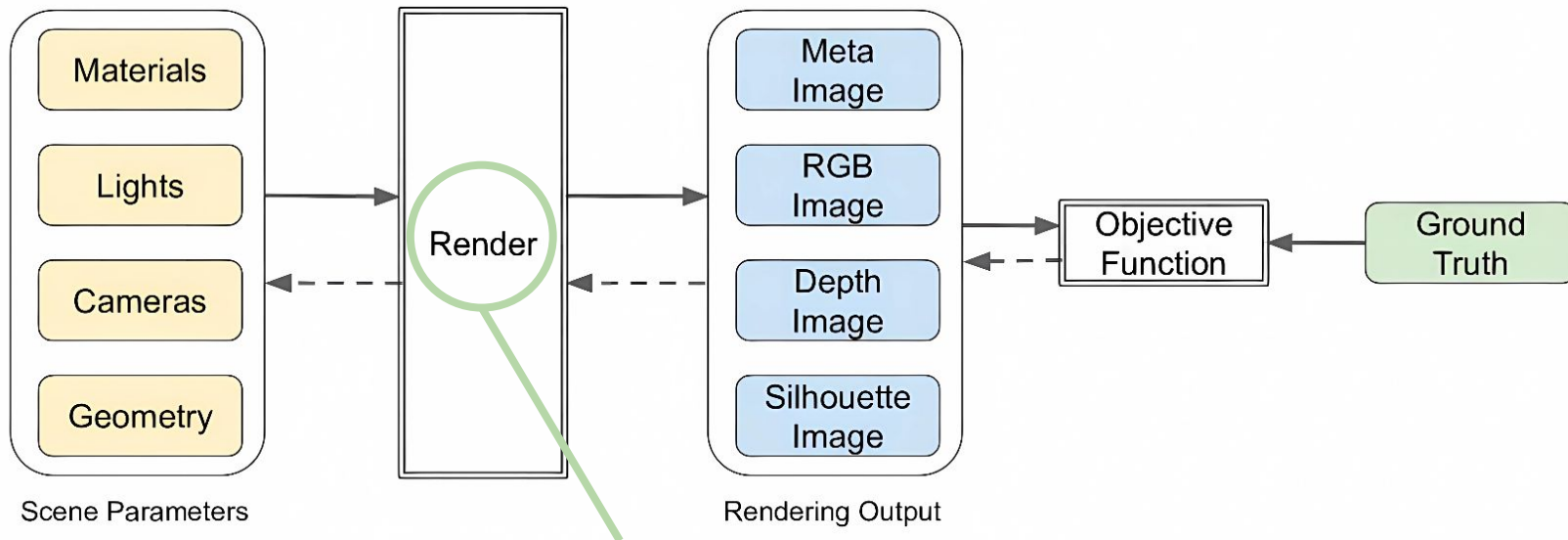
Traditional CV Methods

- Constrained optimization
 - SLAM, Structure from Motion
 - Light probes, structured light



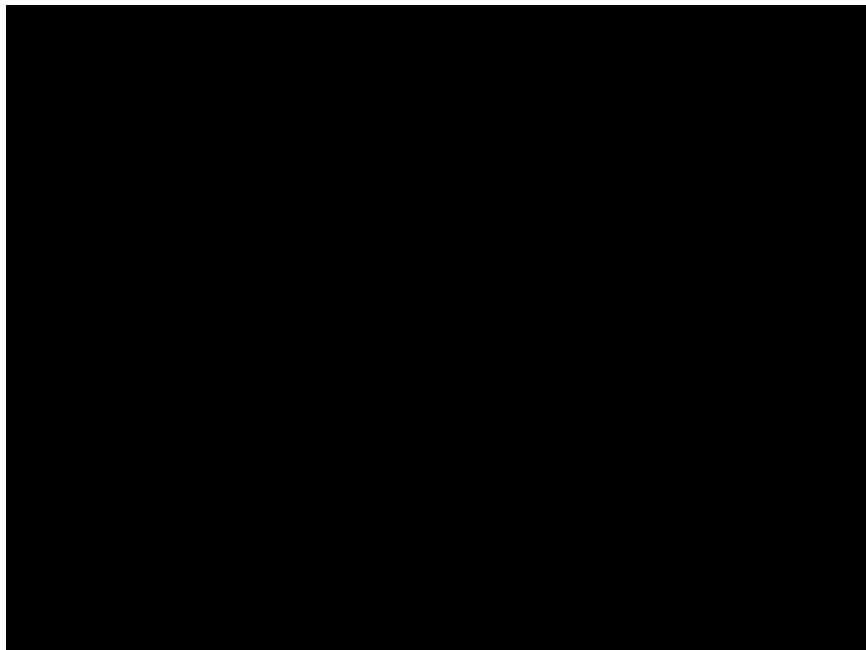
Differentiable Rendering

Generalization of traditional CV methods

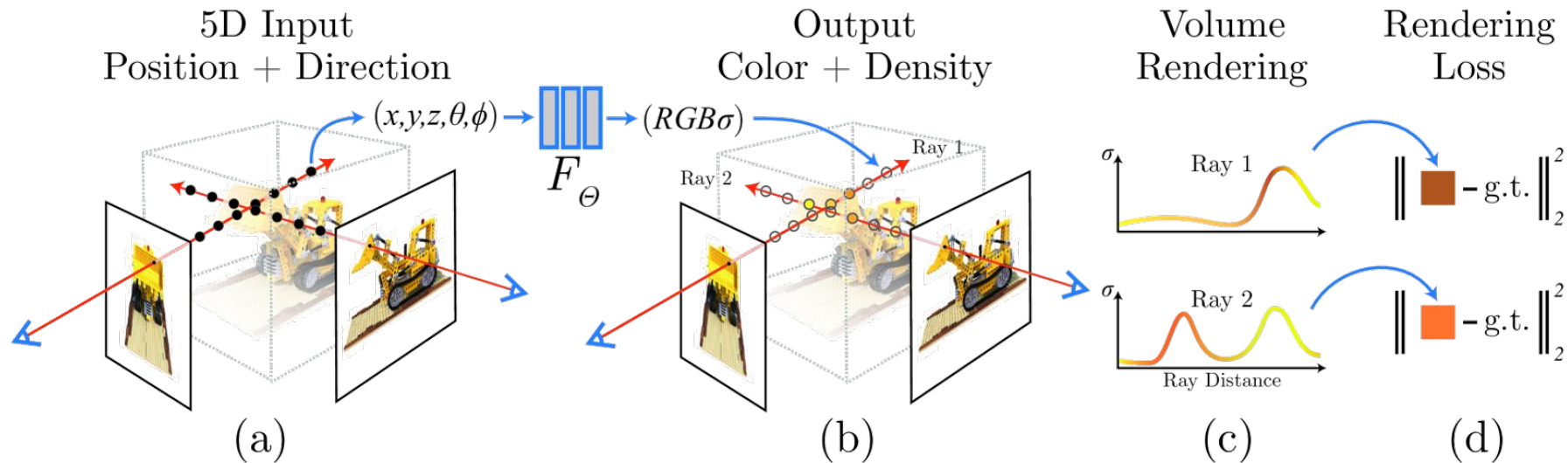


Derive useful gradients in rendering

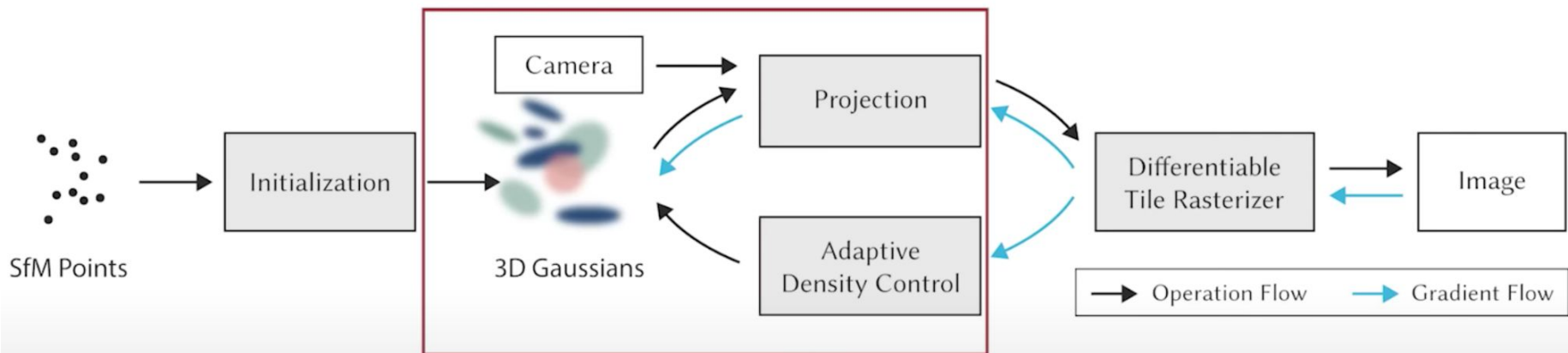
Differentiable Volume Rendering



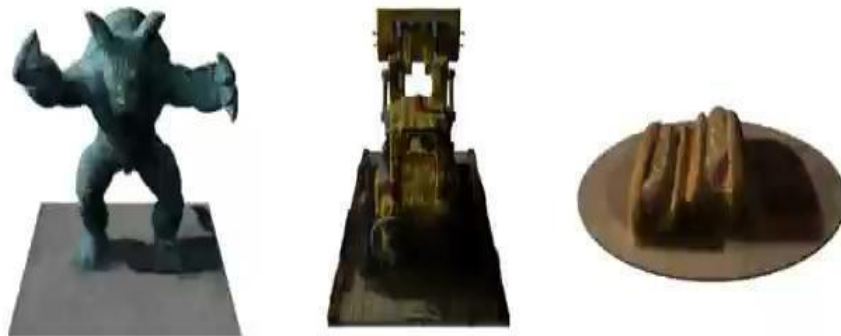
Differentiable Volume Rendering



Differentiable Volume Rendering



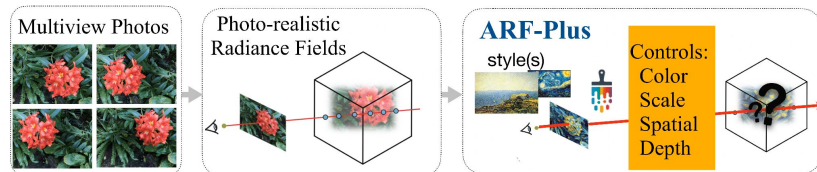
Differentiable Volume Rendering



Differentiable Volume Rendering



Differentiable Volume Rendering



Color Preservation Control



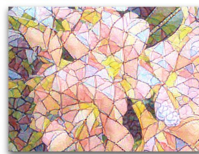
With Color Preservation



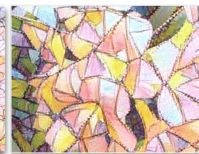
Without Color Preservation



Scale Control



Scale Down



Scale Up



Spatial Control



Multiple Styles Spatial Control



Without Spatial Control



Depth Enhancement Control

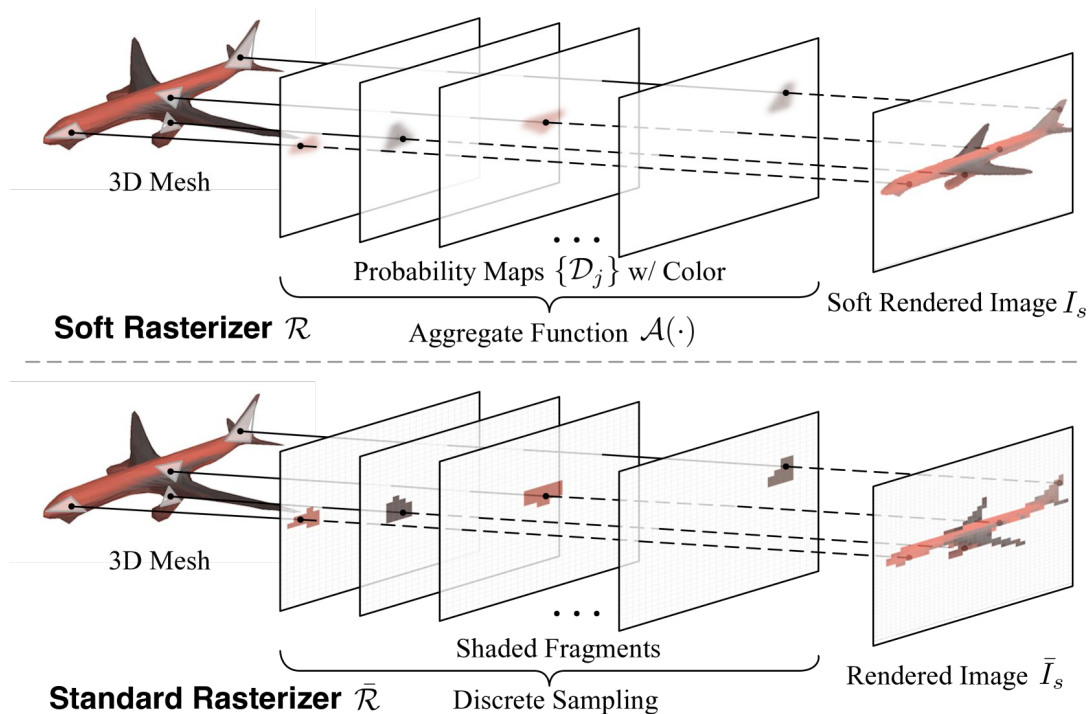


More Perceptible Depth

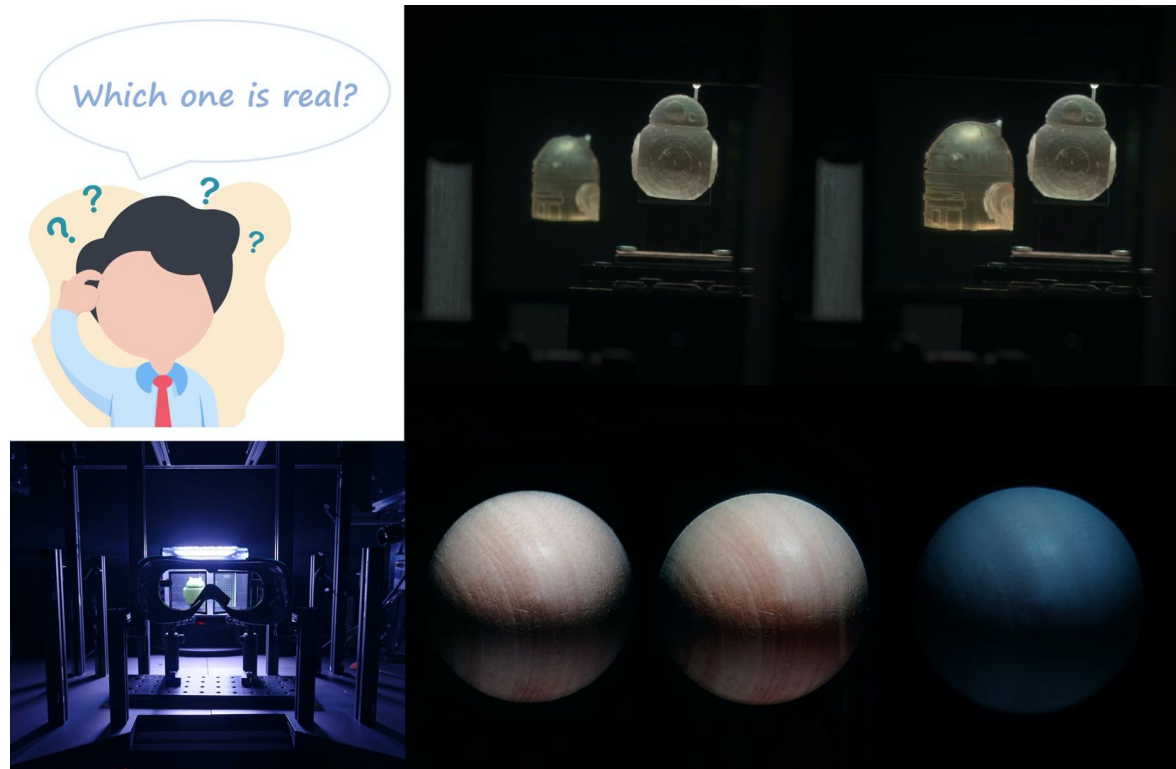


Less Perceptible Depth

Differentiable Surface Rendering



Differentiable Surface Rendering



Fangcheng Zhong, Akshay Jindal, Ali Özgür Yöntem, Param Hanji, Simon J. Watt, and Rafał K. Mantiuk. 2021. Reproducing Reality with a High-Dynamic-Range Multi-Focal Stereo Display. ACM Transactions on Graphics (Proceedings of ACM SIGGRAPH Asia, Journal Track), 2021

Differentiable Surface Rendering

Reparameterizing Discontinuous Integrands for Differentiable Rendering

Guillaume Loubet (EPFL) Nicolas Holzschuch (INRIA) Wenzel Jakob (EPFL)

SIGGRAPH Asia 2019

Differentiable Surface Rendering



RGB



NeuS



HFS



MipNeRF360 ($\sigma = 50$)



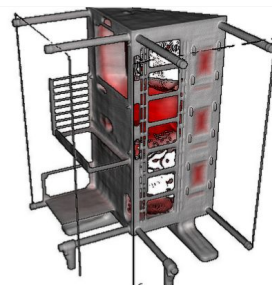
Plenoxels ($\sigma = 50$)



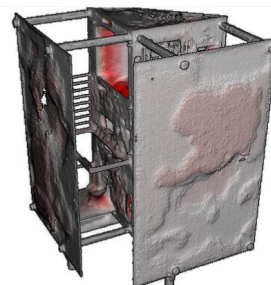
Ours



RGB



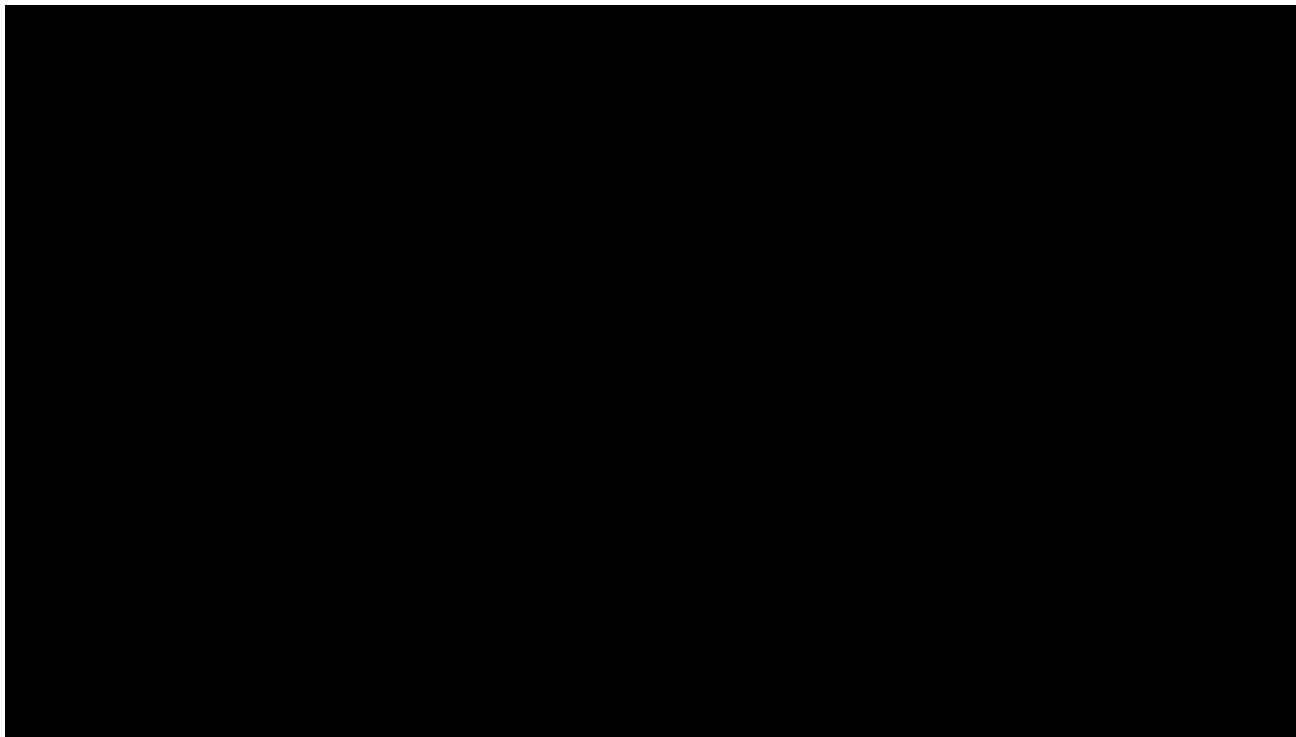
NeuS



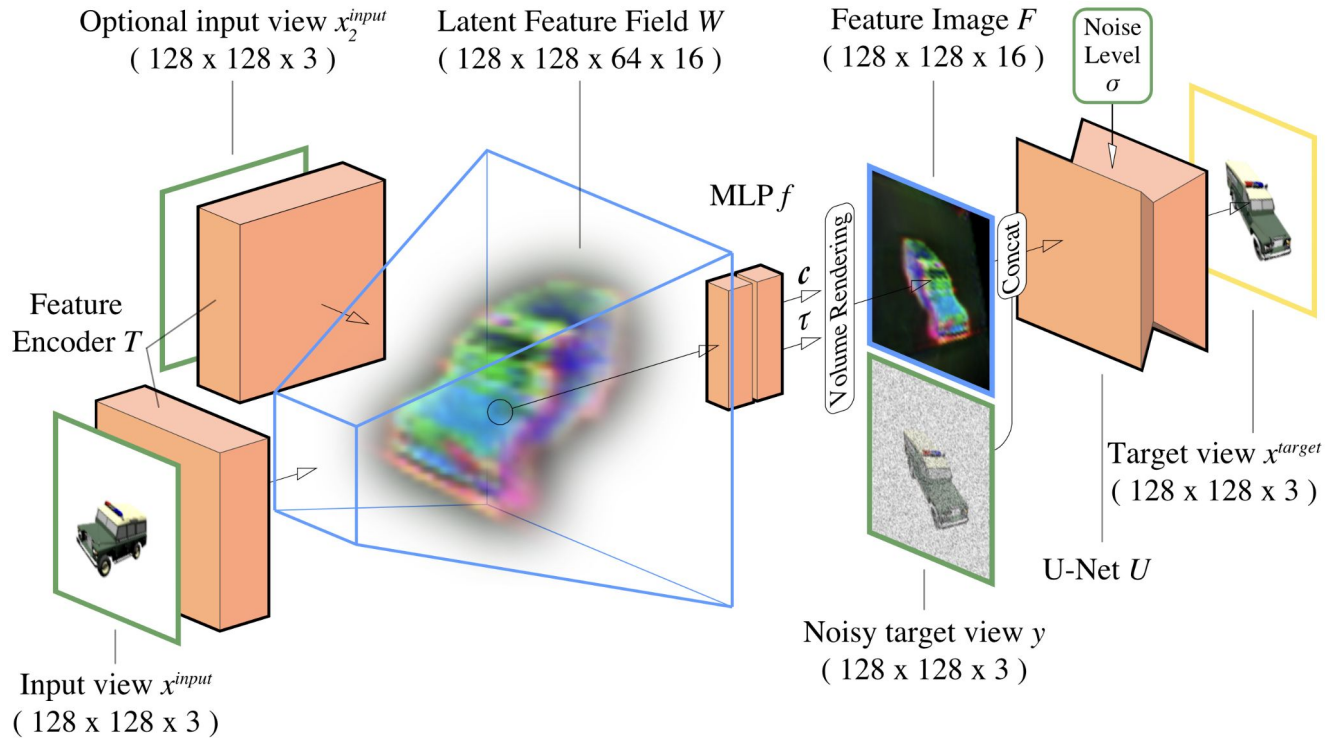
Ours



Hybrid Representations for Differentiable Rendering

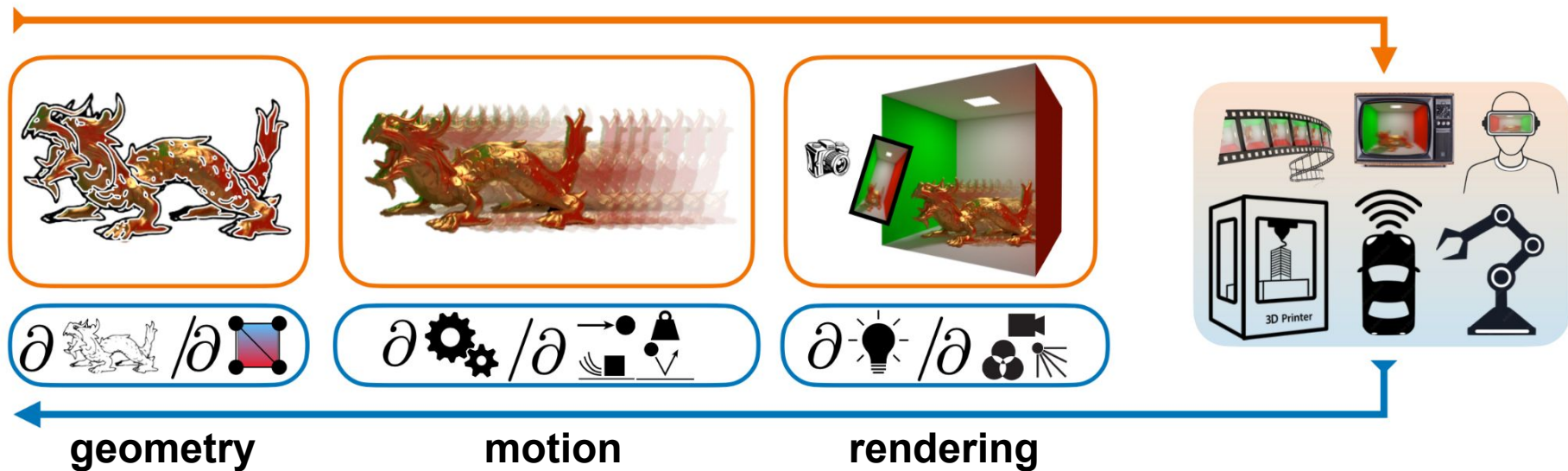


Differentiable Rendering with Data-Driven Prior

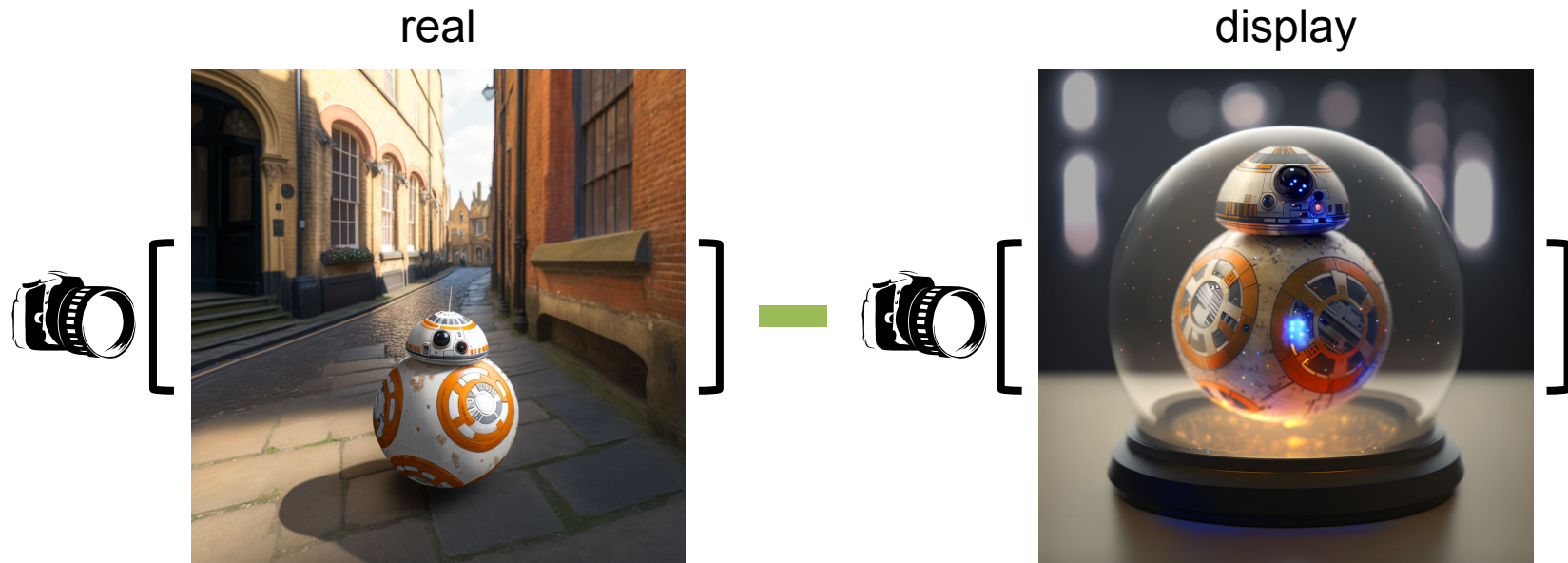


Extended Differentiable Visual Computing

Everything differentiable can be integrated!

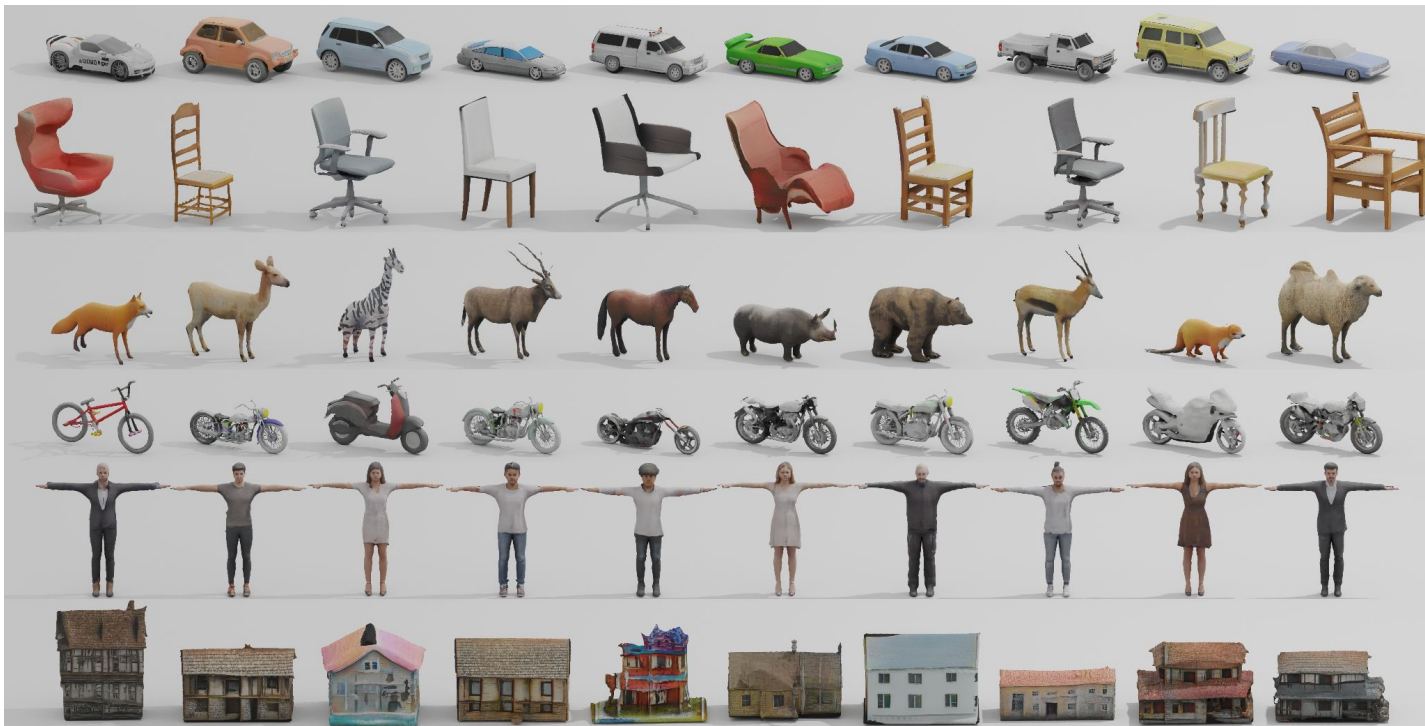


Extended Differentiable Visual Computing



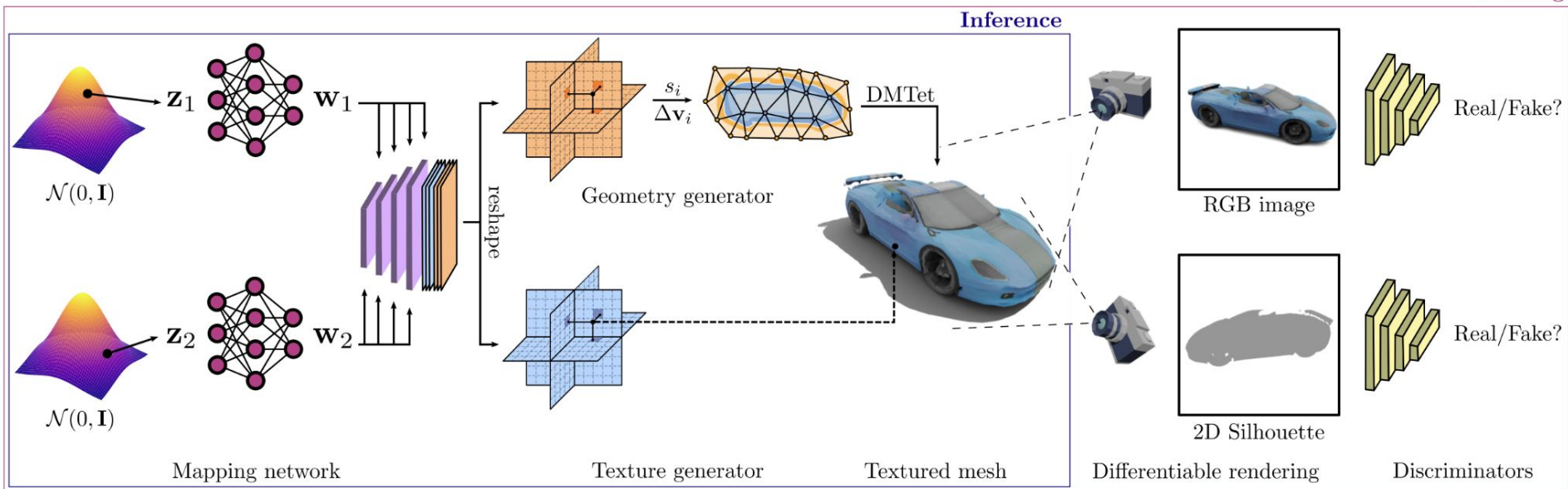
Differentiable displays and cameras

Differentiable Visual Computing for Generative AI

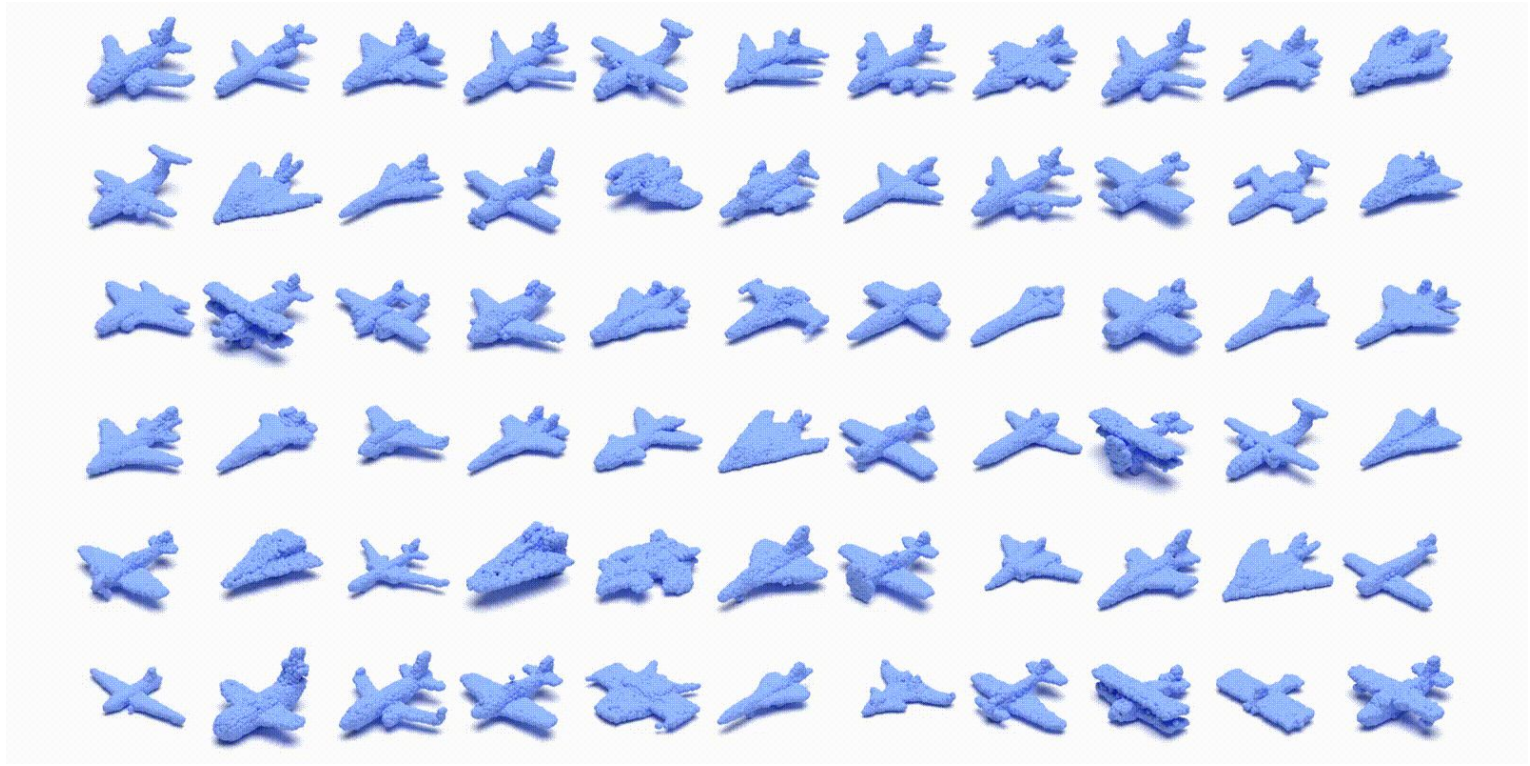


Differentiable Visual Computing for Generative AI

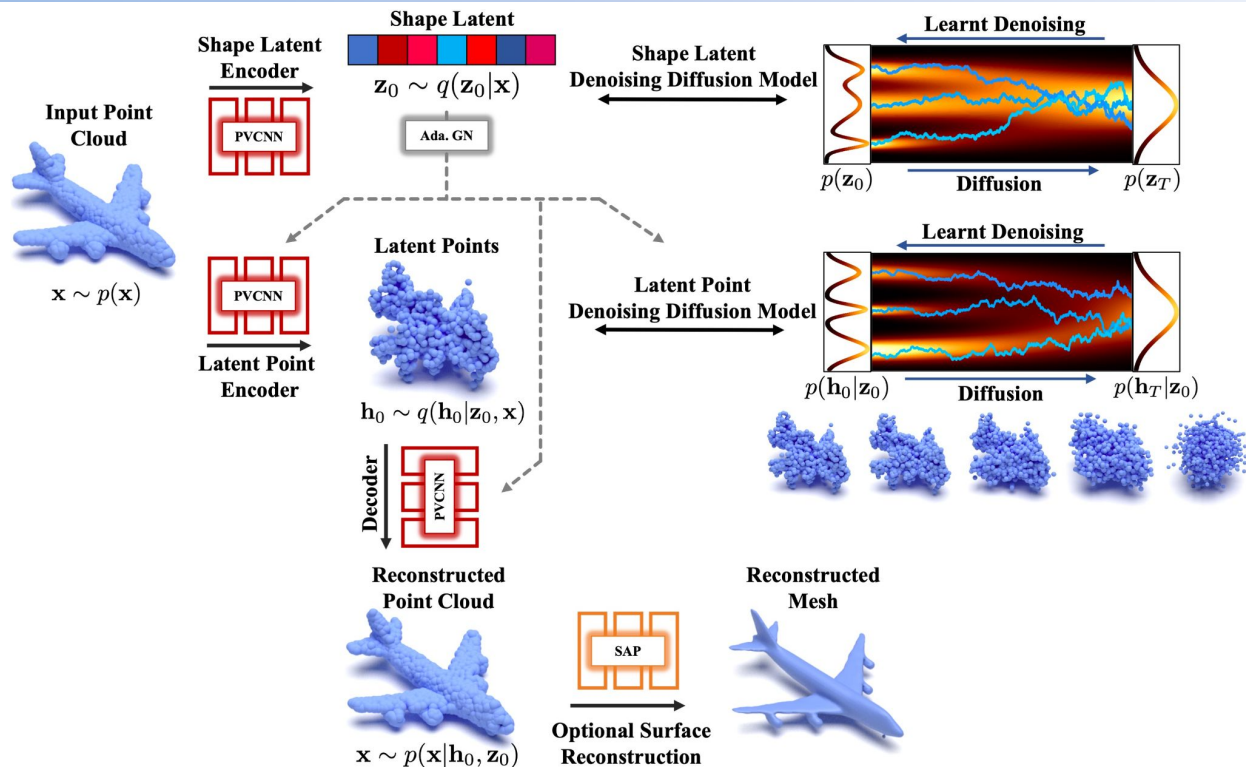
Training



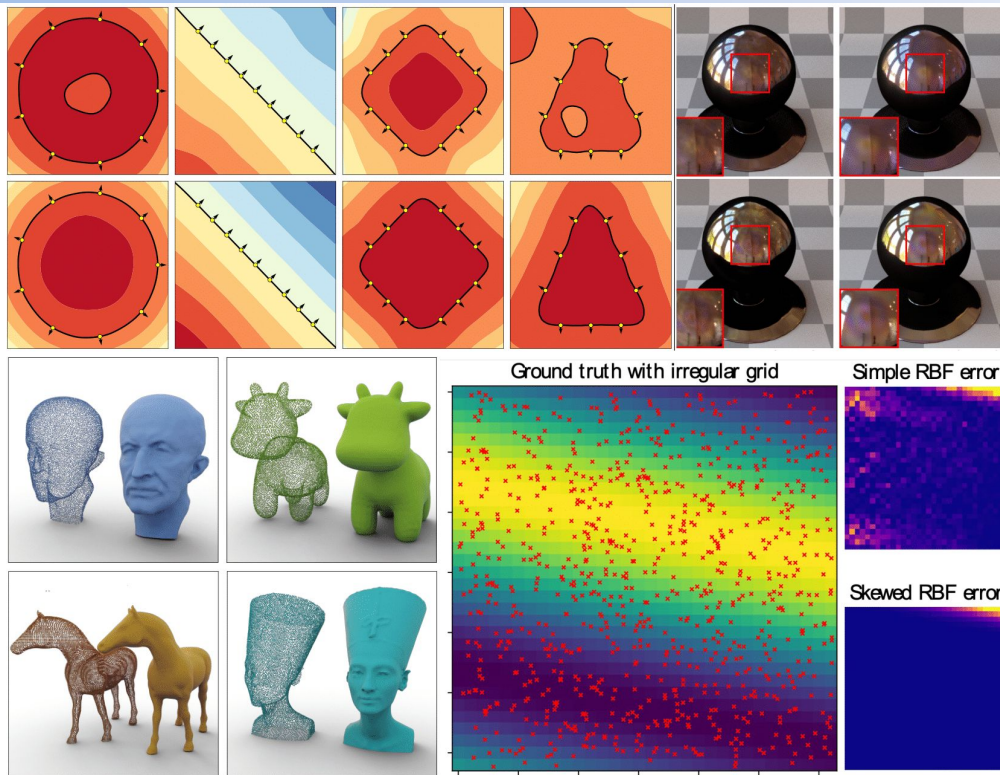
Differentiable Visual Computing for Generative AI



Differentiable Visual Computing for Generative AI



Constrained Neural Fields for Differentiable Visual Computing



Summary

- Differentiable visual computing for inverse problems
- Differentiable visual computing for machine learning
- Basics concepts, applications, research topics