

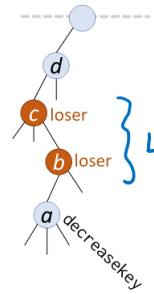
REVIEW

Amortized analysis

```

32 def decreasekey(v, k'):
33     let n be the node where this value is stored
34     n.key = k'
35     if n violates the heap condition:
36         repeat:
37             p = n.parent
38             remove n from p.children
39             insert n into the list of roots, updating minroot if necessary
40             n.loser = False
41             n = p
42         until p.loser == False
43         if p is not a root:
44             p.loser = True

```



Case I: no heap violation. $c = O(1)$ $\Delta\Phi = 0$ $c + \Delta\Phi = O(1)$.

Case II: heap violation.

1. move a to root list. $c = O(1)$ $\Delta\Phi = 1$ $c + \Delta\Phi = O(1)$
 or $\Delta\Phi = -1$ if a was loser.

2. move up L losers $c = O(L)$ $\Delta\Phi = +L - 2L = -L$. $c + \Delta\Phi = O(1)$

3. mark d as loser. $c = O(1)$ $\Delta\Phi = 2$ $c + \Delta\Phi = O(1)$
 or $\Delta\Phi = 0$ if d was a root

in each case,
 $O(1)$ am.
 cost.
 (total is $O(1)$)

Q1. What on earth does this maths mean? –

$$O(L) - L = O(1)$$

Q2. How do we come up with potential functions?

Only use $O(n) - n = O(1)$ when working with potential functions.

EXAMPLE: DYNAMIC ARRAY

A Python list is implemented as a dynamically-sized arrays. It starts with capacity 1, and doubles its capacity whenever it becomes full.

Suppose the cost of writing an item is $O(1)$, and the cost of doubling capacity from m to $2m$ (and copying across the existing items) is $O(m)$.

Show that the amortized cost of append is $O(1)$.

$$\begin{aligned} \Delta \Phi &= \Phi_{\text{after}} - \Phi_{\text{before}} \\ &= (1 - \frac{n}{2}) \epsilon \end{aligned}$$

$$\begin{aligned} \text{am.cost} &= \text{cost} + \Delta \Phi \\ &\leq k_1 n + k_2 + (1 - \frac{n}{2}) \epsilon \\ &= n (k_1 - \frac{\epsilon}{2}) + k_2 + \epsilon. \end{aligned}$$

let's set $\epsilon = 2k_1$. Then

$$\text{am.cost} \leq k_2 + 2k_1 = O(1).$$

$\Phi = \# \text{ items added since last doubling. } \times \epsilon$
 When working with Φ , there's always an arbitrary exch. rate.



"cost = $O(n) + O(1)$ "

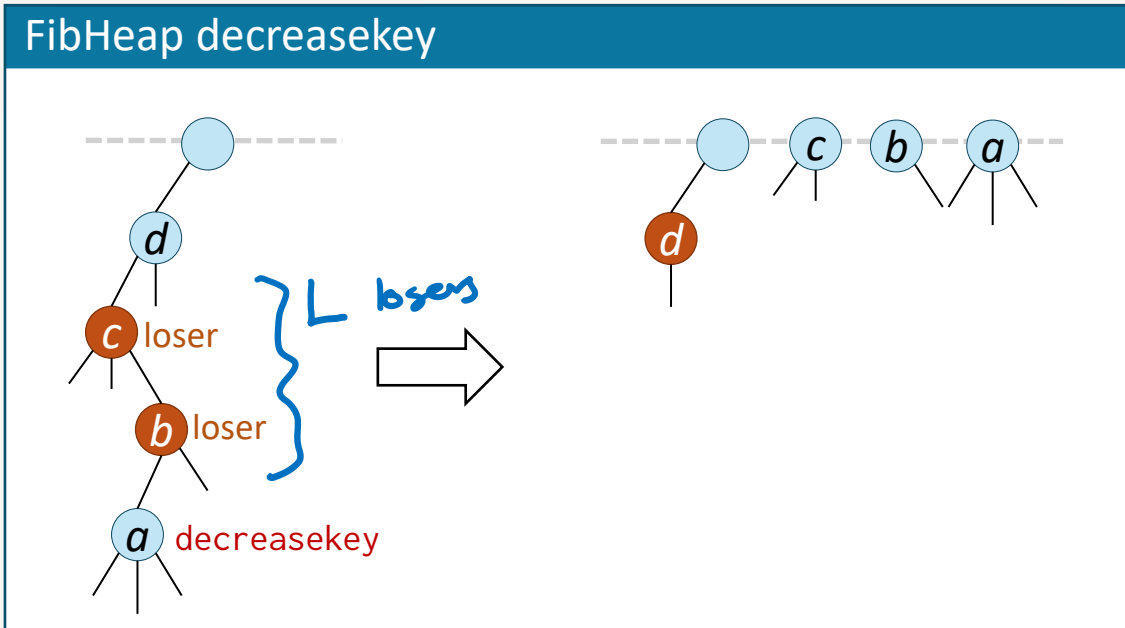
really means: $\text{cost} = c_{\text{double}} + c_{\text{app}}$.

$$\left. \begin{aligned} c_{\text{double}} &\leq k_1 n \\ c_{\text{app}} &\leq k_2 \end{aligned} \right\} \text{for } n \text{ suff. long.}$$

$$\begin{array}{c} \text{const. } \times \\ \downarrow \\ O(n) - n \\ \hline 1 \end{array}$$

$\leq kn$. To make them cancel, set const. = k .

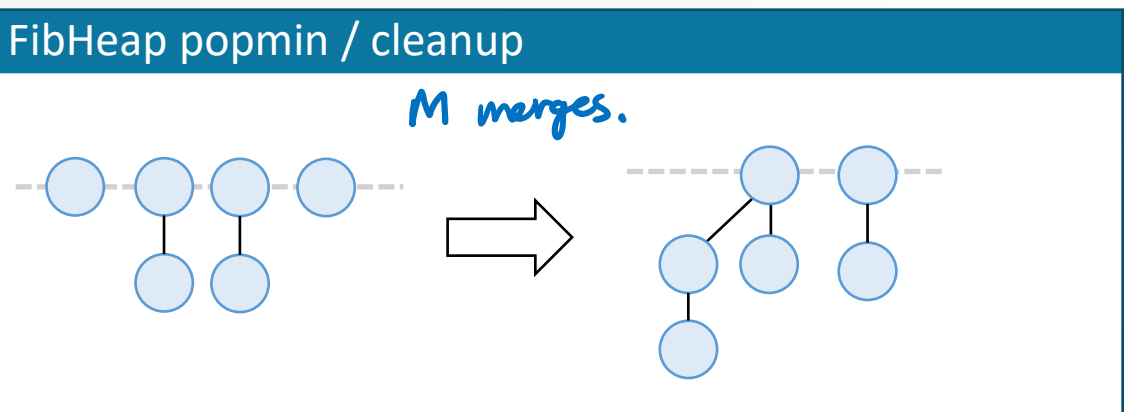
We should design our potential function to pay for "unbounded" costs.



true cost is $O(L)$
 Can we make decreasekey be $O(1)$?
 We'd need $\Delta \Phi = -L$.

IDEA: put credit on each loser, and release the credit when loser is moved to root.

So: $\Phi = \text{const} \times \# \text{losers}$.



true cost is $O(M + \log N)$ $N = \# \text{ items in heap}$
 Can we make popmin be $O(\log N)$?
 Can we get $\Delta \Phi = -M$?

THINK: put credit on each tree/root.
 Release the credit when the tree is made a child.

So: $\Phi = \text{const} \times \# \text{trees}$.

So: $\Phi = \boxed{\text{const}_1} \times \# \text{trees} + \boxed{\text{const}_2} \times \# \text{losers}$.

Finally: look meticulously at all the operations to see if there's a tradeoff between the two constraints,