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may not after out - V[Q]

All my logic SEEMS right! I'll set a breakpoint where it's about to go wrong, and step through. File Edit Selection View Go Run Terminal Help × resalloc.py private > res-alloc > test > 🕏 resalloc.py > 🛇 f def max weight alloc(requests): 1 2 print(requests) first start = min(r.start for r in requests) 3 last end = max(r.end for r in requests) 4 _, list_of_labels = f(first_start, last_end, requests) 5 return list of labels Bug: this cache isoit cleaned. The rode ends up re-using cached values from $memo = \{\}$ 10 11 previous problem instances. def f(i, j, requests): 12 13 if (i, j) in memo: 14 return memo[(i, j)] if i == j: 15 16 return 0, [] X = [r for r in requests if r.start >= i and r.end <= j] 17 if not X: 18 19 return 0, [] 20 max_val = 0 21 max req = X[0]22 max_req_before_out = X[0] 23 max reg =ftpp out - Y[A] 33 max_req_before_out = X[0] 23

Assertion (line 9). Just after a vertex v is popped, v.distance = distance(s to v)

CLAIM: This assertion never fails.

PROOF: Suppose it does fail. Consider the instant T at which it first fails, and let v be the vertex for which it fails.

By assumption, our assertion succeeded at every point prior to T. We can use this to reason about the events leading up to the failure at T.

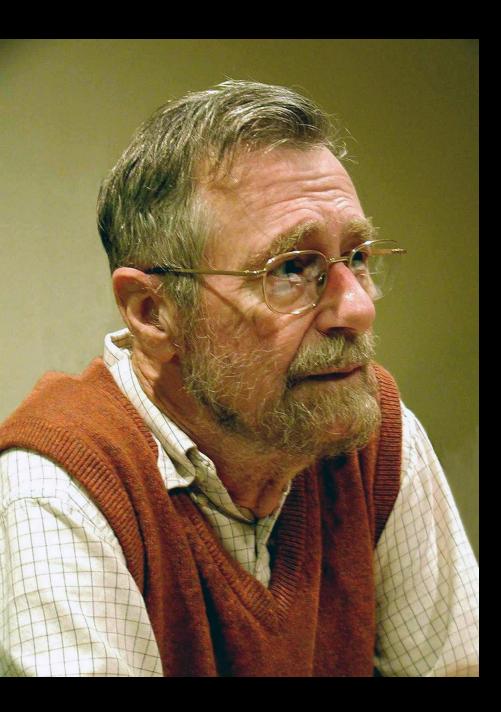
We obtain a contradiction. Therefore the supposition is false, i.e. the claim is true.

I call this the "breakpoint" proof strategy.

It's a proof by induction on program execution ...

- 1. Decide on a property we want to be true at all times
- 2. Assume it's true up to time T 1
- 3. Show that it must therefore be true at time T

SECTION 5.5 Algorithms and proofs



Programming is one of the most difficult branches of applied mathematics; the poorer mathematicians had better remain pure mathematicians.

Edsger Dijkstra, How do we tell truths that might hurt?

How to learn a proof

PASSIVE LEARNING	ACTIVE LEARNING	REFLECTIVE LEARNING	
 read it / watch it 	 copy it out 	 refactor it to be more elegant 	
	hide part of the proof,		
	and try to fill it in	see if it still works	
	 identify the "beats" of the argument 	when we tweak the problem statement	

Problem statement. Given a directed graph in which each edge is labelled with a cost ≥ 0 , and a start vertex *s*, compute the distance from *s* to every other vertex.

CLAIM. The assertion on line 9 never fails.

PROOF. By induction on program execution. Suppose it first fails at some vertex v. Then,

```
distance(s to v)
```

```
< v. distance from our induction supposition &
   \leq u_i. distance by the nature of the priority queue \blacktriangleleft
     \leq u_{i-1}.distance + cost(u_{i-1} \rightarrow u_i) edge relaxation by u_i^{1} def dijkstra(g, s):
                                                                                   for v in g.vertices:
      = \text{distance}(s \text{ to } u_{i-1}) + \text{cost}(u_{i-1} \rightarrow u_i) \quad \text{induction} \\ \text{hypothesis}
                                                                                       v.distance = \infty
                                                                                   s.distance = 0
                                                                                   toexplore = PriorityQueue([s],
        \leq distance(s to v)
                                                                                                          sortkey = \lambda v: v.distance)
                                                                                   while not toexplore.is_empty():
Every "beat" of the proof relies
on some crucial part of code, or
                                                                                       v = toexplore.popmin()
                                                                                        # Assert: v.distance is distance(s to v)
                                                                          10
                                                                                        # Assert: v is never put back into toexplore
   an assumption.
                                                                          11
                                                                                       for (w,edgecost) in v.neighbours:
                                                                          12
                                                                                            dist_w = v.distance + edgecost
                                                                          13
                                                                                            if dist_w < w.distance:</pre>
(EXERCISE. where is the assumption "cost = 0"
                                                                          14
                                                                                                 w.distance = dist_w
 used in this proof?)
                                                                          15
                                                                                                 if w in toexplore:
                                                                          16
                                                                                                      toexplore.decreasekey(w)
                                                                          17
                                                                                                 else:
                                                                          18
                                                                                                      toexplore.push(w)
```

Example sheet 4 Graphs and path finding Algorithms—DJW*_2022/2023

Question 6. Modify $bfs_path(g, s, t)$ to find all shortest paths from s to t. [There is a <u>tester</u>, linked to on the course website, for you to check your code.]

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Orrection	+ New chat		ChatGPT		n linked to an the
Question 6. <i>N website, for you</i>			·		r, linked to on the course
	D Maximizing UK's Prosperity Po	-兴- Examples	4 Capabilities	<u>^</u> Limitations	
	D Jack and Finnegan	"Explain quantum computing in simple	Remembers what user said earlier in the	May occasionally generate incorrect	
 Light Modern Dinner BFS Shortest Path Alg 	Story Of Mysterious Supernatu	terms" →	conversation	information	
	Light Modern Dinner Party Me	"Got any creative ideas for a 10 year	Allows user to provide follow-up corrections	May occasionally produce harmful	
	BFS Shortest Path Algorithm	old's birthday?" →	Trained to decline I make an inappropriate equest in requests	instructions or biased content	
		"How do I make an HTTP request in Javascript?" →		Limited knowledge of world and events after	
	回 Clear conversations			2021	
	▲ Upgrade to Plus NEW	Give psoudor	code for an algor	ithm that	
	🕒 Dark mode	Give pseudocode for an algorithm that finds all shortest paths between a given pair			
	🖸 Updates & FAQ	of nodes, on a directed graph.			
	[→ Log out				

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Here is the pseudocode for finding all shortest paths between a given pair of nodes using Breadth-First Search (BFS) algorithm:

の分

Copy code SCSS BFS_shortest_paths(graph, start, end): queue = [] paths = [] visited = set() queue.append((start, [start])) visited.add(start) while queue: node, path = queue.pop(0) if node == end: paths.append(path) for neighbor in graph[node]: if neighbor not in visited: queue.append((neighbor, path + [neighbor])) visited.add(neighbor)

return paths

Note: The `graph` variable is a dictionary where each key is a node and its values are a list of neighbors of that node. The `start` and `end` variables are the nodes between which the shortest paths are to be found.

DW

This code is meant to find all shortest paths between a pair of nodes in a graph. However, I'm not sure it's correct. Is there a problem with this code?



The problem with this code is that it does not necessarily find all shortest paths between the given pair of nodes in the graph.

The code uses Breadth-First Search (BFS) to explore the graph and finds the shortest path from the start node to the end node. However, it only adds the first path that it finds to the **`paths`** list, and does not continue searching for other shortest paths.

To find all shortest paths between the given pair of nodes, the code needs to be modified to continue searching for other paths after finding the first shortest path. One way to do this is to use a **`visited`** set to keep track of the visited nodes and add all paths with the same length as the shortest path found so far to the **`paths`** list. DW

This code is meant to find all shortest paths between a pair of nodes in a graph. However, I'm not sure it's correct. Is there a problem with this code?

> I am **∃loise**. The code is incorrect: there **exists** an input for which the set $A = \{\text{paths returned}\}\$ is not equal to the set $B = \{\text{shortest paths}\}\$

I am \forall belard. The code is correct: for all inputs, A = B.

How do we prove this sore of recult? Typically by proving $A \leq B$ and $B \leq A$. I'm expecting these as the "beats" of the proof.



х

Algorithms challenge: chatgpt-bfs Ask ChatGPT to prove a graph algorithm correct

Find prompts that instruct <u>ChatGPT</u> to produce a valid algorithm for solving <u>tick bfs-all</u>.

Then find prompts that instruct ChatGPT to give a valid proof that its algorithm is correct.

Submit a text document (.txt, .rtf, .docx, .odt) containing both sides of your dialogue, including the finished algorithm, on Moodle.

You should run the algorithm through the tester for bfs-all. You may make syntactical tweaks if necessary to turn the code into valid Python. If you can't get it to produce a valid algorithm, you may use your own algorithm instead.

Types of answer to a question

Right

Wrong

Not even wrong

Wolfgang Pauli (1900–1958)

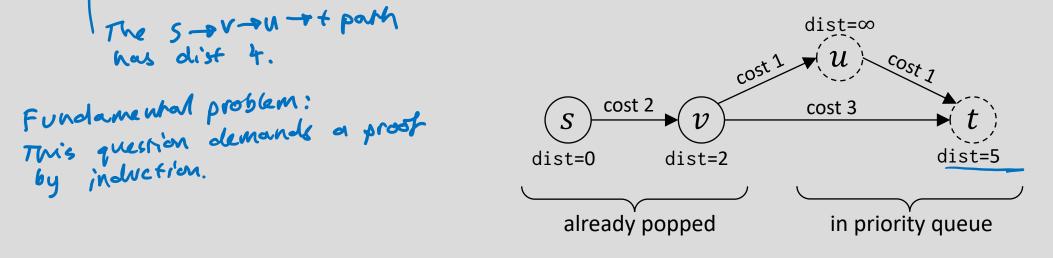
"Das ist nicht nur nicht richtig; es ist nicht einmal falsch"



Exam question. Let dijkstra_path(g,s,t) be an implementation of Dijkstra's shortest path algorithm that returns the shortest path from vertex s to vertex t in a graph g. Prove that the implementation can safely terminate when it first encounters vertex t.

PROPOSED ANSWER.

At the moment when the vertex t is popped from the priority queue, it computed has to be the vertex in the priority queue with the least distance from s. This means that any other vertex in the priority queue has distance \geq computed that for t. Since all edge weights in the graph are \geq 0, any path from s to t via anything still in the priority queue will have distance \geq that of the distance from s to t when it is popped, thus the distance to t is correct when t is popped.



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v. distance = distance (s to v)

mathe mostice

compute

"This algorithm is correct."

When we evaluate a claim, our answer is either \forall or \exists

- ∀ inputs, the algorithm's output is correct
- ∃ input for which the algorithm's output is incorrect

"This proof is correct."

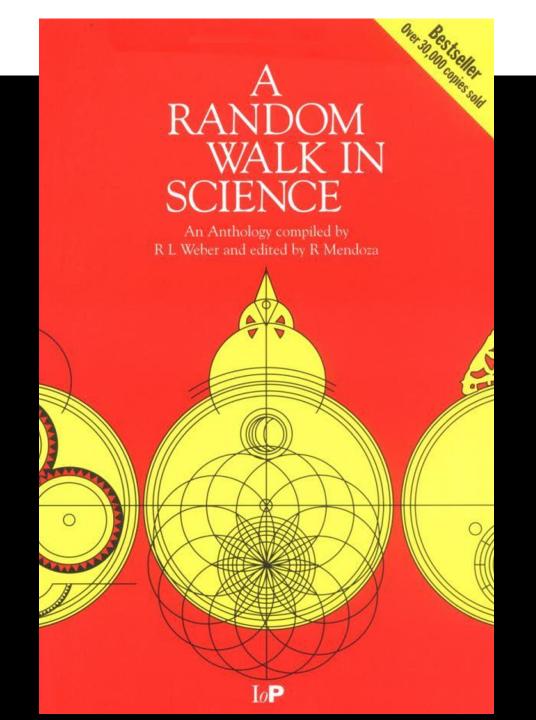
When the conclusion is true and we're evaluating a *proof*, our answer is again either \forall or \exists

- ∀ steps of the proof, ∀ cases that satisfy the step's premise, the step's conclusion is correct
- ∃ a step of the proof, ∃ a case satisfying the step's premise, for which its conclusion is false



Proof strategies

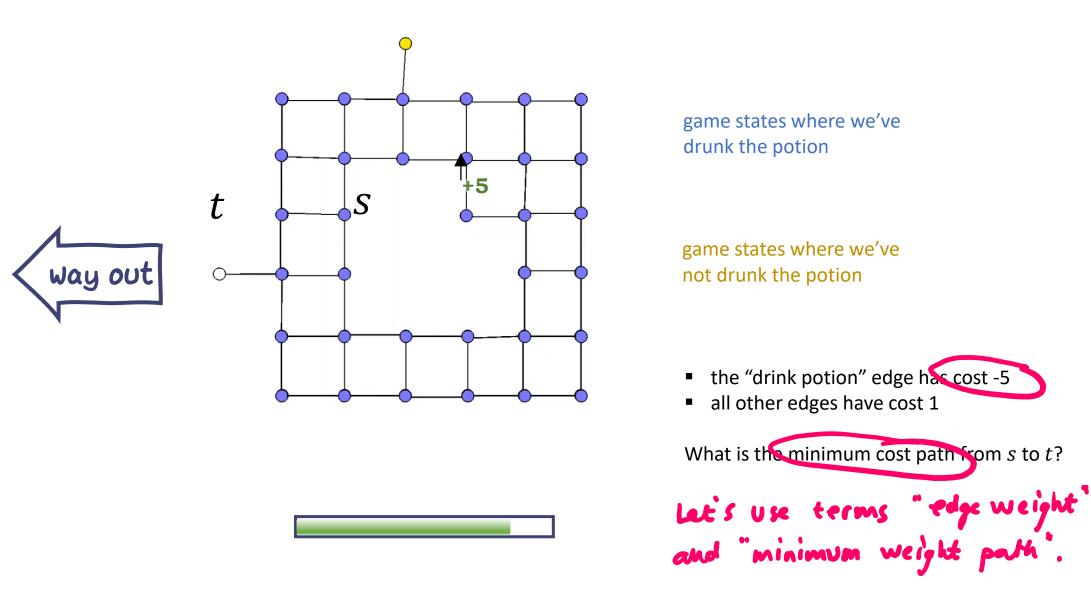
- Breakpoint strategy (a type of proof by induction)
- Reductio ad absurdum (proof by contradiction)
- Reductio ad nauseam
- Proof by assignment
- Proof by sleight of timetable



SECTION 5.6 Graphs with negative edge weights

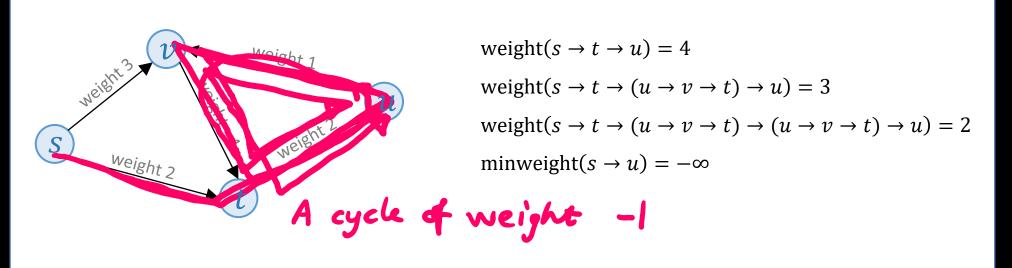
Goal: reach the way out before your health runs out.

You can move one step per tick, and your health runs out one unit per tick. There is a health potion — but is it worth the detour?



What's the issue with negative edge weights?





On this graph, Dijkstra's algorithm will get stuck in an infinite loop.

Clearly, in graphs with negative edge weights, the proof of correctness of Dijkstra's algorithm is invalid. What goes wrong?

Problem statement. Given a directed graph in which each edge is labelled with a cost ≥ 0 , and a start vertex *s*, compute the distance from *s* to every other vertex.

CLAIM. The assertion on line 9 never fails.

PROOF. By induction on program execution. Suppose it first fails at some vertex v. Then,

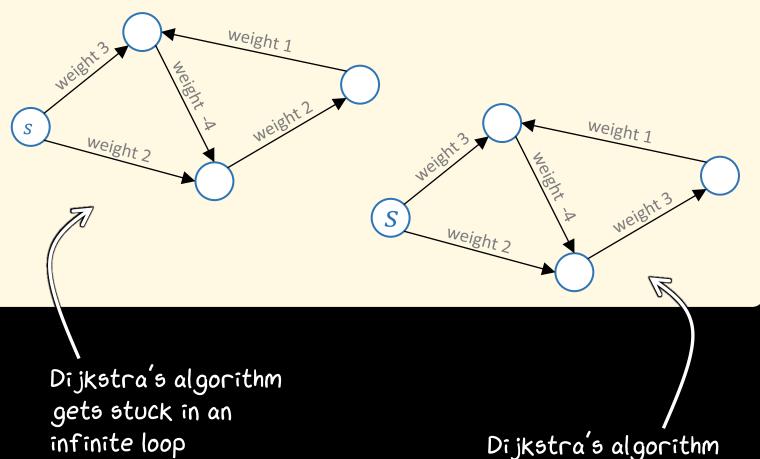
distance(s to v)

< v.distance</p>
by supposition (point of our proof by induction)
< u_i .distance
by the nature of Priority Queue
< u_{i-1} .distance + $cost(u_{i-1} \rightarrow u_i)$ by Edge Relaxation logic
= distance(s to u_{i-1}) + $cost(u_{i-1} \rightarrow u_i)$ by induction hyporthesis
< distance(s to v)</p>
since all edge costs are zo.

Proof strangy: check if your proof does indeed up all your assumptions.

EXERCISE (ex4 q13)

Run Dijkstra's algorithm by hand on these two graphs. What happens?



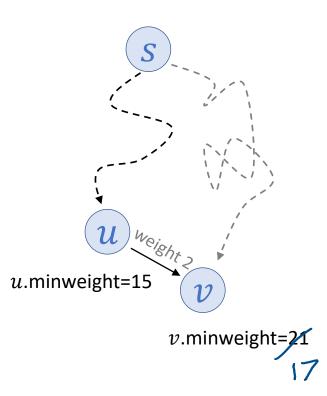
terminates, with the

correct distances

- Could we add a check to Dijkstra's algorithm, so that we can run it safely on any graph?
- For graphs where it terminates, is it always correct?
- If so, is it a good algorithm, or are there better algorithms?

SECTION 5.6 Beliman-Ford

How can we find minimum-cost paths in graphs where some edge costs may be negative?



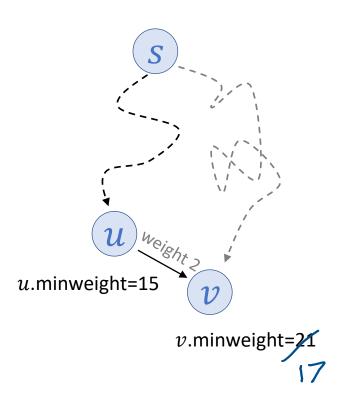
Edge relaxation

We're looking for minimum-weight paths from *s*

For each vertex *w*, let's store the minimum weight that we've found so far. Call it *w*.minweight.

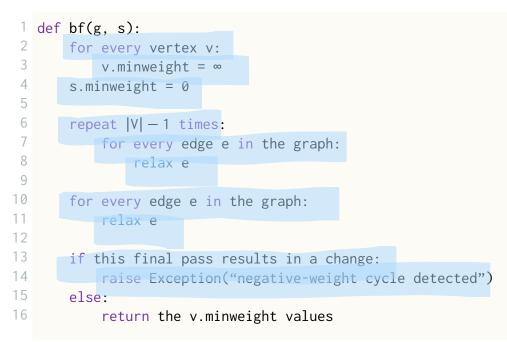
If there's an edge $u \rightarrow v$, we may be able to improve v.minweight:

if $u.minweight + weight(u \rightarrow v) < v.minweight:$ set $v.minweight = u.minweight + weight(u \rightarrow v)$



Bellman-Ford algorithm

Just keep on relaxing all the edges in the graph, over and over again! (It only takes *V* rounds.)





Theorem

Given a directed graph g where each edge is labelled with a weight, and given a start vertex s,

- if g has no -ve weight cycles reachable from s, this algorithm finds the true minimum weight from s to every other vertex
- otherwise, it throws an exception