For advanced data structures like a Priority Queue

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- This might not be as bad as the per-operation worst cases suggest
- Amortized costs are a handy way to reason about aggregate costs

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- We should care about the aggregate cost of a sequence of operations
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page 55 I've designed a data structure that supports push at amortized cost O(1) and popmin at amortized cost *Ex. sheet 6 q.6 asks you to* $O(\log N)$, if the number of items think through why this is never exceeds N. a sensible restriction For any sequence of $m_1 \times \text{push}$ and $M_2 \times \text{popmin}$, applied to an initially empty data structure, aggregate aggregate \leq amortized $\leq m_1 O(1) + m_2 O(\log N) = O(m_1 + m_2 \log N)$ true cost cost

SECTION 7.4 Potential functions

or, how on earth do we come up with useful amortized costs?

class MinList<T>:

def append(T value):

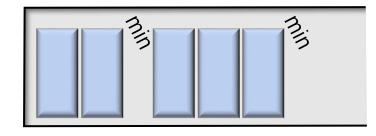
append a new value

def T min():

caches the result, so we

only need to iterate over

newly-appended items



append	append	min	append	append	append	min	
C _A	C _A	$c_M + 2c_I$	CA	C _A	C _A	$c_M + 3c_I$	aggregate true cost

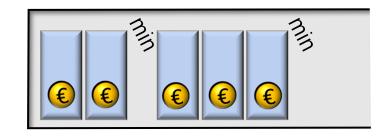
- Suppose we can store 'credit' in the data structure, and operations can either store or release credit
- ✤ Let the 'accounting' cost of an operation be:
- $\begin{pmatrix} \text{accounting} \\ \text{cost} \end{pmatrix} = \begin{pmatrix} \text{true} \\ \text{cost} \end{pmatrix} + \begin{pmatrix} \text{credit} \\ \text{it stores} \end{pmatrix} \begin{pmatrix} \text{credit} \\ \text{it releases} \end{pmatrix}$
- Let's 'pay ahead' for the potentially-costly operations

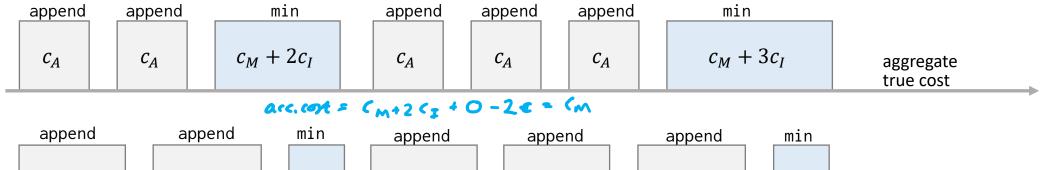
class MinList<T>:

```
def append(T value):
# append a new value
```

def T min():

- # caches the result, so we
- # only need to iterate over
- # newly-appended items





$c_A + \epsilon$ $c_A + \epsilon$ c_M $c_A + \epsilon$ $c_A + \epsilon$ $c_A + \epsilon$ $c_A + \epsilon$ aggregate accounting cost

Store l= G

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Suppose we can store 'credit' in the data structure, and operations can either store or release credit = $\left(\frac{\text{true}}{\text{credit}} \right) + \left(\frac{\text{credit}}{\text{credit}} \right)$ ⟨accounting⟩ credit Let the 'accounting' cost of an operation be: /it stores ∖it releases cost **\cost**ノ Let's 'pay ahead' for the potentially-costly operations page 57 class MinList<T>: def append(T value): # append a new value def T min(): These are valid amortized costs # caches the result, so we i.e. for any sequence of operations on an # only need to iterate over # newly-appended items initially-empty data structure aggregate aggregate true < amortized min append append append cost cost $c_{M} + 2c_{I}$ C_A C_A C_A C_A $C_M + 3C_I$ aggregate true cost append min append append min append append $c_A + \in$ $c_A + \in$ $c_A + \in$ $c_A + \in$ C_M $C_A + \in$ C_M aggregate accounting cost

Let Ω be the set of all states our data structure might be in. page 57 page 61 A function $\Phi: \Omega \to \mathbb{R}$ is called a **potential function** if · Jank balance $\Phi(\mathcal{S}) \geq 0$ for all $\mathcal{S} \in \Omega$ = total amount of credit shored in the data stucture. $---- \Phi(empty) = 0$ stare before stare for For an operation $S_{ante} \rightarrow S_{post}$ with true cost *c*, define the **accounting cost** to be $c' = c + \Phi(S_{\text{post}}) - \Phi(S_{\text{ante}})$ THE 'POTENTIAL' THEOREM: These are valid amortized costs. PROOF: Consider an arbitrary sequence of operations, starting from empty: $\mathcal{S}_0 \xrightarrow{c_1} \mathcal{S}_1 \xrightarrow{c_2} \mathcal{S}_2 \to \cdots \xrightarrow{c_m} \mathcal{S}_m$ aggregate accounting $= c'_1 + c'_2 + \dots + c'_m$ cost $= -\Phi(\mathcal{S}_{0}) + c_{1} + \Phi(\mathcal{S}_{1}) - \Phi(\mathcal{S}_{1}) + c_{2} + \Phi(\mathcal{S}_{2}) \cdots - \Phi(\mathcal{S}_{m-1}) + c_{m} + \Phi(\mathcal{S}_{m})$ $= -\Phi(\mathcal{S}_{0}) + c_{1} + \cdots + c_{m} + \Phi(\mathcal{S}_{m})$ $= -\Phi(\mathcal{S}_{0}) + c_{1} + \cdots + c_{m} + \Phi(\mathcal{S}_{m})$ aggregate true cost

Example

Consider a dynamically-sized array to which we append items. It starts with capacity 1, and doubles its capacity whenever it becomes full.

Suppose the cost of writing an item is 1, and the cost of doubling capacity from m to 2m (and copying across the existing items) is κm .

Show that the amortized cost of append is O(1).

xzk	

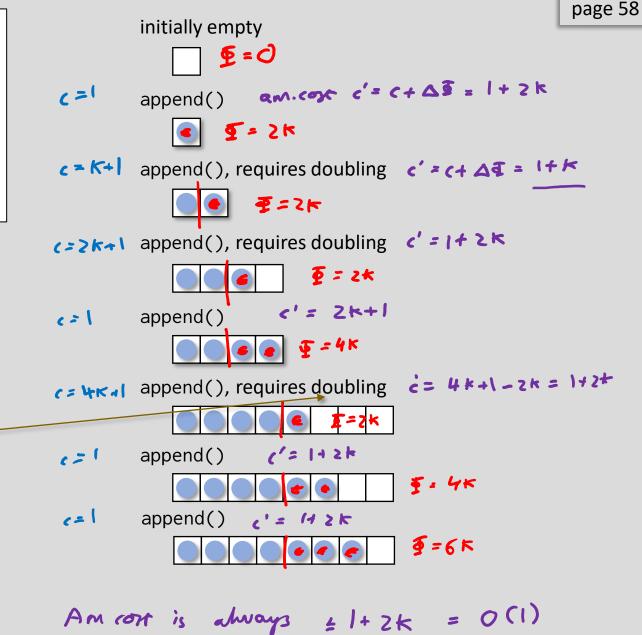
We want the coins that

we've stored so far (2€)

to pay for the doubling

(cost 4κ). So we want

1€=2*κ*.



Example (sloppy style)

Consider a dynamically-sized array to which we append items. It starts with capacity 1, and doubles its capacity whenever it becomes full.

Suppose the cost of writing an item is O(1), and the cost of doubling capacity from m to 2m (and copying across the existing items) is O(m).

Show that the amortized cost of append is O(1).

class MinList<T>:

def append(T value):

append a new value

def T min():

- # return the smallest
- # (without removing it)

night Doth

QUESTION. What potential function might we use, to show that append and min both have amortized cost O(1)?

L = # item added since last min

₽ = L

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Stage O

- Use a linked list
- min iterates over the entire list

Stage 1

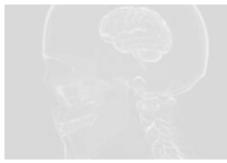
- Use a linked list
- min caches its result, so that next time it only needs to iterate over newer values

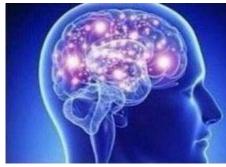
Stage 2

- Use a linked list
- Store the current minimum, and update it on every append

Stage 3

- min caches its result, the same as Stage 1
- ... but we argue it's just as good as Stage 2









For one-shot algorithms such as sorting:

After we show that our algorithm is $O(n \log n)$, it's good manners to also show that the worst case is $\Omega(n \log n)$.

> $\exists \kappa > 0$ such that, for all sufficiently large n, $\operatorname{cost}_n \le \kappa n \log n$

 $\exists \delta > 0$ and a sequence of example inputs with increasing *n* such that

 $\operatorname{cost}_n \geq \delta n \log n$

i.e. design a family of example inputs of increasing size n where $cost_n = \Omega(n \log n)$



and, if we can't find matching O- Ω bounds, then maybe our O bound isn't as good as it could be.

For advanced data structures:

After we find big-*O* upper bounds for amortized costs, it's good manners to show matching worst-case performance.

> $\exists \kappa > 0$ such that, for all sufficiently large N, and any operation-sequence s having $m_1 \times \text{push} + m_2 \times \text{popmin}$ such that #items is always $\leq N$, $\text{cost}_s \leq \kappa \ (m_1 + m_2 \log N)$

Design a family of operation-sequences s(N)having $m_1(N) \times \text{push} + m_2(N) \times \text{popmin}$ such that #items is always $\leq N$, and

 $\operatorname{cost}_{\mathcal{S}(N)} = \Omega(m_1(N) + m_2(N)\log N)$

I've designed a data structure that supports push at amortized cost O(1) and popmin at amortized cost O(log M), if the number of items never exceeds N.

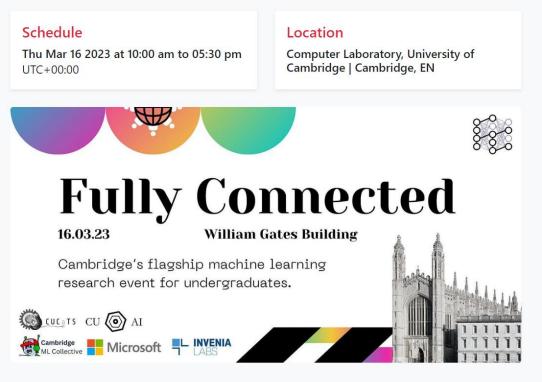
for any seq of m, push m2 popmin agg. am cost = m, O(1)+mzU(byN)

and, if we can't find matching $O-\Omega$ bounds, then maybe our amortized costs aren't as good as they could be. [See ex.sheet 6 q.7] $\checkmark \$ ← → C ▲ happeningnext.com/event/fully-connected-2023-eid4so2cab6f91

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