

III. Approximation Algorithms: Covering Problems

Thomas Sauerwald

Easter 2021



UNIVERSITY OF
CAMBRIDGE

Outline

Introduction

Vertex Cover

The Set-Covering Problem



Motivation

Many fundamental problems are **NP-complete**, yet they are too important to be abandoned.



Many fundamental problems are **NP-complete**, yet they are too important to be abandoned.

Examples: HAMILTON, 3-SAT, VERTEX-COVER, KNAPSACK,...

Many fundamental problems are **NP-complete**, yet they are too important to be abandoned.

Examples: HAMILTON, 3-SAT, VERTEX-COVER, KNAPSACK,...

Strategies to cope with NP-complete problems

1. If inputs (or solutions) are small, an algorithm with **exponential running time** may be satisfactory.
2. Isolate important **special cases** which can be solved in polynomial-time.
3. Develop algorithms which find **near-optimal** solutions in polynomial-time.



Many fundamental problems are **NP-complete**, yet they are too important to be abandoned.

Examples: HAMILTON, 3-SAT, VERTEX-COVER, KNAPSACK,...

Strategies to cope with NP-complete problems

1. If inputs (or solutions) are small, an algorithm with **exponential running time** may be satisfactory.
2. Isolate important **special cases** which can be solved in polynomial-time.
3. **Develop algorithms which find near-optimal solutions in polynomial-time.**



Many fundamental problems are **NP-complete**, yet they are too important to be abandoned.

Examples: HAMILTON, 3-SAT, VERTEX-COVER, KNAPSACK,...

Strategies to cope with NP-complete problems

1. If inputs (or solutions) are small, an algorithm with **exponential running time** may be satisfactory.
2. Isolate important **special cases** which can be solved in polynomial-time.
3. **Develop algorithms which find near-optimal solutions in polynomial-time.**

We will call these **approximation algorithms**.



Performance Ratios for Approximation Algorithms

Approximation Ratio

An algorithm for a problem has **approximation ratio** $\rho(n)$, if for any input of size n , the cost C of the returned solution and optimal cost C^* satisfy:

$$\max\left(\frac{C}{C^*}, \frac{C^*}{C}\right) \leq \rho(n).$$



Performance Ratios for Approximation Algorithms

Approximation Ratio

An algorithm for a problem has **approximation ratio** $\rho(n)$, if for any input of size n , the cost C of the returned solution and optimal cost C^* satisfy:

$$\max\left(\frac{C}{C^*}, \frac{C^*}{C}\right) \leq \rho(n).$$

This covers both **maximization** and **minimization** problems.



Performance Ratios for Approximation Algorithms

Approximation Ratio

An algorithm for a problem has **approximation ratio** $\rho(n)$, if for any input of size n , the cost C of the returned solution and optimal cost C^* satisfy:

$$\max\left(\frac{C}{C^*}, \frac{C^*}{C}\right) \leq \rho(n).$$

- **Maximization** problem: $\frac{C^*}{C} \geq 1$

This covers both **maximization** and **minimization** problems.



Performance Ratios for Approximation Algorithms

Approximation Ratio

An algorithm for a problem has **approximation ratio** $\rho(n)$, if for any input of size n , the cost C of the returned solution and optimal cost C^* satisfy:

$$\max\left(\frac{C}{C^*}, \frac{C^*}{C}\right) \leq \rho(n).$$

- **Maximization** problem: $\frac{C^*}{C} \geq 1$
- **Minimization** problem: $\frac{C}{C^*} \geq 1$

This covers both **maximization** and **minimization** problems.



Performance Ratios for Approximation Algorithms

Approximation Ratio

An algorithm for a problem has **approximation ratio** $\rho(n)$, if for any input of size n , the cost C of the returned solution and optimal cost C^* satisfy:

$$\max\left(\frac{C}{C^*}, \frac{C^*}{C}\right) \leq \rho(n).$$

- **Maximization** problem: $\frac{C^*}{C} \geq 1$
- **Minimization** problem: $\frac{C}{C^*} \geq 1$

This covers both **maximization** and **minimization** problems.

For many problems: **tradeoff** between **runtime** and **approximation ratio**.



Performance Ratios for Approximation Algorithms

Approximation Ratio

An algorithm for a problem has **approximation ratio** $\rho(n)$, if for any input of size n , the cost C of the returned solution and optimal cost C^* satisfy:

$$\max\left(\frac{C}{C^*}, \frac{C^*}{C}\right) \leq \rho(n).$$

- **Maximization** problem: $\frac{C^*}{C} \geq 1$
- **Minimization** problem: $\frac{C}{C^*} \geq 1$

This covers both **maximization** and **minimization** problems.

For many problems: **tradeoff** between **runtime** and **approximation ratio**.

Approximation Schemes



Performance Ratios for Approximation Algorithms

Approximation Ratio

An algorithm for a problem has **approximation ratio** $\rho(n)$, if for any input of size n , the cost C of the returned solution and optimal cost C^* satisfy:

$$\max\left(\frac{C}{C^*}, \frac{C^*}{C}\right) \leq \rho(n).$$

- **Maximization** problem: $\frac{C^*}{C} \geq 1$
- **Minimization** problem: $\frac{C}{C^*} \geq 1$

This covers both **maximization** and **minimization** problems.

For many problems: **tradeoff** between **runtime** and **approximation ratio**.

Approximation Schemes

An **approximation scheme** is an approximation algorithm, which given any input and $\epsilon > 0$, is a $(1 + \epsilon)$ -approximation algorithm.



Performance Ratios for Approximation Algorithms

Approximation Ratio

An algorithm for a problem has **approximation ratio** $\rho(n)$, if for any input of size n , the cost C of the returned solution and optimal cost C^* satisfy:

$$\max\left(\frac{C}{C^*}, \frac{C^*}{C}\right) \leq \rho(n).$$

- **Maximization** problem: $\frac{C^*}{C} \geq 1$
- **Minimization** problem: $\frac{C}{C^*} \geq 1$

This covers both **maximization** and **minimization** problems.

For many problems: **tradeoff** between **runtime** and **approximation ratio**.

Approximation Schemes

An **approximation scheme** is an approximation algorithm, which given any input and $\epsilon > 0$, is a $(1 + \epsilon)$ -approximation algorithm.

- It is a **polynomial-time approximation scheme** (PTAS) if for any fixed $\epsilon > 0$, the runtime is polynomial in n .



Performance Ratios for Approximation Algorithms

Approximation Ratio

An algorithm for a problem has **approximation ratio** $\rho(n)$, if for any input of size n , the cost C of the returned solution and optimal cost C^* satisfy:

$$\max\left(\frac{C}{C^*}, \frac{C^*}{C}\right) \leq \rho(n).$$

- **Maximization** problem: $\frac{C^*}{C} \geq 1$
- **Minimization** problem: $\frac{C}{C^*} \geq 1$

This covers both **maximization** and **minimization** problems.

For many problems: **tradeoff** between **runtime** and **approximation ratio**.

Approximation Schemes

An **approximation scheme** is an approximation algorithm, which given any input and $\epsilon > 0$, is a $(1 + \epsilon)$ -approximation algorithm.

- It is a **polynomial-time approximation scheme** (PTAS) if for any fixed $\epsilon > 0$, the runtime is polynomial in n . For example, $O(n^{2/\epsilon})$.



Performance Ratios for Approximation Algorithms

Approximation Ratio

An algorithm for a problem has **approximation ratio** $\rho(n)$, if for any input of size n , the cost C of the returned solution and optimal cost C^* satisfy:

$$\max\left(\frac{C}{C^*}, \frac{C^*}{C}\right) \leq \rho(n).$$

- **Maximization** problem: $\frac{C^*}{C} \geq 1$
- **Minimization** problem: $\frac{C}{C^*} \geq 1$

This covers both **maximization** and **minimization** problems.

For many problems: **tradeoff** between **runtime** and **approximation ratio**.

Approximation Schemes

An **approximation scheme** is an approximation algorithm, which given any input and $\epsilon > 0$, is a $(1 + \epsilon)$ -approximation algorithm.

- It is a **polynomial-time approximation scheme** (PTAS) if for any fixed $\epsilon > 0$, the runtime is polynomial in n . (For example, $O(n^{2/\epsilon})$.)
- It is a **fully polynomial-time approximation scheme** (FPTAS) if the runtime is polynomial in both $1/\epsilon$ and n .



Performance Ratios for Approximation Algorithms

Approximation Ratio

An algorithm for a problem has **approximation ratio** $\rho(n)$, if for any input of size n , the cost C of the returned solution and optimal cost C^* satisfy:

$$\max\left(\frac{C}{C^*}, \frac{C^*}{C}\right) \leq \rho(n).$$

- **Maximization** problem: $\frac{C^*}{C} \geq 1$
- **Minimization** problem: $\frac{C}{C^*} \geq 1$

This covers both **maximization** and **minimization** problems.

For many problems: **tradeoff** between **runtime** and **approximation ratio**.

Approximation Schemes

An **approximation scheme** is an approximation algorithm, which given any input and $\epsilon > 0$, is a $(1 + \epsilon)$ -approximation algorithm.

- It is a **polynomial-time approximation scheme (PTAS)** if for any fixed $\epsilon > 0$, the runtime is polynomial in n . (For example, $O(n^{2/\epsilon})$.)
- It is a **fully polynomial-time approximation scheme (FPTAS)** if the runtime is polynomial in both $1/\epsilon$ and n . (For example, $O((1/\epsilon)^2 \cdot n^3)$.)



Outline

Introduction

Vertex Cover

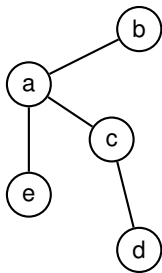
The Set-Covering Problem



The Vertex-Cover Problem

Vertex Cover Problem

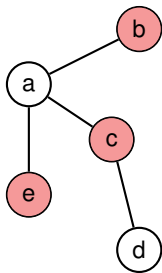
- **Given:** Undirected graph $G = (V, E)$
- **Goal:** Find a minimum-cardinality subset $V' \subseteq V$ such that if $(u, v) \in E(G)$, then $u \in V'$ or $v \in V'$.



The Vertex-Cover Problem

Vertex Cover Problem

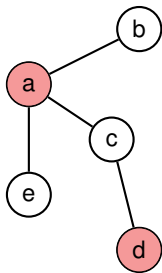
- **Given:** Undirected graph $G = (V, E)$
- **Goal:** Find a minimum-cardinality subset $V' \subseteq V$ such that if $(u, v) \in E(G)$, then $u \in V'$ or $v \in V'$.



The Vertex-Cover Problem

Vertex Cover Problem

- **Given:** Undirected graph $G = (V, E)$
- **Goal:** Find a minimum-cardinality subset $V' \subseteq V$ such that if $(u, v) \in E(G)$, then $u \in V'$ or $v \in V'$.

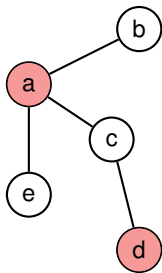


The Vertex-Cover Problem

We are covering edges by picking vertices!

Vertex Cover Problem

- **Given:** Undirected graph $G = (V, E)$
- **Goal:** Find a minimum-cardinality subset $V' \subseteq V$ such that if $(u, v) \in E(G)$, then $u \in V'$ or $v \in V'$.



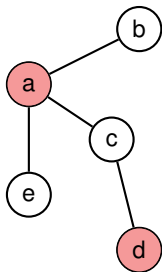
The Vertex-Cover Problem

We are covering **edges** by picking **vertices**!

Vertex Cover Problem

- **Given:** Undirected graph $G = (V, E)$
- **Goal:** Find a minimum-cardinality subset $V' \subseteq V$ such that if $(u, v) \in E(G)$, then $u \in V'$ or $v \in V'$.

This is an NP-hard problem.



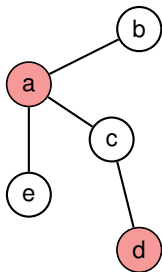
The Vertex-Cover Problem

We are covering **edges** by picking **vertices**!

Vertex Cover Problem

- **Given:** Undirected graph $G = (V, E)$
- **Goal:** Find a minimum-cardinality subset $V' \subseteq V$ such that if $(u, v) \in E(G)$, then $u \in V'$ or $v \in V'$.

This is an NP-hard problem.



Applications:



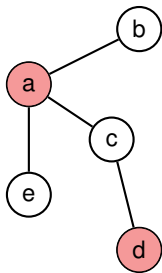
The Vertex-Cover Problem

We are covering **edges** by picking **vertices**!

Vertex Cover Problem

- **Given:** Undirected graph $G = (V, E)$
- **Goal:** Find a minimum-cardinality subset $V' \subseteq V$ such that if $(u, v) \in E(G)$, then $u \in V'$ or $v \in V'$.

This is an NP-hard problem.



Applications:

- Every **edge** forms a **task**, and every **vertex** represents a **person/machine** which can execute that task



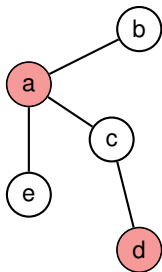
The Vertex-Cover Problem

We are covering **edges** by picking **vertices**!

Vertex Cover Problem

- **Given:** Undirected graph $G = (V, E)$
- **Goal:** Find a minimum-cardinality subset $V' \subseteq V$ such that if $(u, v) \in E(G)$, then $u \in V'$ or $v \in V'$.

This is an NP-hard problem.



Applications:

- Every **edge** forms a **task**, and every **vertex** represents a **person/machine** which can execute that task
- Perform all tasks with the **minimal amount of resources**



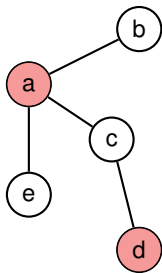
The Vertex-Cover Problem

We are covering **edges** by picking **vertices**!

Vertex Cover Problem

- **Given:** Undirected graph $G = (V, E)$
- **Goal:** Find a minimum-cardinality subset $V' \subseteq V$ such that if $(u, v) \in E(G)$, then $u \in V'$ or $v \in V'$.

This is an NP-hard problem.



Applications:

- Every **edge** forms a **task**, and every **vertex** represents a **person/machine** which can execute that task
- Perform all tasks with the **minimal amount of resources**
- **Extensions:** weighted vertices or hypergraphs (\rightsquigarrow Set-Covering Problem)





Exercise: Be creative and design your own algorithm for VERTEX-COVER!

An Approximation Algorithm based on Greedy

APPROX-VERTEX-COVER(G)

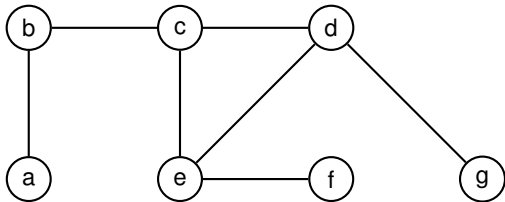
```
1  $C = \emptyset$ 
2  $E' = G.E$ 
3 while  $E' \neq \emptyset$ 
4     let  $(u, v)$  be an arbitrary edge of  $E'$ 
5      $C = C \cup \{u, v\}$ 
6     remove from  $E'$  every edge incident on either  $u$  or  $v$ 
7 return  $C$ 
```



An Approximation Algorithm based on Greedy

APPROX-VERTEX-COVER(G)

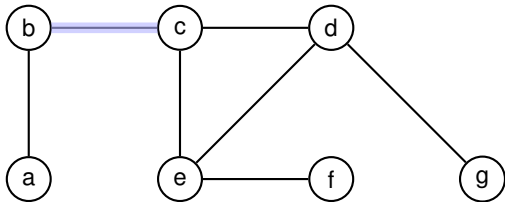
- 1 $C = \emptyset$
- 2 $E' = G.E$
- 3 **while** $E' \neq \emptyset$
- 4 let (u, v) be an arbitrary edge of E'
- 5 $C = C \cup \{u, v\}$
- 6 remove from E' every edge incident on either u or v
- 7 **return** C



An Approximation Algorithm based on Greedy

APPROX-VERTEX-COVER(G)

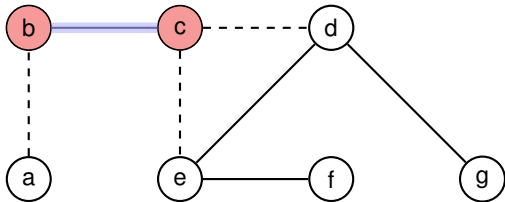
- 1 $C = \emptyset$
- 2 $E' = G.E$
- 3 **while** $E' \neq \emptyset$
- 4 let (u, v) be an arbitrary edge of E'
- 5 $C = C \cup \{u, v\}$
- 6 remove from E' every edge incident on either u or v
- 7 **return** C



An Approximation Algorithm based on Greedy

APPROX-VERTEX-COVER(G)

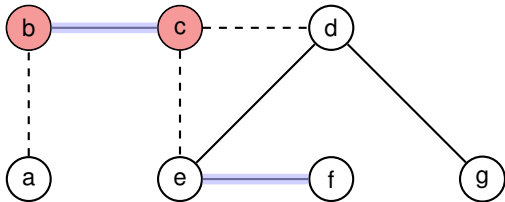
- 1 $C = \emptyset$
- 2 $E' = G.E$
- 3 **while** $E' \neq \emptyset$
- 4 let (u, v) be an arbitrary edge of E'
- 5 $C = C \cup \{u, v\}$
- 6 remove from E' every edge incident on either u or v
- 7 **return** C



An Approximation Algorithm based on Greedy

APPROX-VERTEX-COVER(G)

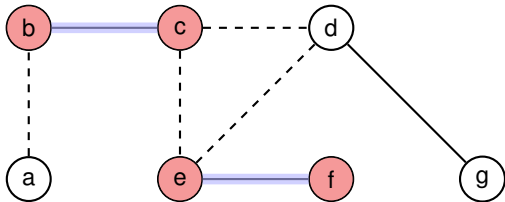
- 1 $C = \emptyset$
- 2 $E' = G.E$
- 3 **while** $E' \neq \emptyset$
- 4 let (u, v) be an arbitrary edge of E'
- 5 $C = C \cup \{u, v\}$
- 6 remove from E' every edge incident on either u or v
- 7 **return** C



An Approximation Algorithm based on Greedy

APPROX-VERTEX-COVER(G)

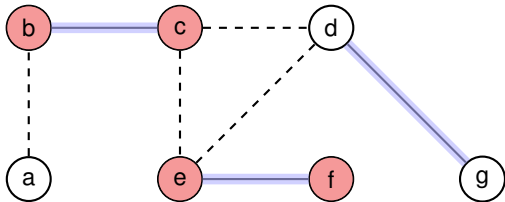
- 1 $C = \emptyset$
- 2 $E' = G.E$
- 3 **while** $E' \neq \emptyset$
- 4 let (u, v) be an arbitrary edge of E'
- 5 $C = C \cup \{u, v\}$
- 6 remove from E' every edge incident on either u or v
- 7 **return** C



An Approximation Algorithm based on Greedy

APPROX-VERTEX-COVER(G)

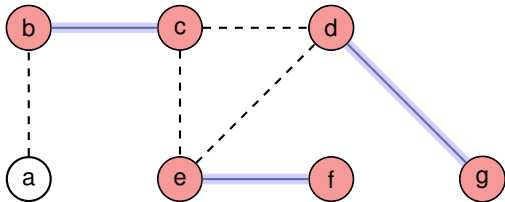
- 1 $C = \emptyset$
- 2 $E' = G.E$
- 3 **while** $E' \neq \emptyset$
- 4 let (u, v) be an arbitrary edge of E'
- 5 $C = C \cup \{u, v\}$
- 6 remove from E' every edge incident on either u or v
- 7 **return** C



An Approximation Algorithm based on Greedy

APPROX-VERTEX-COVER(G)

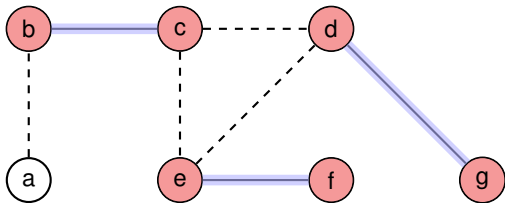
- 1 $C = \emptyset$
- 2 $E' = G.E$
- 3 **while** $E' \neq \emptyset$
- 4 let (u, v) be an arbitrary edge of E'
- 5 $C = C \cup \{u, v\}$
- 6 remove from E' every edge incident on either u or v
- 7 **return** C



An Approximation Algorithm based on Greedy

APPROX-VERTEX-COVER(G)

- 1 $C = \emptyset$
- 2 $E' = G.E$
- 3 **while** $E' \neq \emptyset$
- 4 let (u, v) be an arbitrary edge of E'
- 5 $C = C \cup \{u, v\}$
- 6 remove from E' every edge incident on either u or v
- 7 **return** C



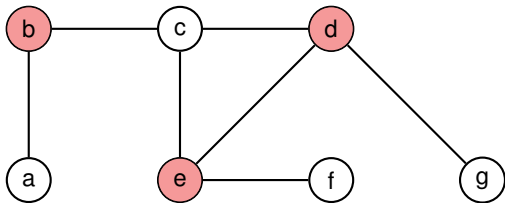
APPROX-VERTEX-COVER produces a set of size 6.



An Approximation Algorithm based on Greedy

APPROX-VERTEX-COVER(G)

- 1 $C = \emptyset$
- 2 $E' = G.E$
- 3 **while** $E' \neq \emptyset$
- 4 let (u, v) be an arbitrary edge of E'
- 5 $C = C \cup \{u, v\}$
- 6 remove from E' every edge incident on either u or v
- 7 **return** C



The optimal solution has size 3.



Analysis of Greedy for Vertex Cover

APPROX-VERTEX-COVER(G)

```
1  $C = \emptyset$ 
2  $E' = G.E$ 
3 while  $E' \neq \emptyset$ 
4     let  $(u, v)$  be an arbitrary edge of  $E'$ 
5      $C = C \cup \{u, v\}$ 
6     remove from  $E'$  every edge incident on either  $u$  or  $v$ 
7 return  $C$ 
```



Analysis of Greedy for Vertex Cover

APPROX-VERTEX-COVER(G)

```
1  $C = \emptyset$ 
2  $E' = G.E$ 
3 while  $E' \neq \emptyset$ 
4     let  $(u, v)$  be an arbitrary edge of  $E'$ 
5      $C = C \cup \{u, v\}$ 
6     remove from  $E'$  every edge incident on either  $u$  or  $v$ 
7 return  $C$ 
```

Theorem 35.1

APPROX-VERTEX-COVER is a poly-time 2-approximation algorithm.



Analysis of Greedy for Vertex Cover

APPROX-VERTEX-COVER(G)

```
1  $C = \emptyset$ 
2  $E' = G.E$ 
3 while  $E' \neq \emptyset$ 
4     let  $(u, v)$  be an arbitrary edge of  $E'$ 
5      $C = C \cup \{u, v\}$ 
6     remove from  $E'$  every edge incident on either  $u$  or  $v$ 
7 return  $C$ 
```

Theorem 35.1

APPROX-VERTEX-COVER is a poly-time 2-approximation algorithm.

Proof:



Analysis of Greedy for Vertex Cover

APPROX-VERTEX-COVER(G)

```
1  $C = \emptyset$ 
2  $E' = G.E$ 
3 while  $E' \neq \emptyset$ 
4     let  $(u, v)$  be an arbitrary edge of  $E'$ 
5      $C = C \cup \{u, v\}$ 
6     remove from  $E'$  every edge incident on either  $u$  or  $v$ 
7 return  $C$ 
```

Theorem 35.1

APPROX-VERTEX-COVER is a poly-time 2-approximation algorithm.

Proof:

- Running time is $O(V + E)$ (using adjacency lists to represent E')



Analysis of Greedy for Vertex Cover

APPROX-VERTEX-COVER(G)

```
1  $C = \emptyset$ 
2  $E' = G.E$ 
3 while  $E' \neq \emptyset$ 
4     let  $(u, v)$  be an arbitrary edge of  $E'$ 
5      $C = C \cup \{u, v\}$ 
6     remove from  $E'$  every edge incident on either  $u$  or  $v$ 
7 return  $C$ 
```

Theorem 35.1

APPROX-VERTEX-COVER is a poly-time 2-approximation algorithm.

Proof:

- Running time is $O(V + E)$ (using adjacency lists to represent E')
- Let $A \subseteq E$ denote the set of edges picked in line 4



Analysis of Greedy for Vertex Cover

APPROX-VERTEX-COVER(G)

```
1  $C = \emptyset$ 
2  $E' = G.E$ 
3 while  $E' \neq \emptyset$ 
4     let  $(u, v)$  be an arbitrary edge of  $E'$ 
5      $C = C \cup \{u, v\}$ 
6     remove from  $E'$  every edge incident on either  $u$  or  $v$ 
7 return  $C$ 
```

Theorem 35.1

APPROX-VERTEX-COVER is a poly-time 2-approximation algorithm.

Proof:

- Running time is $O(V + E)$ (using adjacency lists to represent E')
- Let $A \subseteq E$ denote the set of edges picked in line 4
- **Key Observation:** A is a set of vertex-disjoint edges, i.e., A is a matching



Analysis of Greedy for Vertex Cover

APPROX-VERTEX-COVER(G)

```
1  $C = \emptyset$ 
2  $E' = G.E$ 
3 while  $E' \neq \emptyset$ 
4     let  $(u, v)$  be an arbitrary edge of  $E'$ 
5      $C = C \cup \{u, v\}$ 
6     remove from  $E'$  every edge incident on either  $u$  or  $v$ 
7 return  $C$ 
```

Theorem 35.1

APPROX-VERTEX-COVER is a poly-time 2-approximation algorithm.

Proof:

- Running time is $O(V + E)$ (using adjacency lists to represent E')
 - Let $A \subseteq E$ denote the set of edges picked in line 4
 - **Key Observation:** A is a set of vertex-disjoint edges, i.e., A is a matching
- ⇒ Every optimal cover C^* must include at least one endpoint:



Analysis of Greedy for Vertex Cover

APPROX-VERTEX-COVER(G)

```
1  $C = \emptyset$ 
2  $E' = G.E$ 
3 while  $E' \neq \emptyset$ 
4     let  $(u, v)$  be an arbitrary edge of  $E'$ 
5      $C = C \cup \{u, v\}$ 
6     remove from  $E'$  every edge incident on either  $u$  or  $v$ 
7 return  $C$ 
```

Theorem 35.1

APPROX-VERTEX-COVER is a poly-time 2-approximation algorithm.

Proof:

- Running time is $O(V + E)$ (using adjacency lists to represent E')
 - Let $A \subseteq E$ denote the set of edges picked in line 4
 - **Key Observation:** A is a set of vertex-disjoint edges, i.e., A is a matching
- ⇒ Every optimal cover C^* must include at least one endpoint: $|C^*| \geq |A|$



Analysis of Greedy for Vertex Cover

APPROX-VERTEX-COVER(G)

```
1  $C = \emptyset$ 
2  $E' = G.E$ 
3 while  $E' \neq \emptyset$ 
4     let  $(u, v)$  be an arbitrary edge of  $E'$ 
5      $C = C \cup \{u, v\}$ 
6     remove from  $E'$  every edge incident on either  $u$  or  $v$ 
7 return  $C$ 
```

Theorem 35.1

APPROX-VERTEX-COVER is a poly-time 2-approximation algorithm.

Proof:

- Running time is $O(V + E)$ (using adjacency lists to represent E')
 - Let $A \subseteq E$ denote the set of edges picked in line 4
 - **Key Observation:** A is a set of vertex-disjoint edges, i.e., A is a matching
- ⇒ Every optimal cover C^* must include at least one endpoint: $|C^*| \geq |A|$
- Every edge in A contributes 2 vertices to $|C|$:



Analysis of Greedy for Vertex Cover

APPROX-VERTEX-COVER(G)

```
1  $C = \emptyset$ 
2  $E' = G.E$ 
3 while  $E' \neq \emptyset$ 
4     let  $(u, v)$  be an arbitrary edge of  $E'$ 
5      $C = C \cup \{u, v\}$ 
6     remove from  $E'$  every edge incident on either  $u$  or  $v$ 
7 return  $C$ 
```

Theorem 35.1

APPROX-VERTEX-COVER is a poly-time 2-approximation algorithm.

Proof:

- Running time is $O(V + E)$ (using adjacency lists to represent E')
 - Let $A \subseteq E$ denote the set of edges picked in line 4
 - **Key Observation:** A is a set of vertex-disjoint edges, i.e., A is a **matching**
- ⇒ Every optimal cover C^* must include at least one endpoint: $|C^*| \geq |A|$
- Every edge in A contributes 2 vertices to $|C|$: $|C| = 2|A|$



Analysis of Greedy for Vertex Cover

APPROX-VERTEX-COVER(G)

```
1  $C = \emptyset$ 
2  $E' = G.E$ 
3 while  $E' \neq \emptyset$ 
4     let  $(u, v)$  be an arbitrary edge of  $E'$ 
5      $C = C \cup \{u, v\}$ 
6     remove from  $E'$  every edge incident on either  $u$  or  $v$ 
7 return  $C$ 
```

Theorem 35.1

APPROX-VERTEX-COVER is a poly-time 2-approximation algorithm.

Proof:

- Running time is $O(V + E)$ (using adjacency lists to represent E')
 - Let $A \subseteq E$ denote the set of edges picked in line 4
 - Key Observation:** A is a set of vertex-disjoint edges, i.e., A is a matching
- ⇒ Every optimal cover C^* must include at least one endpoint: $|C^*| \geq |A|$
- Every edge in A contributes 2 vertices to $|C|$: $|C| = 2|A| \leq 2|C^*|$.



Analysis of Greedy for Vertex Cover

APPROX-VERTEX-COVER(G)

```
1  $C = \emptyset$ 
2  $E' = G.E$ 
3 while  $E' \neq \emptyset$ 
4     let  $(u, v)$  be an arbitrary edge of  $E'$ 
5      $C = C \cup \{u, v\}$ 
6     remove from  $E'$  every edge incident on either  $u$  or  $v$ 
7 return  $C$ 
```

Theorem 35.1

APPROX-VERTEX-COVER is a poly-time 2-approximation algorithm.

Proof:

- Running time is $O(V + E)$ (using adjacency lists to represent E')
 - Let $A \subseteq E$ denote the set of edges picked in line 4
 - Key Observation:** A is a set of vertex-disjoint edges, i.e., A is a matching
- ⇒ Every optimal cover C^* must include at least one endpoint: $|C^*| \geq |A|$
- Every edge in A contributes 2 vertices to $|C|$: $|C| = 2|A| \leq 2|C^*|$. □



Analysis of Greedy for Vertex Cover

APPROX-VERTEX-COVER(G)

```
1  $C = \emptyset$ 
2  $E' = G.E$ 
3 while  $E' \neq \emptyset$ 
4   let  $(u, v)$  be an arbitrary edge of  $E'$ 
5    $C = C \cup \{u, v\}$ 
6   remove from  $E'$  every edge incident on either  $u$  or  $v$ 
7 return  $C$ 
```

We can bound the size of the returned solution without knowing the (size of an) optimal solution!

Theorem 35.1

APPROX-VERTEX-COVER is a poly-time 2-approximation algorithm.

Proof:

- Running time is $O(V + E)$ (using adjacency lists to represent E')
 - Let $A \subseteq E$ denote the set of edges picked in line 4
 - **Key Observation:** A is a set of vertex-disjoint edges, i.e., A is a matching
- ⇒ Every optimal cover C^* must include at least one endpoint: $|C^*| \geq |A|$
- Every edge in A contributes 2 vertices to $|C|$: $|C| = 2|A| \leq 2|C^*|$. \square



Analysis of Greedy for Vertex Cover

APPROX-VERTEX-COVER(G)

```
1  $C = \emptyset$ 
2  $E' = G.E$ 
3 while  $E' \neq \emptyset$ 
4   let  $(u, v)$  be an arbitrary edge of  $E'$ 
5    $C = C \cup \{u, v\}$ 
6   remove from  $E'$  every edge incident on either  $u$  or  $v$ 
7 return  $C$ 
```

A "vertex-based" Greedy that adds **one** vertex at each iteration fails to achieve an approximation ratio of 2 (Supervision Exercise)!

We can bound the size of the returned solution **without knowing** the (size of an) optimal solution!

Theorem 35.1

APPROX-VERTEX-COVER is a poly-time 2-approximation algorithm.

Proof:

- Running time is $O(V + E)$ (using adjacency lists to represent E')
 - Let $A \subseteq E$ denote the set of edges picked in line 4
 - **Key Observation:** A is a set of vertex-disjoint edges, i.e., A is a **matching**
- ⇒ Every optimal cover C^* must include at least one endpoint: $|C^*| \geq |A|$
- Every edge in A contributes 2 vertices to $|C|$: $|C| = 2|A| \leq 2|C^*|$. \square



Solving Special Cases

Strategies to cope with NP-complete problems

1. If inputs are small, an algorithm with exponential running time may be satisfactory.
2. Isolate important special cases which can be solved in polynomial-time.
3. Develop algorithms which find near-optimal solutions in polynomial-time.



Solving Special Cases

Strategies to cope with NP-complete problems

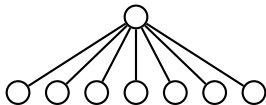
1. If inputs are small, an algorithm with exponential running time may be satisfactory.
2. Isolate important special cases which can be solved in polynomial-time.
3. Develop algorithms which find near-optimal solutions in polynomial-time.



Solving Special Cases

Strategies to cope with NP-complete problems

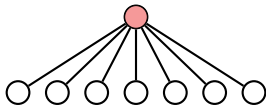
1. If inputs are small, an algorithm with exponential running time may be satisfactory.
2. Isolate important special cases which can be solved in polynomial-time.
3. Develop algorithms which find near-optimal solutions in polynomial-time.



Solving Special Cases

Strategies to cope with NP-complete problems

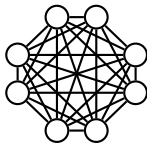
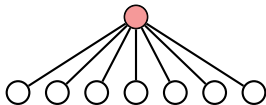
1. If inputs are small, an algorithm with exponential running time may be satisfactory.
2. Isolate important special cases which can be solved in polynomial-time.
3. Develop algorithms which find near-optimal solutions in polynomial-time.



Solving Special Cases

Strategies to cope with NP-complete problems

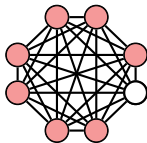
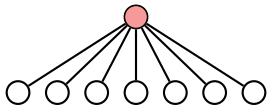
1. If inputs are small, an algorithm with exponential running time may be satisfactory.
2. Isolate important special cases which can be solved in polynomial-time.
3. Develop algorithms which find near-optimal solutions in polynomial-time.



Solving Special Cases

Strategies to cope with NP-complete problems

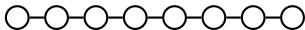
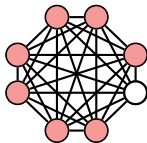
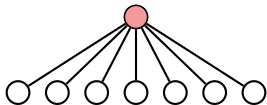
1. If inputs are small, an algorithm with exponential running time may be satisfactory.
2. Isolate important special cases which can be solved in polynomial-time.
3. Develop algorithms which find near-optimal solutions in polynomial-time.



Solving Special Cases

Strategies to cope with NP-complete problems

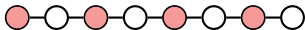
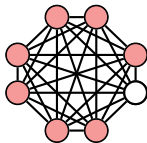
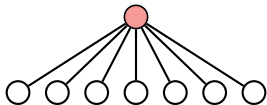
1. If inputs are small, an algorithm with exponential running time may be satisfactory.
2. Isolate important special cases which can be solved in polynomial-time.
3. Develop algorithms which find near-optimal solutions in polynomial-time.



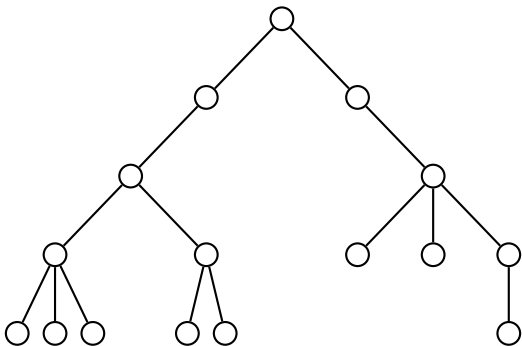
Solving Special Cases

Strategies to cope with NP-complete problems

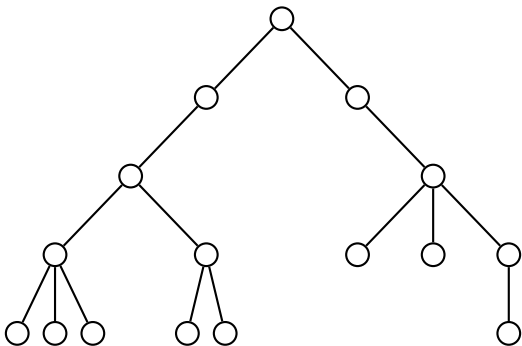
1. If inputs are small, an algorithm with exponential running time may be satisfactory.
2. Isolate important special cases which can be solved in polynomial-time.
3. Develop algorithms which find near-optimal solutions in polynomial-time.



Vertex Cover on Trees



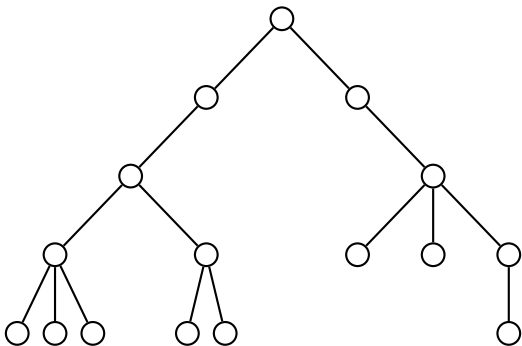
Vertex Cover on Trees



There exists an **optimal vertex cover** which does not include any **leaves**.



Vertex Cover on Trees

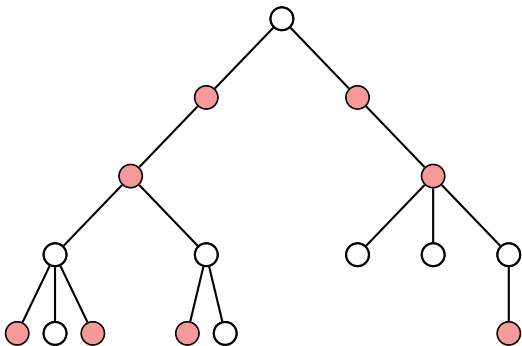


There exists an **optimal vertex cover** which does not include any **leaves**.

Exchange-Argument: Replace any leaf in the cover by its parent.



Vertex Cover on Trees

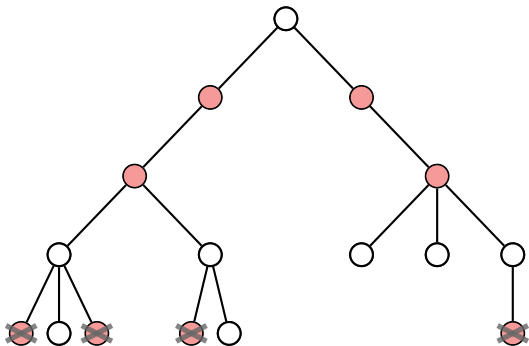


There exists an **optimal vertex cover** which does not include any **leaves**.

Exchange-Argument: Replace any leaf in the cover by its parent.



Vertex Cover on Trees

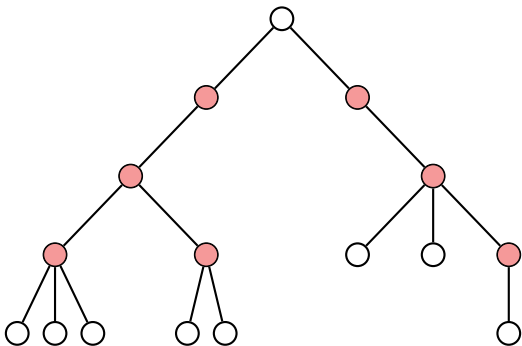


There exists an **optimal vertex cover** which does not include any **leaves**.

Exchange-Argument: Replace any leaf in the cover by its parent.



Vertex Cover on Trees



There exists an **optimal vertex cover** which does not include any **leaves**.

Exchange-Argument: Replace any leaf in the cover by its parent.



Solving Vertex Cover on Trees

There exists an **optimal vertex cover** which does not include any **leaves**.



There exists an optimal vertex cover which does not include any leaves.

VERTEX-COVER-TREES(G)

- 1: $C = \emptyset$
- 2: **while** \exists leaves in G
- 3: Add all parents to C
- 4: Remove all leaves and their parents from G
- 5: **return** C



Solving Vertex Cover on Trees

There exists an **optimal vertex cover** which does not include any **leaves**.

VERTEX-COVER-TREES(G)

- 1: $C = \emptyset$
- 2: **while** \exists leaves in G
- 3: Add all parents to C
- 4: Remove all leaves and their parents from G
- 5: **return** C

Clear: **Running time** is $O(V)$, and the returned solution is a **vertex cover**.



Solving Vertex Cover on Trees

There exists an **optimal vertex cover** which does not include any **leaves**.

VERTEX-COVER-TREES(G)

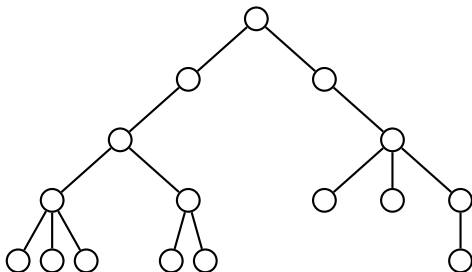
- 1: $C = \emptyset$
- 2: **while** \exists leaves in G
- 3: Add all parents to C
- 4: Remove all leaves and their parents from G
- 5: **return** C

Clear: **Running time** is $O(V)$, and the returned solution is a **vertex cover**.

Solution is also **optimal**. (Use inductively the existence of an optimal vertex cover without leaves)



Execution on a Small Example

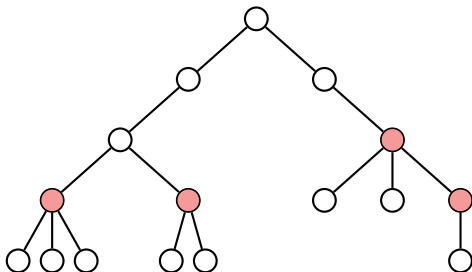


VERTEX-COVER-TREES(G)

- 1: $C = \emptyset$
- 2: **while** \exists leaves in G
- 3: Add all parents to C
- 4: Remove all leaves and their parents from G
- 5: **return** C



Execution on a Small Example

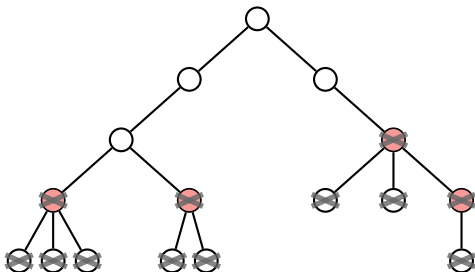


VERTEX-COVER-TREES(G)

- 1: $C = \emptyset$
- 2: **while** \exists leaves in G
- 3: Add all parents to C
- 4: Remove all leaves and their parents from G
- 5: **return** C



Execution on a Small Example

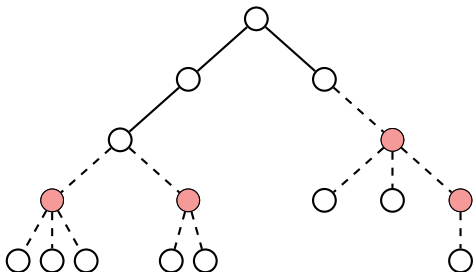


VERTEX-COVER-TREES(G)

- 1: $C = \emptyset$
- 2: **while** \exists leaves in G
- 3: Add all parents to C
- 4: Remove all leaves and their parents from G
- 5: **return** C



Execution on a Small Example

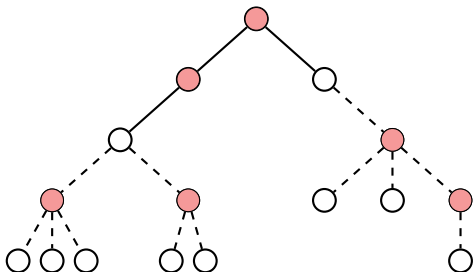


VERTEX-COVER-TREES(G)

- 1: $C = \emptyset$
- 2: **while** \exists leaves in G
- 3: Add all parents to C
- 4: Remove all leaves and their parents from G
- 5: **return** C



Execution on a Small Example

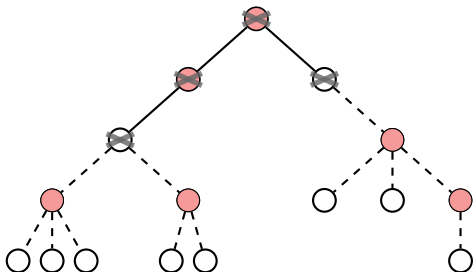


VERTEX-COVER-TREES(G)

- 1: $C = \emptyset$
- 2: **while** \exists leaves in G
- 3: Add all parents to C
- 4: Remove all leaves and their parents from G
- 5: **return** C



Execution on a Small Example

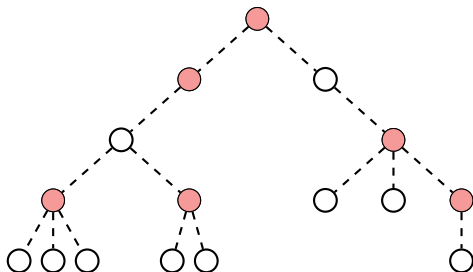


VERTEX-COVER-TREES(G)

- 1: $C = \emptyset$
- 2: **while** \exists leaves in G
- 3: Add all parents to C
- 4: Remove all leaves and their parents from G
- 5: **return** C



Execution on a Small Example

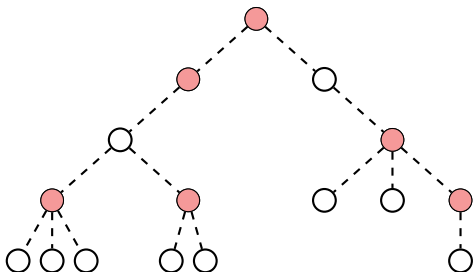


VERTEX-COVER-TREES(G)

- 1: $C = \emptyset$
- 2: **while** \exists leaves in G
- 3: Add all parents to C
- 4: Remove all leaves and their parents from G
- 5: **return** C



Execution on a Small Example



VERTEX-COVER-TREES(G)

- 1: $C = \emptyset$
- 2: **while** \exists leaves in G
- 3: Add all parents to C
- 4: Remove all leaves and their parents from G
- 5: **return** C

Problem can be also solved on bipartite graphs, using Max-Flows and Min-Cuts.



Exact Algorithms

Strategies to cope with NP-complete problems

1. If inputs (or solutions) are small, an algorithm with **exponential running time** may be satisfactory
2. **Isolate important special cases which can be solved in polynomial-time.**
3. Develop algorithms which find **near-optimal** solutions in polynomial-time.



Exact Algorithms

Strategies to cope with NP-complete problems

1. If inputs (or solutions) are small, an algorithm with exponential running time may be satisfactory
2. Isolate important special cases which can be solved in polynomial-time.
3. Develop algorithms which find near-optimal solutions in polynomial-time.



Exact Algorithms

Such algorithms are called **exact algorithms**.

Strategies to cope with NP-complete problems

1. If inputs (or solutions) are small, an algorithm with exponential running time may be satisfactory
2. Isolate important special cases which can be solved in polynomial-time.
3. Develop algorithms which find near-optimal solutions in polynomial-time.



Exact Algorithms

Such algorithms are called **exact algorithms**.

Strategies to cope with NP-complete problems

1. If **inputs (or solutions) are small**, an algorithm with **exponential running time may be satisfactory**
2. Isolate important **special cases** which can be solved in polynomial-time.
3. Develop algorithms which find **near-optimal** solutions in polynomial-time.

Focus on instances where the minimum vertex cover is small, that is, **less or equal** than some given integer k .



Exact Algorithms

Such algorithms are called **exact algorithms**.

Strategies to cope with NP-complete problems

1. If **inputs (or solutions) are small**, an algorithm with **exponential running time may be satisfactory**
2. Isolate important **special cases** which can be solved in polynomial-time.
3. Develop algorithms which find **near-optimal** solutions in polynomial-time.

Focus on instances where the minimum vertex cover is small, that is, **less or equal** than some given integer k .

Simple **Brute-Force Search** would take $\approx \binom{n}{k} = \Theta(n^k)$ time.



Towards a more efficient Search

Substructure Lemma

Consider a graph $G = (V, E)$, edge $\{u, v\} \in E(G)$ and integer $k \geq 1$. Let G_u be the graph obtained by deleting u and its incident edges (G_v is defined similarly). Then G has a vertex cover of size k if and only if G_u or G_v (or both) have a vertex cover of size $k - 1$.



Towards a more efficient Search

Substructure Lemma

Consider a graph $G = (V, E)$, edge $\{u, v\} \in E(G)$ and integer $k \geq 1$. Let G_u be the graph obtained by deleting u and its incident edges (G_v is defined similarly). Then G has a vertex cover of size k if and only if G_u or G_v (or both) have a vertex cover of size $k - 1$.

Reminiscent of [Dynamic Programming](#).



Towards a more efficient Search

Substructure Lemma

Consider a graph $G = (V, E)$, edge $\{u, v\} \in E(G)$ and integer $k \geq 1$. Let G_u be the graph obtained by deleting u and its incident edges (G_v is defined similarly). Then G has a vertex cover of size k if and only if G_u or G_v (or both) have a vertex cover of size $k - 1$.

Proof:

\Leftarrow Assume G_u has a vertex cover C_u of size $k - 1$.



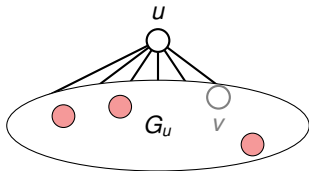
Towards a more efficient Search

Substructure Lemma

Consider a graph $G = (V, E)$, edge $\{u, v\} \in E(G)$ and integer $k \geq 1$. Let G_u be the graph obtained by deleting u and its incident edges (G_v is defined similarly). Then G has a vertex cover of size k if and only if G_u or G_v (or both) have a vertex cover of size $k - 1$.

Proof:

\Leftarrow Assume G_u has a vertex cover C_u of size $k - 1$.



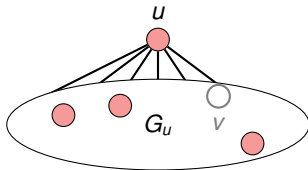
Towards a more efficient Search

Substructure Lemma

Consider a graph $G = (V, E)$, edge $\{u, v\} \in E(G)$ and integer $k \geq 1$. Let G_u be the graph obtained by deleting u and its incident edges (G_v is defined similarly). Then G has a vertex cover of size k if and only if G_u or G_v (or both) have a vertex cover of size $k - 1$.

Proof:

- \Leftarrow Assume G_u has a vertex cover C_u of size $k - 1$.
Adding u yields a vertex cover of G which is of size k



Towards a more efficient Search

Substructure Lemma

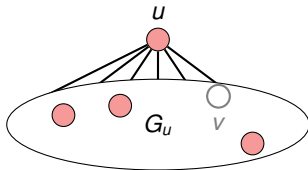
Consider a graph $G = (V, E)$, edge $\{u, v\} \in E(G)$ and integer $k \geq 1$. Let G_u be the graph obtained by deleting u and its incident edges (G_v is defined similarly). Then G has a vertex cover of size k if and only if G_u or G_v (or both) have a vertex cover of size $k - 1$.

Proof:

\Leftarrow Assume G_u has a vertex cover C_u of size $k - 1$.

Adding u yields a vertex cover of G which is of size k

\Rightarrow Assume G has a vertex cover C of size k , which contains, say u .



Towards a more efficient Search

Substructure Lemma

Consider a graph $G = (V, E)$, edge $\{u, v\} \in E(G)$ and integer $k \geq 1$. Let G_u be the graph obtained by deleting u and its incident edges (G_v is defined similarly). Then G has a vertex cover of size k if and only if G_u or G_v (or both) have a vertex cover of size $k - 1$.

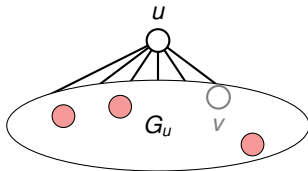
Proof:

\Leftarrow Assume G_u has a vertex cover C_u of size $k - 1$.

Adding u yields a vertex cover of G which is of size k

\Rightarrow Assume G has a vertex cover C of size k , which contains, say u .

Removing u from C yields a vertex cover of G_u which is of size $k - 1$. \square



A More Efficient Search Algorithm

VERTEX-COVER-SEARCH(G, k)

- 1: **if** $E = \emptyset$ **return** \emptyset
- 2: **if** $k = 0$ and $E \neq \emptyset$ **return** \perp
- 3: Pick an arbitrary edge $(u, v) \in E$
- 4: $S_1 = \text{VERTEX-COVER-SEARCH}(G_u, k - 1)$
- 5: $S_2 = \text{VERTEX-COVER-SEARCH}(G_v, k - 1)$
- 6: **if** $S_1 \neq \perp$ **return** $S_1 \cup \{u\}$
- 7: **if** $S_2 \neq \perp$ **return** $S_2 \cup \{v\}$
- 8: **return** \perp



A More Efficient Search Algorithm

VERTEX-COVER-SEARCH(G, k)

- 1: **if** $E = \emptyset$ **return** \emptyset
- 2: **if** $k = 0$ and $E \neq \emptyset$ **return** \perp
- 3: Pick an arbitrary edge $(u, v) \in E$
- 4: $S_1 = \text{VERTEX-COVER-SEARCH}(G_u, k - 1)$
- 5: $S_2 = \text{VERTEX-COVER-SEARCH}(G_v, k - 1)$
- 6: **if** $S_1 \neq \perp$ **return** $S_1 \cup \{u\}$
- 7: **if** $S_2 \neq \perp$ **return** $S_2 \cup \{v\}$
- 8: **return** \perp

Correctness follows by the Substructure Lemma and induction.



A More Efficient Search Algorithm

VERTEX-COVER-SEARCH(G, k)

- 1: **if** $E = \emptyset$ **return** \emptyset
- 2: **if** $k = 0$ and $E \neq \emptyset$ **return** \perp
- 3: Pick an arbitrary edge $(u, v) \in E$
- 4: $S_1 = \text{VERTEX-COVER-SEARCH}(G_u, k - 1)$
- 5: $S_2 = \text{VERTEX-COVER-SEARCH}(G_v, k - 1)$
- 6: **if** $S_1 \neq \perp$ **return** $S_1 \cup \{u\}$
- 7: **if** $S_2 \neq \perp$ **return** $S_2 \cup \{v\}$
- 8: **return** \perp

Running time:



A More Efficient Search Algorithm

VERTEX-COVER-SEARCH(G, k)

- 1: **if** $E = \emptyset$ **return** \emptyset
- 2: **if** $k = 0$ and $E \neq \emptyset$ **return** \perp
- 3: Pick an arbitrary edge $(u, v) \in E$
- 4: $S_1 = \text{VERTEX-COVER-SEARCH}(G_u, k - 1)$
- 5: $S_2 = \text{VERTEX-COVER-SEARCH}(G_v, k - 1)$
- 6: **if** $S_1 \neq \perp$ **return** $S_1 \cup \{u\}$
- 7: **if** $S_2 \neq \perp$ **return** $S_2 \cup \{v\}$
- 8: **return** \perp

Running time:

- Depth k , branching factor 2



A More Efficient Search Algorithm

VERTEX-COVER-SEARCH(G, k)

- 1: **if** $E = \emptyset$ **return** \emptyset
- 2: **if** $k = 0$ and $E \neq \emptyset$ **return** \perp
- 3: Pick an arbitrary edge $(u, v) \in E$
- 4: $S_1 = \text{VERTEX-COVER-SEARCH}(G_u, k - 1)$
- 5: $S_2 = \text{VERTEX-COVER-SEARCH}(G_v, k - 1)$
- 6: **if** $S_1 \neq \perp$ **return** $S_1 \cup \{u\}$
- 7: **if** $S_2 \neq \perp$ **return** $S_2 \cup \{v\}$
- 8: **return** \perp

Running time:

- Depth k , branching factor 2 \Rightarrow total number of calls is $O(2^k)$



A More Efficient Search Algorithm

VERTEX-COVER-SEARCH(G, k)

- 1: **if** $E = \emptyset$ **return** \emptyset
- 2: **if** $k = 0$ and $E \neq \emptyset$ **return** \perp
- 3: Pick an arbitrary edge $(u, v) \in E$
- 4: $S_1 = \text{VERTEX-COVER-SEARCH}(G_u, k - 1)$
- 5: $S_2 = \text{VERTEX-COVER-SEARCH}(G_v, k - 1)$
- 6: **if** $S_1 \neq \perp$ **return** $S_1 \cup \{u\}$
- 7: **if** $S_2 \neq \perp$ **return** $S_2 \cup \{v\}$
- 8: **return** \perp

Running time:

- Depth k , branching factor 2 \Rightarrow total number of calls is $O(2^k)$
- $O(E)$ worst-case time for one call (computing G_u or G_v could take $\Theta(E)$!)



A More Efficient Search Algorithm

VERTEX-COVER-SEARCH(G, k)

- 1: **if** $E = \emptyset$ **return** \emptyset
- 2: **if** $k = 0$ and $E \neq \emptyset$ **return** \perp
- 3: Pick an arbitrary edge $(u, v) \in E$
- 4: $S_1 = \text{VERTEX-COVER-SEARCH}(G_u, k - 1)$
- 5: $S_2 = \text{VERTEX-COVER-SEARCH}(G_v, k - 1)$
- 6: **if** $S_1 \neq \perp$ **return** $S_1 \cup \{u\}$
- 7: **if** $S_2 \neq \perp$ **return** $S_2 \cup \{v\}$
- 8: **return** \perp

Running time:

- Depth k , branching factor 2 \Rightarrow total number of calls is $O(2^k)$
- $O(E)$ worst-case time for one call (computing G_u or G_v could take $\Theta(E)$!)
- Total runtime: $O(2^k \cdot E)$.



A More Efficient Search Algorithm

VERTEX-COVER-SEARCH(G, k)

- 1: **if** $E = \emptyset$ **return** \emptyset
- 2: **if** $k = 0$ and $E \neq \emptyset$ **return** \perp
- 3: Pick an arbitrary edge $(u, v) \in E$
- 4: $S_1 = \text{VERTEX-COVER-SEARCH}(G_u, k - 1)$
- 5: $S_2 = \text{VERTEX-COVER-SEARCH}(G_v, k - 1)$
- 6: **if** $S_1 \neq \perp$ **return** $S_1 \cup \{u\}$
- 7: **if** $S_2 \neq \perp$ **return** $S_2 \cup \{v\}$
- 8: **return** \perp

Running time:

- Depth k , branching factor 2 \Rightarrow total number of calls is $O(2^k)$
- $O(E)$ worst-case time for one call (computing G_u or G_v could take $\Theta(E)$!)
- Total runtime: $O(2^k \cdot E)$.

exponential in k , but much better than $\Theta(n^k)$ (i.e., still polynomial for $k = O(\log n)$)



Outline

Introduction

Vertex Cover

The Set-Covering Problem



The Set-Covering Problem

Set Cover Problem

- **Given:** set X of size n and family of subsets \mathcal{F}
- **Goal:** Find a **minimum-size** subset $\mathcal{C} \subseteq \mathcal{F}$

$$\text{s.t.} \quad X = \bigcup_{S \in \mathcal{C}} S.$$



The Set-Covering Problem

Set Cover Problem

- **Given:** set X of size n and family of subsets \mathcal{F}
- **Goal:** Find a **minimum-size** subset $\mathcal{C} \subseteq \mathcal{F}$

$$\text{s.t.} \quad X = \bigcup_{S \in \mathcal{C}} S.$$

Only solvable if $\bigcup_{S \in \mathcal{F}} S = X$!



The Set-Covering Problem

Set Cover Problem

- **Given:** set X of size n and family of subsets \mathcal{F}
- **Goal:** Find a **minimum-size** subset $\mathcal{C} \subseteq \mathcal{F}$

Number of **sets**
(and not elements)

$$\text{s.t. } X = \bigcup_{S \in \mathcal{C}} S.$$

Only solvable if $\bigcup_{S \in \mathcal{F}} S = X!$



The Set-Covering Problem

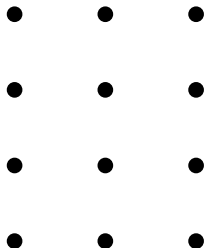
Set Cover Problem

- **Given:** set X of size n and family of subsets \mathcal{F}
- **Goal:** Find a **minimum-size** subset $\mathcal{C} \subseteq \mathcal{F}$

Number of **sets**
(and not elements)

$$\text{s.t. } X = \bigcup_{S \in \mathcal{C}} S.$$

Only solvable if $\bigcup_{S \in \mathcal{F}} S = X!$



The Set-Covering Problem

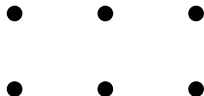
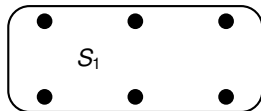
Set Cover Problem

- **Given:** set X of size n and family of subsets \mathcal{F}
- **Goal:** Find a **minimum-size** subset $\mathcal{C} \subseteq \mathcal{F}$

Number of **sets**
(and not elements)

$$\text{s.t. } X = \bigcup_{S \in \mathcal{C}} S.$$

Only solvable if $\bigcup_{S \in \mathcal{F}} S = X!$



The Set-Covering Problem

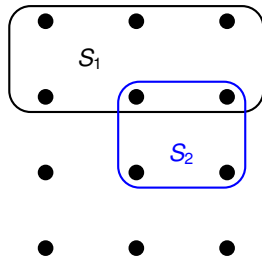
Set Cover Problem

- **Given:** set X of size n and family of subsets \mathcal{F}
- **Goal:** Find a **minimum-size** subset $\mathcal{C} \subseteq \mathcal{F}$

Number of **sets**
(and not elements)

$$\text{s.t. } X = \bigcup_{S \in \mathcal{C}} S.$$

Only solvable if $\bigcup_{S \in \mathcal{F}} S = X!$



The Set-Covering Problem

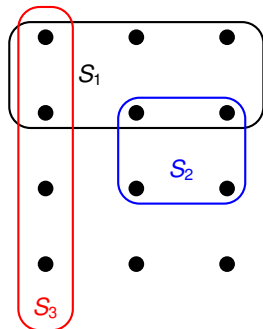
Set Cover Problem

- **Given:** set X of size n and family of subsets \mathcal{F}
- **Goal:** Find a **minimum-size** subset $\mathcal{C} \subseteq \mathcal{F}$

Number of **sets**
(and not elements)

$$\text{s.t. } X = \bigcup_{S \in \mathcal{C}} S.$$

Only solvable if $\bigcup_{S \in \mathcal{F}} S = X!$



The Set-Covering Problem

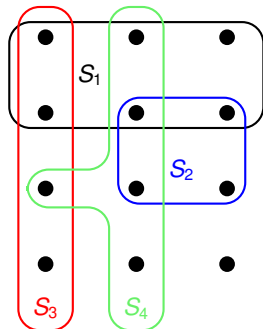
Set Cover Problem

- **Given:** set X of size n and family of subsets \mathcal{F}
- **Goal:** Find a **minimum-size** subset $\mathcal{C} \subseteq \mathcal{F}$

Number of **sets**
(and not elements)

$$\text{s.t. } X = \bigcup_{S \in \mathcal{C}} S.$$

Only solvable if $\bigcup_{S \in \mathcal{F}} S = X!$



The Set-Covering Problem

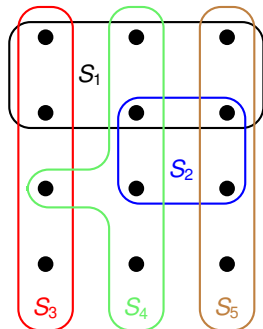
Set Cover Problem

- **Given:** set X of size n and family of subsets \mathcal{F}
- **Goal:** Find a **minimum-size** subset $\mathcal{C} \subseteq \mathcal{F}$

Number of **sets**
(and not elements)

$$\text{s.t. } X = \bigcup_{S \in \mathcal{C}} S.$$

Only solvable if $\bigcup_{S \in \mathcal{F}} S = X!$



The Set-Covering Problem

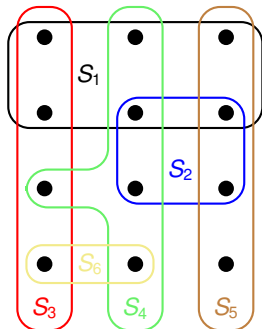
Set Cover Problem

- **Given:** set X of size n and family of subsets \mathcal{F}
- **Goal:** Find a **minimum-size** subset $\mathcal{C} \subseteq \mathcal{F}$

Number of **sets**
(and not elements)

$$\text{s.t. } X = \bigcup_{S \in \mathcal{C}} S.$$

Only solvable if $\bigcup_{S \in \mathcal{F}} S = X!$



The Set-Covering Problem

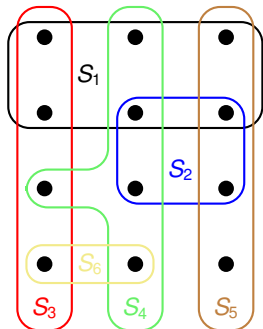
Set Cover Problem

- Given: set X of size n and family of subsets \mathcal{F}
- Goal: Find a minimum-size subset $\mathcal{C} \subseteq \mathcal{F}$

Number of sets
(and not elements)

$$\text{s.t. } X = \bigcup_{S \in \mathcal{C}} S.$$

Only solvable if $\bigcup_{S \in \mathcal{F}} S = X!$



Remarks:



The Set-Covering Problem

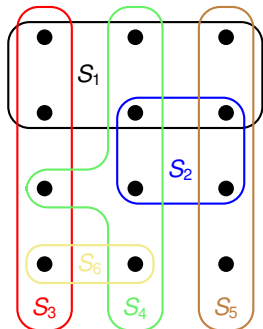
Set Cover Problem

- Given: set X of size n and family of subsets \mathcal{F}
- Goal: Find a minimum-size subset $\mathcal{C} \subseteq \mathcal{F}$

Number of sets
(and not elements)

$$\text{s.t. } X = \bigcup_{S \in \mathcal{C}} S.$$

Only solvable if $\bigcup_{S \in \mathcal{F}} S = X!$



Remarks:

- generalisation of the vertex-cover problem and hence also NP-hard.



The Set-Covering Problem

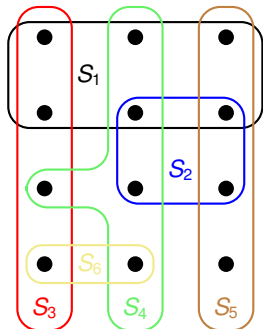
Set Cover Problem

- Given: set X of size n and family of subsets \mathcal{F}
- Goal: Find a minimum-size subset $\mathcal{C} \subseteq \mathcal{F}$

Number of sets
(and not elements)

$$\text{s.t. } X = \bigcup_{S \in \mathcal{C}} S.$$

Only solvable if $\bigcup_{S \in \mathcal{F}} S = X!$



Remarks:

- generalisation of the vertex-cover problem and hence also NP-hard.
- models resource allocation problems, e.g., wireless coverage



Greedy

Strategy: Pick the set S that covers the largest number of uncovered elements.



Greedy

Strategy: Pick the set S that covers the largest number of uncovered elements.

GREEDY-SET-COVER(X, \mathcal{F})

```
1  $U = X$ 
2  $\mathcal{C} = \emptyset$ 
3 while  $U \neq \emptyset$ 
4     select an  $S \in \mathcal{F}$  that maximizes  $|S \cap U|$ 
5      $U = U - S$ 
6      $\mathcal{C} = \mathcal{C} \cup \{S\}$ 
7 return  $\mathcal{C}$ 
```

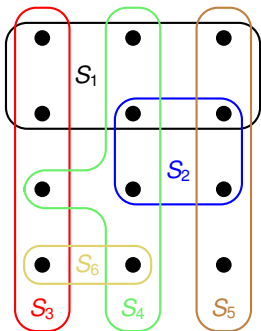


Greedy

Strategy: Pick the set S that covers the largest number of uncovered elements.

GREEDY-SET-COVER(X, \mathcal{F})

```
1  $U = X$ 
2  $\mathcal{C} = \emptyset$ 
3 while  $U \neq \emptyset$ 
4     select an  $S \in \mathcal{F}$  that maximizes  $|S \cap U|$ 
5      $U = U - S$ 
6      $\mathcal{C} = \mathcal{C} \cup \{S\}$ 
7 return  $\mathcal{C}$ 
```

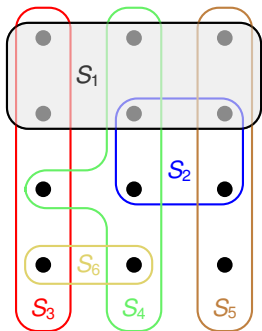


Greedy

Strategy: Pick the set S that covers the largest number of uncovered elements.

GREEDY-SET-COVER(X, \mathcal{F})

```
1  $U = X$ 
2  $\mathcal{C} = \emptyset$ 
3 while  $U \neq \emptyset$ 
4     select an  $S \in \mathcal{F}$  that maximizes  $|S \cap U|$ 
5      $U = U - S$ 
6      $\mathcal{C} = \mathcal{C} \cup \{S\}$ 
7 return  $\mathcal{C}$ 
```

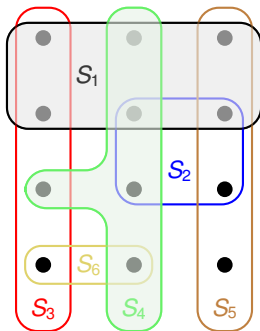


Greedy

Strategy: Pick the set S that covers the largest number of uncovered elements.

GREEDY-SET-COVER(X, \mathcal{F})

```
1  $U = X$ 
2  $\mathcal{C} = \emptyset$ 
3 while  $U \neq \emptyset$ 
4     select an  $S \in \mathcal{F}$  that maximizes  $|S \cap U|$ 
5      $U = U - S$ 
6      $\mathcal{C} = \mathcal{C} \cup \{S\}$ 
7 return  $\mathcal{C}$ 
```

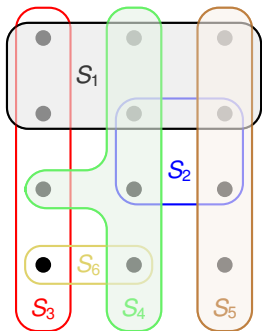


Greedy

Strategy: Pick the set S that covers the largest number of uncovered elements.

GREEDY-SET-COVER(X, \mathcal{F})

```
1  $U = X$ 
2  $\mathcal{C} = \emptyset$ 
3 while  $U \neq \emptyset$ 
4     select an  $S \in \mathcal{F}$  that maximizes  $|S \cap U|$ 
5      $U = U - S$ 
6      $\mathcal{C} = \mathcal{C} \cup \{S\}$ 
7 return  $\mathcal{C}$ 
```

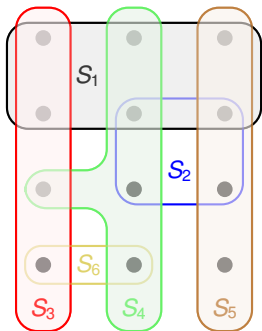


Greedy

Strategy: Pick the set S that covers the largest number of uncovered elements.

GREEDY-SET-COVER(X, \mathcal{F})

```
1  $U = X$ 
2  $\mathcal{C} = \emptyset$ 
3 while  $U \neq \emptyset$ 
4     select an  $S \in \mathcal{F}$  that maximizes  $|S \cap U|$ 
5      $U = U - S$ 
6      $\mathcal{C} = \mathcal{C} \cup \{S\}$ 
7 return  $\mathcal{C}$ 
```

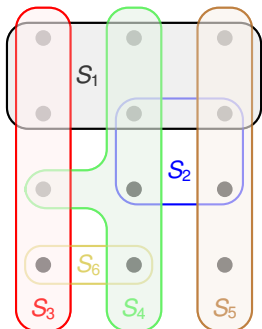


Greedy

Strategy: Pick the set S that covers the largest number of uncovered elements.

GREEDY-SET-COVER(X, \mathcal{F})

```
1  $U = X$ 
2  $\mathcal{C} = \emptyset$ 
3 while  $U \neq \emptyset$ 
4     select an  $S \in \mathcal{F}$  that maximizes  $|S \cap U|$ 
5      $U = U - S$ 
6      $\mathcal{C} = \mathcal{C} \cup \{S\}$ 
7 return  $\mathcal{C}$ 
```



Greedy chooses S_1, S_4, S_5 and S_3 (or S_6), which is a cover of size 4.

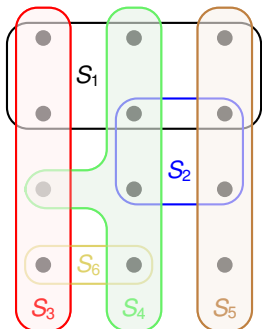


Greedy

Strategy: Pick the set S that covers the largest number of uncovered elements.

GREEDY-SET-COVER(X, \mathcal{F})

```
1  $U = X$ 
2  $\mathcal{C} = \emptyset$ 
3 while  $U \neq \emptyset$ 
4     select an  $S \in \mathcal{F}$  that maximizes  $|S \cap U|$ 
5      $U = U - S$ 
6      $\mathcal{C} = \mathcal{C} \cup \{S\}$ 
7 return  $\mathcal{C}$ 
```



Greedy chooses S_1, S_4, S_5 and S_3 (or S_6), which is a cover of size 4.

Optimal cover is $\mathcal{C} = \{S_3, S_4, S_5\}$



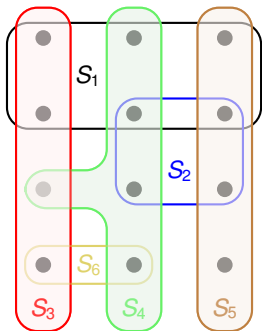
Greedy

Strategy: Pick the set S that covers the largest number of uncovered elements.

GREEDY-SET-COVER(X, \mathcal{F})

```
1  $U = X$ 
2  $\mathcal{C} = \emptyset$ 
3 while  $U \neq \emptyset$ 
4     select an  $S \in \mathcal{F}$  that maximizes  $|S \cap U|$ 
5      $U = U - S$ 
6      $\mathcal{C} = \mathcal{C} \cup \{S\}$ 
7 return  $\mathcal{C}$ 
```

Can be easily implemented to run in time polynomial in $|X|$ and $|\mathcal{F}|$



Greedy

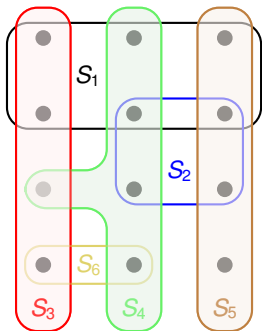
Strategy: Pick the set S that covers the largest number of uncovered elements.

GREEDY-SET-COVER(X, \mathcal{F})

```
1  $U = X$ 
2  $\mathcal{C} = \emptyset$ 
3 while  $U \neq \emptyset$ 
4     select an  $S \in \mathcal{F}$  that maximizes  $|S \cap U|$ 
5      $U = U - S$ 
6      $\mathcal{C} = \mathcal{C} \cup \{S\}$ 
7 return  $\mathcal{C}$ 
```

Can be easily implemented to run in time polynomial in $|X|$ and $|\mathcal{F}|$

How good is the approximation ratio?



Approximation Ratio of Greedy

Theorem 35.4

GREEDY-SET-COVER is a polynomial-time $\rho(n)$ -algorithm, where

$$\rho(n) = H(\max\{|S| : S \in \mathcal{F}\})$$



Approximation Ratio of Greedy

Theorem 35.4

GREEDY-SET-COVER is a polynomial-time $\rho(n)$ -algorithm, where

$$\rho(n) = H(\max\{|S| : S \in \mathcal{F}\})$$

$$H(k) := \sum_{i=1}^k \frac{1}{i} \leq \ln(k) + 1$$



Approximation Ratio of Greedy

Theorem 35.4

GREEDY-SET-COVER is a polynomial-time $\rho(n)$ -algorithm, where

$$\rho(n) = H(\max\{|S| : S \in \mathcal{F}\}) \leq \ln(n) + 1.$$

$$H(k) := \sum_{i=1}^k \frac{1}{i} \leq \ln(k) + 1$$



Approximation Ratio of Greedy

Theorem 35.4

GREEDY-SET-COVER is a polynomial-time $\rho(n)$ -algorithm, where

$$\rho(n) = H(\max\{|S| : S \in \mathcal{F}\}) \leq \ln(n) + 1.$$

$$H(k) := \sum_{i=1}^k \frac{1}{i} \leq \ln(k) + 1$$

Idea: Distribute cost of 1 for each added set over newly covered elements.



Approximation Ratio of Greedy

Theorem 35.4

GREEDY-SET-COVER is a polynomial-time $\rho(n)$ -algorithm, where

$$\rho(n) = H(\max\{|S| : S \in \mathcal{F}\}) \leq \ln(n) + 1.$$

$$H(k) := \sum_{i=1}^k \frac{1}{i} \leq \ln(k) + 1$$

Idea: Distribute cost of 1 for each added set over newly covered elements.

Definition of cost

If an element x is covered for the first time by set S_i in iteration i , then

$$c_x := \frac{1}{|S_i \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})|}.$$



Approximation Ratio of Greedy

Theorem 35.4

GREEDY-SET-COVER is a polynomial-time $\rho(n)$ -algorithm, where

$$\rho(n) = H(\max\{|S| : S \in \mathcal{F}\}) \leq \ln(n) + 1.$$

$$H(k) := \sum_{i=1}^k \frac{1}{i} \leq \ln(k) + 1$$

Idea: Distribute cost of 1 for each added set over newly covered elements.

Definition of cost

If an element x is covered for the first time by set S_i in iteration i , then

$$c_x := \frac{1}{|S_i \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})|}.$$

Notice that in the mathematical analysis, S_i is the set chosen in iteration i - not to be confused with the sets S_1, S_2, \dots, S_6 in the example.



Illustration of Costs for Greedy picking S_1, S_4, S_5 and S_3

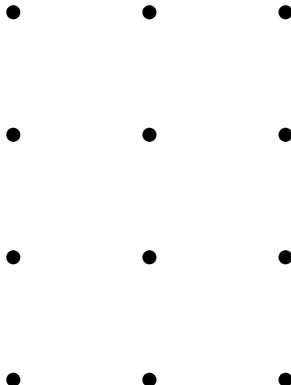


Illustration of Costs for Greedy picking S_1, S_4, S_5 and S_3

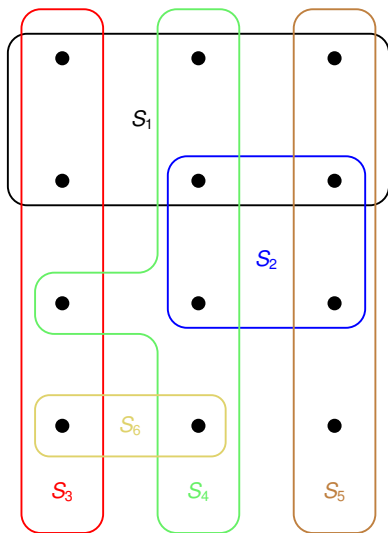


Illustration of Costs for Greedy picking S_1, S_4, S_5 and S_3

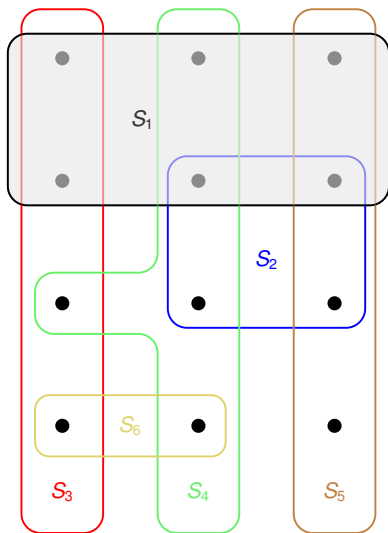


Illustration of Costs for Greedy picking S_1, S_4, S_5 and S_3

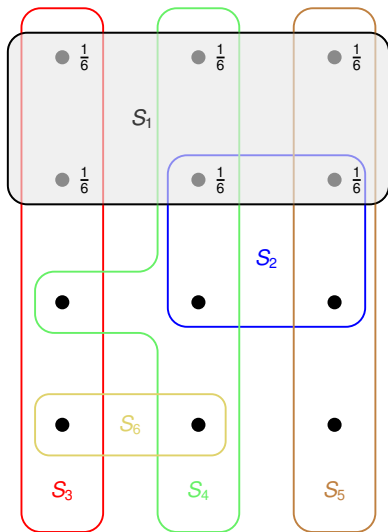


Illustration of Costs for Greedy picking S_1, S_4, S_5 and S_3

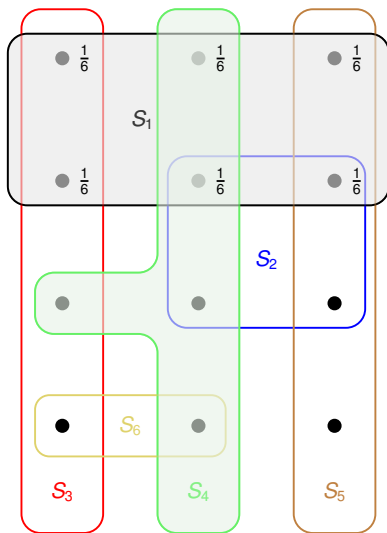


Illustration of Costs for Greedy picking S_1, S_4, S_5 and S_3

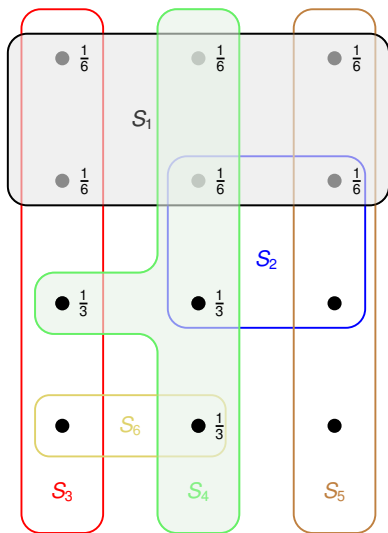


Illustration of Costs for Greedy picking S_1, S_4, S_5 and S_3

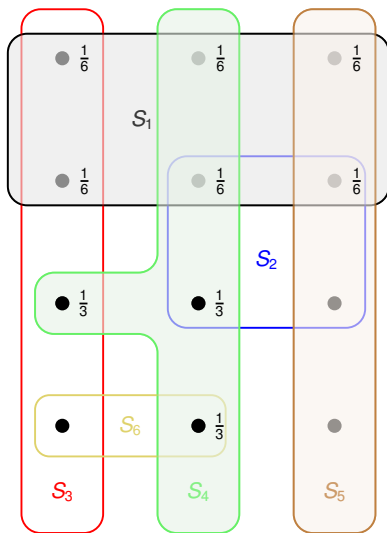


Illustration of Costs for Greedy picking S_1, S_4, S_5 and S_3

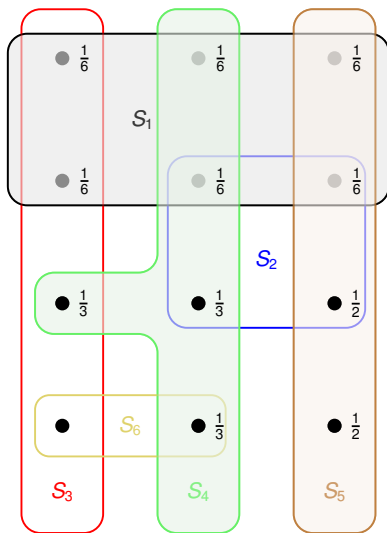


Illustration of Costs for Greedy picking S_1, S_4, S_5 and S_3

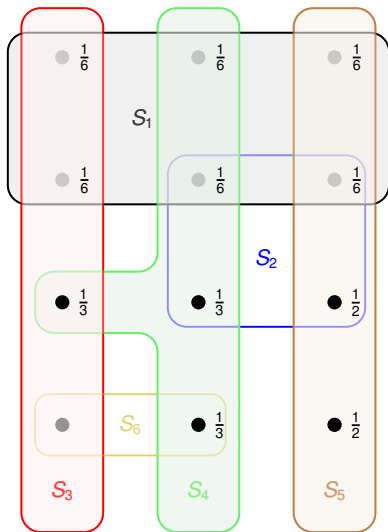


Illustration of Costs for Greedy picking S_1, S_4, S_5 and S_3

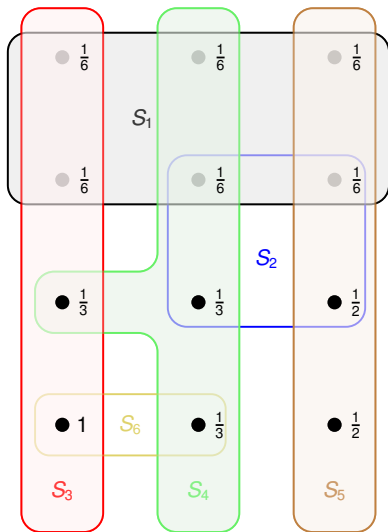
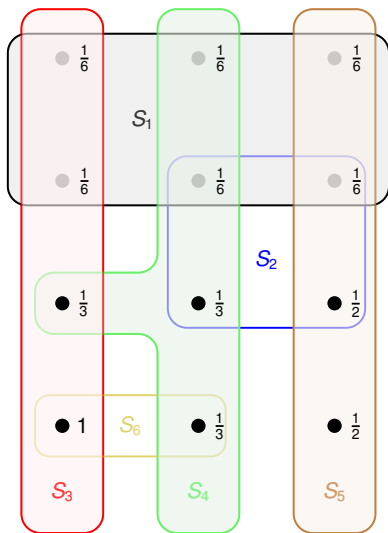


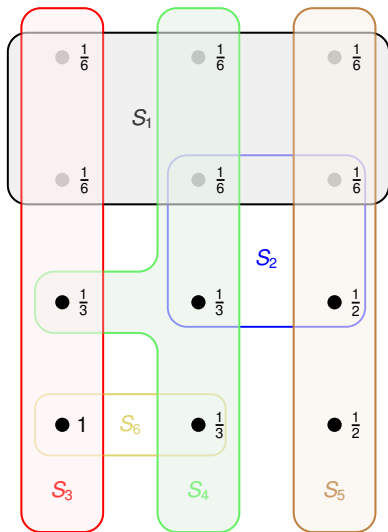
Illustration of Costs for Greedy picking S_1, S_4, S_5 and S_3



$$\frac{1}{6} + \frac{1}{6} + \frac{1}{6} + \frac{1}{6} + \frac{1}{6} + \frac{1}{6} + \frac{1}{3} + \frac{1}{3} + \frac{1}{3} + \frac{1}{2} + \frac{1}{2} + 1 = ??$$



Illustration of Costs for Greedy picking S_1, S_4, S_5 and S_3



$$\frac{1}{6} + \frac{1}{6} + \frac{1}{6} + \frac{1}{6} + \frac{1}{6} + \frac{1}{6} + \frac{1}{3} + \frac{1}{3} + \frac{1}{3} + \frac{1}{2} + \frac{1}{2} + 1 = 4$$



Proof of Theorem 35.4 (1/2)

Definition of cost

If x is covered for the first time by a set S_j , then $c_x := \frac{1}{|S_j \setminus (S_1 \cup S_2 \cup \dots \cup S_{j-1})|}$.



Proof of Theorem 35.4 (1/2)

Definition of cost

If x is covered for the first time by a set S_i , then $c_x := \frac{1}{|S_i \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})|}$.

Proof.

- Each step of the algorithm assigns one unit of cost, so

(1)



Proof of Theorem 35.4 (1/2)

Definition of cost

If x is covered for the first time by a set S_j , then $c_x := \frac{1}{|S_j \setminus (S_1 \cup S_2 \cup \dots \cup S_{j-1})|}$.

Proof.

- Each step of the algorithm assigns one unit of cost, so

$$|\mathcal{C}| = \sum_{x \in X} c_x \quad (1)$$



Proof of Theorem 35.4 (1/2)

Definition of cost

If x is covered for the first time by a set S_j , then $c_x := \frac{1}{|S_j \setminus (S_1 \cup S_2 \cup \dots \cup S_{j-1})|}$.

Proof.

- Each step of the algorithm assigns one unit of cost, so

$$|\mathcal{C}| = \sum_{x \in X} c_x \quad (1)$$

- Each element $x \in X$ is in at least one set in the optimal cover \mathcal{C}^* , so



Proof of Theorem 35.4 (1/2)

Definition of cost

If x is covered for the first time by a set S_j , then $c_x := \frac{1}{|S_j \setminus (S_1 \cup S_2 \cup \dots \cup S_{j-1})|}$.

Proof.

- Each step of the algorithm assigns one unit of cost, so

$$|\mathcal{C}| = \sum_{x \in X} c_x \quad (1)$$

- Each element $x \in X$ is in at least one set in the optimal cover \mathcal{C}^* , so

$$\sum_{S \in \mathcal{C}^*} \sum_{x \in S} c_x \geq \sum_{x \in X} c_x \quad (2)$$



Proof of Theorem 35.4 (1/2)

Definition of cost

If x is covered for the first time by a set S_j , then $c_x := \frac{1}{|S_j \setminus (S_1 \cup S_2 \cup \dots \cup S_{j-1})|}$.

Proof.

- Each step of the algorithm assigns one unit of cost, so

$$|\mathcal{C}| = \sum_{x \in X} c_x \quad (1)$$

- Each element $x \in X$ is in at least one set in the optimal cover \mathcal{C}^* , so

$$\sum_{S \in \mathcal{C}^*} \sum_{x \in S} c_x \geq \sum_{x \in X} c_x \quad (2)$$

- Combining 1 and 2 gives



Proof of Theorem 35.4 (1/2)

Definition of cost

If x is covered for the first time by a set S_j , then $c_x := \frac{1}{|S_j \setminus (S_1 \cup S_2 \cup \dots \cup S_{j-1})|}$.

Proof.

- Each step of the algorithm assigns one unit of cost, so

$$|\mathcal{C}| = \sum_{x \in X} c_x \quad (1)$$

- Each element $x \in X$ is in at least one set in the optimal cover \mathcal{C}^* , so

$$\sum_{S \in \mathcal{C}^*} \sum_{x \in S} c_x \geq \sum_{x \in X} c_x \quad (2)$$

- Combining 1 and 2 gives

$$|\mathcal{C}| \leq \sum_{S \in \mathcal{C}^*} \sum_{x \in S} c_x$$



Proof of Theorem 35.4 (1/2)

Definition of cost

If x is covered for the first time by a set S_j , then $c_x := \frac{1}{|S_j \setminus (S_1 \cup S_2 \cup \dots \cup S_{j-1})|}$.

Proof.

- Each step of the algorithm assigns one unit of cost, so

$$|C| = \sum_{x \in X} c_x \quad (1)$$

- Each element $x \in X$ is in at least one set in the optimal cover C^* , so

$$\sum_{S \in C^*} \sum_{x \in S} c_x \geq \sum_{x \in X} c_x \quad (2)$$

- Combining 1 and 2 gives

$$|C| \leq \sum_{S \in C^*} \sum_{x \in S} c_x$$

Key Inequality: $\sum_{x \in S} c_x \leq H(|S|)$.



Proof of Theorem 35.4 (1/2)

Definition of cost

If x is covered for the first time by a set S_j , then $c_x := \frac{1}{|S_j \setminus (S_1 \cup S_2 \cup \dots \cup S_{j-1})|}$.

Proof.

- Each step of the algorithm assigns one unit of cost, so

$$|\mathcal{C}| = \sum_{x \in X} c_x \quad (1)$$

- Each element $x \in X$ is in at least one set in the optimal cover \mathcal{C}^* , so

$$\sum_{S \in \mathcal{C}^*} \sum_{x \in S} c_x \geq \sum_{x \in X} c_x \quad (2)$$

- Combining 1 and 2 gives

$$|\mathcal{C}| \leq \sum_{S \in \mathcal{C}^*} \sum_{x \in S} c_x \leq \sum_{S \in \mathcal{C}^*} H(|S|)$$

Key Inequality: $\sum_{x \in S} c_x \leq H(|S|)$.



Proof of Theorem 35.4 (1/2)

Definition of cost

If x is covered for the first time by a set S_j , then $c_x := \frac{1}{|S_j \setminus (S_1 \cup S_2 \cup \dots \cup S_{j-1})|}$.

Proof.

- Each step of the algorithm assigns one unit of cost, so

$$|\mathcal{C}| = \sum_{x \in X} c_x \quad (1)$$

- Each element $x \in X$ is in at least one set in the optimal cover \mathcal{C}^* , so

$$\sum_{S \in \mathcal{C}^*} \sum_{x \in S} c_x \geq \sum_{x \in X} c_x \quad (2)$$

- Combining 1 and 2 gives

$$|\mathcal{C}| \leq \sum_{S \in \mathcal{C}^*} \sum_{x \in S} c_x \leq \sum_{S \in \mathcal{C}^*} H(|S|) \leq |\mathcal{C}^*| \cdot H(\max\{|S| : S \in \mathcal{F}\}) \quad \square$$

Key Inequality: $\sum_{x \in S} c_x \leq H(|S|)$.



Proof of Theorem 35.4 (2/2)

Proof of the Key Inequality $\sum_{x \in S} c_x \leq H(|S|)$



Proof of Theorem 35.4 (2/2)

Proof of the Key Inequality $\sum_{x \in S} c_x \leq H(|S|)$

- For any $S \in \mathcal{F}$ and $i = 1, 2, \dots, |C| = k$ let



Proof of Theorem 35.4 (2/2)

Proof of the Key Inequality $\sum_{x \in S} c_x \leq H(|S|)$

- For any $S \in \mathcal{F}$ and $i = 1, 2, \dots, |C| = k$ let $u_i := |S \setminus (S_1 \cup S_2 \cup \dots \cup S_i)|$



Proof of Theorem 35.4 (2/2)

Proof of the Key Inequality $\sum_{x \in S} c_x \leq H(|S|)$

Remaining uncovered elements in S

- For any $S \in \mathcal{F}$ and $i = 1, 2, \dots, |C| = k$ let $u_i := |S \setminus (S_1 \cup S_2 \cup \dots \cup S_i)|$



Proof of Theorem 35.4 (2/2)

Proof of the Key Inequality $\sum_{x \in S} c_x \leq H(|S|)$

Sets chosen by the algorithm

- For any $S \in \mathcal{F}$ and $i = 1, 2, \dots, |C| = k$ let $u_i := |S \setminus (S_1 \cup S_2 \cup \dots \cup S_i)|$



Proof of Theorem 35.4 (2/2)

Proof of the Key Inequality $\sum_{x \in S} c_x \leq H(|S|)$

- For any $S \in \mathcal{F}$ and $i = 1, 2, \dots, |C| = k$ let $u_i := |S \setminus (S_1 \cup S_2 \cup \dots \cup S_i)|$
 $\Rightarrow |S| = u_0 \geq u_1 \geq \dots \geq u_{|C|} = 0$ and $u_{i-1} - u_i$ counts the items in S covered first time by S_i .



Proof of Theorem 35.4 (2/2)

Proof of the Key Inequality $\sum_{x \in S} c_x \leq H(|S|)$

- For any $S \in \mathcal{F}$ and $i = 1, 2, \dots, |C| = k$ let $u_i := |S \setminus (S_1 \cup S_2 \cup \dots \cup S_i)|$
- $\Rightarrow |S| = u_0 \geq u_1 \geq \dots \geq u_{|C|} = 0$ and $u_{i-1} - u_i$ counts the items in S covered first time by S_i .

\Rightarrow

$$\sum_{x \in S} c_x$$



Proof of Theorem 35.4 (2/2)

Proof of the Key Inequality $\sum_{x \in S} c_x \leq H(|S|)$

- For any $S \in \mathcal{F}$ and $i = 1, 2, \dots, |C| = k$ let $u_i := |S \setminus (S_1 \cup S_2 \cup \dots \cup S_i)|$
- $\Rightarrow |S| = u_0 \geq u_1 \geq \dots \geq u_{|C|} = 0$ and $u_{i-1} - u_i$ counts the items in S covered first time by S_i .

\Rightarrow

$$\sum_{x \in S} c_x = \sum_{i=1}^k (u_{i-1} - u_i) \cdot \frac{1}{|S_i \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})|}$$



Proof of Theorem 35.4 (2/2)

Proof of the Key Inequality $\sum_{x \in S} c_x \leq H(|S|)$

- For any $S \in \mathcal{F}$ and $i = 1, 2, \dots, |C| = k$ let $u_i := |S \setminus (S_1 \cup S_2 \cup \dots \cup S_i)|$
- $\Rightarrow |S| = u_0 \geq u_1 \geq \dots \geq u_{|C|} = 0$ and $u_{i-1} - u_i$ counts the items in S covered first time by S_i .

\Rightarrow

$$\sum_{x \in S} c_x = \sum_{i=1}^k (u_{i-1} - u_i) \cdot \frac{1}{|S_i \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})|}$$



Proof of Theorem 35.4 (2/2)

Proof of the Key Inequality $\sum_{x \in S} c_x \leq H(|S|)$

- For any $S \in \mathcal{F}$ and $i = 1, 2, \dots, |C| = k$ let $u_i := |S \setminus (S_1 \cup S_2 \cup \dots \cup S_i)|$
- $\Rightarrow |S| = u_0 \geq u_1 \geq \dots \geq u_{|C|} = 0$ and $u_{i-1} - u_i$ counts the items in S covered first time by S_i .

\Rightarrow

$$\sum_{x \in S} c_x = \sum_{i=1}^k (u_{i-1} - u_i) \cdot \frac{1}{|S_i \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})|}$$

- Further, by definition of the **GREEDY-SET-COVER**:



Proof of Theorem 35.4 (2/2)

Proof of the Key Inequality $\sum_{x \in S} c_x \leq H(|S|)$

- For any $S \in \mathcal{F}$ and $i = 1, 2, \dots, |C| = k$ let $u_i := |S \setminus (S_1 \cup S_2 \cup \dots \cup S_i)|$
- $\Rightarrow |S| = u_0 \geq u_1 \geq \dots \geq u_{|C|} = 0$ and $u_{i-1} - u_i$ counts the items in S covered first time by S_i .

\Rightarrow

$$\sum_{x \in S} c_x = \sum_{i=1}^k (u_{i-1} - u_i) \cdot \frac{1}{|S_i \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})|}$$

- Further, by definition of the **GREEDY-SET-COVER**:

$$|S_i \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})| \geq |S \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})|$$



Proof of Theorem 35.4 (2/2)

Proof of the Key Inequality $\sum_{x \in S} c_x \leq H(|S|)$

- For any $S \in \mathcal{F}$ and $i = 1, 2, \dots, |C| = k$ let $u_i := |S \setminus (S_1 \cup S_2 \cup \dots \cup S_i)|$
- $\Rightarrow |S| = u_0 \geq u_1 \geq \dots \geq u_{|C|} = 0$ and $u_{i-1} - u_i$ counts the items in S covered first time by S_i .

\Rightarrow

$$\sum_{x \in S} c_x = \sum_{i=1}^k (u_{i-1} - u_i) \cdot \frac{1}{|S_i \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})|}$$

- Further, by definition of the **GREEDY-SET-COVER**:

$$|S_i \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})| \geq |S \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})| = u_{i-1}.$$



Proof of Theorem 35.4 (2/2)

Proof of the Key Inequality $\sum_{x \in S} c_x \leq H(|S|)$

- For any $S \in \mathcal{F}$ and $i = 1, 2, \dots, |C| = k$ let $u_i := |S \setminus (S_1 \cup S_2 \cup \dots \cup S_i)|$
- $\Rightarrow |S| = u_0 \geq u_1 \geq \dots \geq u_{|C|} = 0$ and $u_{i-1} - u_i$ counts the items in S covered first time by S_i .

\Rightarrow

$$\sum_{x \in S} c_x = \sum_{i=1}^k (u_{i-1} - u_i) \cdot \frac{1}{|S_i \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})|}$$

- Further, by definition of the **GREEDY-SET-COVER**:

$$|S_i \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})| \geq |S \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})| = u_{i-1}.$$

- Combining the last inequalities gives:

$$\sum_{x \in S} c_x$$



Proof of Theorem 35.4 (2/2)

Proof of the Key Inequality $\sum_{x \in S} c_x \leq H(|S|)$

- For any $S \in \mathcal{F}$ and $i = 1, 2, \dots, |C| = k$ let $u_i := |S \setminus (S_1 \cup S_2 \cup \dots \cup S_i)|$
- $\Rightarrow |S| = u_0 \geq u_1 \geq \dots \geq u_{|C|} = 0$ and $u_{i-1} - u_i$ counts the items in S covered first time by S_i .

\Rightarrow

$$\sum_{x \in S} c_x = \sum_{i=1}^k (u_{i-1} - u_i) \cdot \frac{1}{|S_i \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})|}$$

- Further, by definition of the **GREEDY-SET-COVER**:

$$|S_i \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})| \geq |S \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})| = u_{i-1}.$$

- Combining the last inequalities gives:

$$\sum_{x \in S} c_x \leq \sum_{i=1}^k (u_{i-1} - u_i) \cdot \frac{1}{u_{i-1}}$$



Proof of Theorem 35.4 (2/2)

Proof of the Key Inequality $\sum_{x \in S} c_x \leq H(|S|)$

- For any $S \in \mathcal{F}$ and $i = 1, 2, \dots, |C| = k$ let $u_i := |S \setminus (S_1 \cup S_2 \cup \dots \cup S_i)|$
- $\Rightarrow |S| = u_0 \geq u_1 \geq \dots \geq u_{|C|} = 0$ and $u_{i-1} - u_i$ counts the items in S covered first time by S_i .

\Rightarrow

$$\sum_{x \in S} c_x = \sum_{i=1}^k (u_{i-1} - u_i) \cdot \frac{1}{|S_i \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})|}$$

- Further, by definition of the **GREEDY-SET-COVER**:

$$|S_i \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})| \geq |S \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})| = u_{i-1}.$$

- Combining the last inequalities gives:

$$\sum_{x \in S} c_x \leq \sum_{i=1}^k (u_{i-1} - u_i) \cdot \frac{1}{u_{i-1}} = \sum_{i=1}^k \sum_{j=u_i+1}^{u_{i-1}} \frac{1}{u_{i-1}}$$



Proof of Theorem 35.4 (2/2)

Proof of the Key Inequality $\sum_{x \in S} c_x \leq H(|S|)$

- For any $S \in \mathcal{F}$ and $i = 1, 2, \dots, |C| = k$ let $u_i := |S \setminus (S_1 \cup S_2 \cup \dots \cup S_i)|$
- $\Rightarrow |S| = u_0 \geq u_1 \geq \dots \geq u_{|C|} = 0$ and $u_{i-1} - u_i$ counts the items in S covered first time by S_i .

\Rightarrow

$$\sum_{x \in S} c_x = \sum_{i=1}^k (u_{i-1} - u_i) \cdot \frac{1}{|S_i \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})|}$$

- Further, by definition of the **GREEDY-SET-COVER**:

$$|S_i \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})| \geq |S \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})| = u_{i-1}.$$

- Combining the last inequalities gives:

$$\begin{aligned} \sum_{x \in S} c_x &\leq \sum_{i=1}^k (u_{i-1} - u_i) \cdot \frac{1}{u_{i-1}} = \sum_{i=1}^k \sum_{j=u_i+1}^{u_{i-1}} \frac{1}{u_{i-1}} \\ &\leq \sum_{i=1}^k \sum_{j=u_i+1}^{u_{i-1}} \frac{1}{j} \end{aligned}$$



Proof of Theorem 35.4 (2/2)

Proof of the Key Inequality $\sum_{x \in S} c_x \leq H(|S|)$

- For any $S \in \mathcal{F}$ and $i = 1, 2, \dots, |C| = k$ let $u_i := |S \setminus (S_1 \cup S_2 \cup \dots \cup S_i)|$
- $\Rightarrow |S| = u_0 \geq u_1 \geq \dots \geq u_{|C|} = 0$ and $u_{i-1} - u_i$ counts the items in S covered first time by S_i .

\Rightarrow

$$\sum_{x \in S} c_x = \sum_{i=1}^k (u_{i-1} - u_i) \cdot \frac{1}{|S_i \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})|}$$

- Further, by definition of the **GREEDY-SET-COVER**:

$$|S_i \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})| \geq |S \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})| = u_{i-1}.$$

- Combining the last inequalities gives:

$$\begin{aligned} \sum_{x \in S} c_x &\leq \sum_{i=1}^k (u_{i-1} - u_i) \cdot \frac{1}{u_{i-1}} = \sum_{i=1}^k \sum_{j=u_i+1}^{u_{i-1}} \frac{1}{u_{i-1}} \\ &\leq \sum_{i=1}^k \sum_{j=u_i+1}^{u_{i-1}} \frac{1}{j} \\ &= \sum_{i=1}^k (H(u_{i-1}) - H(u_i)) \end{aligned}$$



Proof of Theorem 35.4 (2/2)

Proof of the Key Inequality $\sum_{x \in S} c_x \leq H(|S|)$

- For any $S \in \mathcal{F}$ and $i = 1, 2, \dots, |C| = k$ let $u_i := |S \setminus (S_1 \cup S_2 \cup \dots \cup S_i)|$
- $\Rightarrow |S| = u_0 \geq u_1 \geq \dots \geq u_{|C|} = 0$ and $u_{i-1} - u_i$ counts the items in S covered first time by S_i .

\Rightarrow

$$\sum_{x \in S} c_x = \sum_{i=1}^k (u_{i-1} - u_i) \cdot \frac{1}{|S_i \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})|}$$

- Further, by definition of the **GREEDY-SET-COVER**:

$$|S_i \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})| \geq |S \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})| = u_{i-1}.$$

- Combining the last inequalities gives:

$$\begin{aligned} \sum_{x \in S} c_x &\leq \sum_{i=1}^k (u_{i-1} - u_i) \cdot \frac{1}{u_{i-1}} = \sum_{i=1}^k \sum_{j=u_i+1}^{u_{i-1}} \frac{1}{u_{i-1}} \\ &\leq \sum_{i=1}^k \sum_{j=u_i+1}^{u_{i-1}} \frac{1}{j} \\ &= \sum_{i=1}^k (H(u_{i-1}) - H(u_i)) = H(u_0) - H(u_k) \end{aligned}$$



Proof of Theorem 35.4 (2/2)

Proof of the Key Inequality $\sum_{x \in S} c_x \leq H(|S|)$

- For any $S \in \mathcal{F}$ and $i = 1, 2, \dots, |C| = k$ let $u_i := |S \setminus (S_1 \cup S_2 \cup \dots \cup S_i)|$
- $\Rightarrow |S| = u_0 \geq u_1 \geq \dots \geq u_{|C|} = 0$ and $u_{i-1} - u_i$ counts the items in S covered first time by S_i .

\Rightarrow

$$\sum_{x \in S} c_x = \sum_{i=1}^k (u_{i-1} - u_i) \cdot \frac{1}{|S_i \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})|}$$

- Further, by definition of the **GREEDY-SET-COVER**:

$$|S_i \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})| \geq |S \setminus (S_1 \cup S_2 \cup \dots \cup S_{i-1})| = u_{i-1}.$$

- Combining the last inequalities gives:

$$\begin{aligned} \sum_{x \in S} c_x &\leq \sum_{i=1}^k (u_{i-1} - u_i) \cdot \frac{1}{u_{i-1}} = \sum_{i=1}^k \sum_{j=u_i+1}^{u_{i-1}} \frac{1}{u_{i-1}} \\ &\leq \sum_{i=1}^k \sum_{j=u_i+1}^{u_{i-1}} \frac{1}{j} \\ &= \sum_{i=1}^k (H(u_{i-1}) - H(u_i)) = H(u_0) - H(u_k) = H(|S|). \quad \square \end{aligned}$$



Set-Covering Problem (Summary)

Theorem 35.4

GREEDY-SET-COVER is a polynomial-time $\rho(n)$ -algorithm, where

$$\rho(n) = H(\max\{|S| : S \in \mathcal{F}\}) \leq \ln(n) + 1.$$



Set-Covering Problem (Summary)

The same approach also gives an approximation ratio of $O(\ln(n))$ if there exists a cost function $c : \mathcal{F} \rightarrow \mathbb{R}^+$

Theorem 35.4

GREEDY-SET-COVER is a polynomial-time $\rho(n)$ -algorithm, where

$$\rho(n) = H(\max\{|S| : S \in \mathcal{F}\}) \leq \ln(n) + 1.$$



Set-Covering Problem (Summary)

Theorem 35.4

GREEDY-SET-COVER is a polynomial-time $\rho(n)$ -algorithm, where

$$\rho(n) = H(\max\{|S| : S \in \mathcal{F}\}) \leq \ln(n) + 1.$$

- Is the bound on the approximation ratio in Theorem 35.4 **tight**?
- Is there a **better algorithm**?



Set-Covering Problem (Summary)

Theorem 35.4

GREEDY-SET-COVER is a polynomial-time $\rho(n)$ -algorithm, where

$$\rho(n) = H(\max\{|S| : S \in \mathcal{F}\}) \leq \ln(n) + 1.$$

- Is the bound on the approximation ratio in Theorem 35.4 **tight**?
- Is there a **better algorithm**?

Lower Bound

Unless $P=NP$, there is no $c \cdot \ln(n)$ polynomial-time approximation algorithm for some constant $0 < c < 1$.



Example where the solution of Greedy is bad

Instance

- Given any integer $k \geq 3$



Example where the solution of Greedy is bad

Instance

- Given any integer $k \geq 3$
- There are $n = 2^{k+1} - 2$ elements overall (so $k \approx \log_2 n$)

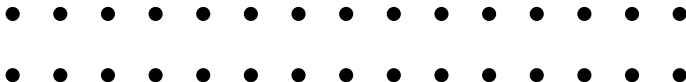


Example where the solution of Greedy is bad

Instance

- Given any integer $k \geq 3$
- There are $n = 2^{k+1} - 2$ elements overall (so $k \approx \log_2 n$)

$k = 4, n = 30$:

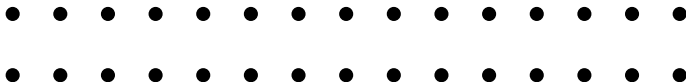


Example where the solution of Greedy is bad

Instance

- Given any integer $k \geq 3$
- There are $n = 2^{k+1} - 2$ elements overall (so $k \approx \log_2 n$)
- Sets S_1, S_2, \dots, S_k are pairwise disjoint and each set contains $2, 4, \dots, 2^k$ elements

$k = 4, n = 30$:

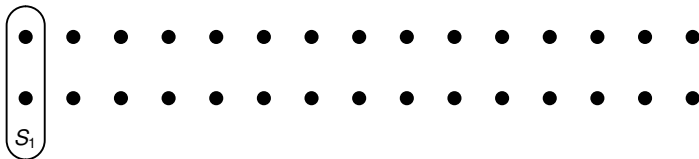


Example where the solution of Greedy is bad

Instance

- Given any integer $k \geq 3$
- There are $n = 2^{k+1} - 2$ elements overall (so $k \approx \log_2 n$)
- Sets S_1, S_2, \dots, S_k are pairwise disjoint and each set contains $2, 4, \dots, 2^k$ elements

$k = 4, n = 30$:

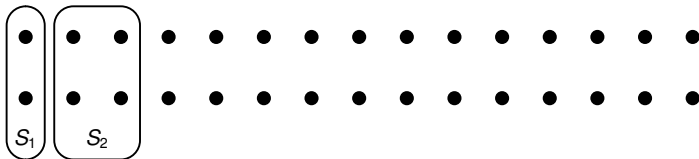


Example where the solution of Greedy is bad

Instance

- Given any integer $k \geq 3$
- There are $n = 2^{k+1} - 2$ elements overall (so $k \approx \log_2 n$)
- Sets S_1, S_2, \dots, S_k are pairwise disjoint and each set contains $2, 4, \dots, 2^k$ elements

$k = 4, n = 30$:

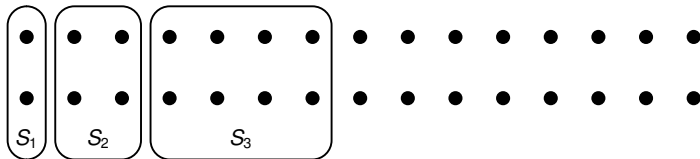


Example where the solution of Greedy is bad

Instance

- Given any integer $k \geq 3$
- There are $n = 2^{k+1} - 2$ elements overall (so $k \approx \log_2 n$)
- Sets S_1, S_2, \dots, S_k are pairwise disjoint and each set contains $2, 4, \dots, 2^k$ elements

$k = 4, n = 30$:

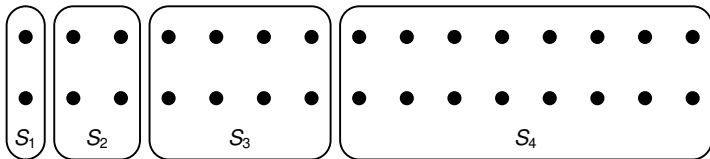


Example where the solution of Greedy is bad

Instance

- Given any integer $k \geq 3$
- There are $n = 2^{k+1} - 2$ elements overall (so $k \approx \log_2 n$)
- Sets S_1, S_2, \dots, S_k are pairwise disjoint and each set contains $2, 4, \dots, 2^k$ elements

$k = 4, n = 30$:

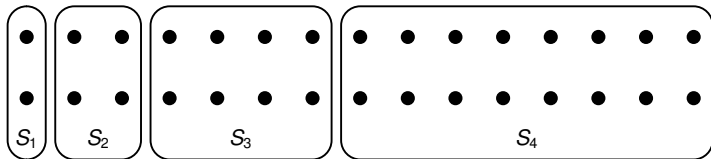


Example where the solution of Greedy is bad

Instance

- Given any integer $k \geq 3$
- There are $n = 2^{k+1} - 2$ elements overall (so $k \approx \log_2 n$)
- Sets S_1, S_2, \dots, S_k are pairwise disjoint and each set contains $2, 4, \dots, 2^k$ elements
- Sets T_1, T_2 are disjoint and each set contains half of the elements of each set S_1, S_2, \dots, S_k

$k = 4, n = 30$:

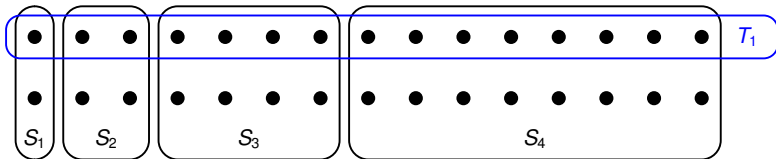


Example where the solution of Greedy is bad

Instance

- Given any integer $k \geq 3$
- There are $n = 2^{k+1} - 2$ elements overall (so $k \approx \log_2 n$)
- Sets S_1, S_2, \dots, S_k are pairwise disjoint and each set contains $2, 4, \dots, 2^k$ elements
- Sets T_1, T_2 are disjoint and each set contains half of the elements of each set S_1, S_2, \dots, S_k

$k = 4, n = 30$:

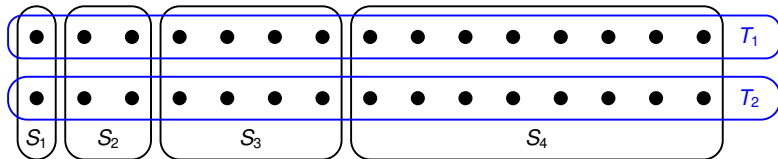


Example where the solution of Greedy is bad

Instance

- Given any integer $k \geq 3$
- There are $n = 2^{k+1} - 2$ elements overall (so $k \approx \log_2 n$)
- Sets S_1, S_2, \dots, S_k are pairwise disjoint and each set contains $2, 4, \dots, 2^k$ elements
- Sets T_1, T_2 are disjoint and each set contains half of the elements of each set S_1, S_2, \dots, S_k

$k = 4, n = 30$:

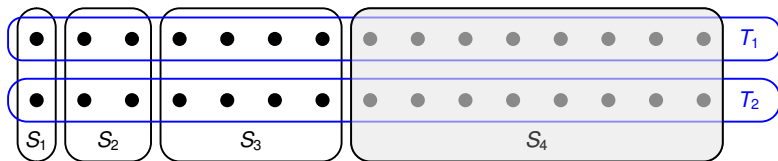


Example where the solution of Greedy is bad

Instance

- Given any integer $k \geq 3$
- There are $n = 2^{k+1} - 2$ elements overall (so $k \approx \log_2 n$)
- Sets S_1, S_2, \dots, S_k are pairwise disjoint and each set contains $2, 4, \dots, 2^k$ elements
- Sets T_1, T_2 are disjoint and each set contains half of the elements of each set S_1, S_2, \dots, S_k

$k = 4, n = 30$:

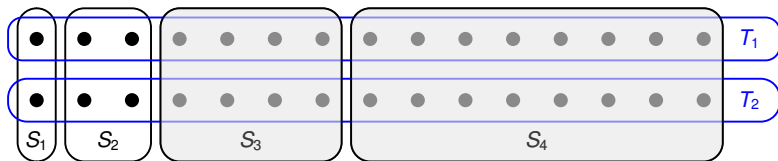


Example where the solution of Greedy is bad

Instance

- Given any integer $k \geq 3$
- There are $n = 2^{k+1} - 2$ elements overall (so $k \approx \log_2 n$)
- Sets S_1, S_2, \dots, S_k are pairwise disjoint and each set contains $2, 4, \dots, 2^k$ elements
- Sets T_1, T_2 are disjoint and each set contains half of the elements of each set S_1, S_2, \dots, S_k

$k = 4, n = 30$:

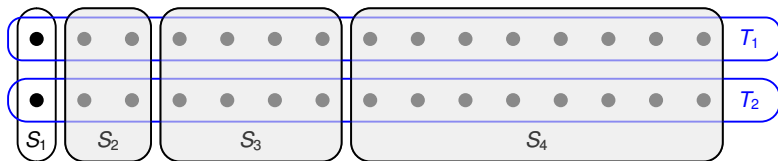


Example where the solution of Greedy is bad

Instance

- Given any integer $k \geq 3$
- There are $n = 2^{k+1} - 2$ elements overall (so $k \approx \log_2 n$)
- Sets S_1, S_2, \dots, S_k are pairwise disjoint and each set contains $2, 4, \dots, 2^k$ elements
- Sets T_1, T_2 are disjoint and each set contains half of the elements of each set S_1, S_2, \dots, S_k

$k = 4, n = 30$:

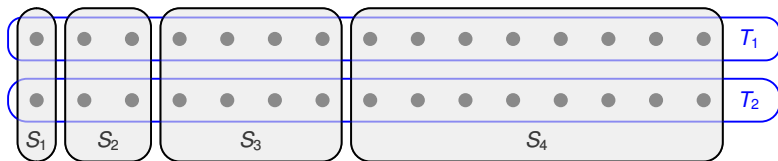


Example where the solution of Greedy is bad

Instance

- Given any integer $k \geq 3$
- There are $n = 2^{k+1} - 2$ elements overall (so $k \approx \log_2 n$)
- Sets S_1, S_2, \dots, S_k are pairwise disjoint and each set contains $2, 4, \dots, 2^k$ elements
- Sets T_1, T_2 are disjoint and each set contains half of the elements of each set S_1, S_2, \dots, S_k

$k = 4, n = 30$:

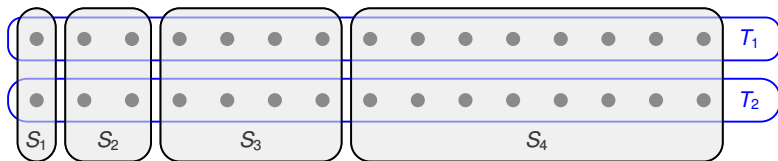


Example where the solution of Greedy is bad

Instance

- Given any integer $k \geq 3$
- There are $n = 2^{k+1} - 2$ elements overall (so $k \approx \log_2 n$)
- Sets S_1, S_2, \dots, S_k are pairwise disjoint and each set contains $2, 4, \dots, 2^k$ elements
- Sets T_1, T_2 are disjoint and each set contains half of the elements of each set S_1, S_2, \dots, S_k

$k = 4, n = 30$:



Solution of Greedy consists of k sets.

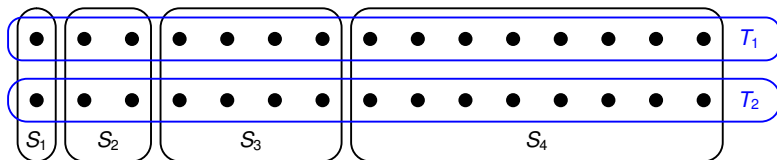


Example where the solution of Greedy is bad

Instance

- Given any integer $k \geq 3$
- There are $n = 2^{k+1} - 2$ elements overall (so $k \approx \log_2 n$)
- Sets S_1, S_2, \dots, S_k are pairwise disjoint and each set contains $2, 4, \dots, 2^k$ elements
- Sets T_1, T_2 are disjoint and each set contains half of the elements of each set S_1, S_2, \dots, S_k

$k = 4, n = 30$:



Solution of Greedy consists of k sets.

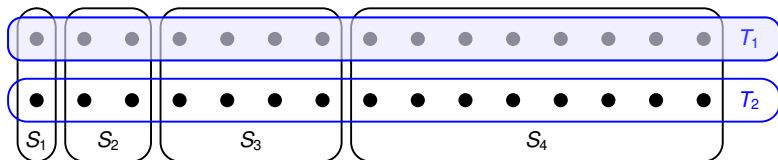


Example where the solution of Greedy is bad

Instance

- Given any integer $k \geq 3$
- There are $n = 2^{k+1} - 2$ elements overall (so $k \approx \log_2 n$)
- Sets S_1, S_2, \dots, S_k are pairwise disjoint and each set contains $2, 4, \dots, 2^k$ elements
- Sets T_1, T_2 are disjoint and each set contains half of the elements of each set S_1, S_2, \dots, S_k

$k = 4, n = 30$:



Solution of Greedy consists of k sets.

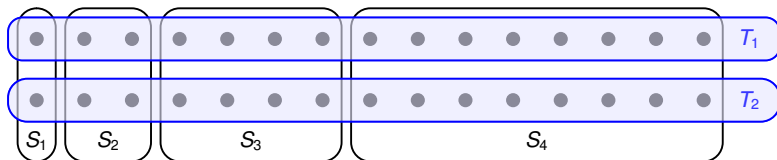


Example where the solution of Greedy is bad

Instance

- Given any integer $k \geq 3$
- There are $n = 2^{k+1} - 2$ elements overall (so $k \approx \log_2 n$)
- Sets S_1, S_2, \dots, S_k are pairwise disjoint and each set contains $2, 4, \dots, 2^k$ elements
- Sets T_1, T_2 are disjoint and each set contains half of the elements of each set S_1, S_2, \dots, S_k

$k = 4, n = 30$:



Solution of Greedy consists of k sets.

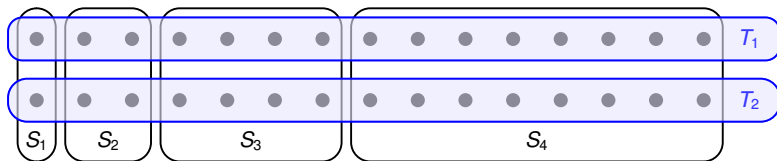


Example where the solution of Greedy is bad

Instance

- Given any integer $k \geq 3$
- There are $n = 2^{k+1} - 2$ elements overall (so $k \approx \log_2 n$)
- Sets S_1, S_2, \dots, S_k are pairwise disjoint and each set contains $2, 4, \dots, 2^k$ elements
- Sets T_1, T_2 are disjoint and each set contains half of the elements of each set S_1, S_2, \dots, S_k

$k = 4, n = 30$:



Solution of Greedy consists of k sets.

Optimum consists of 2 sets.





Exercise: Consider the vertex cover problem, restricted to a graph where every vertex has exactly 3 neighbours. Which approximation ratio can we obtain?

1. 1 (i.e., I can solve it exactly!!!)
2. 2
3. $11/6 = 2 - 1/6$
4. $H(n) \leq \log(n)$