

Topics in Concurrency

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Concurrency and distribution

- Computation has become increasingly distributed, concurrent and interactive
 - boundaries of computation becoming increasingly unclear,
 - behaviour of systems increasingly difficult to reproduce
- \rightsquigarrow problems such as how to structure and understand distributed computation, how to ensure correctness (e.g. security) of processes in an uncontrolled environment
- Concurrency theory is a broad and active field for research, but
- Present ideas of process and logics for distributed computation are unsettled . . .

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- Present ideas of process and logics for distributed computation are unsettled . . . However there are attempts:

topics in concurrency

- Theories of processes, logics & model checking, security
- Unification through strategies in concurrent/distributed games (new)

Topics in Concurrency

- Simple parallelism and non-determinism
- Communicating processes
 - Milner's CCS (Calculus of Communicating Systems)
 - Bisimulation
- Specification logics for processes
 - modal μ -calculus
 - CTL
 - model checking
- Petri nets
 - events, causal dependence, independence
- Security protocols
 - SPL (Security Protocol Language)
 - Petri net semantics
 - Proofs of secrecy and authentication
- Event structures
- Concurrent games - processes as strategies

[Concurrency workbench]

Chapter 1 in the lecture notes revises relevant topics from Discrete Mathematics (well-founded induction and Tarski's fixed point theorem).

While programs

Similar to L1 from *Semantics of Programming Languages*:

$c ::= \text{skip} \mid X := a \mid \text{if } b \text{ then } c_1 \text{ else } c_2 \mid c_0; c_1 \mid \text{while } b \text{ do } c$

- States $\sigma \in \Sigma$ are functions from locations to values
- Configurations: $\langle c, \sigma \rangle$ and σ
- Rules describe a single step of execution:

$$\frac{\langle c_0, \sigma \rangle \rightarrow \langle c'_0, \sigma' \rangle}{\langle c_0; c_1, \sigma \rangle \rightarrow \langle c'_0; c_1, \sigma' \rangle} \qquad \frac{\langle c_0, \sigma \rangle \rightarrow \sigma'}{\langle c_0; c_1, \sigma \rangle \rightarrow \langle c_1, \sigma' \rangle}$$

$$\frac{\langle b, \sigma \rangle \rightarrow \text{true} \quad \langle c, \sigma \rangle \rightarrow \langle c', \sigma' \rangle}{\langle \text{while } b \text{ do } c, \sigma \rangle \rightarrow \langle c'; \text{while } b \text{ do } c, \sigma' \rangle}$$

\vdots

Parallel commands

Syntax extended with parallel composition:

$$c ::= \dots \mid c_0 \parallel c_1$$

Rules:

$$\frac{\langle c_0, \sigma \rangle \rightarrow \langle c'_0, \sigma' \rangle}{\langle c_0 \parallel c_1, \sigma \rangle \rightarrow \langle c'_0 \parallel c_1, \sigma' \rangle}$$

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- Parallelism \rightsquigarrow Non-determinism
- Behaviour of \parallel -commands not a partial function from states to states; when are two \parallel -commands equivalent? [Congruence?]
- Parallelism by non-deterministic interleaving
- “communication by shared variables”

*Study of parallelism (or concurrency)
includes
study of non-determinism*

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What about the converse?

*Can we explain parallelism (or concurrency)
in terms of non-determinism?*

The language of Guarded Commands (Dijkstra)

- Boolean expressions: b
- Arithmetic expressions: a
- Commands:

$$c ::= \text{skip} \mid \text{abort} \mid X := a \mid c_0; c_1 \mid \text{if } gc \text{ fi} \mid \text{do } gc \text{ od}$$

- Guarded commands:

$$\begin{array}{ll} gc & ::= \quad b \rightarrow c & \text{guard} \\ & \mid gc_0 \parallel gc_1 & \text{alternative} \end{array}$$

Operational semantics

- Assume given rules for evaluating Booleans and assignments.
- **Guarded commands:**

$$\frac{\langle b, \sigma \rangle \rightarrow true}{\langle b \rightarrow c, \sigma \rangle \rightarrow \langle c, \sigma \rangle}$$

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introduces non-determinism

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$$\frac{\langle b, \sigma \rangle \rightarrow false}{\langle b \rightarrow c, \sigma \rangle \rightarrow fail}$$

$$\frac{\langle gc_0, \sigma \rangle \rightarrow fail \quad \langle gc_1, \sigma \rangle \rightarrow fail}{\langle gc_0 \parallel gc_1, \sigma \rangle \rightarrow fail}$$

fail is a new configuration

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$$\frac{\langle gc_0, \sigma \rangle \rightarrow fail \quad \langle gc_1, \sigma \rangle \rightarrow fail}{\langle gc_0 \parallel gc_1, \sigma \rangle \rightarrow fail}$$

- **Commands:**

abort has no rules

- **Conditional:**

$$\frac{\langle gc, \sigma \rangle \rightarrow \langle c, \sigma' \rangle}{\langle \text{if } gc \text{ fi}, \sigma \rangle \rightarrow \langle c, \sigma' \rangle}$$

no rule in case $\langle gc, \sigma \rangle \rightarrow \text{fail}$; then conditional behaves like **abort**

- **Loop:**

$$\frac{\langle gc, \sigma \rangle \rightarrow \text{fail}}{\langle \text{do } gc \text{ od}, \sigma \rangle \rightarrow \sigma}$$

$$\frac{\langle gc, \sigma \rangle \rightarrow \langle c, \sigma' \rangle}{\langle \text{do } gc \text{ od}, \sigma \rangle \rightarrow \langle c; \text{do } gc \text{ od}, \sigma' \rangle}$$

in case $\langle gc, \sigma \rangle \rightarrow \text{fail}$, the loop behaves like **skip**:

$$\langle \text{skip}, \sigma \rangle \rightarrow \sigma$$

The process

$$\text{do } b_1 \rightarrow c_1 \parallel \dots \parallel b_n \rightarrow c_n \text{ od}$$

is a form of (non-deterministically interleaved) parallel composition

$$\boxed{b_1 \rightarrow c_1} \parallel \dots \parallel \boxed{b_n \rightarrow c_n}$$

in which each c_i occurs atomically (i.e. uninterruptedly) provided b_i holds each time it starts

→ UNITY (Misra and Chandy)
Hardware languages (Staunstrup)

Examples

- Computing maximum:

```
if
   $X \geq Y \rightarrow MAX = X$ 
[]
   $Y \geq X \rightarrow MAX = Y$ 
fi
```

- Euclid's algorithm:

```
do
   $X > Y \rightarrow X := X - Y$ 
[]
   $Y > X \rightarrow Y := Y - X$ 
od
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if
   $X \geq Y \rightarrow MAX = X$ 
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Have

$$\{X = m \wedge Y = n \wedge m > 0 \wedge n > 0\}$$

Euclid

$$\{X = Y = \gcd(m, n)\}$$

... guarded commands support a neat Hoare-style logic

- Recalling:

$$\gcd(m, n) \mid m, n$$

and

$$\ell \mid m, n \implies \ell \mid \gcd(m, n)$$

- Invariant:

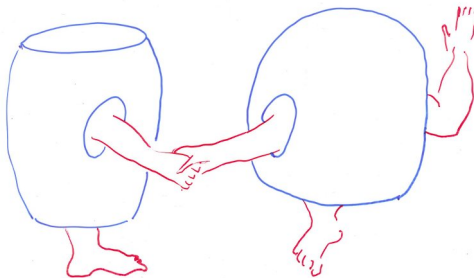
$$\gcd(m, n) = \gcd(X, Y)$$

On exiting loop, $X = Y$.

- Key properties:

$$\begin{aligned}\gcd(m, n) &= \gcd(m - n, n) && \text{if } m > n \\ \gcd(m, n) &= \gcd(m, n - m) && \text{if } n > m \\ \gcd(m, m) &= m\end{aligned}$$

Synchronized communication (Hoare, Milner)



Communication by “handshake”,
with possible exchange of value,
localised to process-process (CSP)
or to a channel (CCS, OCCAM)

[Abstracts away from the protocol underlying coordination/“handshake”
in the implementation]

Extending GCL with synchronization

- Allow processes to send and receive values on channels

$\alpha!a$ evaluate expression a and send value on channel α

$\alpha?X$ receive value on channel α and store it in X

- All interaction between parallel processes is by sending / receiving values on channels
- Communication is **synchronized** and only one process listening on the channel may receive the message
- Allow send and receive in commands c and in guards g :

$\text{do } \underbrace{Y < 100 \wedge \alpha?X}_{g} \rightarrow \underbrace{\alpha!(X * X) \parallel Y := Y + 1}_{c} \text{ od}$ is allowed

- Language close to OCCAM and CSP

Extending GCL with synchronization

Transitions may now carry labels when possibility of interaction with another process.

$$\frac{}{\langle \alpha?X, \sigma \rangle \xrightarrow{\alpha?n} \sigma[n/X]} \qquad \frac{\langle a, \sigma \rangle \rightarrow n}{\langle \alpha!a, \sigma \rangle \xrightarrow{\alpha!n} \sigma}$$

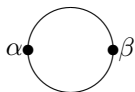
$$\frac{\langle c_0, \sigma \rangle \xrightarrow{\lambda} \langle c'_0, \sigma' \rangle}{\langle c_0 \parallel c_1, \sigma \rangle \xrightarrow{\lambda} \langle c'_0 \parallel c_1, \sigma' \rangle} \quad (\lambda \text{ might be empty label}) + \text{symmetric}$$

$$\frac{\langle c_0, \sigma \rangle \xrightarrow{\alpha?n} \langle c'_0, \sigma' \rangle \quad \langle c_1, \sigma \rangle \xrightarrow{\alpha!n} \langle c'_1, \sigma' \rangle}{\langle c_0 \parallel c_1, \sigma \rangle \rightarrow \langle c'_0 \parallel c'_1, \sigma' \rangle} + \text{symmetric}$$

$$\frac{\langle c, \sigma \rangle \xrightarrow{\lambda} \langle c', \sigma' \rangle}{\langle c \setminus \alpha, \sigma \rangle \xrightarrow{\lambda} \langle c' \setminus \alpha, \sigma' \rangle} \quad \lambda \neq \alpha?n \text{ or } \alpha!n$$

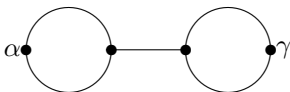
Examples

- forwarder:



$\text{do } \alpha?X \rightarrow \beta!X \text{ od}$

- buffer capacity 2:

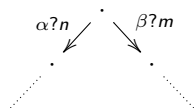


$(\text{do } \alpha?X \rightarrow \beta!X \text{ od} \\ \parallel \text{do } \beta?X \rightarrow \gamma!X \text{ od}) \setminus \beta$

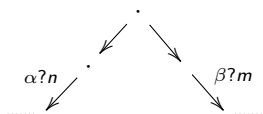
Branching: internal vs external choice

- Compare:

$\text{if } (true \wedge \alpha?X \rightarrow c_0) \parallel (true \wedge \beta?X \rightarrow c_1) \text{ fi}$



$\text{if } (true \rightarrow (\alpha?X; c_0)) \parallel (true \rightarrow (\beta?X; c_1)) \text{ fi}$



- Not equivalent processes w.r.t. their deadlock capabilities.