## 1 Example Class (23rd May 2019, 16.15-17.30)

Question 1. We consider the KNAPSACK-problem, where we are given $n$ items each of which comes with an integral weight $w_{i}>0$ and integral value $v_{i}>0$. The knapsack has capacity $C$ and the goal is to fill the knapsack so as to maximise its total value. Further, we denote by $O P T \leq \max \left\{C, \sum_{i=1}^{n} v_{i}\right\}$ the value obtained by an optimal solution. As a side remark, we may assume that for all items $1 \leq i \leq n, w_{i} \leq C$.

1. Design a simple ("the arguably most natural") greedy algorithm and analyse its approximation ratio.
2. Consider a modified greedy algorithm, which takes the better solution of the algorithm from Part 1 and item with the largest value. Prove that the approximation ratio of this new algorithm is two.
Hint: One way of establishing this approximation ratio involves the following steps:
(a) First define a LP relaxation of the knapsack problem.
(b) Find the optimum solution of the LP relaxation.
(c) Use the result from (b) to argue that the solution of the algorithm is within a factor of two of the optimum LP solution.
3. Consider the dynamic programming technique. Derive two algorithms based on this technique that achieve a runtime of $O(n \cdot C)$ and $O(n \cdot O P T)$, respectively. (Question: Why are both of these algorithms not polynomial-time?)
4. Design a FPTAS based on the second dynamic programming algorithm with runtime $O\left(n^{3} / \epsilon\right)$.
Hint: Round down all values so that they will lie in a suitable range (depending of course on $\epsilon>0$ !).

Answer 1. 1. The most natural greedy algorithm is to sort all items non-increasingly according to their value/weight ratio:

$$
\frac{v_{1}}{w_{1}} \geq \frac{v_{2}}{w_{2}} \geq \cdots \geq \frac{v_{n}}{w_{n}},
$$

and then greedily taking as many items as possible as long as we are not exceeding the capacity $C$.
Unfortunately the approximation ratio can be arbitrarily bad. Consider, for example, the following instance: $w_{1}=1, v_{1}=2, w_{2}=C, v_{2}=C$. The greedy algorithm would only return a solution with value 2 , whereas the optimum solution would achieve a value of $C$.
2. (a) We will be working with the same ordering of the $n$ items according to their value/weight ratio as in the previous part. With this, the LP-relaxation looks
as follows:

$$
\begin{array}{ll}
\text { maximize } & \sum_{i=1}^{n} v_{i} y_{i} \\
\text { subject to } & \sum_{i=1}^{n} w_{i} y_{i} \leq C \\
& 0 \leq y_{i} \leq 1 \quad \text { for all } 1 \leq i \leq n
\end{array}
$$

(b) The optimal solution of this LP will assign as much value as possible to the items with largest value/weight ratio and fill the knapsack exactly up to $C$ (this is a.k.a. fractional knapsack problem). Therefore the optimum $y^{*}$ satisfies, $y_{1}^{*}=1, y_{2}^{*}=1, \ldots, y_{k-1}^{*}=1, y_{k}^{*}=\frac{C-\left(w_{1}+w_{2}+\cdots+w_{k-1}\right)}{w_{k}}$, where $k$ is the largest integer such that $w_{1}+w_{2}+\cdots+w_{k-1} \leq C$.
(c) Note that the unmodified greedy algorithm would yield a profit of $v_{1}+v_{2}+$ $\cdots+v_{k-1}$. Further, the modified greedy algorithm would yield a profit of $\max \left\{v_{1}+v_{2}+\cdots+v_{k-1}, v_{\max }\right\}$, where $v_{\text {max }}$ is the value of the most valuable item (recall that we have made the assumption that $v_{\max } \leq C$, so taking the most valuable item is always feasible!). Since $v_{\max } \geq v_{k}$, the profit of the modified greedy algorithm is a least

$$
\max \left\{v_{1}+v_{2}+\cdots+v_{k-1}, v_{k}\right\} \geq \frac{1}{2} \cdot\left(v_{1}+v_{2}+\cdots+v_{k}\right)
$$

On the other hand, the objective value of the optimal LP is

$$
v_{1}+v_{2}+\cdots+v_{k-1}+\underbrace{\frac{C-\left(w_{1}+w_{2}+\cdots+w_{k-1}\right)}{w_{k}}}_{\leq 1} \cdot v_{k} \leq v_{1}+v_{2}+\cdots+v_{k} .
$$

Hence the approximation ratio of the modified greedy algorithm is at most 2 .
3. For the first dynamic programming solution, let opt $(j, c)$ be the optimal knapsack solution restricted to items $\{1,2, \ldots, j\}$ and capacity $c \leq C$. To find a recurrence formula for $\operatorname{opt}(j, c)$, consider the $j$-th item and note that this item could be part of a optimal solution or not (or possibly both):

$$
\operatorname{opt}(j, c)= \begin{cases}0 & \text { if } j=0 \\ \operatorname{opt}(j-1, c) & \text { if } w_{j}>c, \\ \max \left\{\operatorname{opt}(j-1, c), v_{j}+\operatorname{opt}\left(j-1, c-w_{j}\right)\right\} & \text { otherwise }\end{cases}
$$

This directly leads to a $O(n \cdot C)$ algorithm by filling values of a two-dimensional array with dimensions $n$ and $C$.
The second dynamic programming approach will take a "dual" approach. We let $\operatorname{opt}(j, v)$ be the minimum knapsack weight that yields a total value of exactly $v$ using
only the items in $\{1,2, \ldots, j\}$. For the recurrence formula, the two cases are again whether a optimal solution includes item $j$ or not:

$$
\operatorname{opt}(j, v)= \begin{cases}0 & \text { if } j=0 \\ \operatorname{opt}(j-1, v) & \text { if } v_{j}>v \\ \min \left\{o p t(j-1, v), w_{j}+\operatorname{opt}\left(j-1, v-v_{j}\right)\right\} & \text { otherwise }\end{cases}
$$

(Notice the switch of the roles of $w_{j}$ and $v_{j}$ compared to the first dynamic programming solution.) Again, using a bottom-up approach, all values for opt $(j, v)$ with $1 \leq j \leq n$ and $1 \leq v \leq O P T$ can be computed leading to an algorithm with running time $O(n \cdot O P T)$ (Although it is not strictly needed for the PTAS, this running time can be achieved by computing all values up until opt $\left(n, O P T+v_{\max }\right)$ and stopping when $\operatorname{opt}(n,$.$) does not change. Note that O P T+v_{\max } \leq 2 O P T$ thanks to the assumption on $v_{\text {max }}$ )
Both algorithms are not polynomial-time, since the running time is not polynomial in the input-size (for that, the dependence should be poly-logarithmic in $C$ or $O P T$ !).
We will now describe a FPTAS for the Knapsack Problem.
$\operatorname{KNAPSACK-FPTAS}\left(\epsilon, n, C, v_{1}, v_{2}, \ldots, v_{n}, w_{1}, w_{2}, \ldots, w_{n}\right)$
: For each item $i=1,2, \ldots, n$ set $\bar{v}_{i}=\left\lfloor\frac{v_{i}}{\alpha}\right\rfloor$, where $\alpha=\frac{\epsilon \cdot v_{\max }}{n}$ is the scaling factor.
: Run the exact dynamic programming algorithm on the rounded instance to obtain a subset $\bar{S}^{*}$
3: Return $\bar{S}^{*}$
Let us now analyse this algorithm, first the runtime and then the approximation ratio.

- Running Time. Recall that the exact dynamic programming algorithm has a runtime of $O(n \cdot \overline{O P T})$. The optimum solution of the rounded instance is at most $\overline{O P T} \leq n \cdot n \cdot \bar{v}_{\max }=n^{2} \cdot\lfloor 1 / \epsilon \cdot n\rfloor=O\left(n^{3} / \epsilon\right)$.
- Approximation Ratio. Let $S^{*} \subseteq\{1, \ldots, n\}$ be the optimal set of items in the original instance and $\bar{S}^{*} \subseteq\{1, \ldots, n\}$ be the optimal set of items in the rounded instance. Note that $\sum_{i \in \bar{S}^{*}} v_{i}$ is the value of the computed solution. Then,

$$
\begin{array}{rlr}
\sum_{i \in \bar{S}^{*}} v_{i} & \geq \sum_{i \in \bar{S}^{*}} \alpha \cdot \bar{v}_{i} & \quad \text { (by definition of the rounded instance) } \\
& \geq \sum_{i \in S^{*}} \alpha \cdot \bar{v}_{i} \quad \quad \text { (since } \bar{S}^{*} \text { is the optimum for the rounded instance) } \\
& \geq \sum_{i \in S^{*}}\left(v_{i}-\alpha\right) & \quad \text { (by the definition of scaling) } \\
& \geq \sum_{i \in S^{*}} v_{i}-\alpha \cdot n \\
& \geq O P T-\frac{\epsilon \cdot v_{\max }}{n} \cdot n \\
& \geq O P T-\frac{\epsilon \cdot O P T}{n} \cdot n \\
& =(1-\epsilon) \cdot O P T, & \left.\quad \text { (since } v_{\max } \leq O P T\right)
\end{array}
$$

where in the third inequality we have used the simple fact that $\lfloor x / \alpha\rfloor \geq x / \alpha-1$ implies $\alpha \cdot\lfloor x / \alpha\rfloor \geq x-\alpha$.

