

Mixed Initiative Interaction

MPhil ACS module R230 - Alan Blackwell

http://iui.acm.org/2018/accepted_papers.html

- ▶ "Improved Answers Ranking by Rewriting Question"
- ▶ "Two Tools are Better Than One: Tool Diversity as a Means of Improving Aggregate Crowd Performance"
- ▶ "AnchorViz: Facilitating Classifier Error Discovery through Interactive Semantic Data Exploration"
- ▶ "A Model for Detecting and Locating Behaviour Changes in Mobile Touch Targeting Sequences"
- ▶ "An Interactive Relevance Feedback Interface for Evidence-Based Health Care"
- ▶ "Cubicle: An Adaptive Educational Gaming Platform for Training Spatial Visualization Skills"
- ▶ "Personal Recommendations for Raising Social Eminence in an Enterprise"
- ▶ "Session-based Suggestion of Topics for Geographic Exploratory Search"
- ▶ "Aging and Engaging: A Social Conversational Skills Training Program for Older Adults"
- ▶ "Beyond the Ranked List: User-Driven Exploration and Diversification of Social Recommendation"
- ▶ "Can a Helmet-mounted Display Make Motorcycling Safer?"
- ▶ "Interactive Document Clustering Revisited: A Visual Analytics Approach"
- ▶ "Closing the Loop: User-Centered Design and Evaluation of a Human-in-the-Loop Topic Modeling System"
- ▶ "Ensemble Recommendations via Thompson Sampling: An Experimental Study within e-Commerce"
- ▶ "Opportunity Team Builder for Sales Teams"

What is Mixed Initiative?

A classic example of mixed initiative – predictive text

- ▶ Demo with discussion: Dasher

Principles of Mixed-Initiative User Interfaces

- ▶ Classic paper by Eric Horvitz:
 - ▶ Principles of mixed-initiative user interfaces.
 - ▶ In proceedings CHI 1999, pp. 159-166.
- ▶ Advocates elegant coupling of *automated services* with *direct manipulation*
- ▶ Autonomous actions should be taken only when an agent believes that they will have greater expected value than inaction for the user.

How to add value with automation

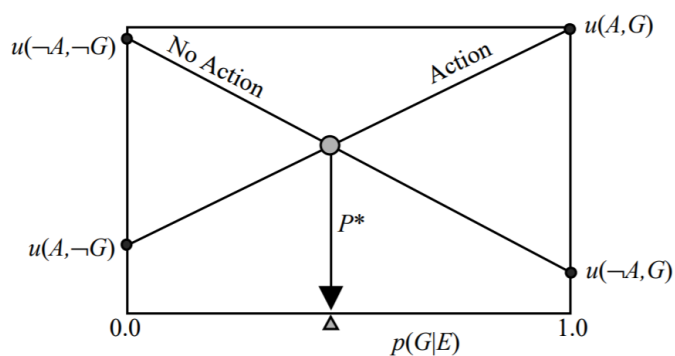
- ▶ Consider uncertainty about user's goals
- ▶ Consider status of user's attention in timing services
 - ▶ with cost/benefit of deferring action to a time when action will be less distracting.
- ▶ Infer ideal action in light of costs, benefits, and uncertainties
- ▶ Employ dialog to resolve key uncertainties
 - ▶ consider costs of bothering user needlessly
- ▶ Allow efficient direct invocation and termination
- ▶ Minimise cost of poor guesses about action and timing

Expected utility of automated action

- ▶ assume an agent can infer $p(G|E)$
 - ▶ likelihood of the user's goal
 - ▶ given observed evidence

	Desired Goal	Not Desired
Action	$u(A, G)$	$u(A, \neg G)$
No Action	$u(\neg A, G)$	$u(\neg A, \neg G)$

Expected utility threshold for action



A probabilistic view of user interaction (from Part II HCI)

- ▶ **Machine:**
 - ▶ I know how to do several things.
 - ▶ I wonder which one the user wants me to do?
- ▶ **User:**
 - ▶ This machine can do a whole bunch of stuff.
 - ▶ What is most likely to make it do the right stuff?
- ▶ **Machine:**
 - ▶ I think the user has made a mistake
- ▶ **User:**
 - ▶ I think the machine has made a mistake

Bayes theorem (for Bayesian inference)

Posterior probability of
Hypothesis *after* taking
new Evidence into account

Prior inferred probability of
this Hypothesis *before* new
Evidence became available.

If Hypothesis is true, how
likely is it that we would see
this Evidence?

$$P(H|E) = \frac{P(E|H) P(H)}{P(E)}$$

What is the probability of
seeing E, under all possible
hypotheses?

▶ H: Hypothesis
E: Evidence

Bayesian inference inference of user intention

Probability that user wants to delete all files, given that they just typed 'rm -rf'

(Prior) probability that user wanted to delete all files *before* we saw this.

If user does want to delete all files, how *likely* is it that they would type 'rm -rf'?

$$P(D|R) = \frac{P(R|D) P(D)}{P(R)}$$

What is the probability user would type 'rm -rf', under all possible hypotheses?

▶ D: User wants to **D**delete all their files
R: User has typed 'rm -rf'

Another classic example of mixed initiative

▶ <https://www.youtube.com/watch?v=0ej4tW7hLkE>

It looks like you're writing a letter.

Would you like help?

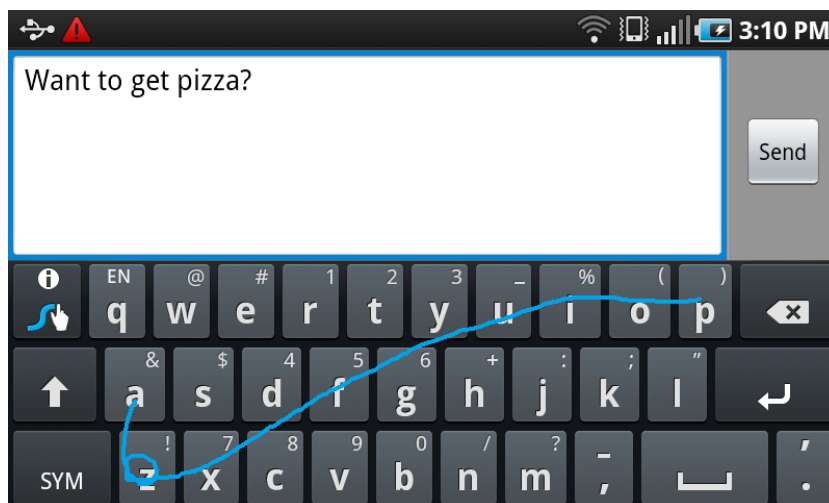
- Get help with writing the letter
- Just type the letter without help
- Don't show me this tip again

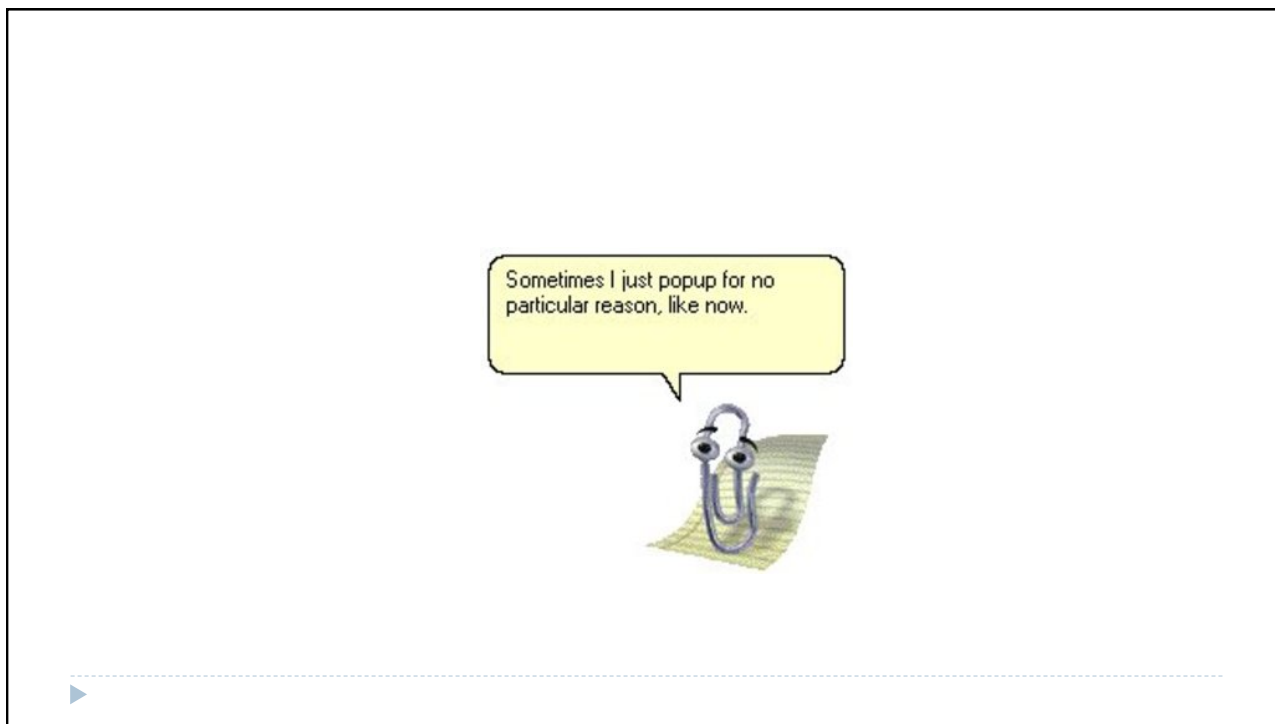


Unobtrusive direct manipulation strategy: semantic pointing



Unobtrusive direct manipulation strategy: gesture keyboard



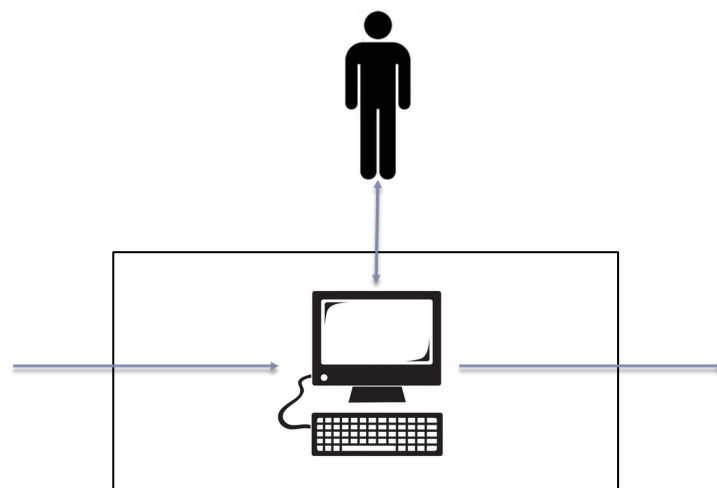


Information flow and mixed initiative

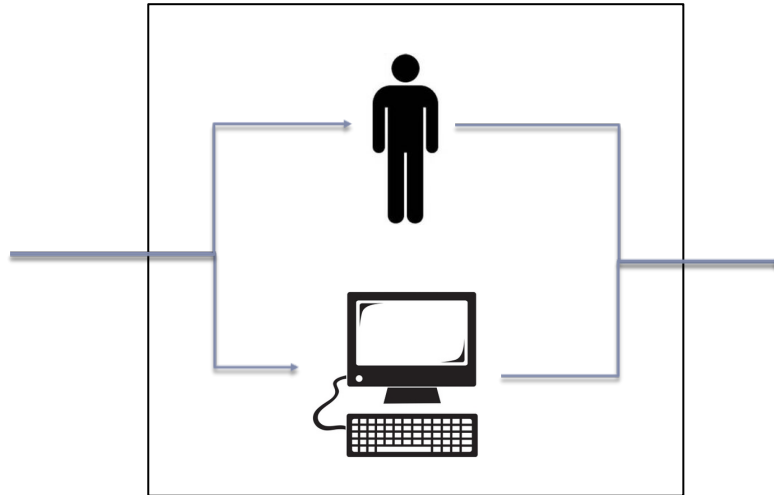
System boundaries – autonomous vehicle case

- ▶ Where does information enter the system?
 - ▶ User defines setpoint (“cruise control”)
 - ▶ Supplier offers features (“active braking”)
 - ▶ Regulator defines policy (“following distance”)
 - ▶ Government provides infrastructure (“lane markings”)
- ▶ Notes:
 - ▶ Even if the system includes “autonomous” closed loop control algorithms, information is acquired through more or less costly interactive processes outside the system boundary.
 - ▶ All closed loop control systems do machine learning (reacting to error signal, tuning gain and stability etc), but as interaction with such systems becomes routine, these *cybernetic* components are no longer considered intelligent.

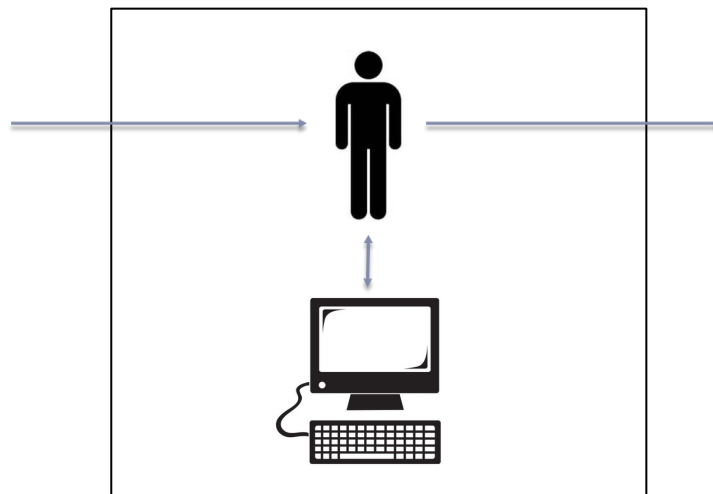
Conventional system design



Hybrid system design



Human-centric system design



Studying Agency and Control

The **experience of agency** is defined as:

- ▶ *The experience of controlling one's own actions and, through this control, affecting the external world.*
- ▶ It is the experience of ourselves as agents that allows us to instinctively say:

“I did that”

Haggard, P. & Tsakiris, M., *The Experience of Agency: Feelings, Judgments, and Responsibility*.
Current Directions in Psychological Science, 2009.

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Fact vs. the experience of agency

- ▶ Passivity phenomena in schizophrenia
 - ▶ People feel that their actions - and sometimes their thoughts and emotions - are not under their own control. Rather they are under the control of some external force or agent.
- ▶ Mellor reports on a patient with schizophrenia saying:

“It is my hand and arm that move, and my fingers pick up the pen, but I don’t control them.”

Mellor, C.S., First rank symptoms of schizophrenia. Br J Psychiatry, 1970.

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Golden rules of HCI

Rule no. 7: “Support an internal locus of control”

This rule is based on the observation that:

“Users strongly desire the sense that they are in charge of the system and that the system responds to their actions.”

*Shneiderman, B. & Plaisant, C. 2009
Designing the User Interface: Strategies for Effective Human-Computer Interaction.*

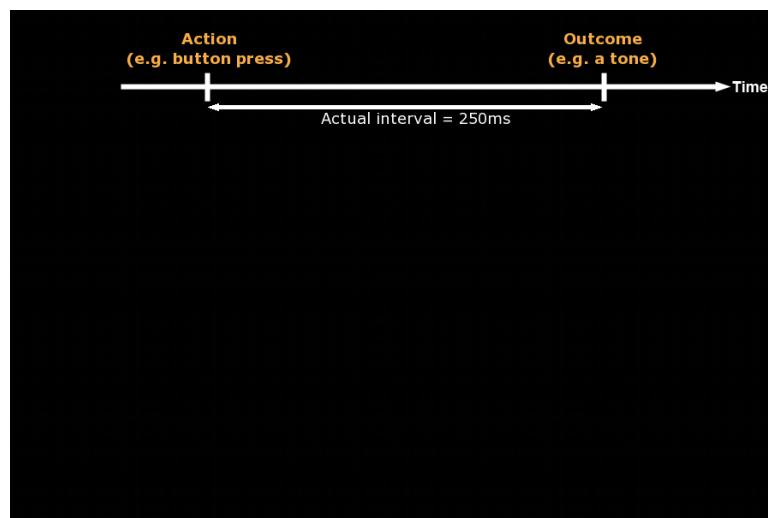
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Developing a research agenda

- ▶ An implicit metric to measure peoples' experience of agency.
- ▶ Two experiments that apply this metric in HCI contexts.

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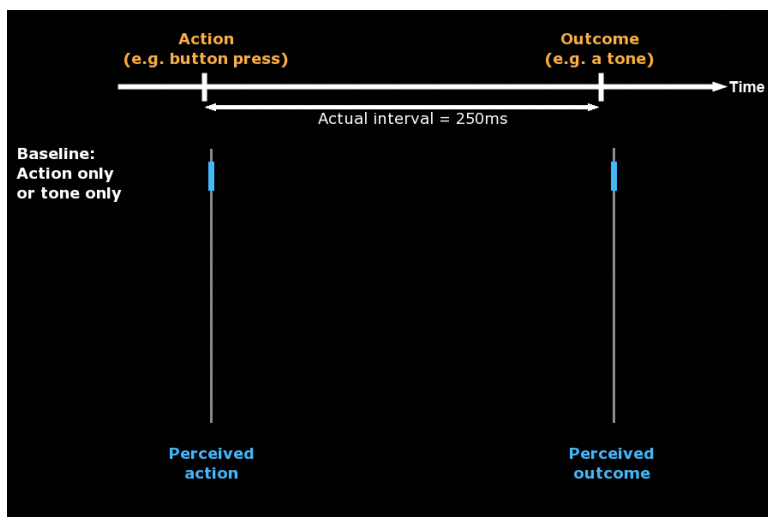
Intentional binding



Haggard, P. & Tsakiris, M., *The Experience of Agency: Feelings, Judgments, and Responsibility*. *Curr Dir Psychol Sci*, 2009, 18(4) p.242-46.

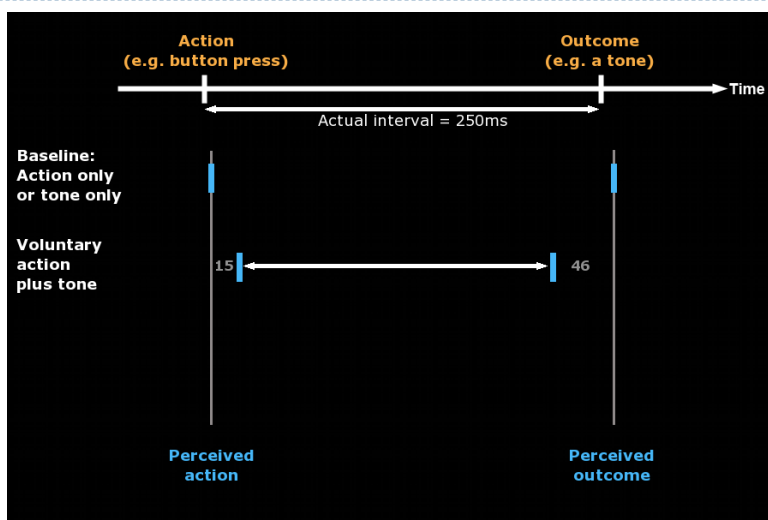
▶ 26

Intentional binding



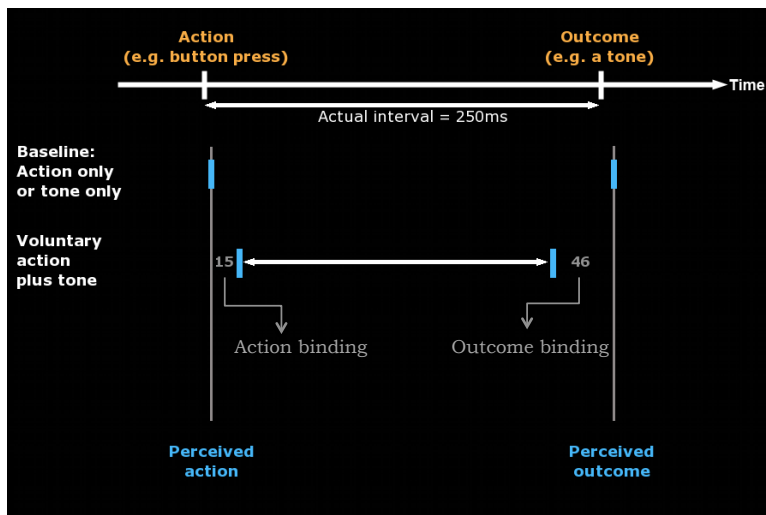
Haggard, P. & Tsakiris, M., *The Experience of Agency: Feelings, Judgments, and Responsibility*. *Curr Dir Psychol Sci*, 2009, 18(4) p.242-46.

Intentional binding



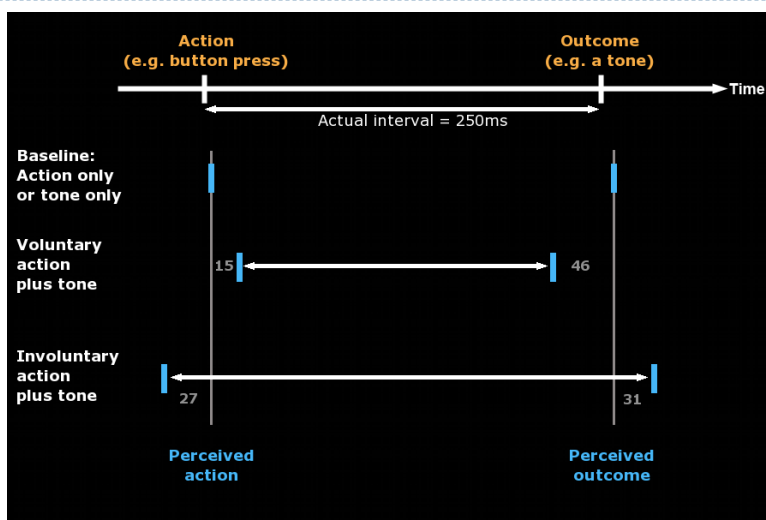
Haggard, P. & Tsakiris, M., *The Experience of Agency: Feelings, Judgments, and Responsibility*. *Curr Dir Psychol Sci*, 2009, 18(4) p.242-46.

Intentional binding



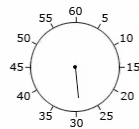
Haggard, P. & Tsakiris, M., *The Experience of Agency: Feelings, Judgments, and Responsibility*. *Curr Dir Psychol Sci*, 2009, 18(4) p.242-46.

Intentional binding



Haggard, P. & Tsakiris, M., *The Experience of Agency: Feelings, Judgments, and Responsibility*. *Curr Dir Psychol Sci*, 2009, 18(4) p.242-46.

The Libet clock method



- Approx. 100px in diameter.
- Shown at the centre of screen.
- Arm rotates once every 2560ms.

Strengths:

- Provides robust measures.
- Detailed breakdown of where binding occurs.

Weaknesses:

- Not suitable for visual tasks.
- Time consuming: 4 blocks of trials per condition.

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Interval estimation

Participants estimate the time between their action and an outcome.

Strengths:

- Suitable for visual tasks.
- Less time consuming:
1 block of trials per condition.

Weaknesses:

- Less robust measure.
- No breakdown of where binding occurs.

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An experimental manipulation

- ▶ Skinput: appropriating the body as an input surface.
 - ▶ Harrison, Tan, & Morris. CHI 2010.



Experiment 1

What’s it like to be a button?

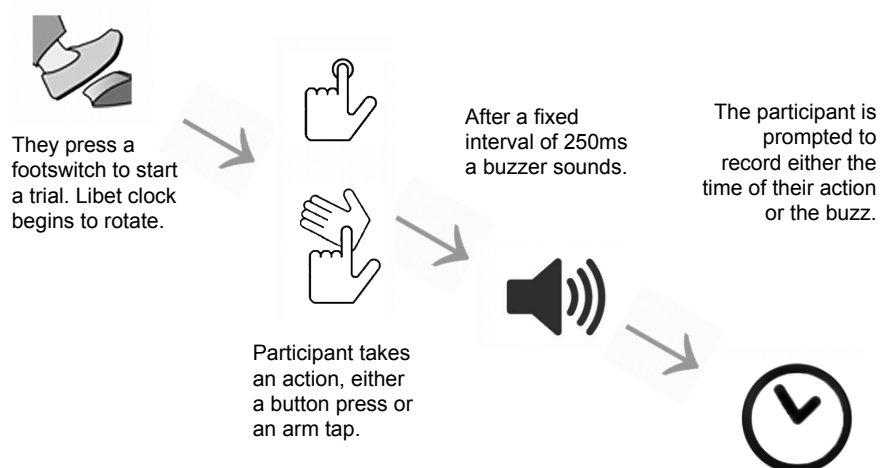
Do changes in the input modality of an action have an impact on the sense of agency?

Two input conditions: button and skin-based input.



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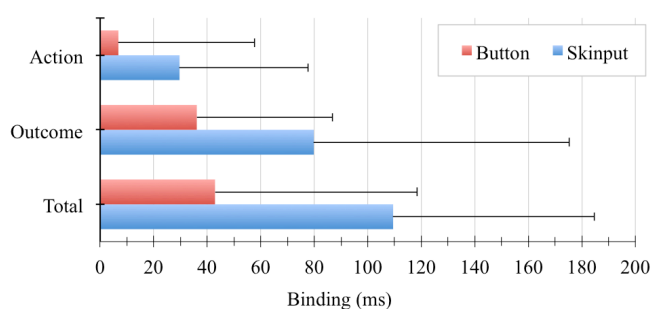
Procedure



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Results

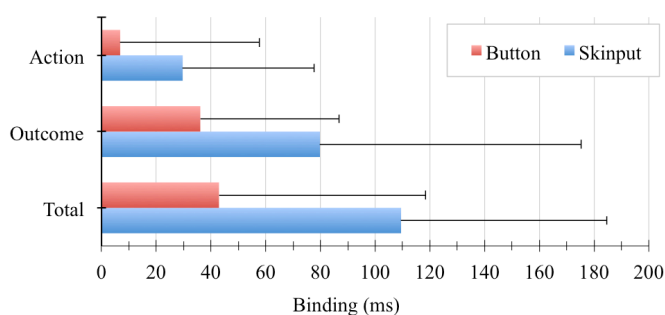
	Action binding	Outcome binding	Total binding
Button	6.81ms (45.6ms)	36.11ms (45.46ms)	42.92ms (67.43ms)
Skin-based	29.66ms (42.84ms)	79.82ms (91.23ms)	109.47ms (74.54ms)



**$t(18) = 4.05,$
 $p < 0.01$**

Observations

- ▶ Yes, changes in the input modality can have an impact on the experience of agency.
 - ▶ Intention binding is a useful metric for design research:
 - ▶ It can be used to compare and refine input techniques.
 - ▶ Compare experiences for a given input technique when other conditions of the interactions change.
- ▶ A question
 - ▶ Why is binding higher in the skin-based condition?



Experiment 2

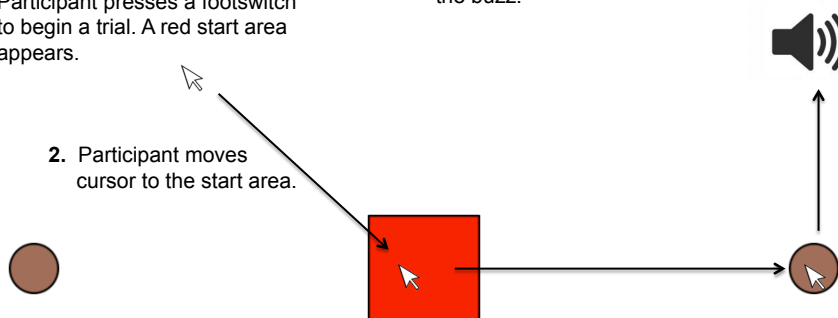
Intelligent interfaces:

What happens when a computer helps out?

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Procedure

1. Participant presses a footswitch to begin a trial. A red start area appears.
2. Participant moves cursor to the start area.
3. Having waited in start area for 1500ms two green targets appear.
4. Participant chooses a target and moves cursor to hit it as quickly and as accurately as possible.
5. Hitting target causes a buzz – with a random time interval.
The participant is prompted to estimate the interval between hitting the target and the buzz.



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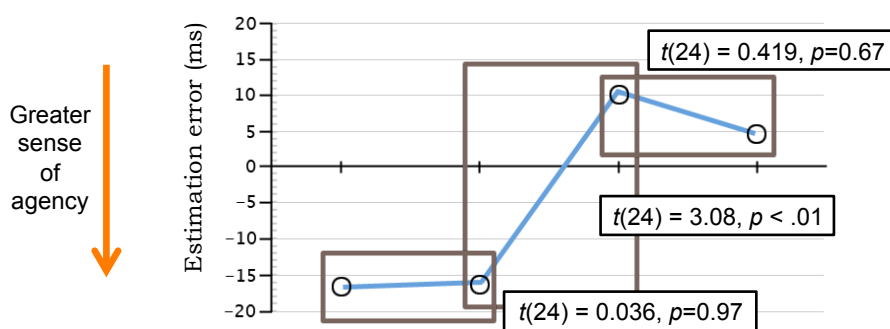
Experiment design

- ▶ Treatment: the assistance algorithm has the effect of adding “gravity” to targets.
 - ▶ Four levels of assistance: none, mild, medium, high.
- ▶ Within subject design, with:
 - ▶ 1 block of trials for each assistance level
 - ▶ 36 trials per block.
 - ▶ 24 participants.
- ▶ The order of the assistance level blocks was counter-balanced across participants.

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Results

	No assistance	Mild assistance	Medium assistance	High assistance
Estimation error	-16.78ms (70.70ms)	-16.32ms (82.03ms)	9.93ms (85.92ms)	4.53ms (79.12ms)

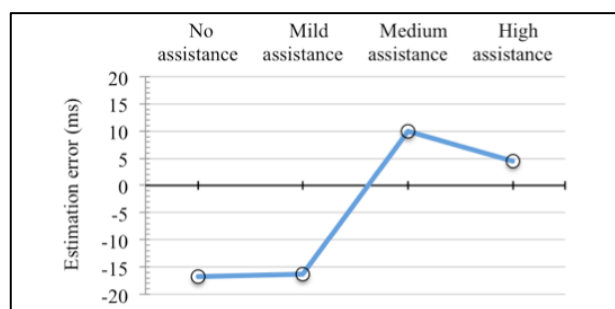


Repeat measure ANOVA: $F(3,69) = 2.74, p=0.05$

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Observations

- ▶ Up to a point, the computer gave assistance, but people retain a sense of agency.
- ▶ Beyond a certain point people experience a loss in sense of agency.
- ▶ This technique could provide an experimental means of mapping the personal agency characteristics of intelligent input techniques.



Overall conclusions

- ▶ Changes in the input modality and in levels of assistance can have a significant impact on users' experience of personal agency.
- ▶ Intentional binding can provide an implicit metric for probing and mapping experiences of agency.
- ▶ This metric can be applied in a wide range of design contexts. E.g.:
 - ▶ Comparison and refinement of different interfaces and assistance techniques.
 - ▶ Investigating the impact of uncertainty or different types of feedback.
 - ▶ Comparisons of user groups, e.g. different age groups, people experiencing mental health difficulties.

Design for control

Case Study: Coda

- ▶ Mixed initiative interface being created for Africa's Voices Foundation
 - ▶ <http://www.africasvoices.org/ideas/newsblog/introducing-our-latest-analysis-tool-coda/>



- ▶ Ongoing work in our group is looking at agency in the rhythm of interaction with this kind of interface