

# **NON-BLOCKING DATA STRUCTURES AND TRANSACTIONAL MEMORY**

Tim Harris, 3 Nov 2017

# Lecture 1/3

- Introduction
- Basic spin-locks
- Queue-based locks
- Hierarchical locks
- Reader-writer locks
- Reading without locking
- Flat combining
- Recent research: parallel work distribution

# Overview

- Building shared memory data structures
  - Lists, queues, hashtables, ...
- Why?
  - Used directly by applications (e.g., in C/C++, Java, C#, ...)
  - Used in the language runtime system (e.g., management of work, implementations of message passing, ...)
  - Used in traditional operating systems (e.g., synchronization between top/bottom-half code)
- Why not?
  - Don't think of "threads + shared data structures" as a default/good/complete/desirable programming model
  - It's better to have shared memory and not need it...

# Different techniques for different problems

Ease to  
write

Correctness

When can it  
be used?

How fast is it?

How well  
does it scale?

# Suggested reading

- “The art of multiprocessor programming”, Herlihy & Shavit  
– excellent coverage of shared memory data structures,  
from both practical and theoretical perspectives

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- “Transactional memory, 2<sup>nd</sup> edition”, Harris, Larus, Rajwar – survey of transactional memory work, with 350+ references
- “NOrec: streamlining STM by abolishing ownership records”, Dalessandro, Spear, Scott, PPOPP 2010



# Basic spin-locks

# Test and set (pseudo-code)

```
bool testAndSet(bool *b) {  
    bool result;  
    atomic {  
        result = *b;  
        *b = TRUE;  
    }  
    return result;  
}
```

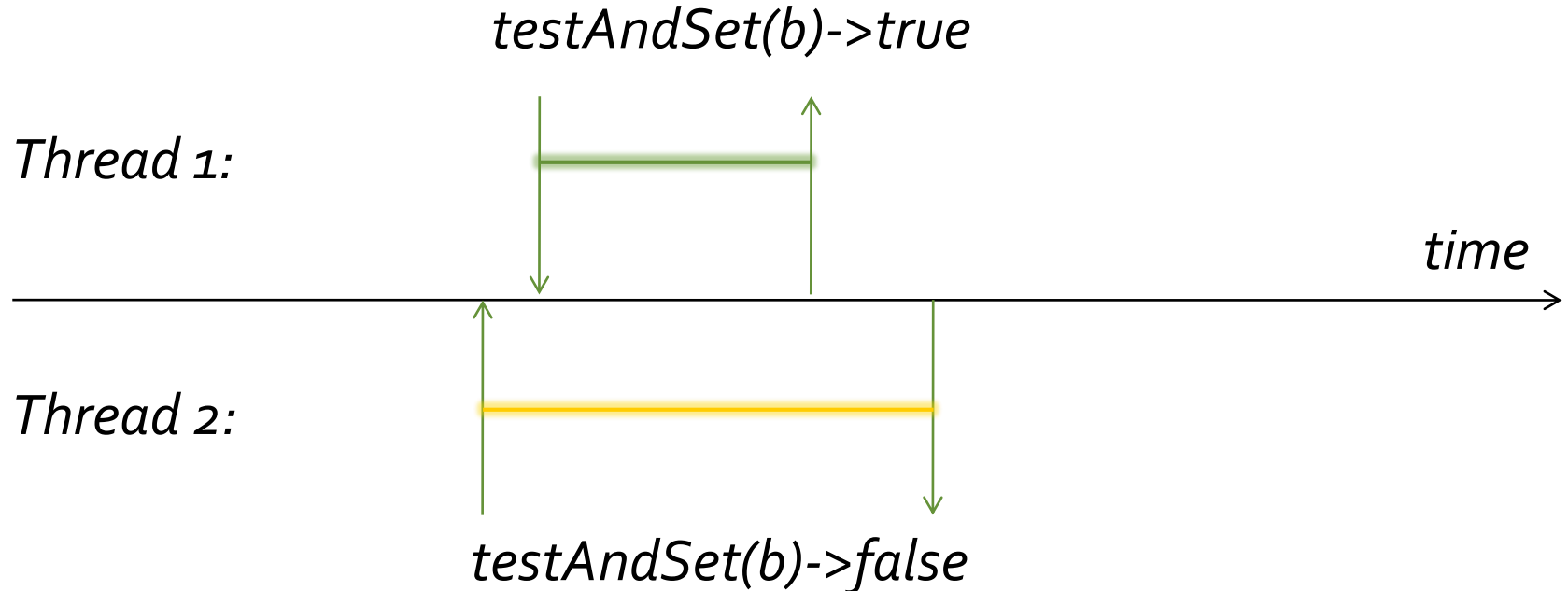
Pointer to a location holding a boolean value (TRUE/FALSE)

Read the current contents of the location b points to...

...set the contents of \*b to TRUE

# Test and set

- Suppose two threads use it at once



# Test and set lock

lock:

FALSE

FALSE => lock available  
TRUE => lock held

```
void acquireLock(bool *lock) {  
    while (testAndSet(lock)) {  
        /* Nothing */  
    }  
}
```

Each call tries to acquire the lock, returning TRUE if it is already held

```
void releaseLock(bool *lock) {  
    *lock = FALSE;  
}
```

NB: all this is pseudo-code, assuming SC memory

# Test and set lock

lock:

TRUE

```
void acquireLock(bool *lock) {  
    while (testAndSet(lock)) {  
        /* Nothing */  
    }  
}
```

```
void releaseLock(bool *lock) {  
    *lock = FALSE;  
}
```

Thread 1



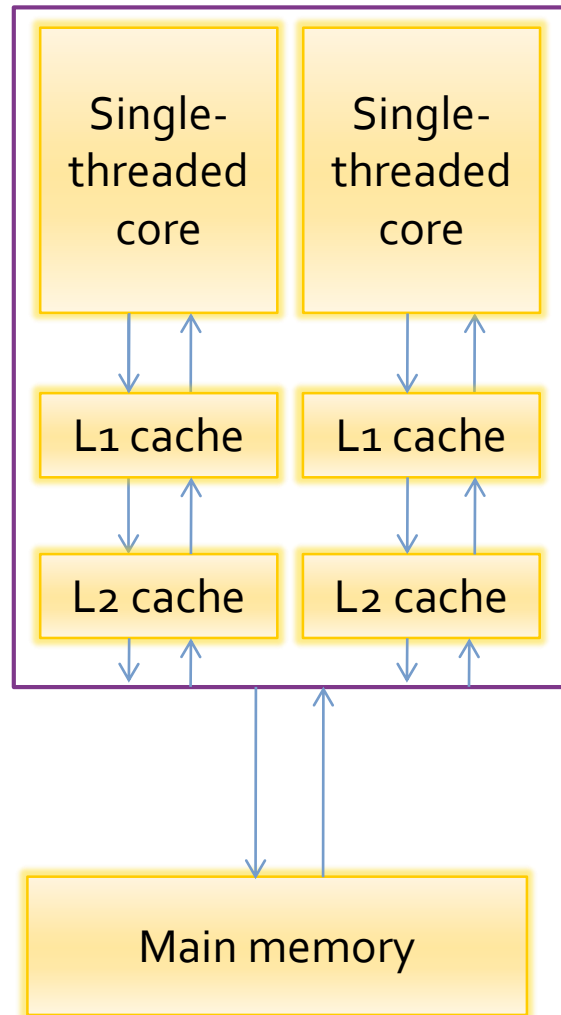
Thread 2



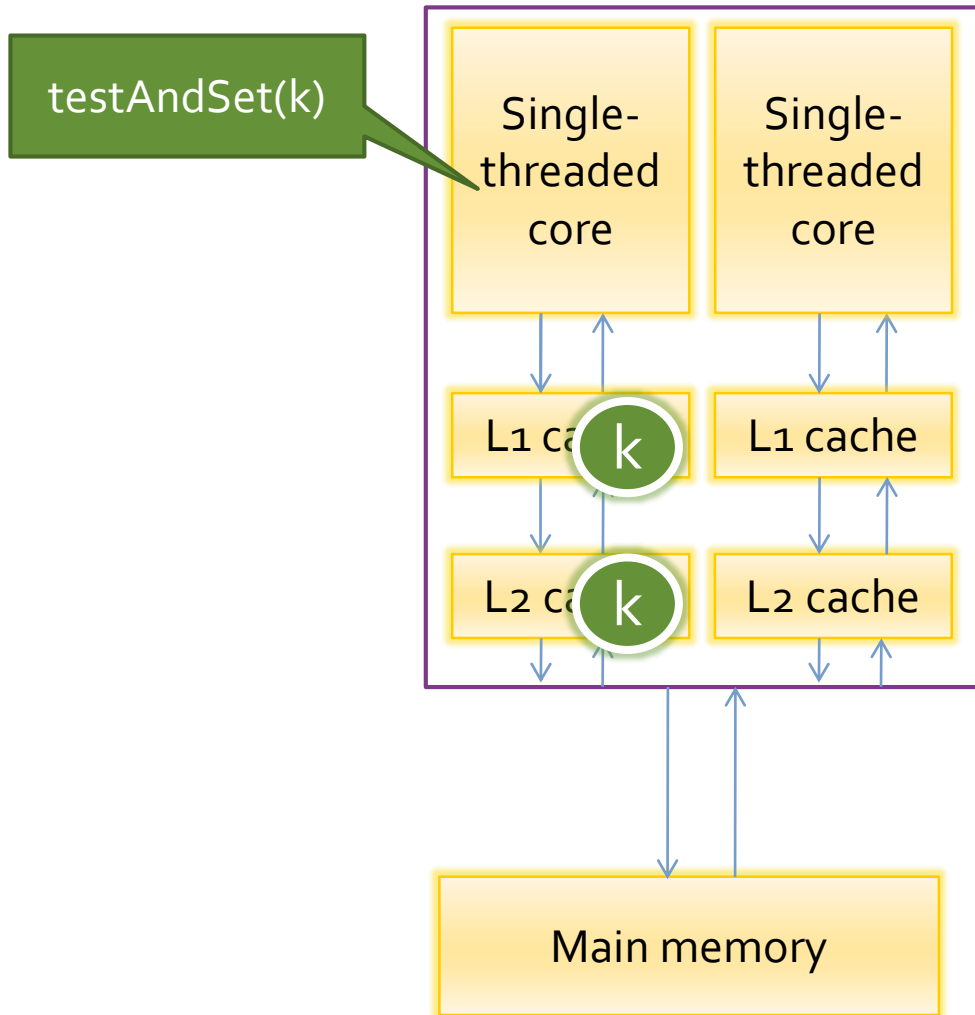
# What are the problems here?

testAndSet  
implementation  
causes contention

# Contention from testAndSet

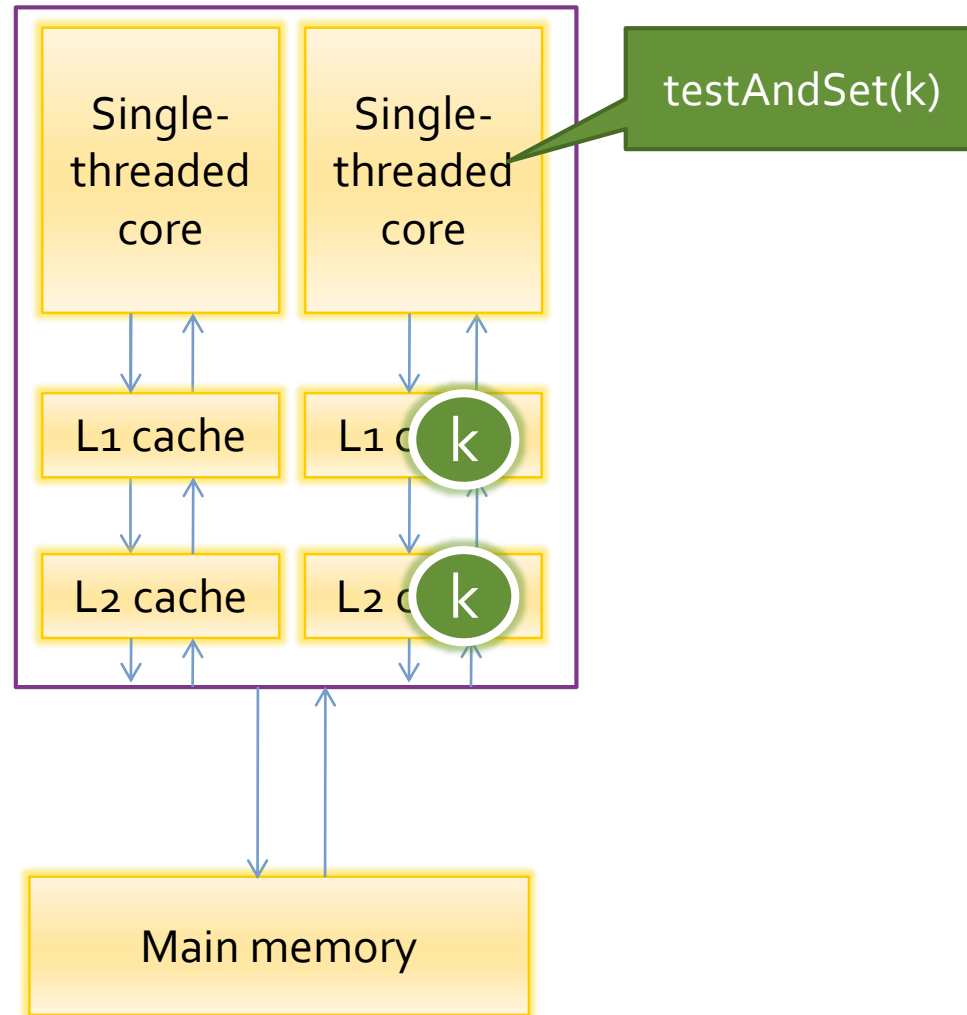


# Multi-core h/w – separate L2

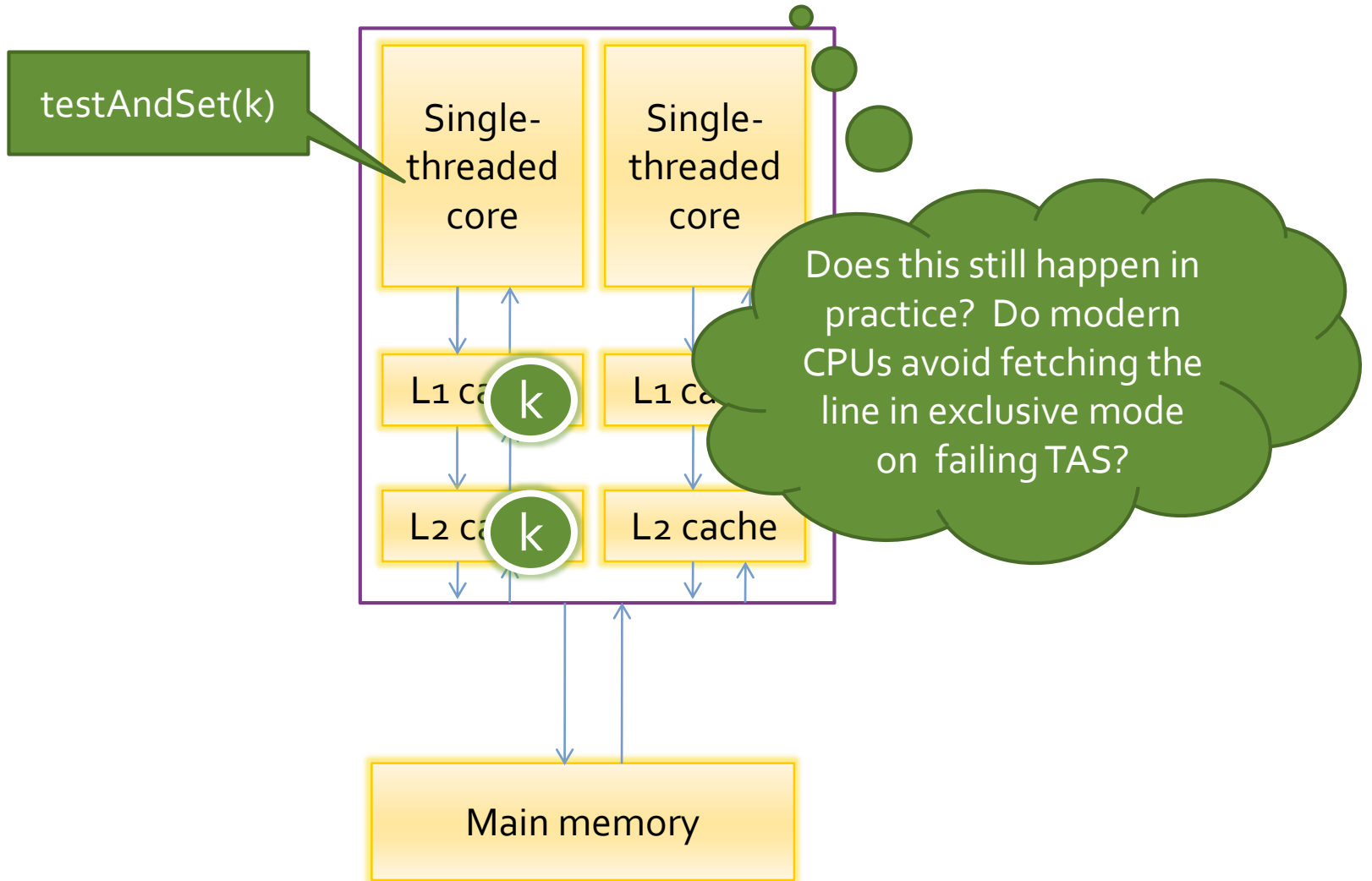




# Multi-core h/w – separate L2



# Multi-core h/w – separate L2



# What are the problems here?

testAndSet  
implementation  
causes contention

No control over  
locking policy

Only supports mutual  
exclusion: not reader-  
writer locking

Spinning may waste  
resources while  
waiting

# General problem

- No logical conflict between two failed lock acquires
- Cache protocol introduces a physical conflict
- For a good algorithm: only introduce physical conflicts if a logical conflict occurs
  - In a lock: successful lock-acquire & failed lock-acquire
  - In a set: successful insert(10) & failed insert(10)
- But not:
  - In a lock: two failed lock acquires
  - In a set: successful insert(10) & successful insert(20)
  - In a non-empty queue: enqueue on the left and remove on the right

# Test and test and set lock

lock:

FALSE

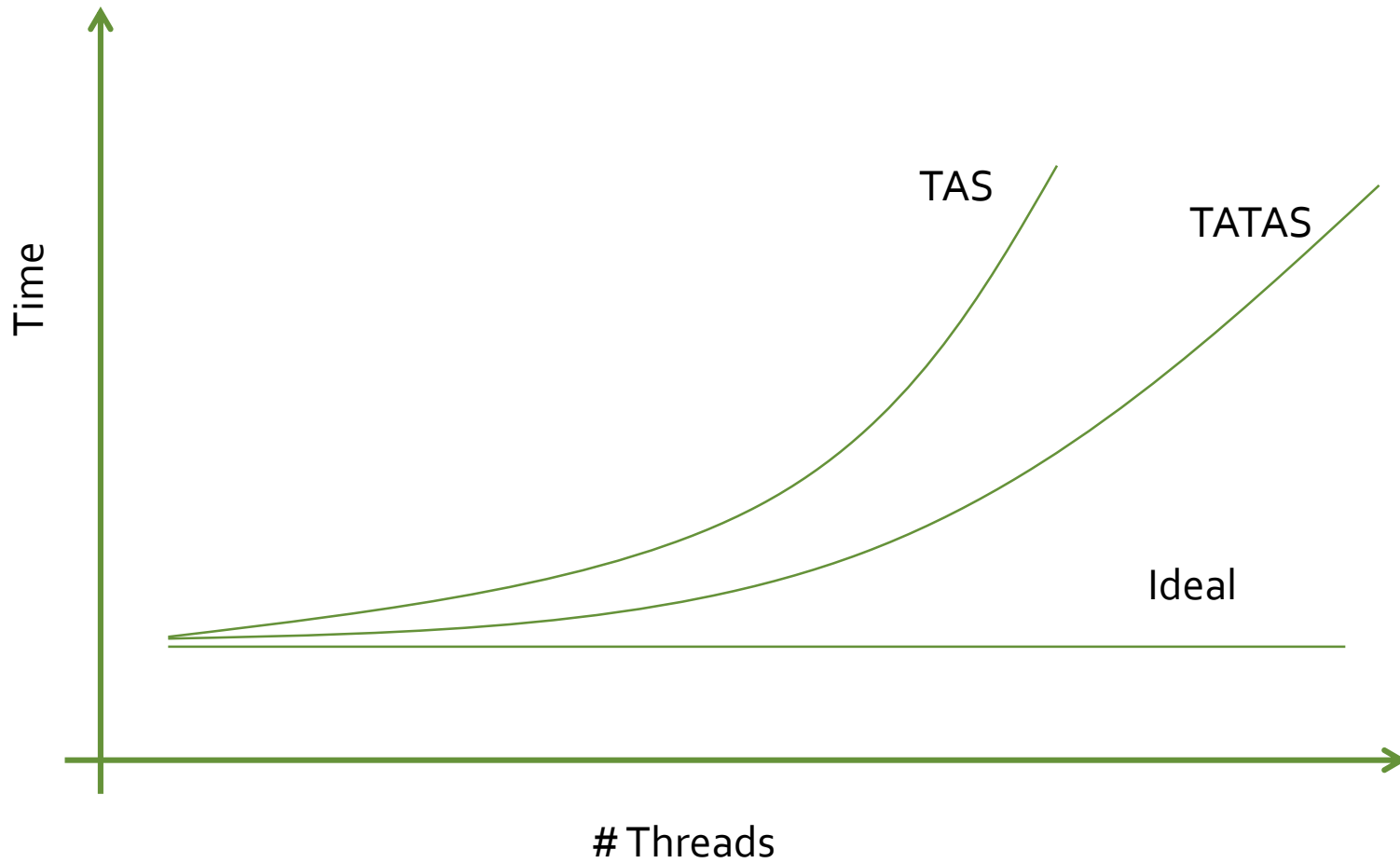
FALSE => lock available  
TRUE => lock held

```
void acquireLock(bool *lock) {  
  do {  
    while (*lock) { }  
  } while (testAndSet(lock));  
}
```

Spin while the lock is  
held... only do  
testAndSet when it is  
clear

```
void releaseLock(bool *lock) {  
  *lock = FALSE;  
}
```

# Performance



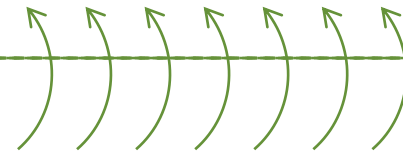
# Stampedes

lock:

TRUE

```
void acquireLock(bool *lock) {  
  do {  
    while (*lock) {}  
  } while (testAndSet(lock));  
}
```

```
void releaseLock(bool *lock) {  
  *lock = FALSE;  
}
```



# Back-off algorithms

1. Start by spinning, watching the lock for “s” iterations
2. If the lock does not become free, wait locally for “w” (*without watching the lock*)

What should “s” be?  
What should “w” be?



# Time spent spinning on the lock “s”

- Lower values:
  - Less time to build up a set of threads that will stampede
  - Less contention in the memory system, if remote reads incur a cost
  - Risk of a delay in noticing when the lock becomes free if we are not watching
- Higher values:
  - Less likelihood of a delay between a lock being released and a waiting thread noticing

# Local waiting time “w”

- Lower values:
  - More responsive to the lock becoming available
- Higher values:
  - If the lock doesn't become available then the thread makes fewer accesses to the shared variable

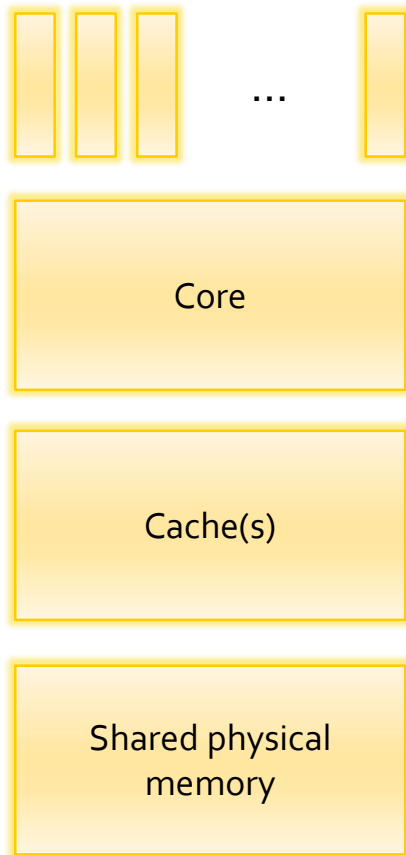
# Methodical approach

- For a given workload and performance model:
  - What is the best that could be done (i.e. given an “oracle” with perfect knowledge of when the lock becomes free)?
  - How does a practical algorithm compare with this?
- Look for an algorithm with a bound between its performance and that of the oracle
- “Competitive spinning”

# Rule of thumb

- Spin on the lock for a duration that's comparable with the shortest back-off interval
- Exponentially increase the per-thread back-off interval (resetting it when the lock is acquired)
- Use a maximum back-off interval that is large enough that waiting threads don't interfere with the other threads' performance

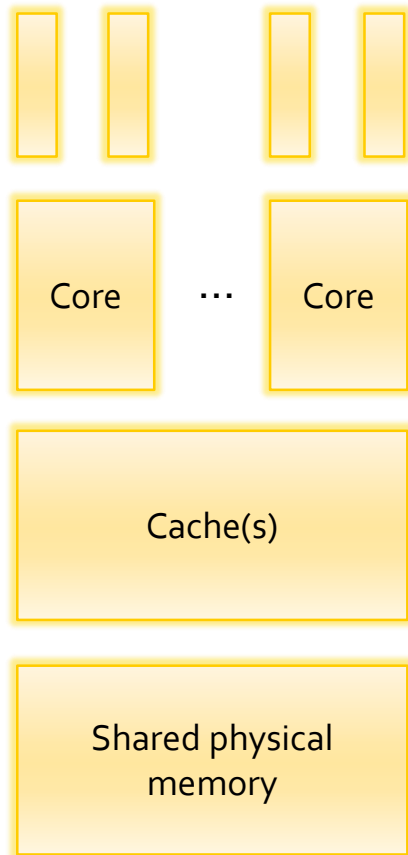
# Systems problems



Lots of h/w threads  
multiplexed over a core

- The threads need to “wait efficiently”
- Not consuming processing resources (contending with lock holder) & not consuming power
- “monitor” / “mwait” operations – e.g., SPARC M7

# Systems problems



S/W threads multiplexed  
on cores

- Spinning gets in the way of other s/w threads, even if done efficiently
- For long delays, may need to actually block and unblock
- ...as with back-off, how long to spin for before blocking?

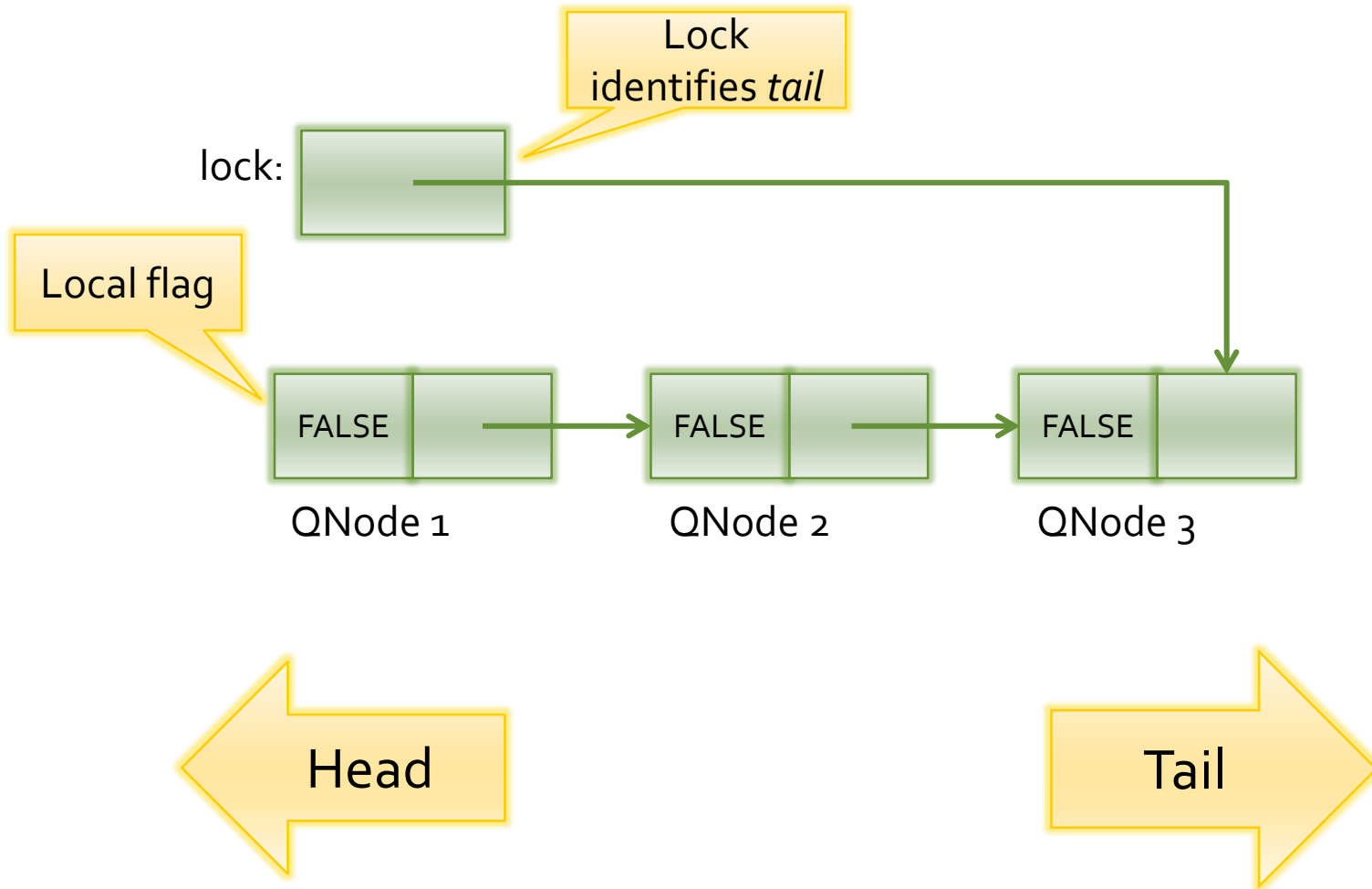
# Queue-based locks

# Queue-based locks

- Lock holders queue up: immediately provides FCFS behavior
- Each spins *locally* on a flag in their queue entry: no remote memory accesses while waiting
- A lock release wakes the next thread directly: no stampede



# MCS locks



# MCS lock acquire

lock:



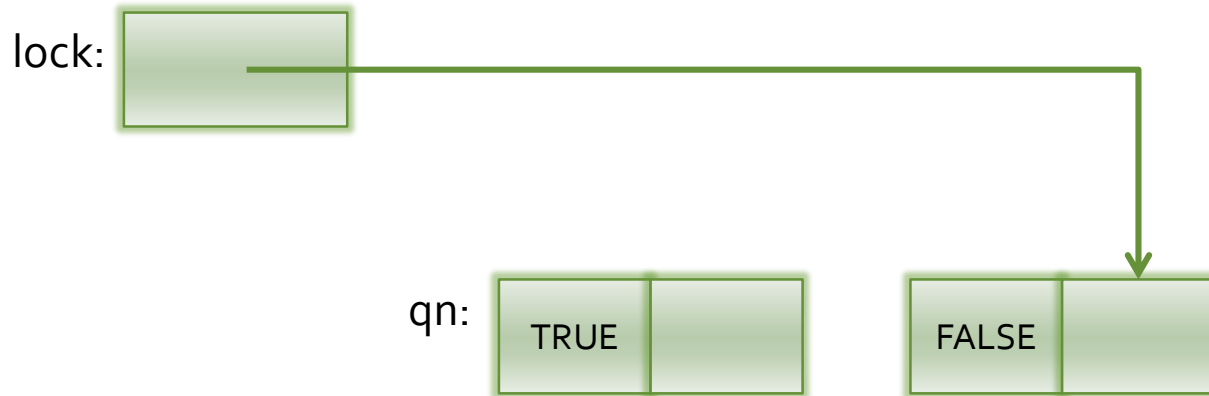
```
void acquireMCS(mcs *lock, QNode *qn) {
    QNode *prev;
    qn->flag = false;
    qn->next = NULL;
    while (true) {
        prev = lock->tail;
        /* Label 1 */
        if (CAS(&lock->tail, prev, qn)) break;
    }
    if (prev != NULL) {
        prev->next = qn; /* Label 2 */
        while (!qn->flag) { } // Spin
    }
}
```

Find previous  
tail node

Atomically replace  
"prev" with "qn" in  
the lock itself

Add link within  
the queue

# MCS lock release



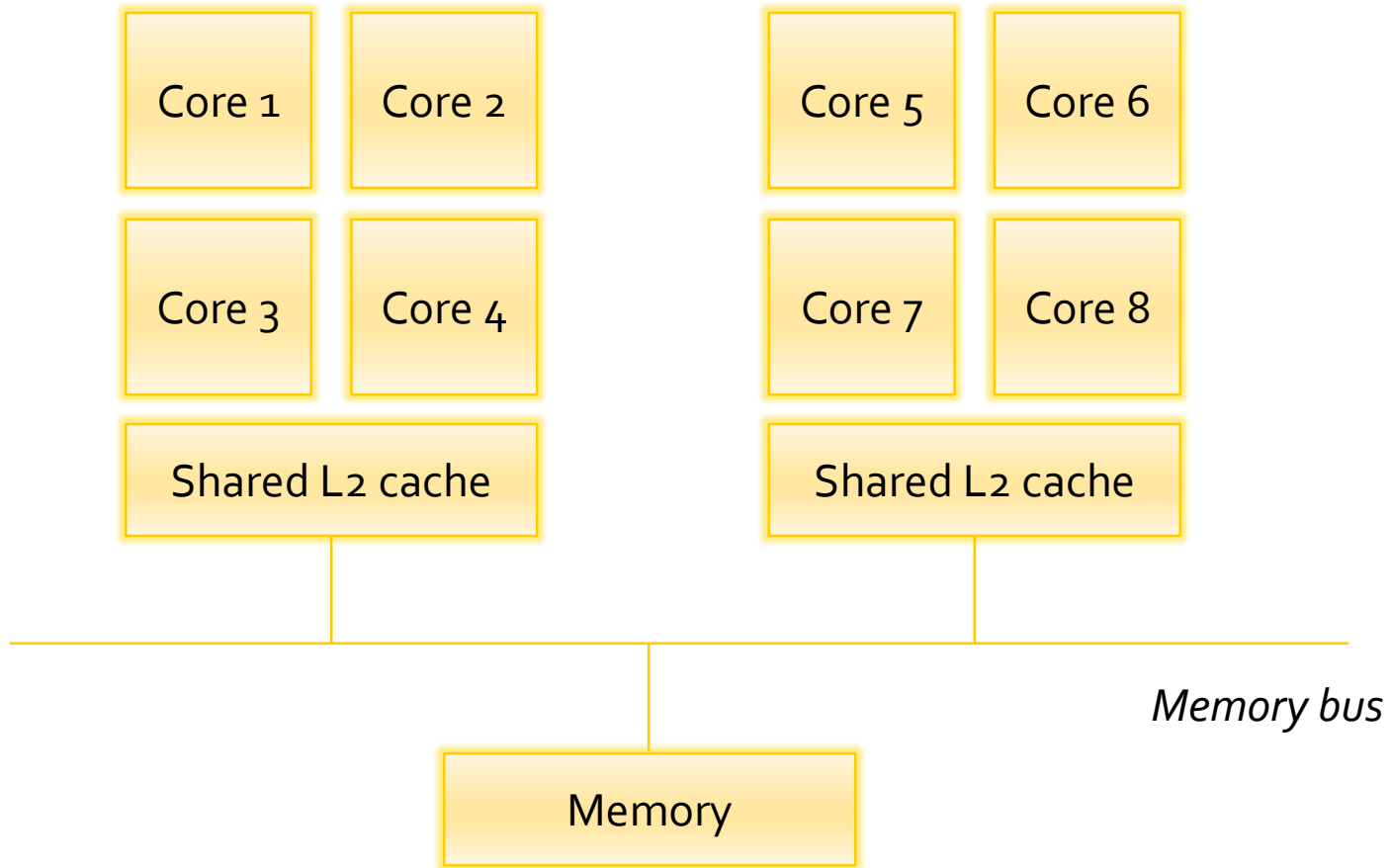
```
void releaseMCS(mcs *lock, QNode *qn) {  
    if (lock->tail = qn) {  
        if (CAS(&lock->tail, qn, NULL)) return;  
    }  
    while (qn->next == NULL) { }  
    qn->next->flag = TRUE;  
}
```

If we were at the tail  
then remove us

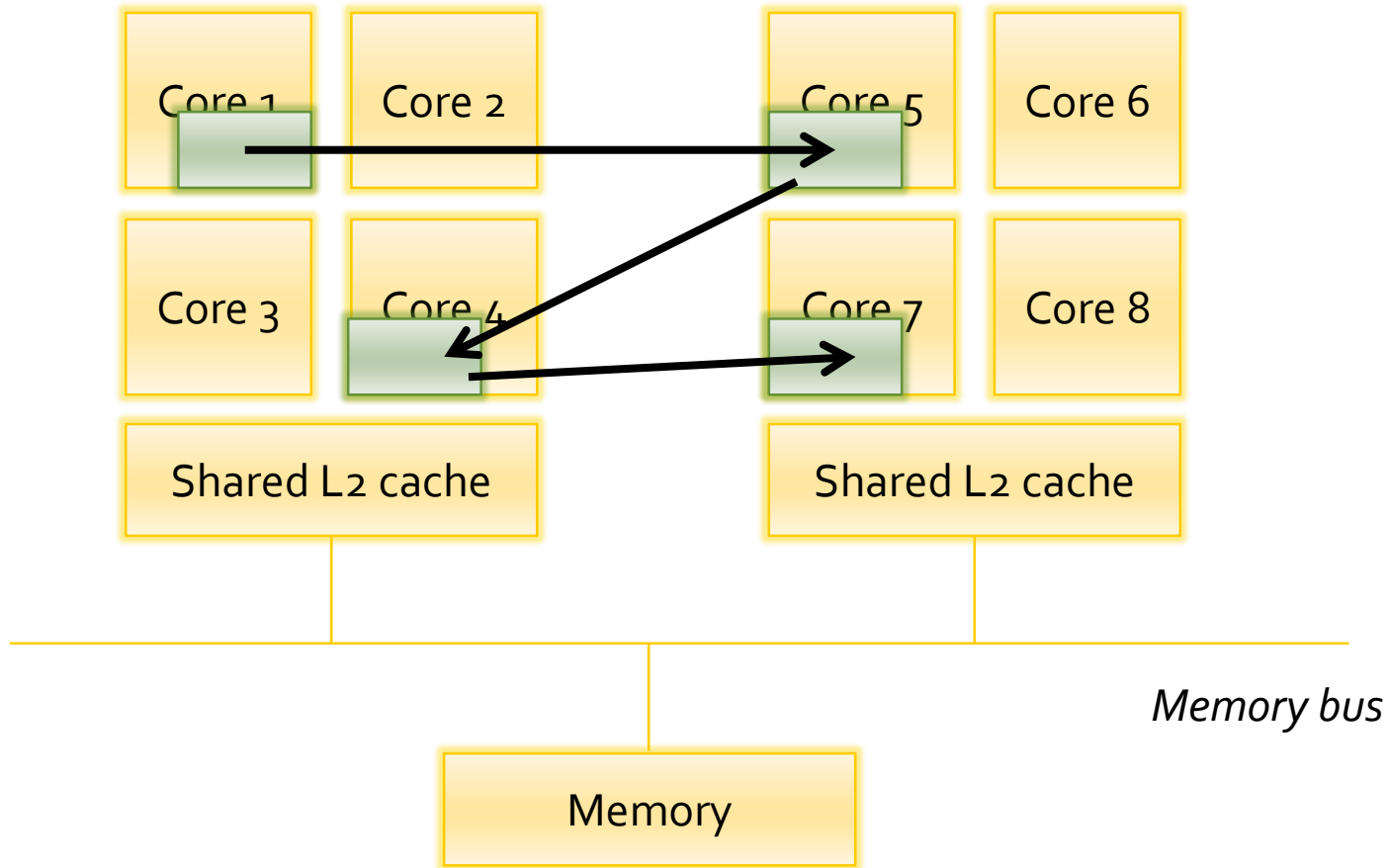
Wait for next lock holder  
to announce themselves;  
signal them

# Hierarchical locks

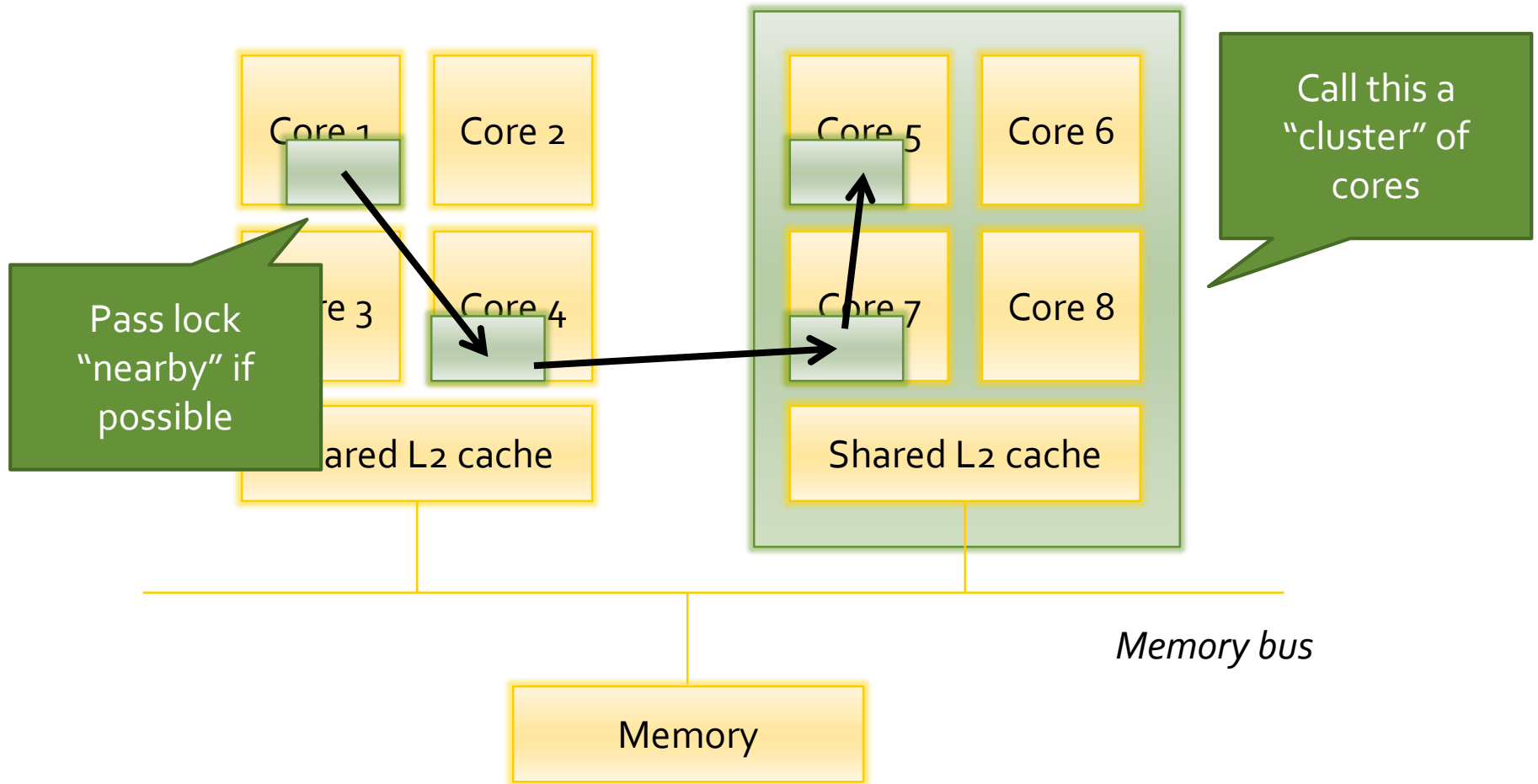
# Hierarchical locks



# Hierarchical locks



# Hierarchical locks



# Hierarchical TATAS with backoff

lock:

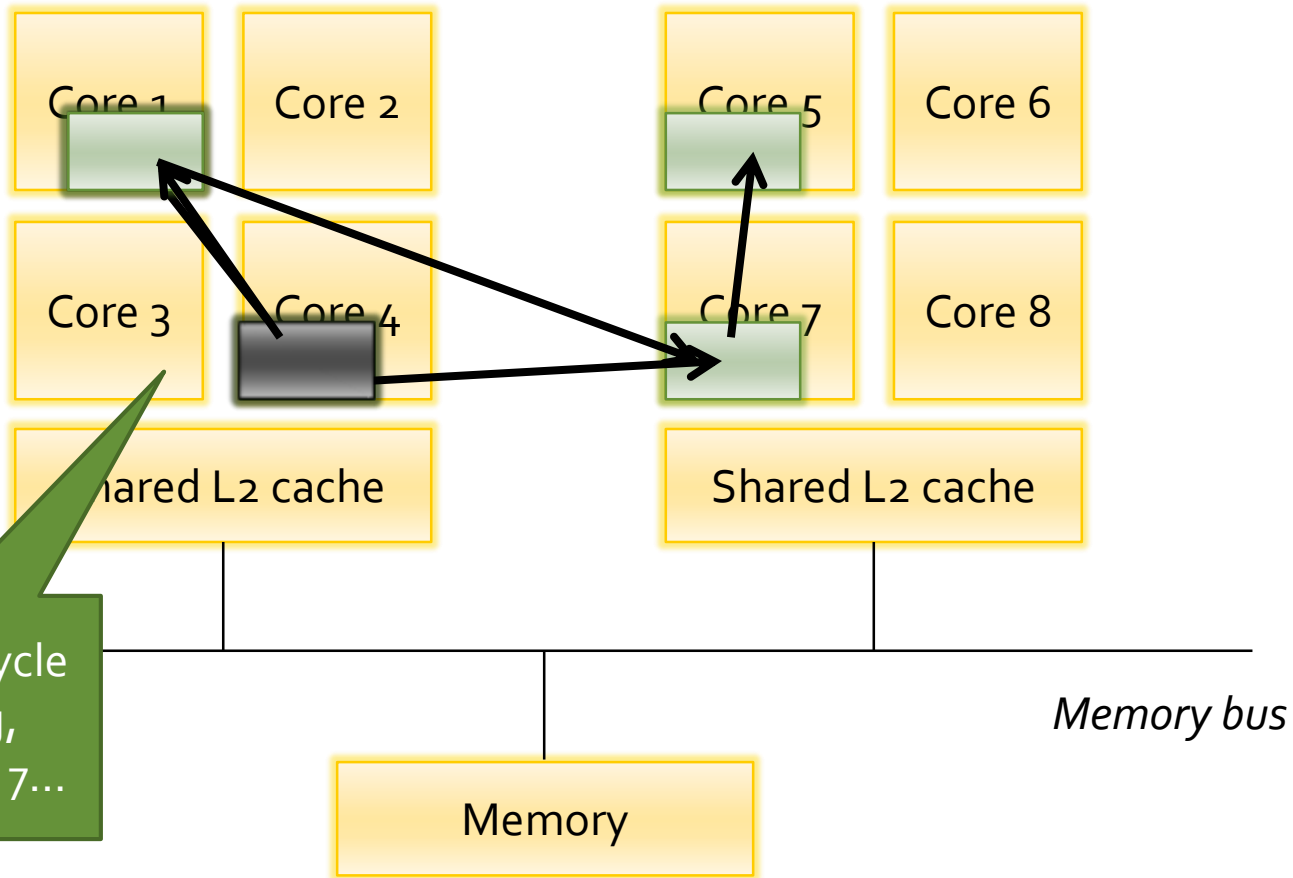
-1

-1 => lock available  
n => lock held by cluster n

```
void acquireLock(bool *lock) {  
  do {  
    holder = *lock;  
    if (holder != -1) {  
      if (holder == MY_CLUSTER) {  
        BackOff(SHORT);  
      } else {  
        BackOff(LONG);  
      }  
    }  
  } while (!CAS(lock, -1, MY_CLUSTER));  
}
```

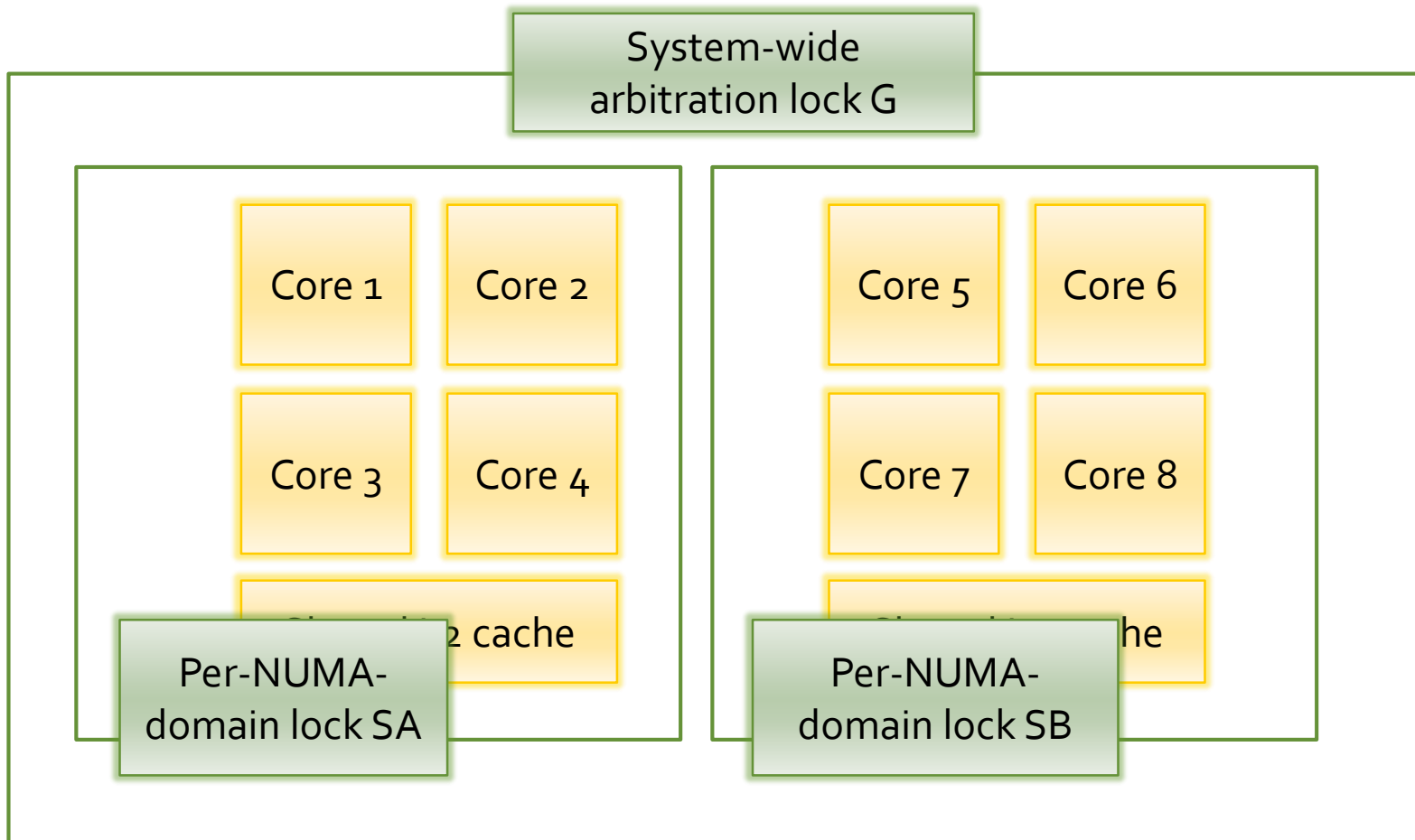


# Hierarchical locks: unfairness v throughput



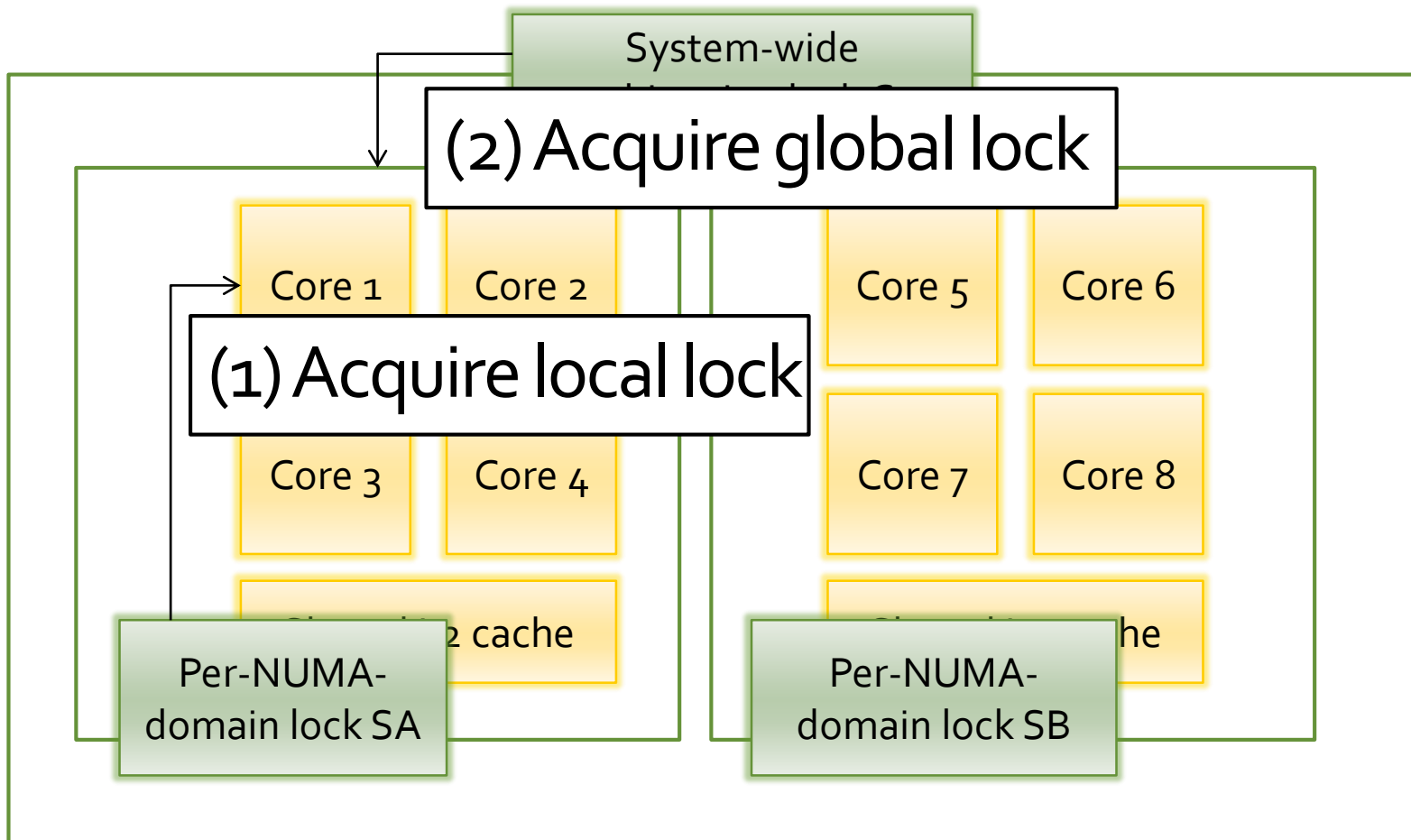
# Lock cohorting

- “Lock Cohorting: A General Technique for Designing NUMA Locks”, Dice *et al* PPOPP 2012



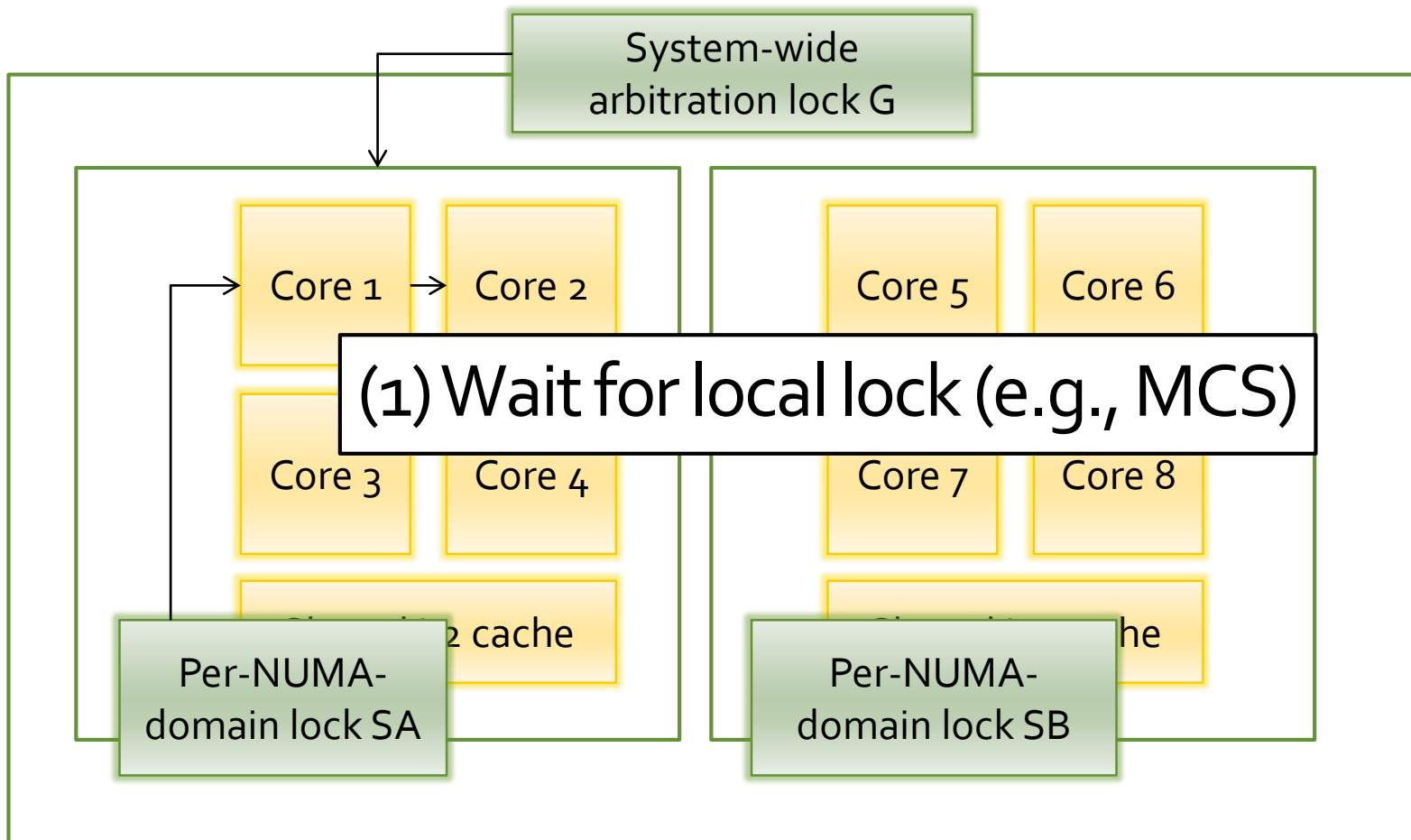
# Lock cohorting

- Lock acquire, uncontended



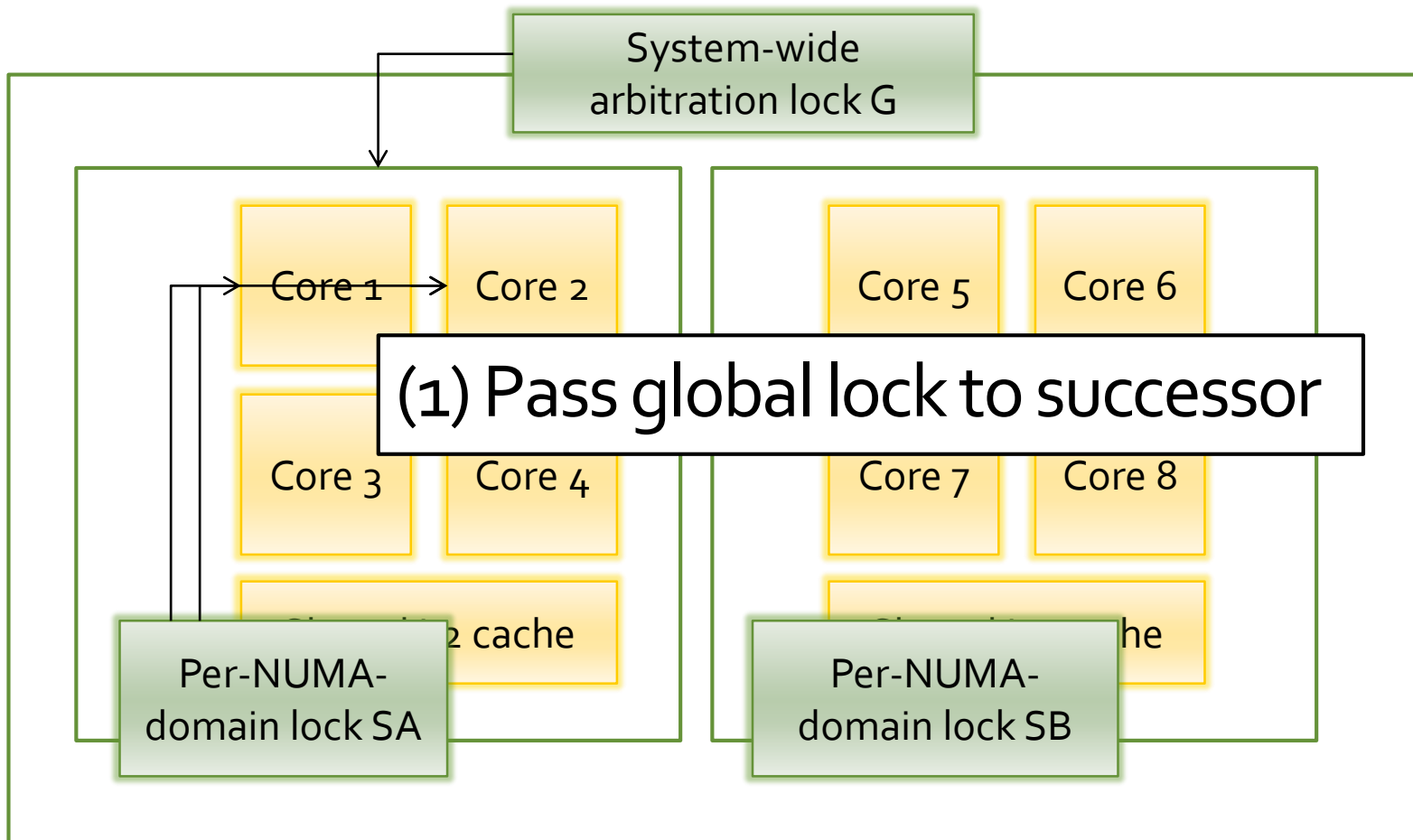
# Lock cohorting

- Lock acquire, contended



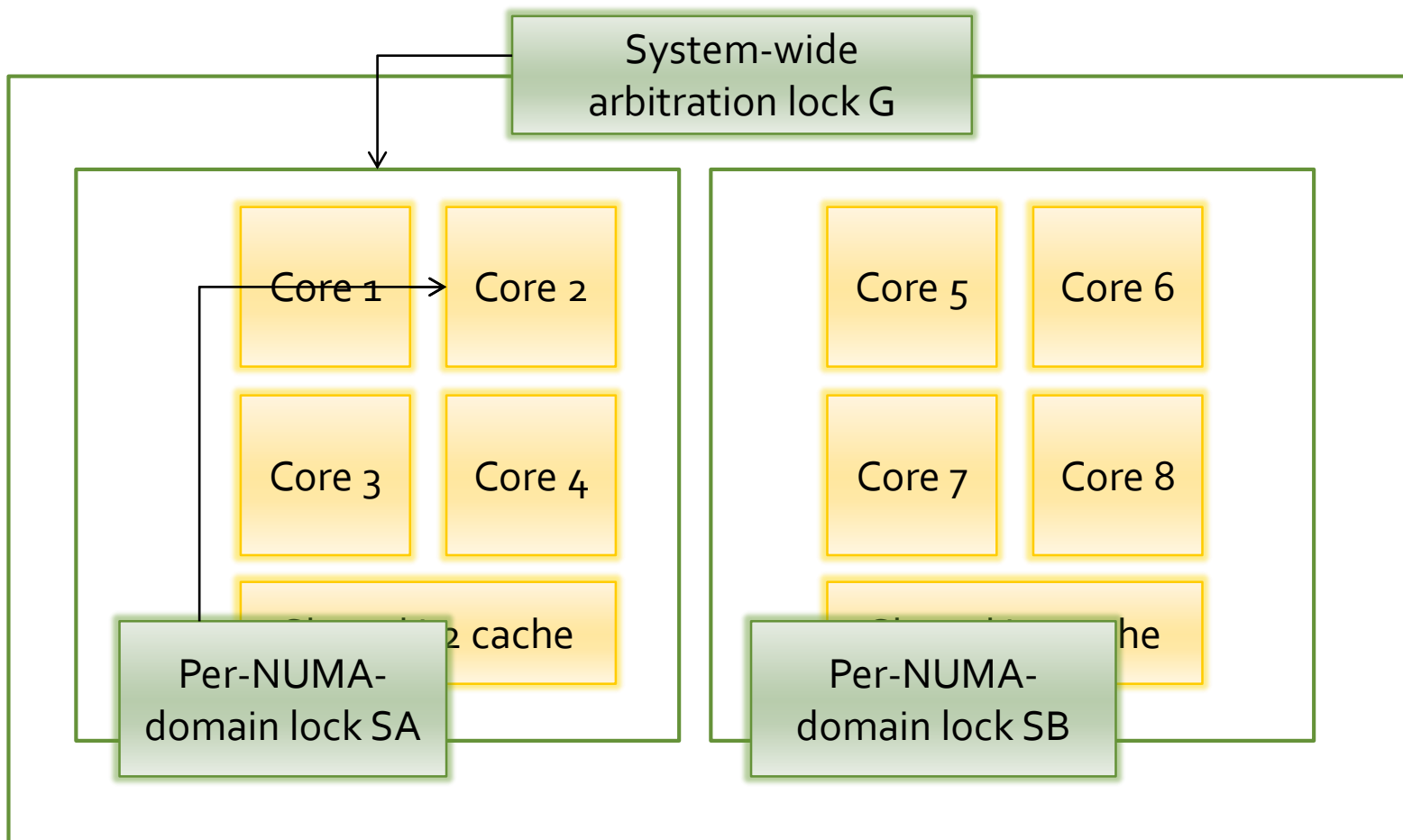
# Lock cohorting

- Lock release, with successor



# Lock cohorting, requirements

- Global: “thread oblivious” (acq one thread, release another)
- Local lock: “cohort detection” (can test for successors)



# Reader-writer locks

# Reader-writer locks (TATAS-like)

lock:

0

-1 => Locked for write  
0 => Lock available  
+n => Locked by n readers

```
void acquireWrite(int *lock) {  
    do {  
        if ((*lock == 0) &&  
            (CAS(lock, 0, -1))) {  
            break;  
        } while (1);  
    }  
}
```

```
void acquireRead(int *lock) {  
    do {  
        int oldVal = *lock;  
        if ((oldVal >= 0) &&  
            (CAS(lock, oldVal, oldVal+1))) {  
            break;  
        } } while (1);  
}
```

```
void releaseWrite(int *lock) {  
    *lock = 0;  
}
```

```
void releaseRead(int *lock) {  
    FADD(lock, -1); // Atomic fetch-and-add  
}
```



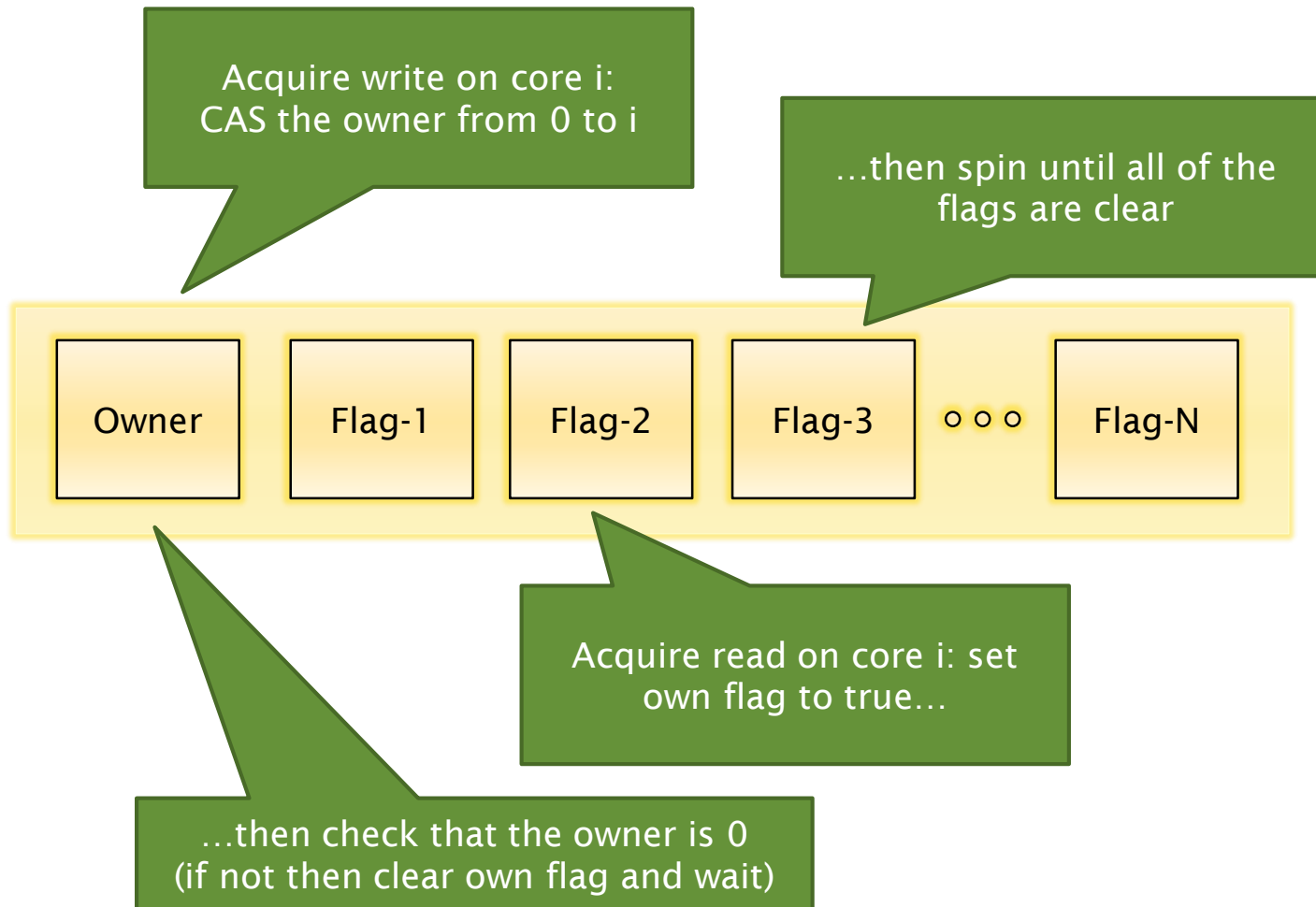
# The problem with readers

```
int readCount() {  
    acquireRead(lock);  
    int result = count;  
    releaseRead(lock);  
    return result;  
}
```

```
void incrementCount() {  
    acquireWrite(lock);  
    count++;  
    releaseWrite(lock);  
}
```

- Each acquireRead fetches the cache line holding the lock in exclusive mode
  - Again: acquireRead are not logically conflicting, but this introduces a physical conflict
- The time spent managing the lock is likely to vastly dominate the actual time looking at the counter
- Many workloads are read-mostly...

# Keeping readers separate



# Keeping readers separate

- With care, readers do not need to synchronize with other readers
  - Extend the flags to be whole cache lines
  - Pack multiple locks flags for the same thread onto the same line
  - Exploit the cache structure in the machine: Dice & Shavit's TLRW byte-lock on SPARC Niagara
- If "N" threads is very large..
  - Dedicate the flags to specific important threads
  - Replace the flags with ordinary multi-reader locks
  - Replace the flags with per-NUMA-domain multi-reader locks

# Other locking techniques

- Affinity
  - Allow one thread fast access to the lock
  - “One thread” – e.g., previous lock holder
  - “Fast access” – e.g., with fewer / no atomic CAS operations
  - Mike Burrows “Implementing unnecessary mutexes”  
(Do the assumptions hold? How slow is an uncontended CAS on a modern machine? Are these techniques still useful?)

# Other locking techniques

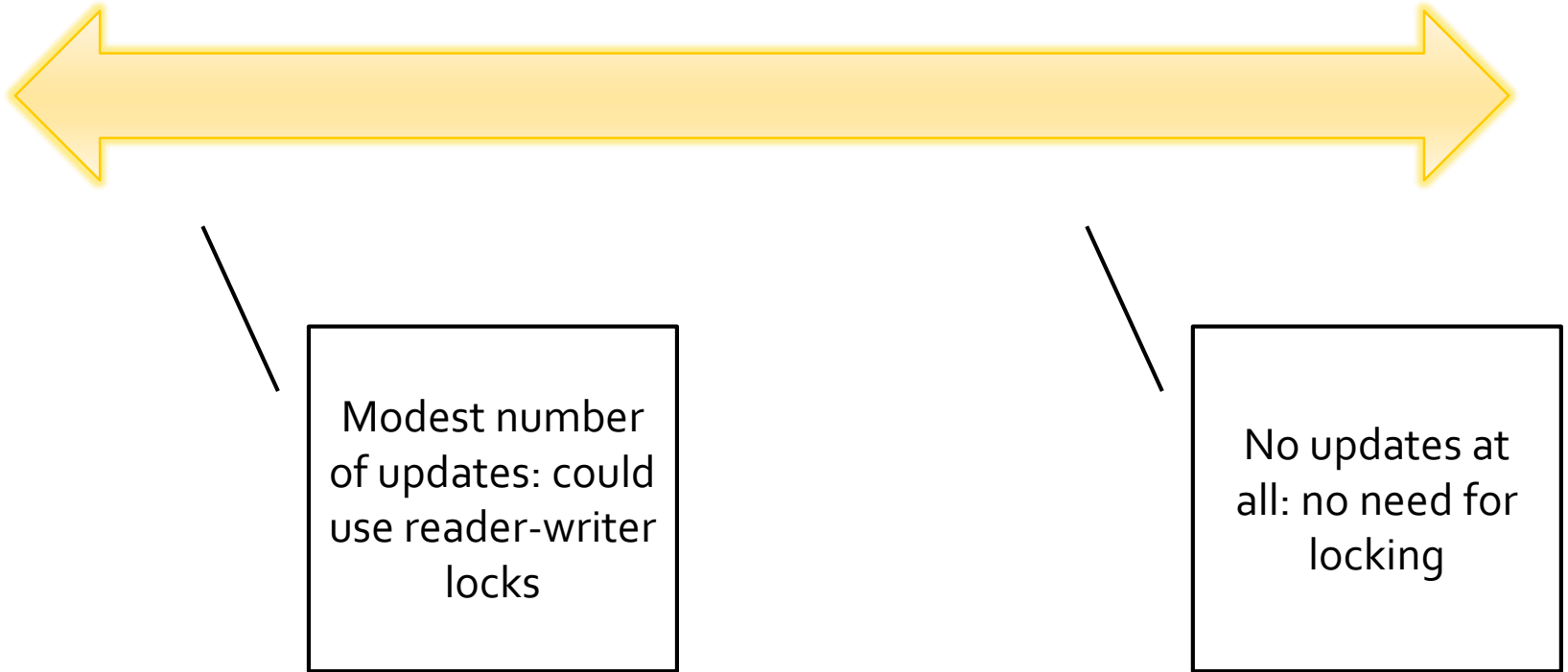
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(Do the assumptions hold? How slow is an uncontended CAS on a modern machine? Are these techniques still useful?)
- Inflation
  - Start out with a simple lock for likely-to-be-uncontended use
  - Replace with a “proper” lock if contended
  - David Bacon (thin locks), Agesen *et al* (meta-locks)
  - Motivating example: standard libraries in Java

# Where are we

- Amdahl's law: to scale to large numbers of cores, we need critical sections to be rare and/or short
- A lock implementation may involve updating a few memory locations
- Accessing a data structure may involve only a few memory locations too
- If we try to shrink critical sections then the time in the lock implementation becomes proportionately greater
- So:
  - try to make the cost of the operations in the critical section lower, or
  - try to write critical sections correctly without locking

# Reading without locking

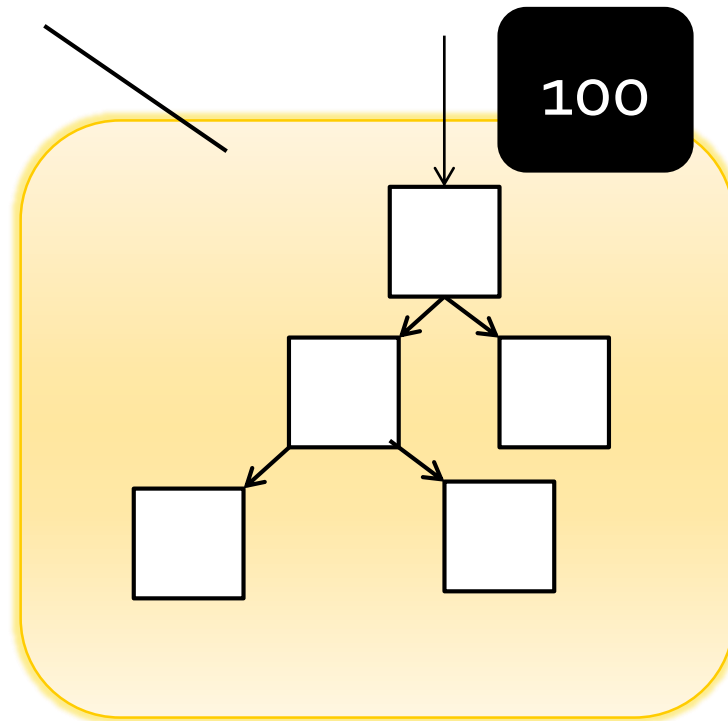
# What if updates are very rare





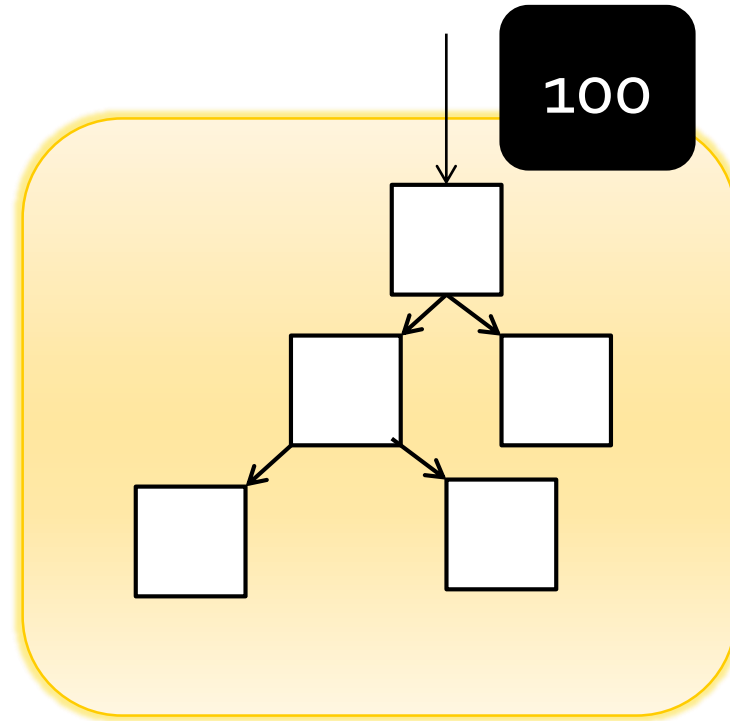
# Version numbers

Sequential  
data structure  
with write  
lock



Per-data-  
structure  
version  
number

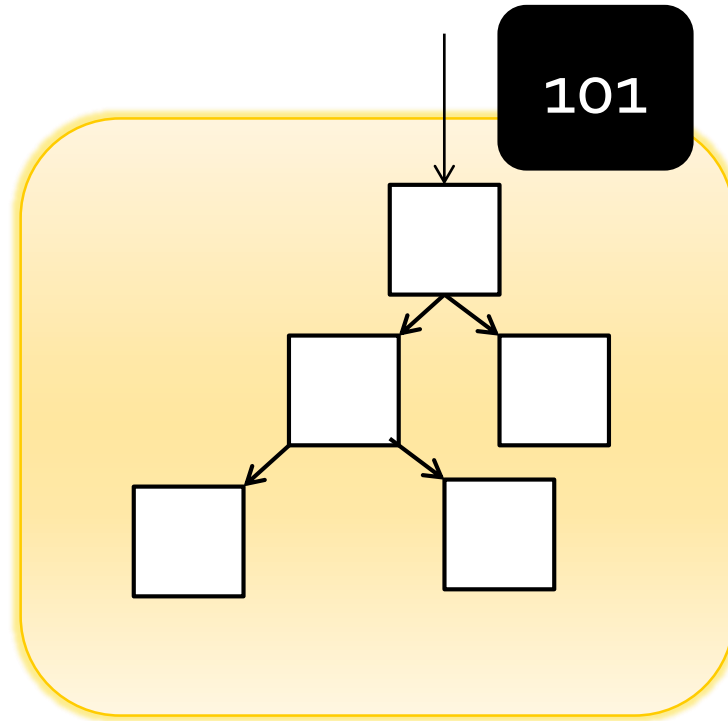
# Version numbers: writers



# Version numbers: writers

*Writers:*

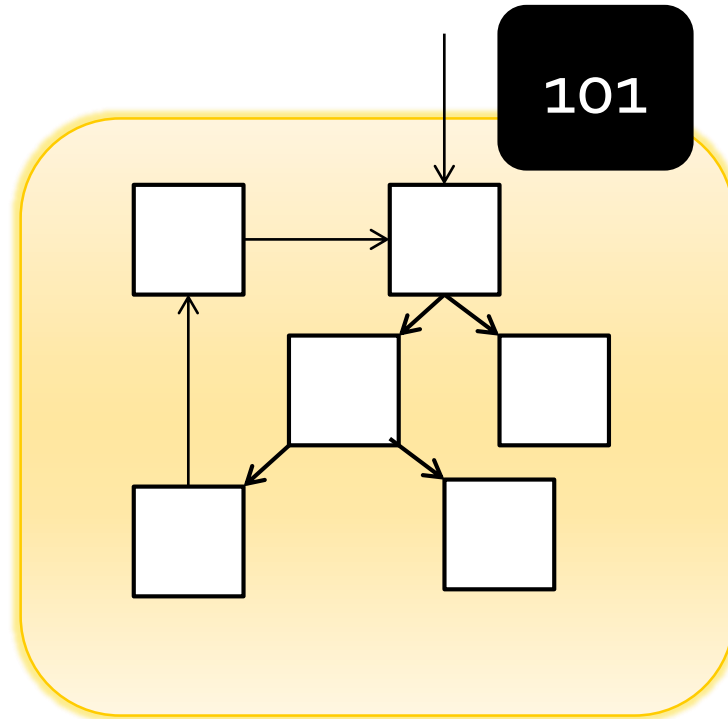
1. Take write lock
2. Increment version number



# Version numbers: writers

*Writers:*

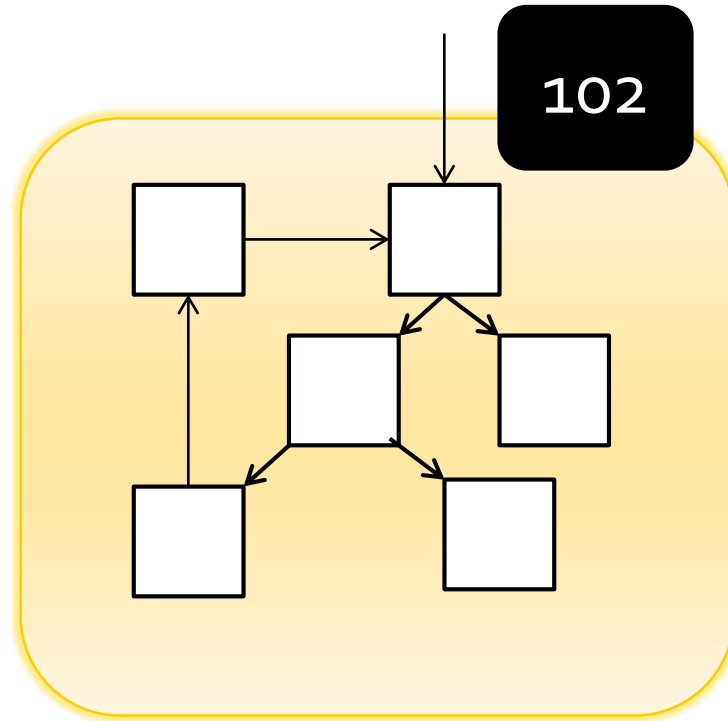
1. Take write lock
2. Increment version number
3. Make update



# Version numbers: writers

*Writers:*

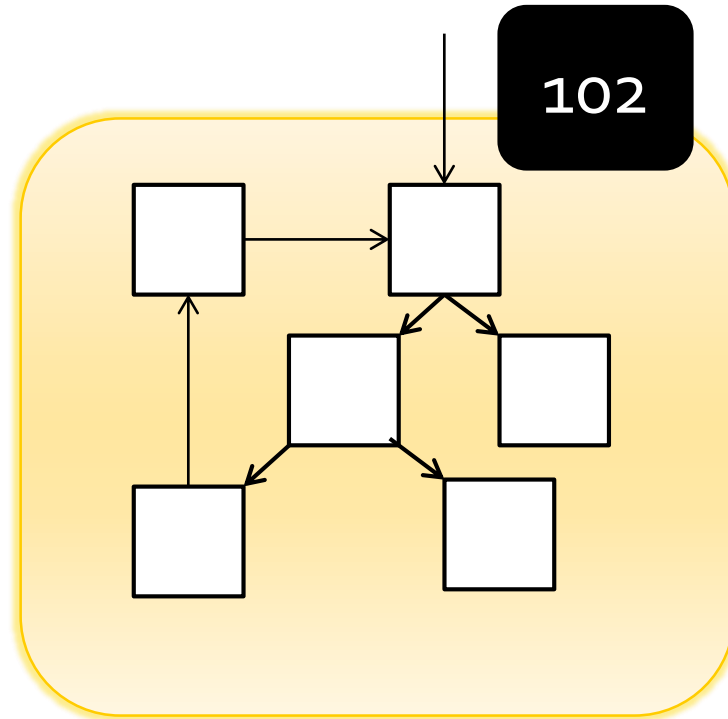
1. Take write lock
2. Increment version number
3. Make update
4. Increment version number
5. Release write lock



# Version numbers: readers

## *Writers:*

1. Take write lock
2. Increment version number
3. Make update
4. Increment version number
5. Release write lock



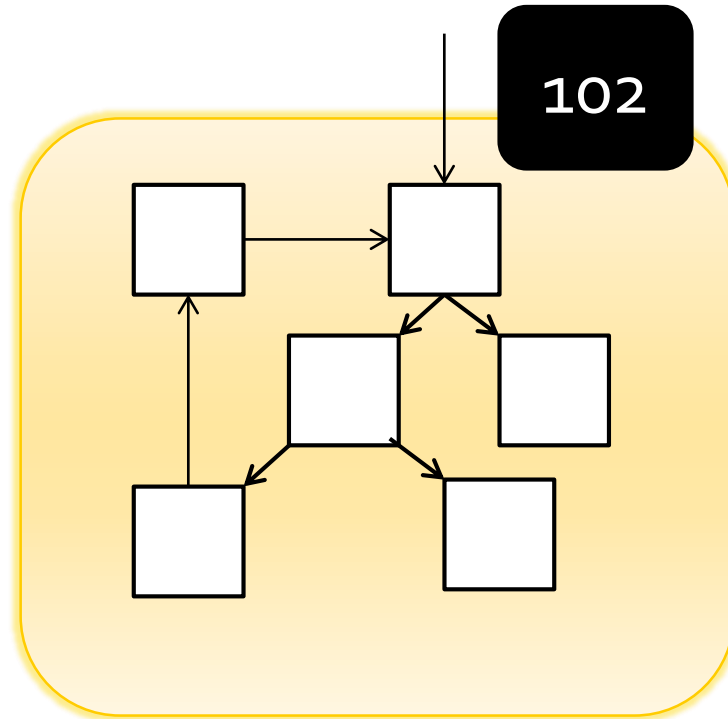
## *Readers:*

1. Wait for version number to be even

# Version numbers: readers

## *Writers:*

1. Take write lock
2. Increment version number
3. Make update
4. Increment version number
5. Release write lock



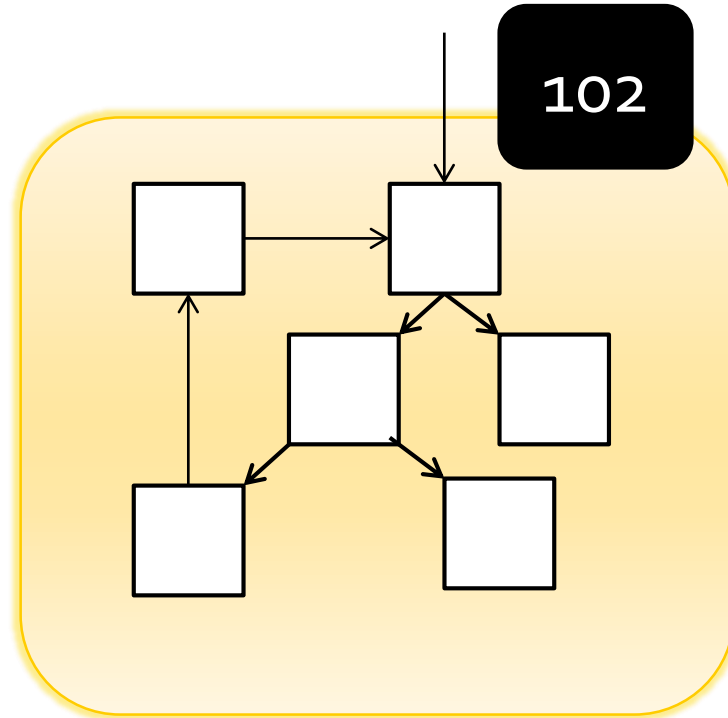
## *Readers:*

1. Wait for version number to be even
2. Do operation

# Version numbers: readers

## *Writers:*

1. Take write lock
2. Increment version number
3. Make update
4. Increment version number
5. Release write lock



## *Readers:*

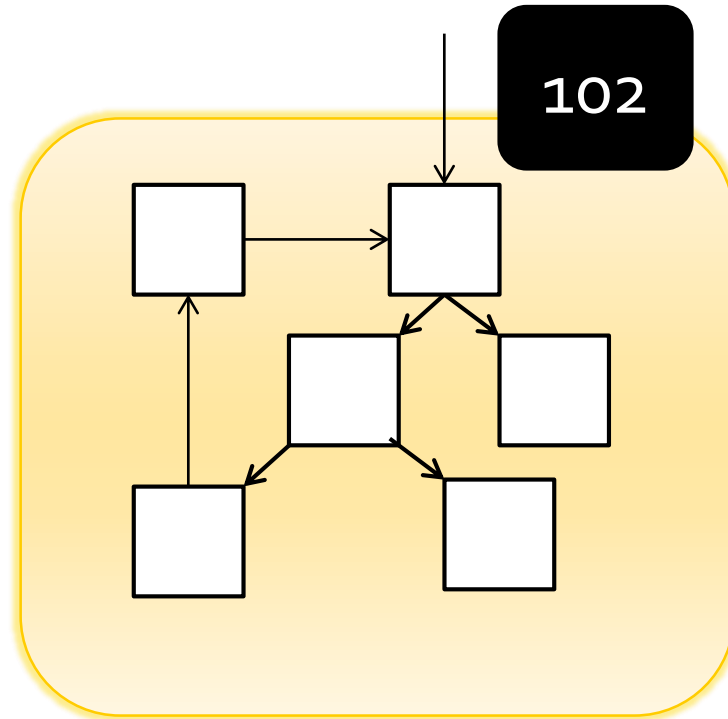
1. Wait for version number to be even
2. Do operation
3. Has the version number changed?
4. Yes? Go to 1



# Why do we need the two steps?

## Writers:

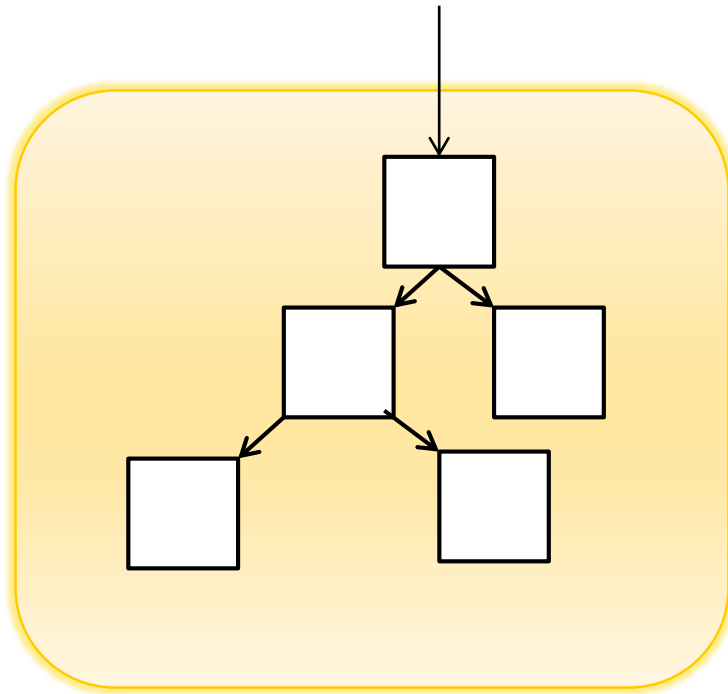
1. Take write lock
2. Increment version number
3. Make update
4. Increment version number
5. Release write lock



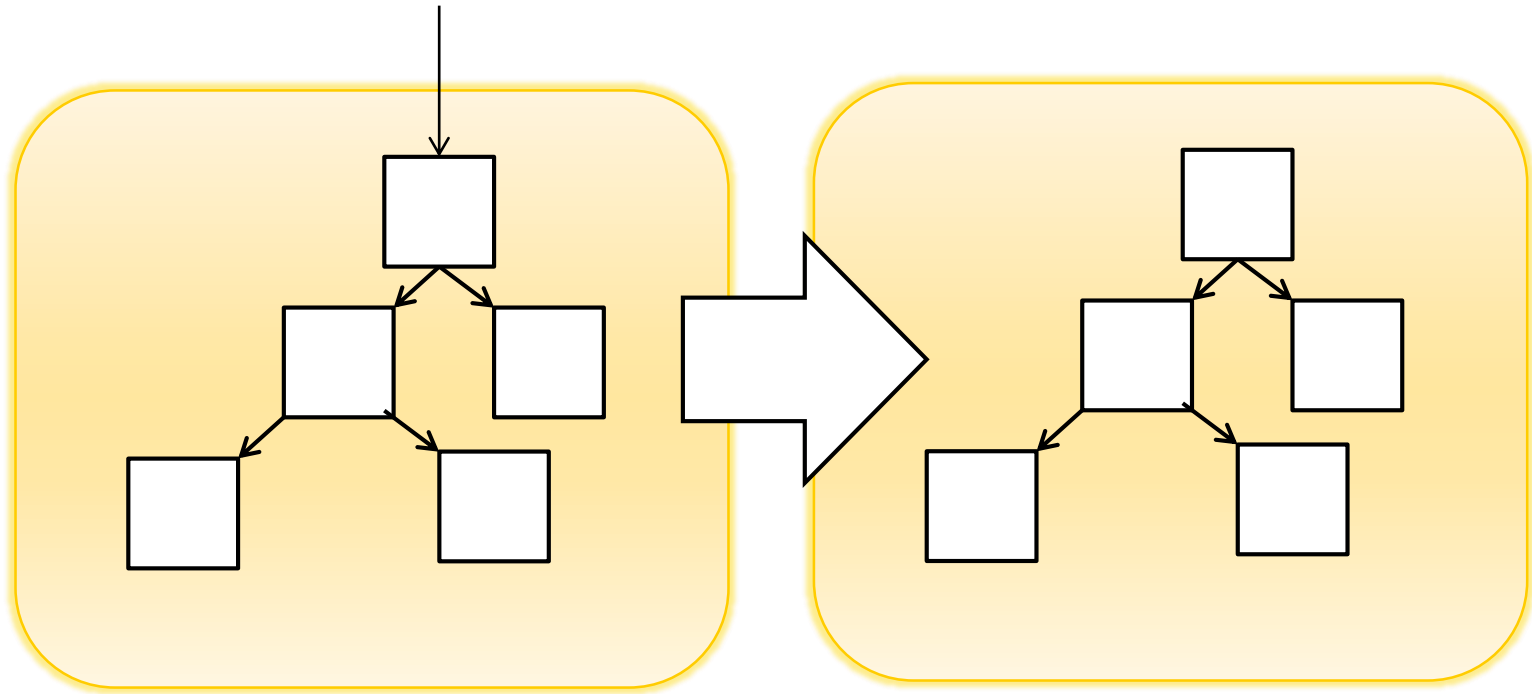
## Readers:

1. Wait for version number to be even
2. Do operation
3. Has the version number changed?
4. Yes? Go to 1

# Read-Copy-Update (RCU)

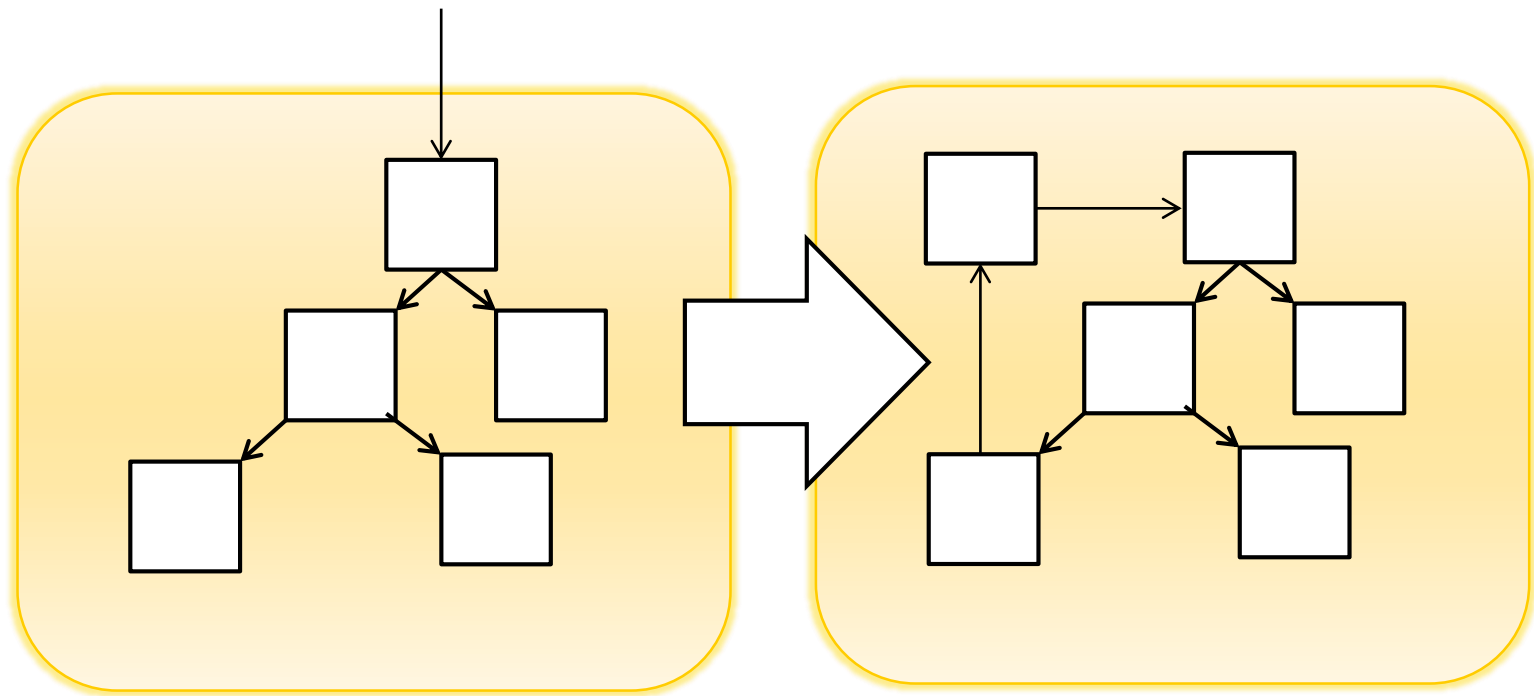


# Read-Copy-Update (RCU)



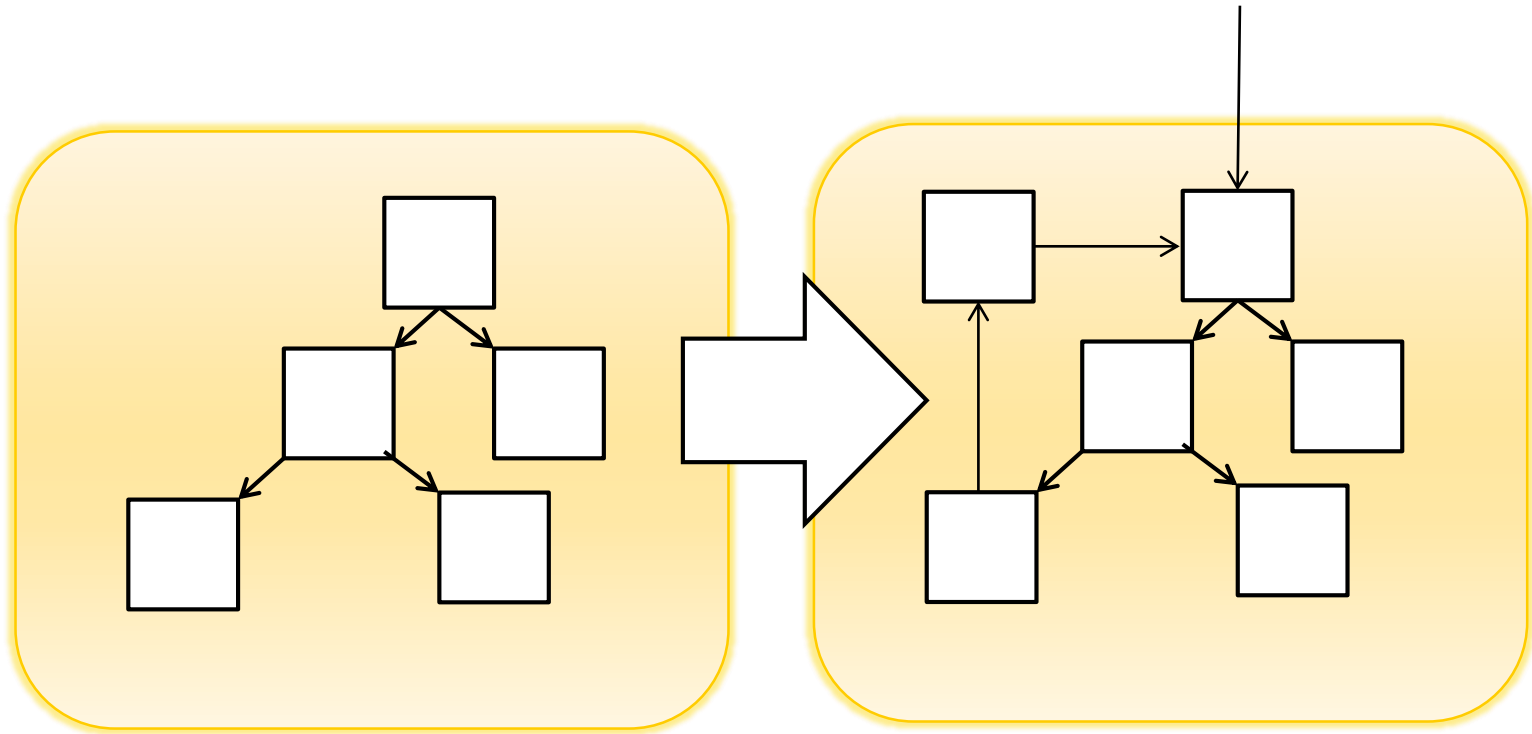
1. Copy existing structure

# Read-Copy-Update (RCU)



1. Copy existing structure
2. Update copy

# Read-Copy-Update (RCU)



1. Copy existing structure
2. Update copy
3. Install copy with CAS on root pointer

# Read-Copy-Update (RCU)

- Use locking to serialize updates (typically)
  - ...but allow readers to operate concurrently with updates
- Ensure that readers don't go wrong if they access data mid-update
  - Have data structures reachable via a single root pointer: update the root pointer rather than updating the data structure in-place
  - Ensure that updates don't affect readers – e.g., initializing nodes before splicing them into a list, and retaining “next” pointers in deleted nodes
  - Exact semantics offered can be subtle (ongoing research direction)
- Memory management problems common with lock-free data structures

# When will these techniques be effective?

- Update rate low
  - So the need to serialize updates is OK
- Readers behaviour is OK mid-update
  - E.g., structure small enough to clone, rather than update in place
  - Readers will be OK until a version number check (not enter endless loops / crash / etc.)
- Deallocation or re-use of memory can be controlled

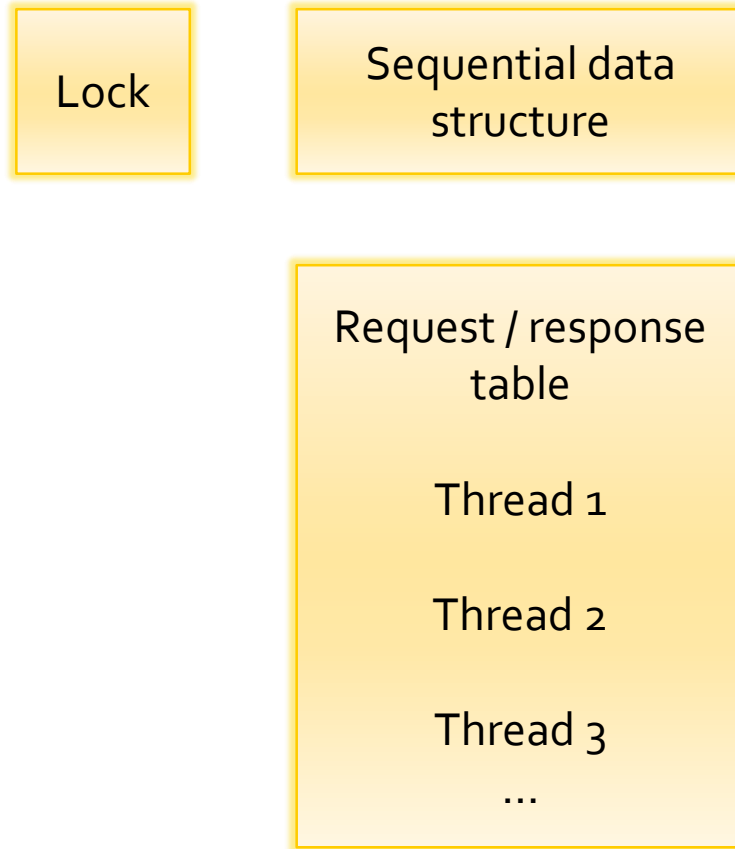
# Flat combining



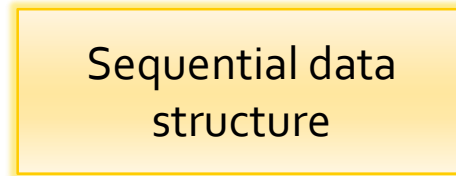
# Flat combining

- “Flat Combining and the Synchronization-Parallelism Tradeoff”, Hendler *et al*
- Intuition:
  - Acquiring and releasing a lock involves numerous cache line transfers on the interconnect
  - These may take hundreds of cycles (e.g., between cores in different NUMA nodes)
  - The work protected by the lock may involve only a few memory accesses...
  - ...and these accesses may be likely to hit in the cache of the previous lock holder (but miss in your own)
  - So: if a lock is not available, request that the current lock holder does the work on your behalf

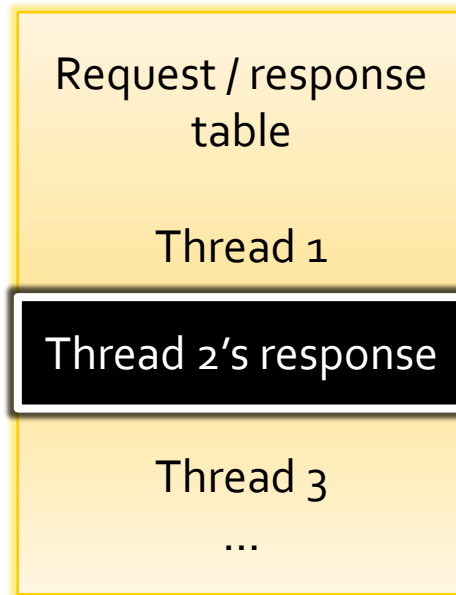
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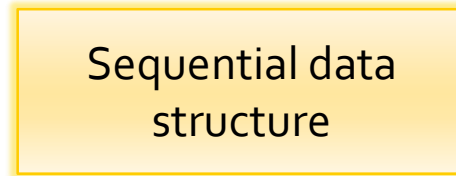
# Flat combining: uncontended acquire



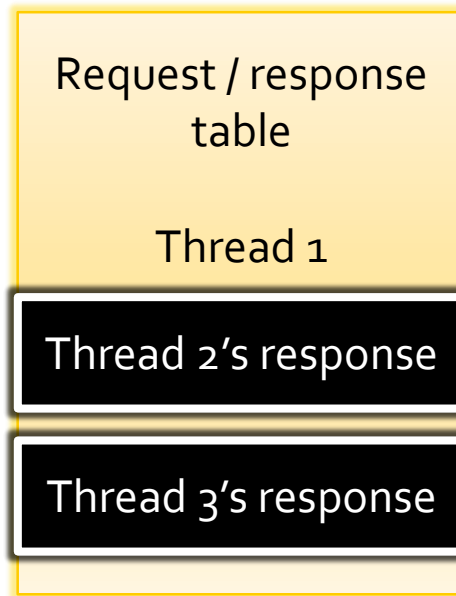
1. Write proposed op to req/resp table
2. Acquire lock if it is free
3. Process requests
4. Release lock
5. Pick up response



# Flat combining: contended acquire



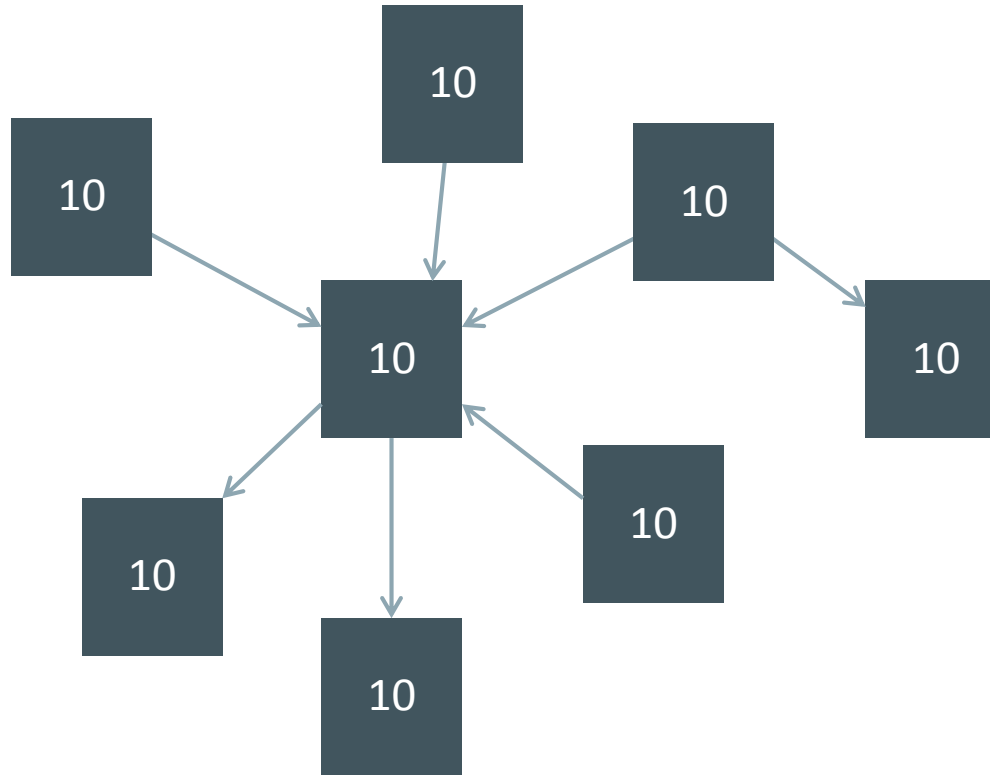
1. Write proposed op to req/resp table
2. See lock is not free
3. Wait for response
4. Pick up response



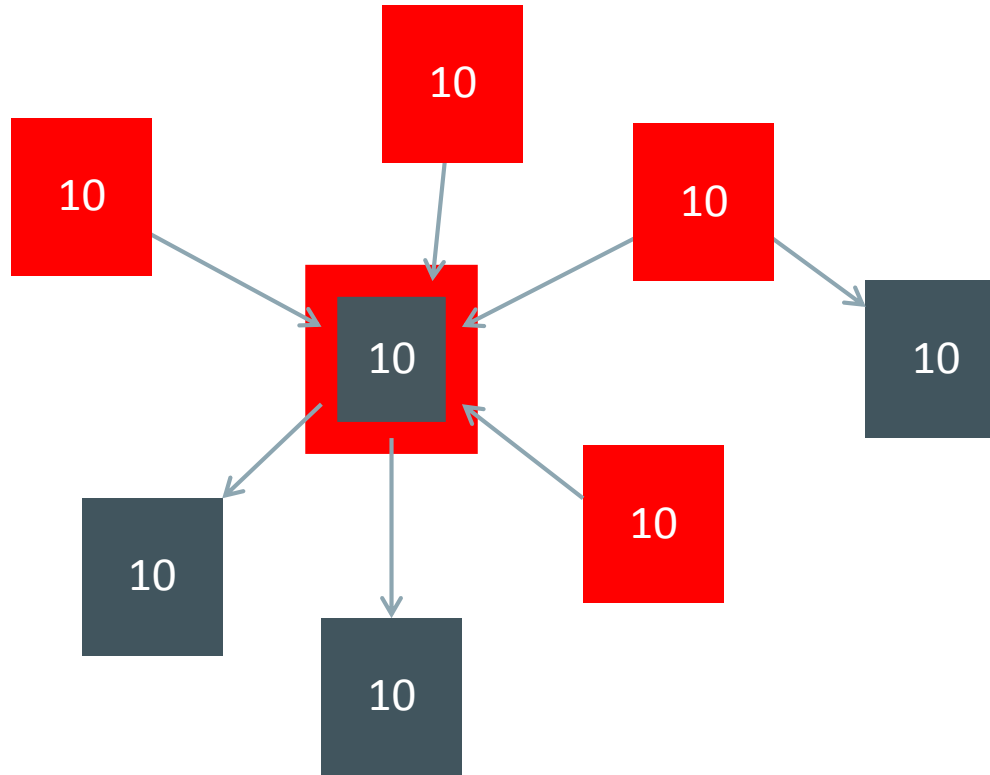
# Recent research: Parallel work distribution

The following is intended to provide some insight into a line of research in Oracle Labs. It is intended for information purposes only, and may not be incorporated into any contract. It is not a commitment to deliver any material, code, or functionality, and should not be relied upon in making purchasing decisions. Oracle reserves the right to alter its development plans and practices at any time, and the development, release, and timing of any features or functionality described in connection with any Oracle product or service remains at the sole discretion of Oracle. Any views expressed in this presentation are my own and do not necessarily reflect the views of Oracle.

# PageRank inner loop

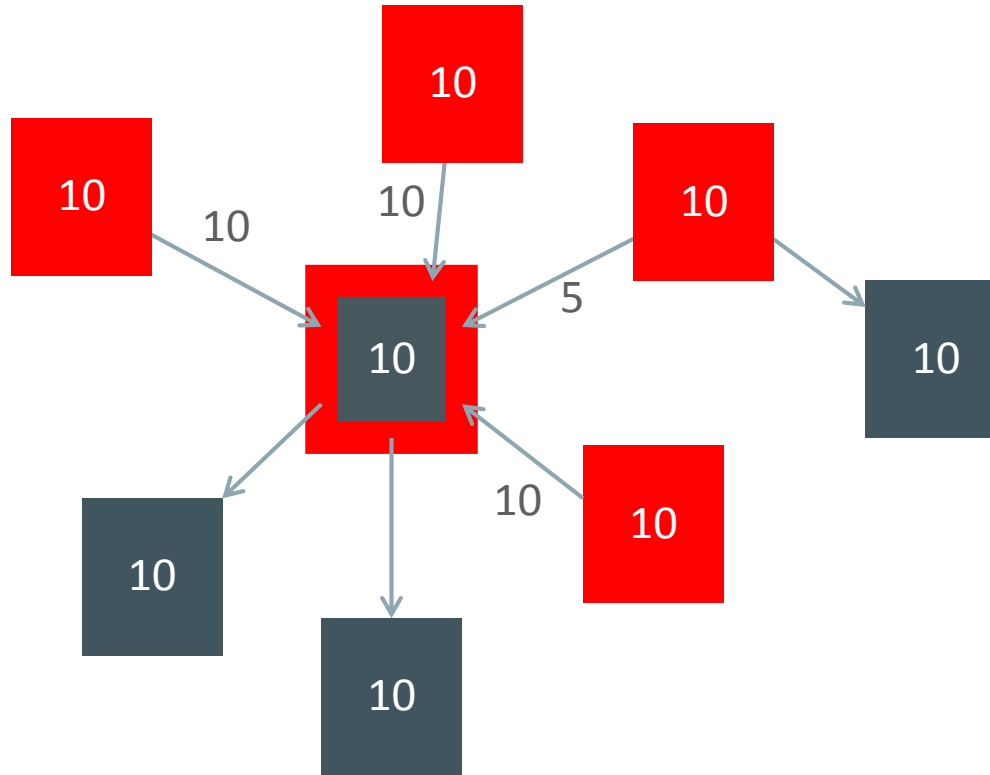


# PageRank inner loop

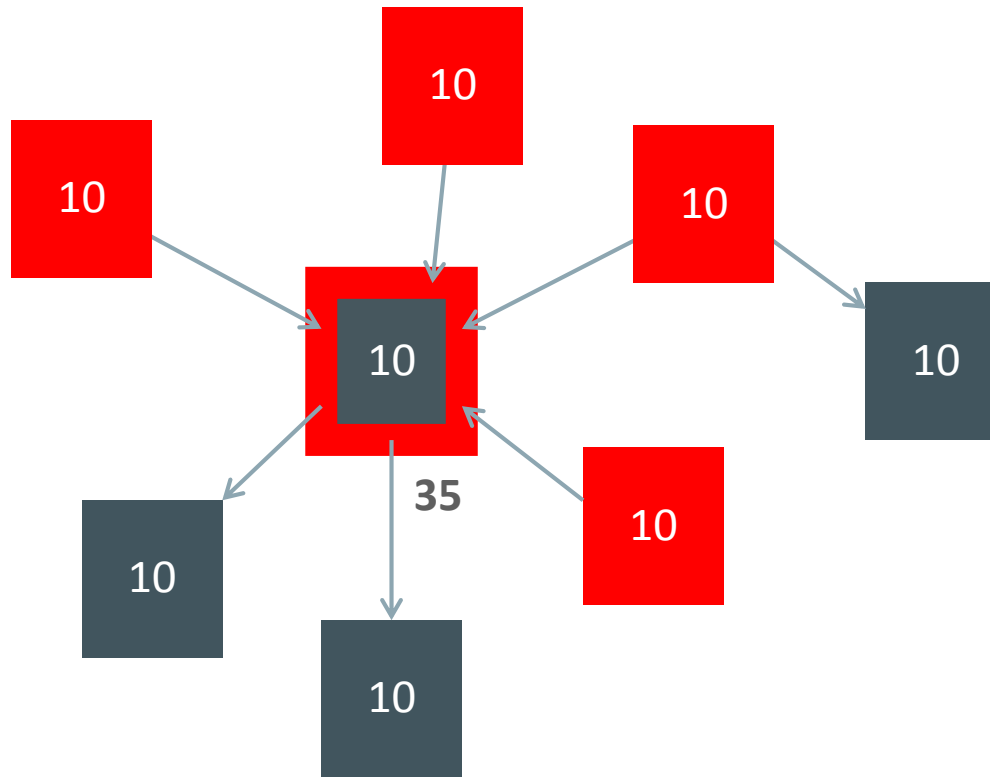




# PageRank inner loop



# PageRank inner loop



# Batch size / load imbalance trade-off



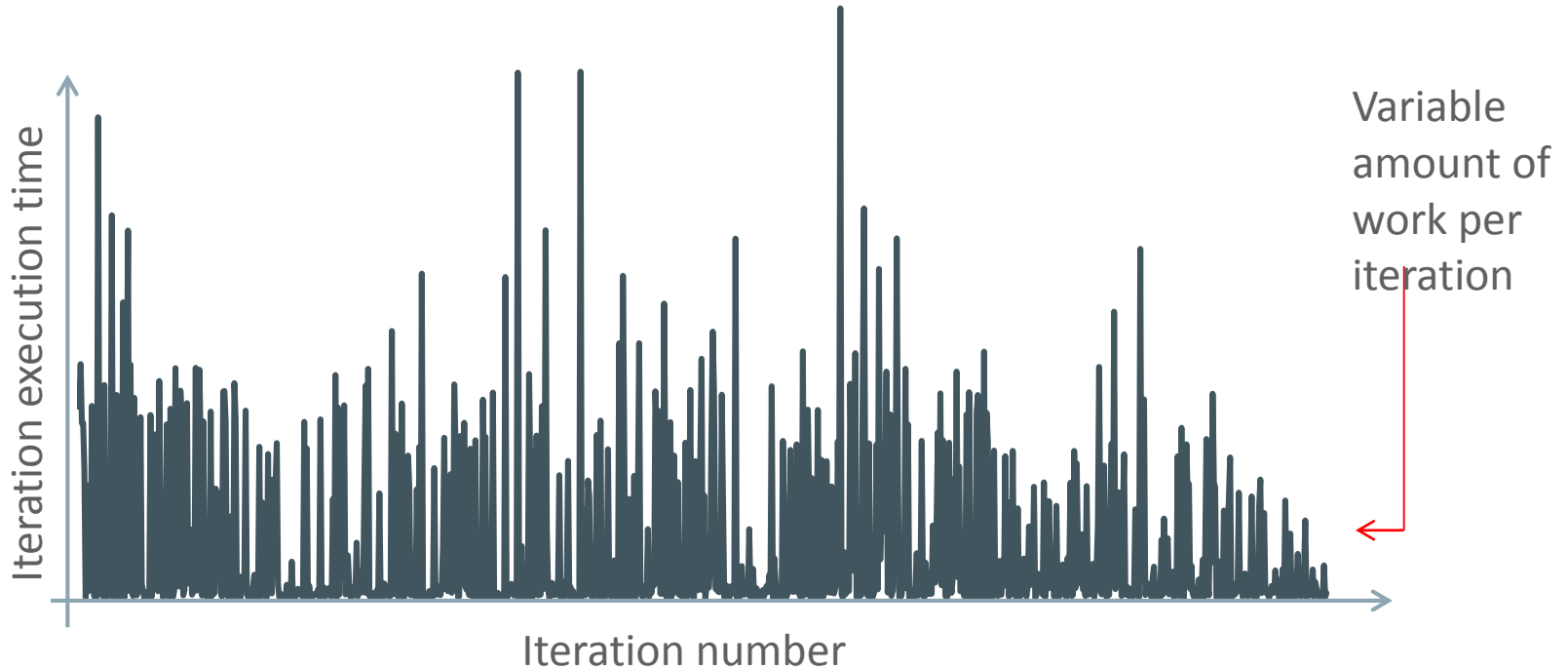
Divide into large batches of vertices

Reduce overheads  
Risk load imbalance

Divide into small batches of vertices

Increase overheads distributing work  
Achieve better load balance

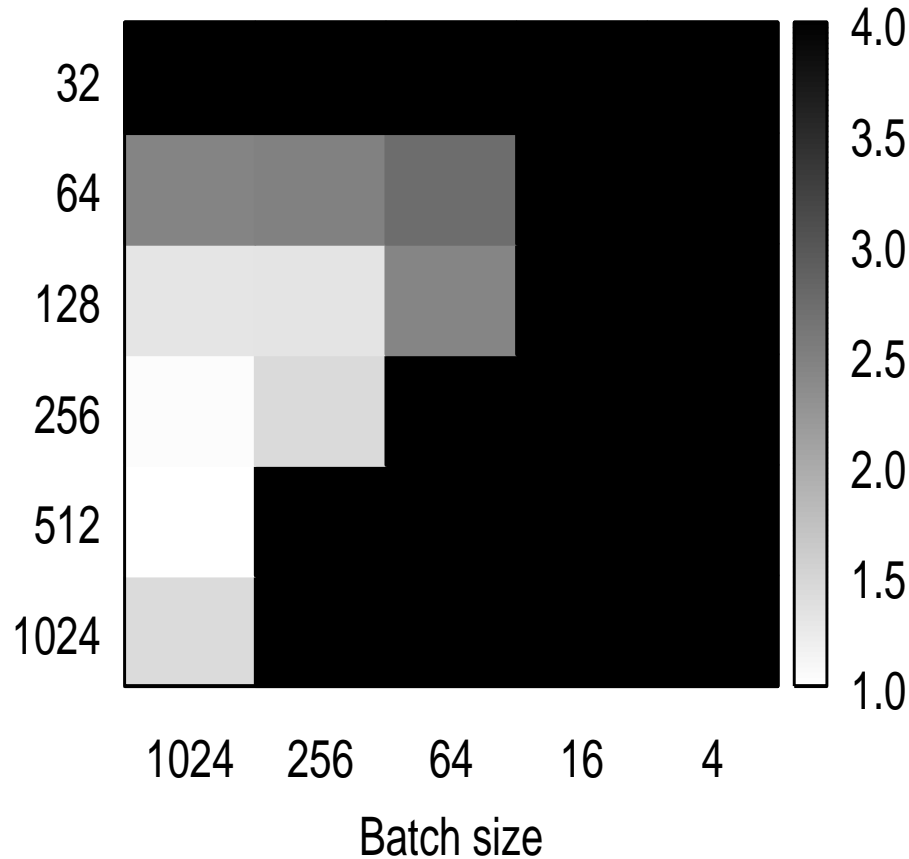
# Batch size / load imbalance trade-off



(Actual data – #out-edges of the top 1000 nodes in the SNAP Twitter dataset)

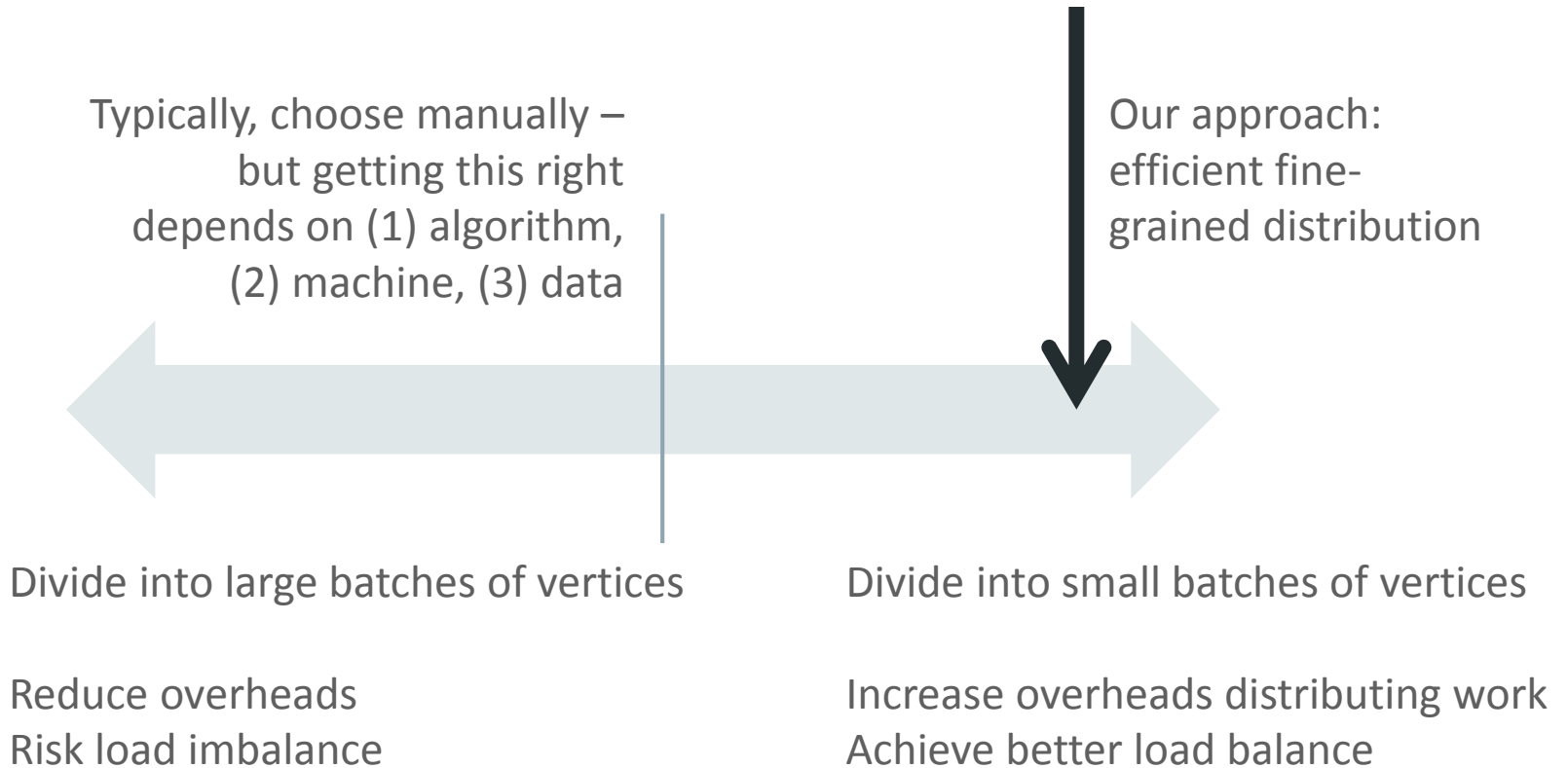
# Example performance

Complete PageRank execution, SNAP LiveJournal data set



8-socket SPARC T5  
16 cores per socket  
8 h/w threads per core

# Batch size / load imbalance trade-off

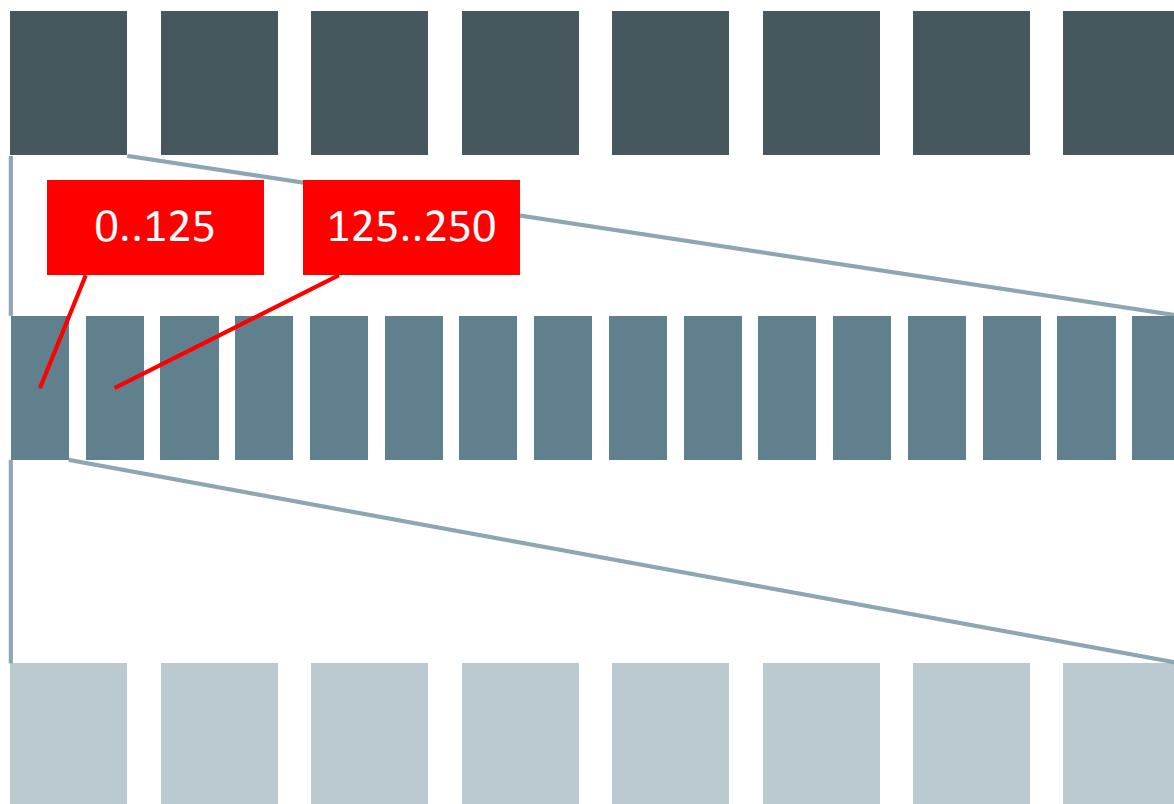


Consider distributing 0..16000 vertices,  
batch size 10



8 sockets

# Consider distributing 0..16000 vertices, batch size 10



8 sockets

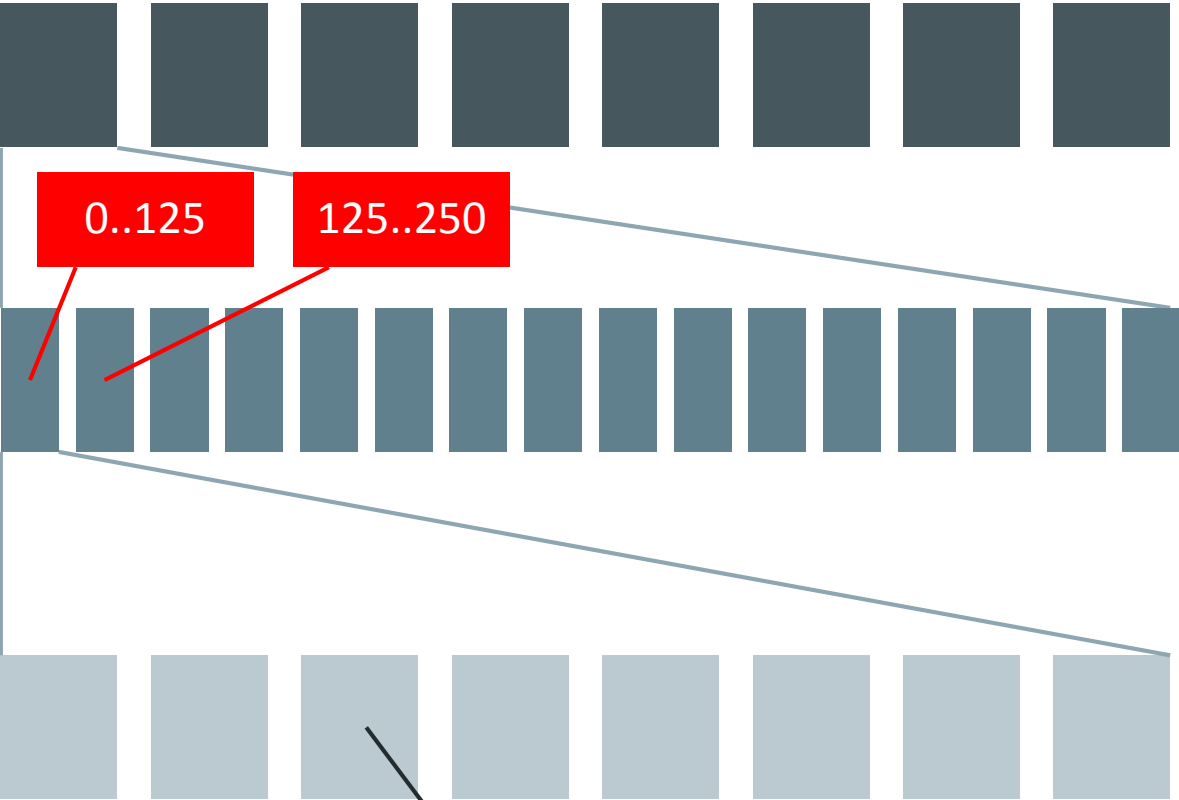
Distribute vertices at  
start of loop down to  
per-core counters

16 cores per socket

8 h/w threads per core



# Consider distributing 0..16000 vertices, batch size 10



8 sockets

Distribute vertices at  
start of loop down to  
per-core counters

16 cores per socket

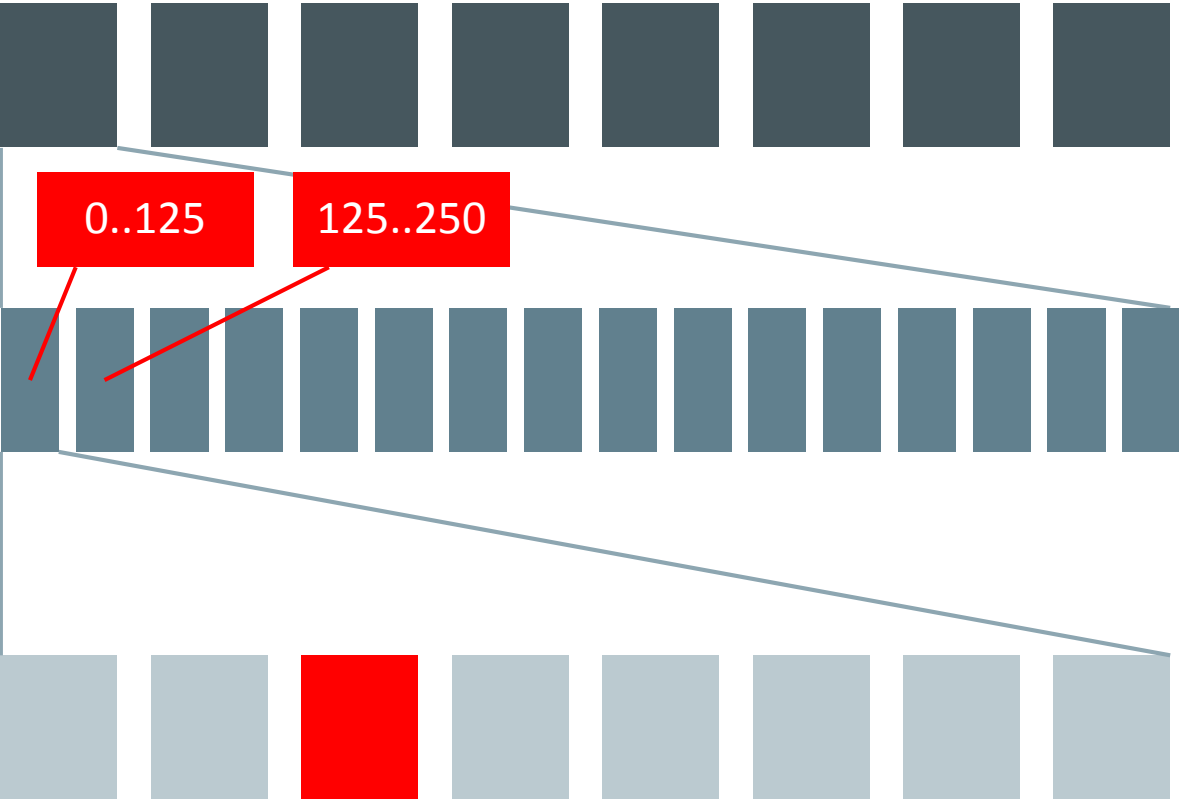
Aggregate requests  
upwards within a core

8 h/w threads per core

Per-thread request flags



# Consider distributing 0..16000 vertices, batch size 10



8 sockets

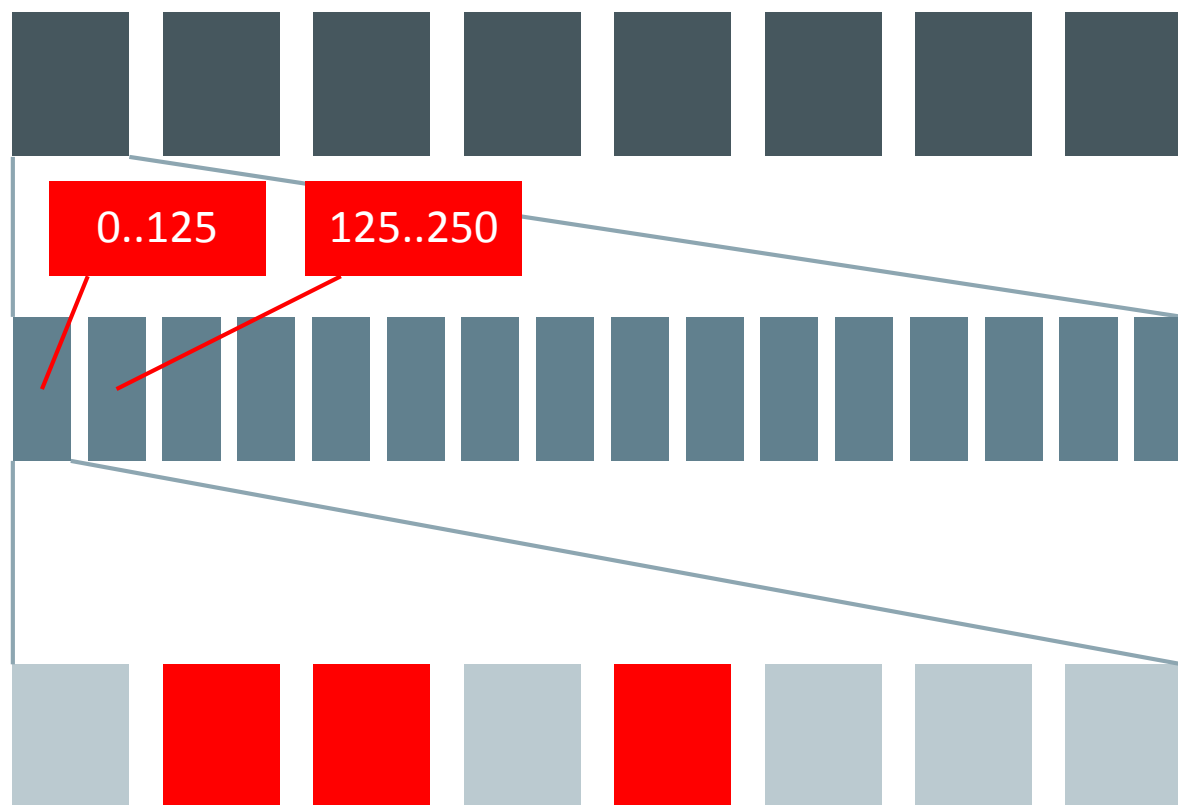
Distribute vertices at  
start of loop down to  
per-core counters

16 cores per socket

Aggregate requests  
upwards within a core

8 h/w threads per core

# Consider distributing 0..16000 vertices, batch size 10



8 sockets

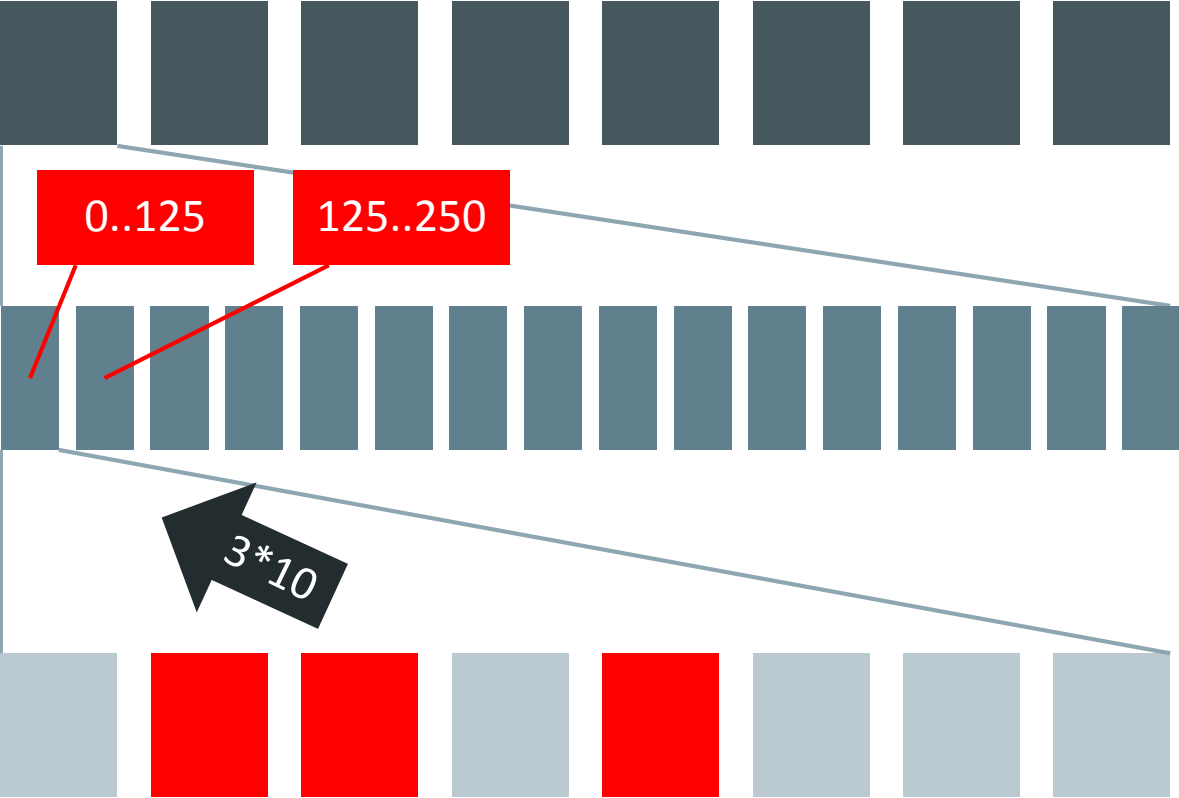
Distribute vertices at  
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16 cores per socket

Aggregate requests  
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8 h/w threads per core

# Consider distributing 0..16000 vertices, batch size 10



8 sockets

Distribute vertices at  
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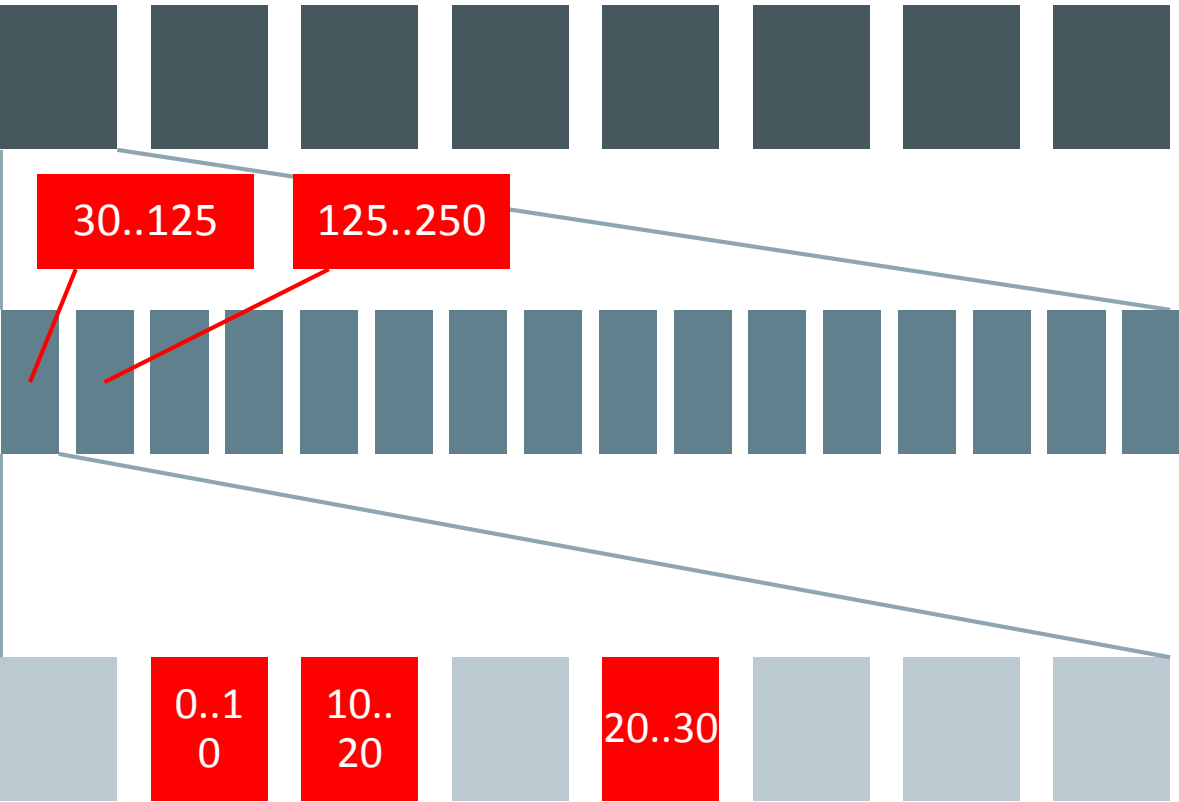
16 cores per socket

Aggregate requests  
upwards within a core

8 h/w threads per core



# Consider distributing 0..16000 vertices, batch size 10



8 sockets

Distribute vertices at start of loop down to per-core counters

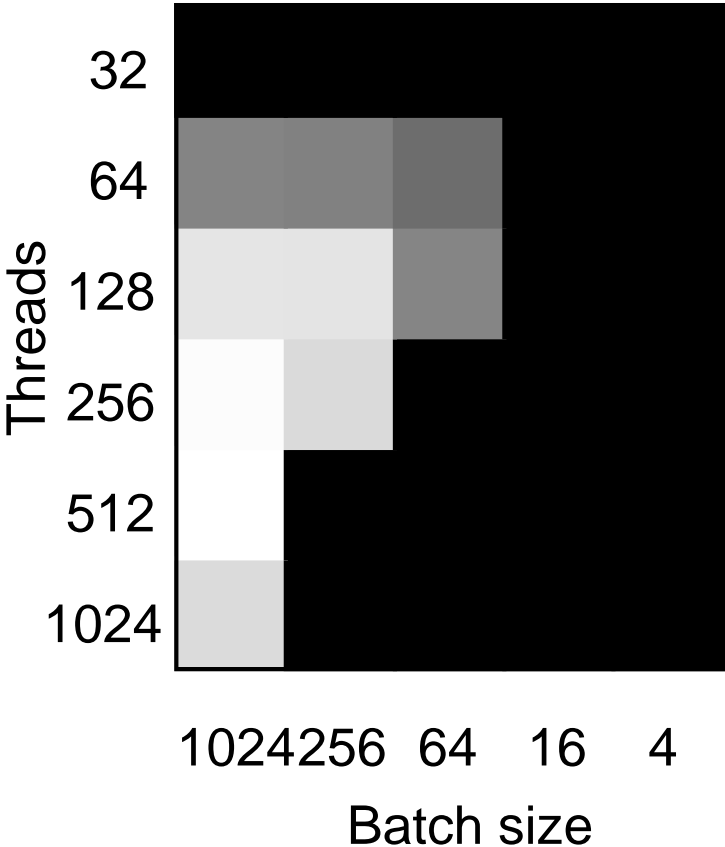
16 cores per socket

Aggregate requests upwards within a core

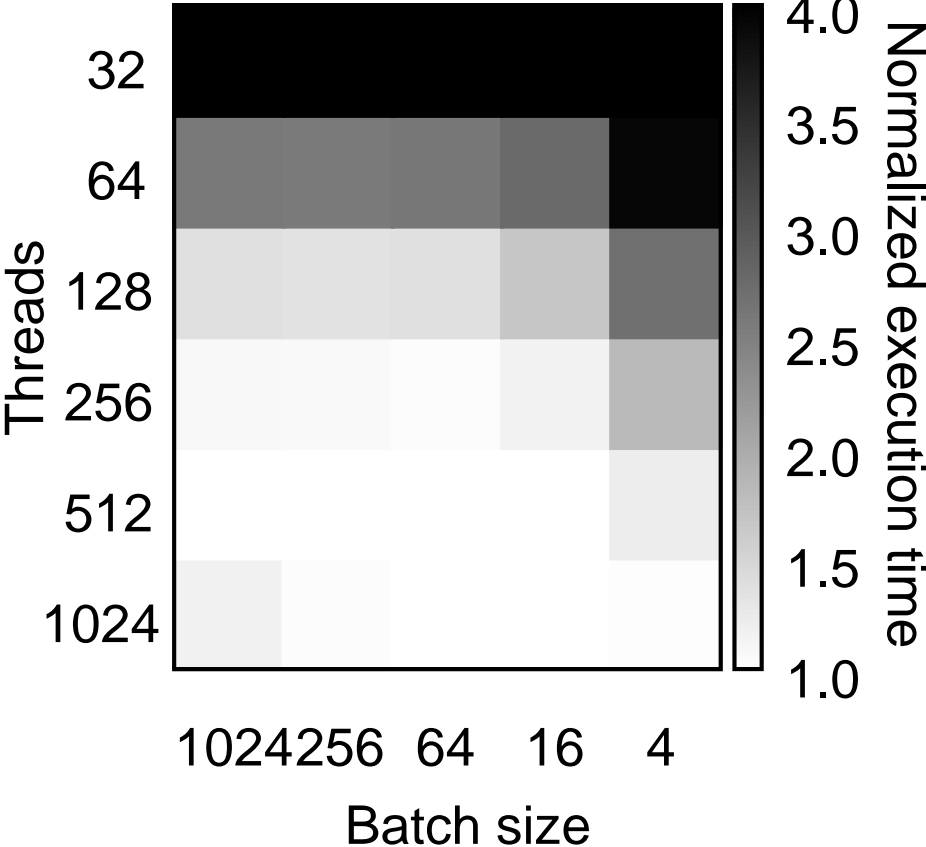
8 h/w threads per core

# PageRank – SNAP LiveJournal (4.8M vertices, 69M edges)

Before



After



# More details

- [Callisto-RTS: Fine-Grain Parallel Loops](#)
- Tim Harris, Stefan Kaestle, *USENIX ATC 2015*
- <https://timharris.uk/papers/2015-atc-callisto.pdf>