13: Betweenness Centrality Machine Learning and Real-world Data

Ann Copestake and Simone Teufel

Computer Laboratory University of Cambridge

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Last session: some simple network statistics

- You measured the degree of each node and the diameter of the network.
- Next two sessions:
 - Today: finding gatekeeper nodes via betweenness centrality.
 - Monday: using betweenness centrality of edges to split graph into cliques.
- Reading for social networks (all sessions):
 - Easley and Kleinberg for background: Chapters 1, 2, 3 (especially 3.6) and first part of Chapter 20.
 - Brandes algorithm: two papers by Brandes (links in practical notes).



Intuition behind clique finding

- Certain nodes/edges are most crucial in linking densely connected regions of the graph: informally gatekeepers.
- Cutting those edges isolates the cliques/clusters.

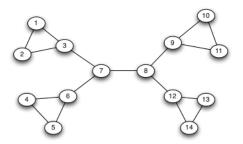


Figure 3-14a from Easley and Kleinberg (2010)

Intuition behind clique finding

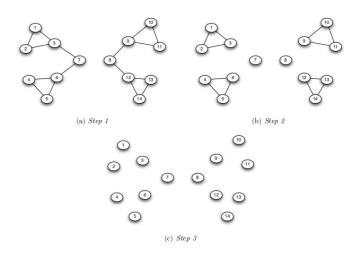


Figure 3-16 from Easley and Kleinberg (2010)

Gatekeepers: generalising the notion of local bridge

Last time we saw the concept of local bridge: an edge which increased the shortest paths if cut.

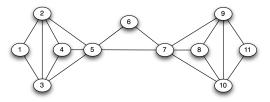
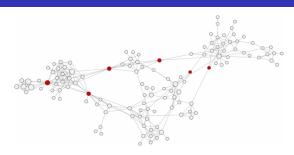


Figure 3-16 from Easley and Kleinberg (2010)

But, more generally, the nodes that are intuitively the gatekeepers can be determined by betweenness centrality.

Betweenness centrality

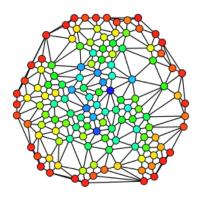


https://www.linkedin.com/pulse/wtf-do-you-actually-know-who-influencers-walter-pike

- The betweenness centrality of a node V is defined as the proportion of shortest paths between all pairs of nodes that go through V.
- Here: the red nodes have high betweenness centrality.
- Note: Easley and Kleinberg talk about 'flow': misleading because we only care about shortest paths.



Betweenness, example



Claudio Rocchini: https://commons.wikimedia.org/wiki/File:Graph_betweenness.svg

■ Betweenness: red is minimum; dark blue is maximum.

Betweenness centrality, formally (from Brandes 2008)

- Directed graph *G* =< *V*, *E* >
- $\sigma(s,t)$: number of shortest paths between nodes s and t
- $\sigma(s, t|v)$: number of shortest paths between nodes s and t that pass through v.
- $lue{C}_B(v)$, the betweenness centrality of v:

$$C_B(v) = \sum_{s,t \in V} \frac{\sigma(s,t|v)}{\sigma(s,t)}$$

- If s = t, then $\sigma(s, t) = 1$
- If $v \in s$, t, then $\sigma(s, t|v) = 0$

Number of shortest paths

 $\sigma(s,t)$ can be calculated recursively:

$$\sigma(s,t) = \sum_{u \in Pred(t)} \sigma(s,u)$$

- Pred $(t) = \{u : (u, t) \in E, d(s, t) = d(s, u) + 1\}$ predecessors of t on shortest path from s
- \blacksquare d(s, u): Distance between nodes s and u
- This can be done by running Breadth First search with each node as source s once, for total complexity of O(V(V+E)).

Pairwise dependencies

There are a cubic number of pairwise dependencies $\delta(s, t|v)$ where:

$$\delta(s,t|v) = \frac{\sigma(s,t|v)}{\sigma(s,t)}$$

- Naive algorithm uses lots of space.
- Brandes (2001) algorithm intuition: the dependencies can be aggregated without calculating them all explicitly.
- Recursive: can calculate dependency of *s* on *v* based on dependencies one step further away.

One-sided dependencies

Define one-sided dependencies:

$$\delta(s|v) = \sum_{t \in V} \delta(s, t|v)$$

Then Brandes (2001) shows:

$$\delta(s|v) = \sum_{\substack{(v,w) \in E \\ w: \ d(s,w) = d(s,v) + 1}} \frac{\sigma(s,v)}{\sigma(s,w)} \cdot (1 + \delta(s|w))$$

And:

$$C_B(v) = \sum_{s \in V} \delta(s|v)$$

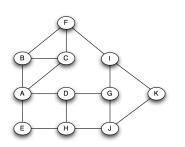
Brandes algorithm

- Iterate over all vertices s in V
- Calculate $\delta(s|v)$ for all $v \in V$ in two phases:
 - 1 Breadth-first search, calculating distances and shortest path counts from *s*, push all vertices onto stack as they're visited.
 - Visit all vertices in reverse order (pop off stack), aggregating dependencies according to equation.

Brandes (2008) pseudocode

```
Shortest-path vertex betweenness (Brandes, 2001).
input: directed graph G = (V, E)
data: queue Q, stack S (both initially empty)
       and for all v \in V:
       dist[v]: distance from source
       Pred[v]: list of predecessors on shortest paths from source
       \sigma[v]: number of shortest paths from source to v \in V
       \delta[v]: dependency of source on v \in V
output: betweenness c_R[v] for all v \in V (initialized to 0)
for s \in V do
     ▼ single-source shortest-paths problem
         ▼ initialization
            for w \in V do Pred[w] \leftarrow \text{empty list}
            for t \in V do dist[t] \leftarrow \infty; \sigma[t] \leftarrow 0
             dist[s] \leftarrow 0; \sigma[s] \leftarrow 1
            enqueue s \rightarrow Q
        while Q not empty do
            dequeue v \leftarrow Q; push v \rightarrow S
            foreach vertex w such that (v, w) \in E do
                  ▼ path discovery // — w found for the first time?
                     if dist[w] = \infty then
                         dist[w] \leftarrow dist[v] + 1
                         enqueue w \rightarrow Q
                  ▼ path counting // — edge (v, w) on a shortest path?
                     if dist[w] = dist[v] + 1 then
                         \sigma[w] \leftarrow \sigma[w] + \sigma[v]
                         append v \rightarrow Pred[w]
     ▼ accumulation // — back-propagation of dependencies
        for v \in V do \delta[v] \leftarrow 0
        while S not empty do
            for v \in Pred[w] do \delta[v] \leftarrow \delta[v] + \frac{\sigma[v]}{\sigma[w]} \cdot (1 + \delta[w])
            if w \neq s then c_B[w] \leftarrow c_B[w] + \delta[w]
```

Step 1 - Prepare for BFS tree walk (Node A as *s*)



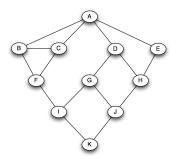
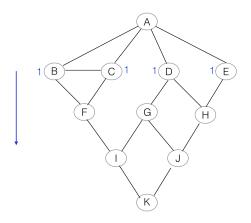


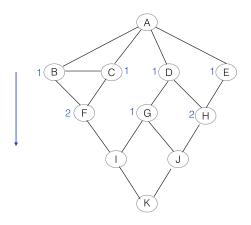
Figure 3-18 from Easley and Kleinberg (2010)

Brandes (2008) pseudocode: phase 1

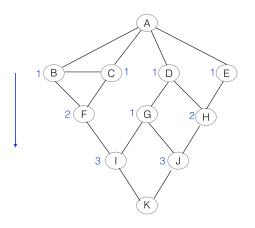
```
while Q not empty do
       dequeue v \leftarrow Q; push v \rightarrow S
     foreach vertex w such that (v, w) \in E do
            ▼ path discovery // — w found for the first time?
 if dist[w] = \infty then
dist[w] \leftarrow dist[v] + 1
enqueue w \rightarrow Q
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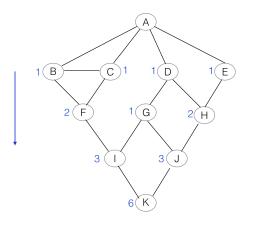
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Brandes (2008) pseudocode: phase 2

```
▼ accumulation // — back-propagation of dependencies

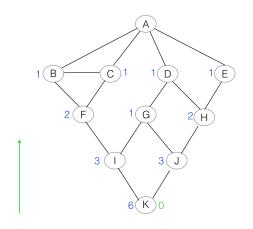
for v \in V do \delta[v] \leftarrow 0

while S not empty do

pop w \leftarrow S

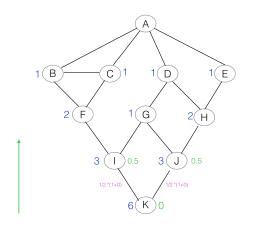
for v \in Pred[w] do \delta[v] \leftarrow \delta[v] + \frac{\sigma[v]}{\sigma[w]} \cdot (1 + \delta[w])

if w \neq s then c_B[w] \leftarrow c_B[w] + \delta[w]
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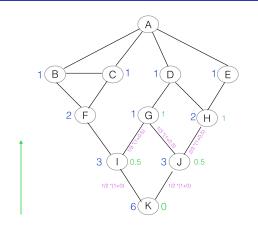


$$\delta(s|v) = \sum_{\substack{(v,w) \in E \\ w: d(s,w) = d(s,v)+1}} \sigma(s,v)/\sigma(s,w).(1+\delta(s|w))$$

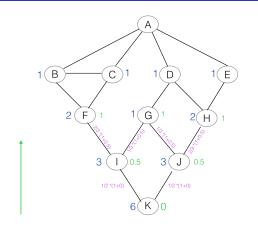




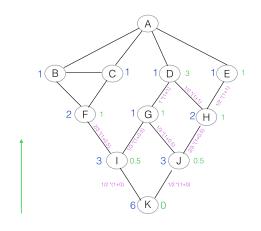
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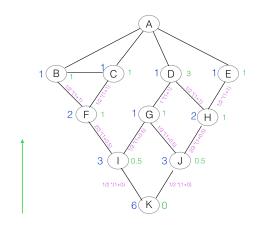


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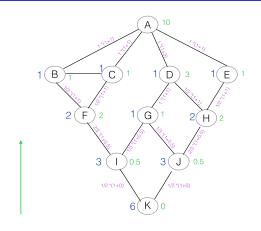


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Step 4 - Calculate betweenness centrality

- You saw one iteration with s = A.
- Now perform *V* iterations, once with each node as source.
- Sum up the $\delta(s|v)$ for each node: this gives the node's betweenness centrality.

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```

Brandes (2008): undirected graphs

- As specified, this is for directed graphs.
- But undirected graphs are easy: the algorithm works in exactly the same way, except that each pair is considered twice, once in each direction.
- Therefore: halve the scores at the end for undirected graphs.
- Brandes (2008) has lots of other variants, including edge betweenness centrality, which we'll use on Monday.

Today

- Task 11: Implement the Brandes algorithm for efficiently determining the betweenness of each node.
- Ticking: Task 10 Network statistics

Literature

- Textbook page 79-82 (does not use notation however)
- Ulrich Brandes (2001). A faster algorithm for betweenness centrality. *Journal of Mathematical Sociology*. 25:163–177.
- Ulrich Brandes (2008) On variants of shortest-path betweenness centrality and their generic computation. *Social Networks.* 30 (2008), pp. 136–145