

Last time: abstraction and parametricity

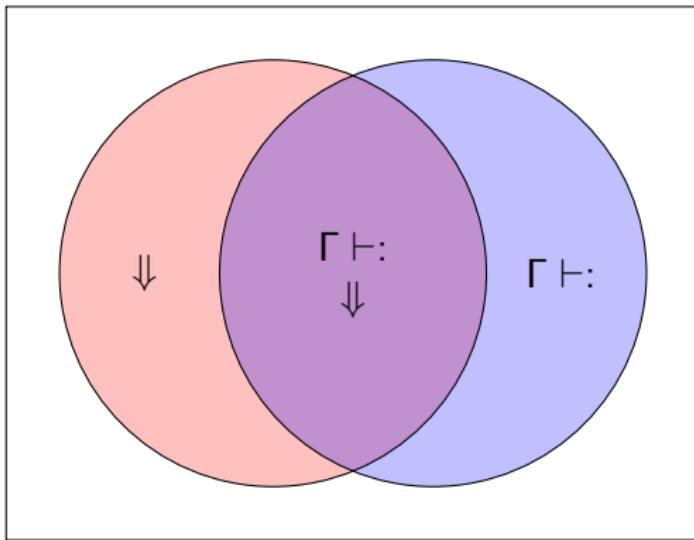
\exists

\forall

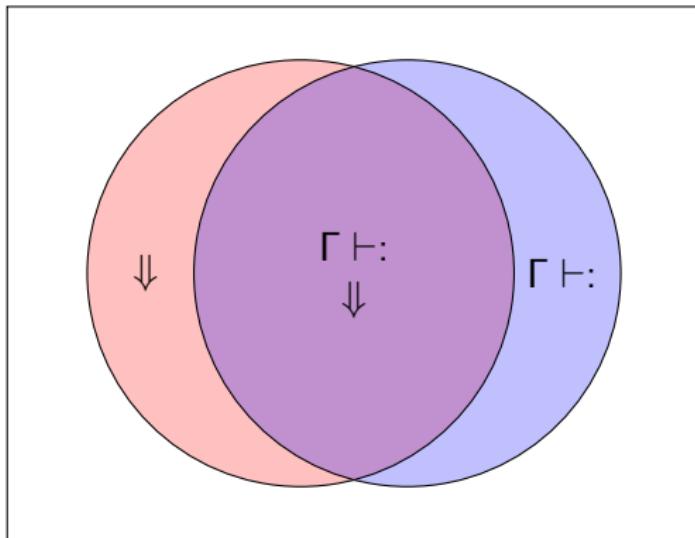
This time: GADTs

$$a \equiv b$$

What we gain



What we gain



(Addtionally, some programs become faster!)

What it costs

We'll need to:

describe our data more precisely

strengthen the **relationship between data and types**

look at programs through a **propositions-as-types lens**

What we'll write

Non-regularity in constructor return types

```
type _ t = T : t1 → t2 t
```

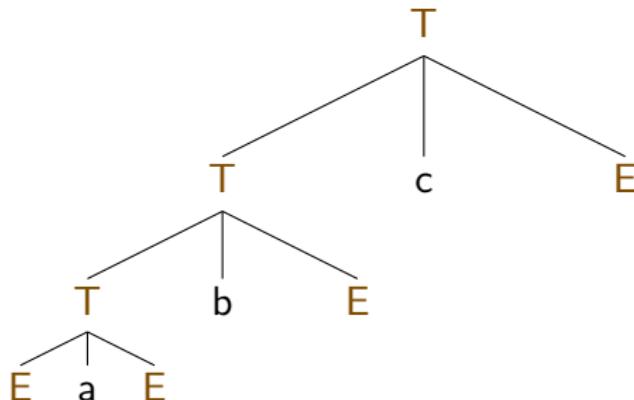
Locally abstract types:

```
let f : type a b. a t → b t = function ...
```

```
let g (type a) (type b) (x : a t) : b t = ...
```

Nested types

Unconstrained trees



```
type 'a tree =
  Empty : 'a tree
  | Tree : 'a tree * 'a * 'a tree → 'a tree
```

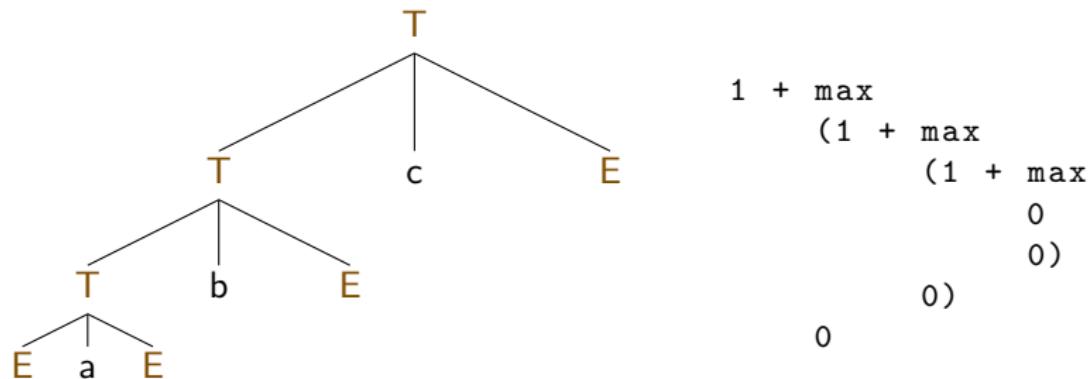
Term inference for unconstrained trees

```
val ? : 'a tree → int
```

```
val ? : 'a tree → 'a option
```

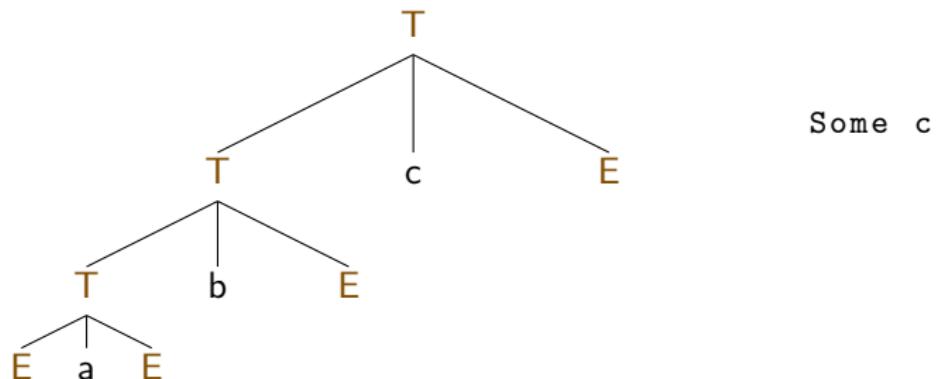
```
val ? : 'a tree → 'a tree
```

Unconstrained trees: depth



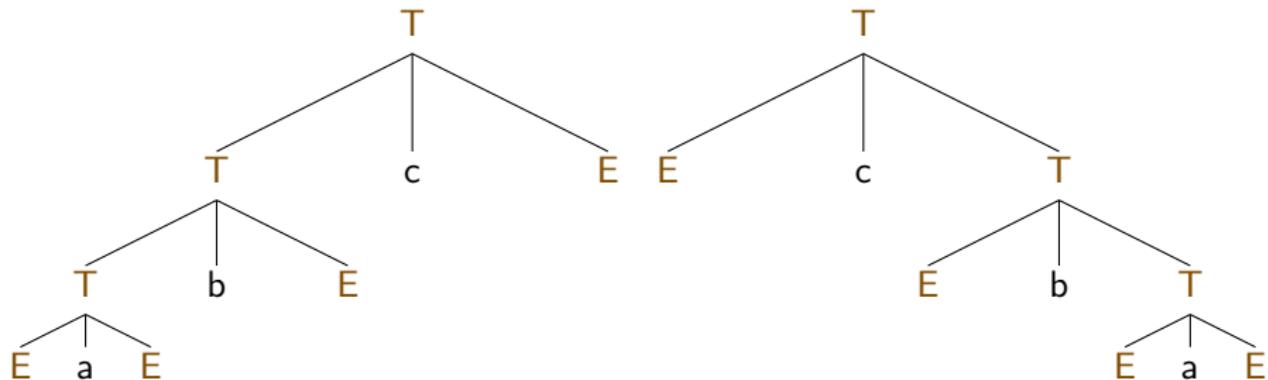
```
let rec depth : 'a . 'a tree → int =
  function
    Empty → 0
  | Tree (l, _, r) → 1 + max (depth l) (depth r)
```

Unconstrained trees: top



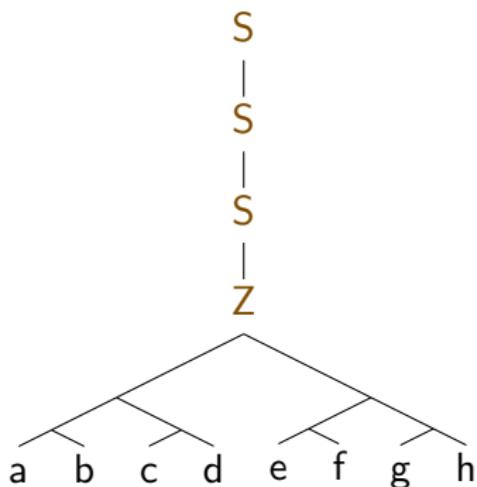
```
let top : 'a.'a tree → 'a option =
  function
    Empty → None
  | Tree (_,v,_) → Some v
```

Unconstrained trees: swivel



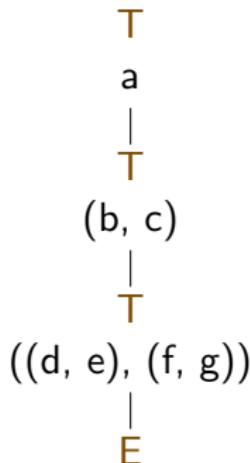
```
let rec swivel : 'a.'a tree → 'a tree =
  function
    Empty → Empty
  | Tree (l,v,r) → Tree (swivel r, v, swivel l)
```

Perfect leaf trees via nesting



```
type 'a perfect =
  ZeroP : 'a → 'a perfect
  | SuccP : ('a * 'a) perfect → 'a perfect
```

Perfect (branch) trees via nesting

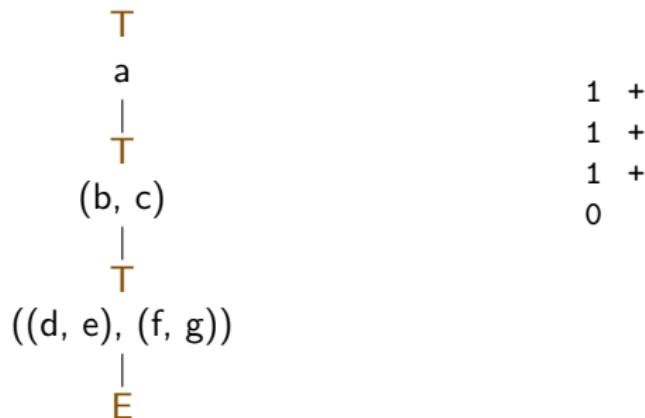


```
type _ ntree =
  EmptyN : 'a ntree
  | TreeN : 'a * ('a * 'a) ntree → 'a ntree
```

Term inference for perfect nested trees

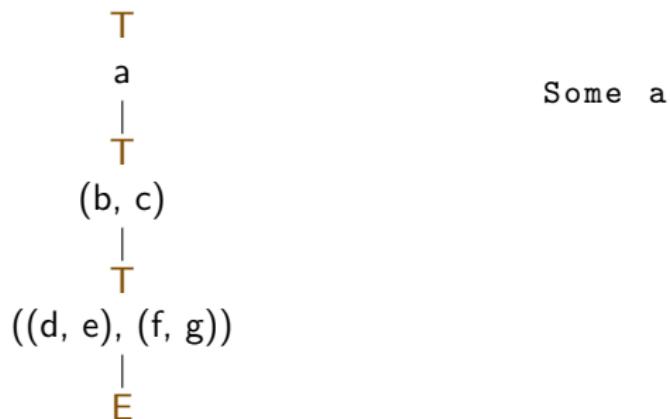
```
val ? : 'a ntree → int  
val ? : 'a ntree → 'a option  
val ? : 'a ntree → 'a ntree
```

Perfect trees: depth



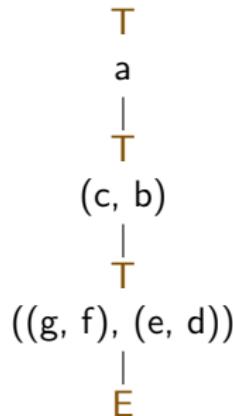
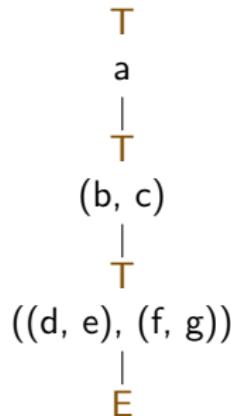
```
let rec depthN : 'a . 'a ntree → int =
  function
    EmptyN → 0
  | TreeN (_, t) → 1 + depthN t
```

Perfect trees: top



```
let rec topN : 'a . 'a ntree → 'a option =
  function
    EmptyN → None
  | TreeN (v, _) → Some v
```

Perfect trees: swivel

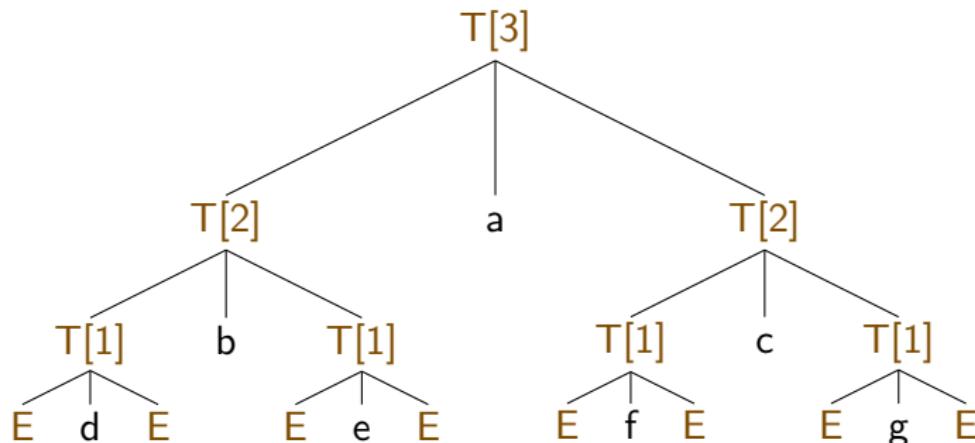


```
let rec swiv : 'a . ('a → 'a) → 'a ntree → 'a ntree =
  fun f t → match t with
    EmptyN → EmptyN
  | TreeN (v, t) →
    TreeN (f v, swiv (fun (x, y) → (f y, f x)) t)

let swivelN p = swiv id p
```

GADTs

Perfect trees, take two



```
type ('a, _) gtree =
  EmptyG : ('a, z) gtree
  | TreeG : ('a, 'n) gtree * 'a * ('a, 'n) gtree → ('a, 'n s)
    gtree
```

Natural numbers

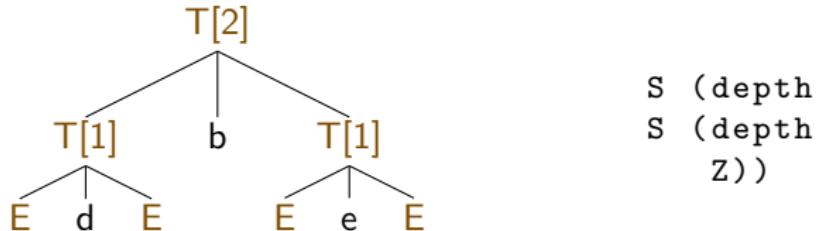
```
type z = Z
type _ s = S : 'n → 'n s

# let zero = Z;;
val zero : z = Z
# let three = S (S (S Z));;
val three : z s s s = S (S (S Z))
```

Term inference for perfect trees (GADTs)

```
val ? : ('a, 'n) gtree → 'n  
val ? : ('a, 'n s) gtree → 'a  
val ? : ('a, 'n) gtree → ('a, 'n) gtree
```

Perfect trees (GADTs): depth



```
let rec depthG : type a n.(a, n) gtree → n =
  function
    EmptyG → Z
  | TreeG (l, _, _) → S (depthG l)
```

Perfect trees (GADTs): depth

```
type ('a, _) gtree =
| EmptyG : ('a, z) gtree
| TreeG : ('a, 'n) gtree * 'a * ('a, 'n) gtree → ('a, 'n s)
  gtree

let rec depthG : type a n.(a, n) gtree → n =
  function
  | EmptyG → Z
  | TreeG (l, _, _) → S (depthG l)
```

Type refinement

In the `EmptyG` branch: $n \equiv z$

In the `TreeG` branch: $n \equiv m\ s$ (for some m)

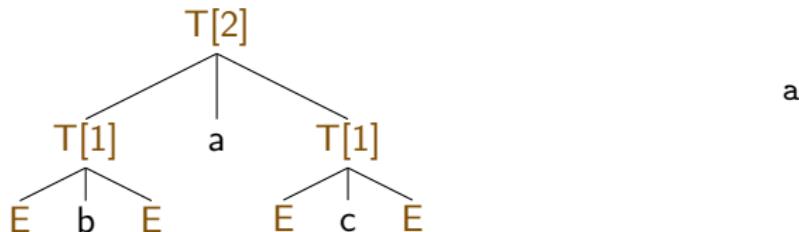
$l : (a, m)gtree$

$\text{depthG } l : m$

Polymorphic recursion

The argument to the recursive call has size m (s.t. $s \equiv m \equiv n$)

Perfect trees (GADTs): top



```
let topG : type a n.(a,n)s gtree → a =
  function TreeG (_,v,_) → v
```

Perfect trees (GADTs): top

```
type ('a, _) gtree =
  EmptyG : ('a, z) gtree
  | TreeG : ('a, 'n) gtree * 'a * ('a, 'n) gtree → ('a, 'n s)
    gtree

let topG : type a n. (a, n s) gtree → a =
  function TreeG (_, v, _) → v
```

Type refinement

In an `EmptyG` branch we would have: $n \ s \equiv z$
— impossible!

Perfect trees (GADTs): swivel



```
let rec swivelG : type a n. (a, n) gtree → (a, n) gtree =
  function
    EmptyG → EmptyG
  | TreeG (l, v, r) → TreeG (swivelG r, v, swivelG l)
```

Perfect trees (GADTs): swivel

```
type ('a, _) gtree =
  EmptyG : ('a, z) gtree
  | TreeG : ('a, 'n) gtree * 'a * ('a, 'n) gtree → ('a, 'n s)
    gtree

let rec swivelG : type a n.(a,n) gtree → (a,n) gtree =
  function
    EmptyG → EmptyG
  | TreeG (l,v,r) → TreeG (swivelG r, v, swivelG l)
```

Type refinement

In the `EmptyG` branch: $n \equiv z$

In the `TreeG` branch: $n \equiv m\ s$ (for some m)

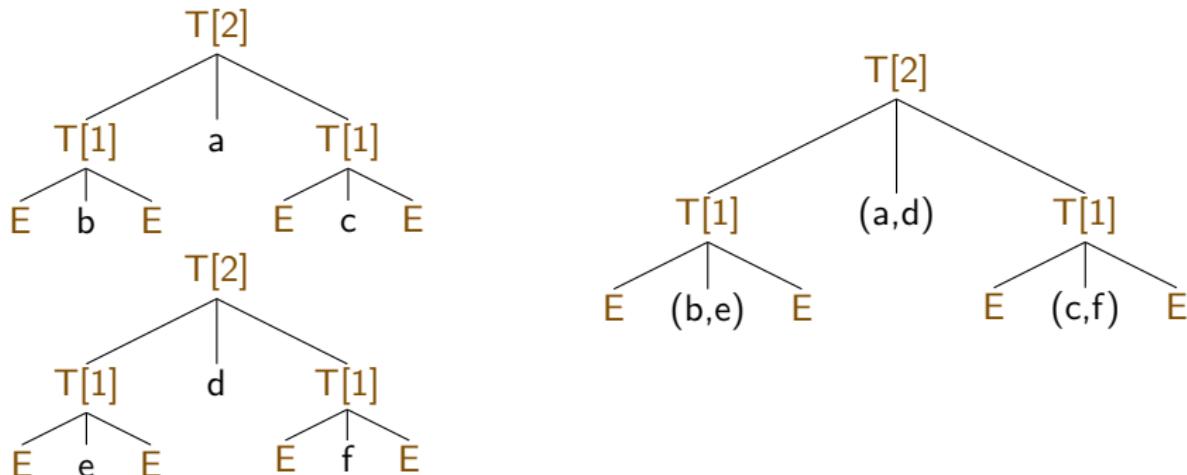
$l, r : (a, m)gtree$

`swivelG l : (a, m)gtree`

Polymorphic recursion

The argument to the recursive call has size m (s.t. $s \equiv m \equiv n$)

Zipping perfect trees



```
let rec zipTree :  
  type a b n.(a,n) gtree → (b,n) gtree →  
    (a * b,n) gtree =  
  fun x y → match x, y with  
    EmptyG, EmptyG → EmptyG  
  | TreeG (l,v,r), TreeG (m,w,s) →  
    TreeG (zipTree l m, (v,w), zipTree r s)
```

Zipping perfect trees

```
type ('a, _) gtree =
  EmptyG : ('a, z) gtree
| TreeG : ('a, 'n) gtree * 'a * ('a, 'n) gtree → ('a, 'n s)
  gtree

let rec zipTree :
  type a b n.(a,n) gtree → (b,n) gtree → (a * b,n)
  gtree =
  fun x y → match x, y with
    EmptyG, EmptyG → EmptyG
  | TreeG (l,v,r), TreeG (m,w,s) →
    TreeG (zipTree l m, (v,w), zipTree r s)
```

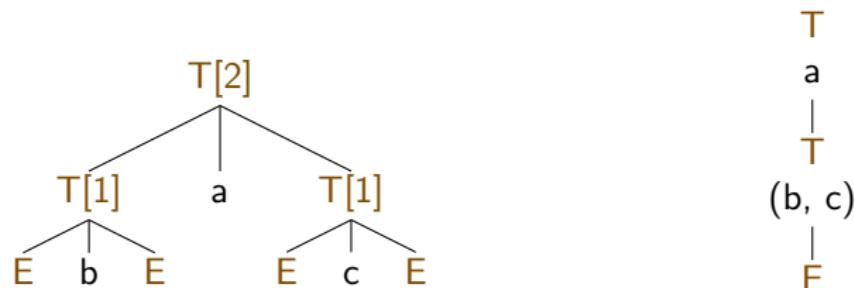
Type refinement

In the `EmptyG` branch: $n \equiv z$

In the `TreeG` branch: $n \equiv m \ s$ (for some m)

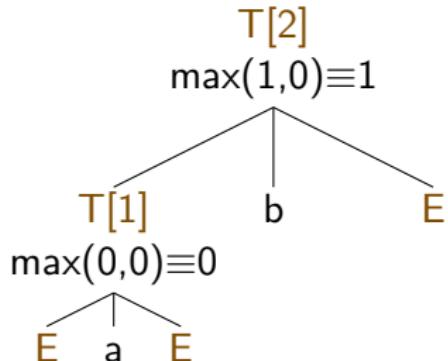
`EmptyG`, `TreeG _` produces $n \equiv z$ and $n \equiv m \ s$
— impossible!

Conversions between perfect tree representations



```
let rec nestify : type a n.(a,n) gtree → a ntree =
  function
    EmptyG → EmptyN
  | TreeG (l, v, r) →
    TreeN (v, nestify (zipTree l r))
```

Depth-annotated trees



```
type ('a,_) dtree =
  EmptyD : ('a,z) dtree
  | TreeD : ('a,'m) dtree * 'a * ('a,'n) dtree * ('m,'n,'o) max
    → ('a,'o s) dtree
```

The untyped maximum function

```
val max : 'a → 'a → 'a
```

Parametricity: `max` is one of

```
fun x _ → x  
fun _ y → y
```

A typed maximum function

```
val max : ('a, 'b, 'c) max → 'a → 'b → 'c
```

$$(\max (a, b) \equiv c) \rightarrow a \rightarrow b \rightarrow c$$

A typed maximum function: a max predicate

```
type (_,_,_)max =  
| MaxEq : ('a,'a,'a)max  
| MaxFlip : ('a,'b,'c)max → ('b,'a,'c)max  
| MaxSuc : ('a,'b,'a)max → ('a s,'b,'a s)max
```

$$a \equiv b \rightarrow \text{max}(a,b) \equiv a$$

$$\text{max}(a,b) \equiv c \rightarrow \text{max}(b,a) \equiv c$$

$$\text{max}(a,b) \equiv a \rightarrow \text{max}(a+1,b) \equiv a+1$$

A typed maximum function

```
type (_,_) eql = Refl : ('a,'a)eql

type (_,_,_) max =
  MaxEq : ('a,'a,'a)max
  | MaxFlip : ('a,'b,'c)max → ('b,'a,'c)max
  | MaxSuc : ('a,'b,'a)max → ('a s,'b,'a s)max

let rec max
: type a b c.(a,b,c)max → a → b → c
= fun mx m n → match mx,m with
  MaxEq , _           → m
  | MaxFlip mx', _    → max mx', n m
  | MaxSuc mx' , S m' → S (max mx' m' n)
```

A typed maximum function

```
type (_,_,_) max =
  MaxEq : ('a,'a,'a) max
| MaxFlip : ('a,'b,'c) max → ('b,'a,'c) max
| MaxSuc : ('a,'b,'a) max → ('a s,'b,'a s) max

let rec max : type a b c.(a,b,c) max → a → b → c
= fun mx m n → match mx,m with
  MaxEq , _           → m
| MaxFlip mx', _     → max mx' n m
| MaxSuc mx' , S m' → S (max mx' m' n)
```

Type refinement

In the MaxEq branch: $a \equiv b, a \equiv c$

$m : c$

In the MaxFlip branch: *no refinement*

In the MaxSuc branch: $a \equiv d\ s, c \equiv d\ s$ (for some d)

$mx' : (d, b, d) \text{max}$

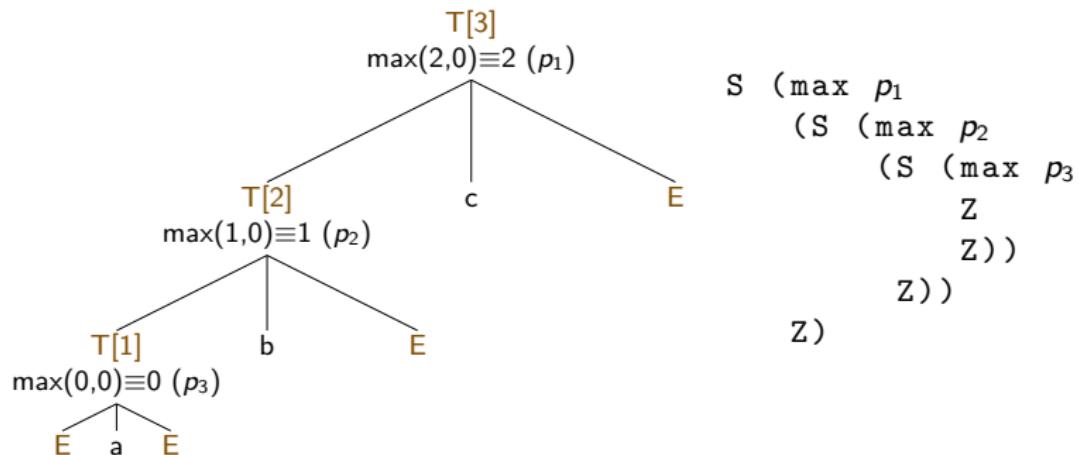
$m' : d$

$\max mx' m' n : d$

Term inference for depth-annotated trees

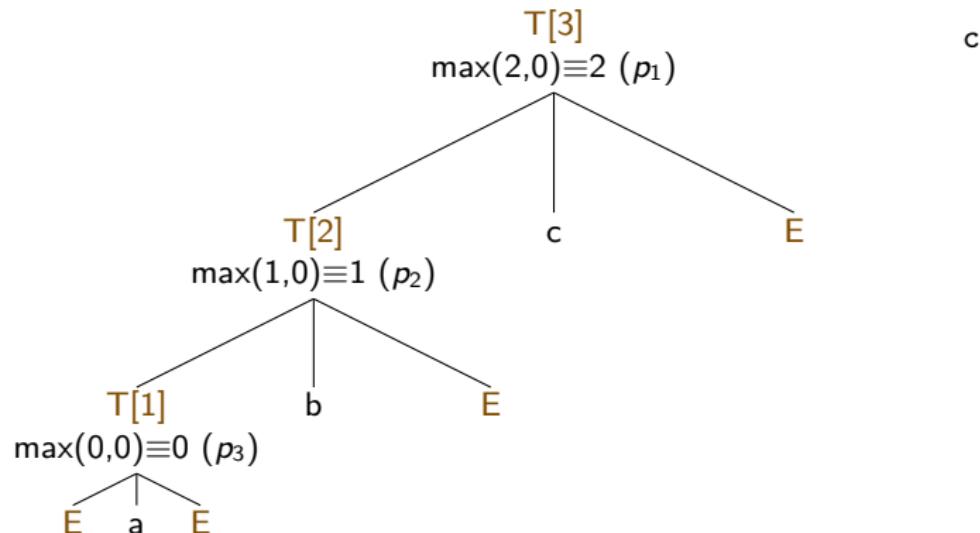
```
val ? : ('a,'n) dtree → 'n  
val ? : ('a,'n s) dtree → 'a  
val ? : ('a,'n) dtree → ('a,'n) dtree
```

Depth-annotated trees: depth



```
let rec depthD : type a n.(a,n) dtree → n =
  function
    EmptyD → Z
  | TreeD (l,_,r,mx) → S (max mx (depthD l) (depthD r))
```

Depth-annotated trees: top



```
let topD : type a n.(a,n s) dtree → a =
  function TreeD (_,v,_,_) → v
```

Depth-annotated trees: swivel



```
let rec swivelD :  
  type a n.(a,n) dtree → (a,n) dtree =  
function  
  EmptyD → EmptyD  
| TreeD (l,v,r,m) →  
  TreeD (swivelD r, v, swivelD l, MaxFlip m)
```

Efficiency

Efficiency: missing branches

```
let top : 'a.'a tree → 'a option = function
  Empty → None
| Tree (_ , v , _) → Some v

(function p (* ocaml -dlambda *)
  (if p
    (makeblock 0 (field 1 p))
    0a))

let topG : type a n .(a , n s) gtree → a = function
  TreeG (_ , v , _) → v

(function p (* ocaml -dlambda *)
  (field 1 p))
```

Efficiency: zips

```
let rec zipTree :  
  type a b n.(a,n) gtree → (b,n) gtree →  
    (a * b,n) gtree =  
  fun x y → match x, y with  
    EmptyG, EmptyG → EmptyG  
  | TreeG (l,v,r), TreeG (m,w,s) →  
    TreeG (zipTree l m, (v,w), zipTree r s)  
  
(letrec (* ocaml -dlambda *)  
  (zipTree  
    (function x y  
      (if x  
        (makeblock 0  
          (apply zipTree (field 0 x) (field 0 y))  
          (makeblock 0 (field 1 x) (field 1 y))  
          (apply zipTree (field 2 x) (field 2 y)))  
        0a)))  
  (apply (field 1 (global Toploop!)) "zipTree" zipTree))
```

Equality

Recall: equality in System F ω

$\text{Eq1} = \lambda\alpha::*. \lambda\beta::*. \forall\phi::* \Rightarrow *. \phi \alpha \rightarrow \phi \beta$

$\text{refl} : \forall\alpha::*. \text{Eq1 } \alpha \alpha$

$\text{refl} = \Lambda\alpha::*. \Lambda\phi::* \Rightarrow *. \lambda x:\phi \alpha . x$

$\text{symm} : \forall\alpha::*. \forall\beta::*. \text{Eq1 } \alpha \beta \rightarrow \text{Eq1 } \beta \alpha$

$\text{symm} = \Lambda\alpha::*. \Lambda\beta::*.$

$\lambda e:(\forall\phi::* \Rightarrow *. \phi \alpha \rightarrow \phi \beta). e [\lambda\gamma::*. \text{Eq } \gamma \alpha] (\text{refl } [\alpha])$

$\text{trans} : \forall\alpha::*. \forall\beta::*. \forall\gamma::*. \text{Eq1 } \alpha \beta \rightarrow \text{Eq1 } \beta \gamma \rightarrow \text{Eq1 } \alpha \gamma$

$\text{trans} = \Lambda\alpha::*. \Lambda\beta::*. \Lambda\gamma::*.$

$\lambda ab:\text{Eq } \alpha \beta. \lambda bc:\text{Eq } \beta \gamma. bc [\text{Eq } \alpha] ab$

Equity with GADTs

```
type (_, _) eql = Refl : ('a, 'a) eql

val refl : ('a, 'a) eql
val symm : ('a, 'b) eql → ('b, 'a) eql
val trans : ('a, 'b) eql → ('b, 'c) eql → ('a, 'c) eql

module Lift (T : sig type _ t end) :
sig
  val lift : ('a, 'b) eql → ('a T.t, 'b T.t) eql
end

val cast : ('a, 'b) eql → 'a → 'b
```

Building GADTs from algebraic types and equality

```
type ('a, _) gtree =
  EmptyG : ('a, z) gtree
  | TreeG : ('a, 'n) gtree * 'a * ('a, 'n) gtree → ('a, 'n s)
    gtree
```

```
type ('a, 'n) etree =
  EmptyE : (z, 'n) eql → ('a, 'n) etree
  | TreeE : ('n, 'm s) eql *
    ('a, 'm) etree * 'a * ('a, 'm) etree → ('a, 'n) etree
```

Building GADTs from algebraic types and equality

```
type ('a, _) gtree =
| EmptyG : ('a, z) gtree
| TreeG : ('a, 'n) gtree * 'a * ('a, 'n) gtree → ('a, 'n s)
    gtree

let rec depthG : type a n.(a, n) gtree → n =
function
| EmptyG → Z
| TreeG (l, _, _) → S (depthG l)
```

Building GADTs from algebraic types and equality

```
type ('a, _) gtree =
| EmptyG : ('a, z) gtree
| TreeG : ('a, 'n) gtree * 'a * ('a, 'n) gtree → ('a, 'n s)
    gtree

let rec depthG : type a n.(a, n) gtree → n =
function
| EmptyG → Z                                     (* n = z *)
| TreeG (l, _, _) → S (depthG l)
```

Building GADTs from algebraic types and equality

```
type ('a, _) gtree =
| EmptyG : ('a, z) gtree
| TreeG : ('a, 'n) gtree * 'a * ('a, 'n) gtree → ('a, 'n s)
    gtree

let rec depthG : type a n.(a, n) gtree → n =
  function
    EmptyG → Z                                     (* n = z *)
  | TreeG (l, _, _) → S (depthG l)           (* n = m s *)
```

Building GADTs from algebraic types and equality

```
type ('a,'n) etree =
| EmptyE : ('n,z) eql → ('a,'n) etree
| TreeE : ('n,'m s) eql *
  ('a,'m) etree * 'a * ('a,'m) etree → ('a,'n) etree

let rec depthE : type a n.(a, n) etree → n =
function
| EmptyE Refl → Z
| TreeE (Refl, l,_,_ ) → S (depthE l)
```

Building GADTs from algebraic types and equality

```
type ('a,'n) etree =
| EmptyE : ('n,z) eql → ('a,'n) etree
| TreeE : ('n,'m s) eql *
  ('a,'m) etree * 'a * ('a,'m) etree → ('a,'n) etree

let rec depthE : type a n.(a, n) etree → n =
function
| EmptyE Refl → Z (* n = z *)
| TreeE (Refl, l,_,-) → S (depthE l)
```

Building GADTs from algebraic types and equality

```
type ('a,'n) etree =
| EmptyE : ('n,z) eql → ('a,'n) etree
| TreeE : ('n,'m s) eql *
  ('a,'m) etree * 'a * ('a,'m) etree → ('a,'n) etree

let rec depthE : type a n.(a, n) etree → n =
  function
    EmptyE Refl → Z                                     (* n = z *)
  | TreeE (Refl, l,_,_ ) → S (depthE l) (* n = m s *)
```

Reorientation

Where are we?

We've enriched data types with indexes describing the data.

Families of types: a type for each nat, each tree depth, etc.

Descriptive data types lead to useful function types.

Phantom types protect abstractions against misuse.

GADTs also protect definitions.

Compilers use the extra information to generate better code.

What's going on?

GADTs are about type equalities (and sometimes inequalities).

GADTs reveal things about types when you examine data.

We need machinery from earlier lectures: existentials, polymorphic recursion, non-regularity.

GADTs lead to rich types which can be viewed as propositions.

Setting up types carefully leads to simple and fast code.

Next time

GADTs in practice