# Hoare Logic and Model Checking

Model Checking

Lecture 11: Model checking for Computation Tree Logic

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## **Learning** outcomes

#### At the end of this lecture, you should:

- Understand the CTL model checking problem
- · Understand the "satisfaction set" of states for CTL formulae
- Know the naïve recursive labelling algorithm for computing satisfaction sets
- Understand CTL model checking is a reachability problem
- Know the computational complexity of CTL model checking

The CTL model checking problem

#### CTL model checking problem

Suppose  $\mathcal{M} = \langle S, S_0, \rightarrow, \mathcal{L} \rangle$  is a CTL model

Suppose also that  $s \in S$  is a state, and  $\Phi$  is a CTL state formula

We want to establish whether  $s \models \Phi$  (as efficiently as possible)

Importantly: we want to establish whether  $s \models \Phi$  for all  $s \in S_0$ 

"All possible initial states satisfy  $\Phi$ "

This is the CTL model checking problem

#### States that satisfy formulae

In  $\mathcal{M}$ , define:

$$Sat(\Phi) = \{ s \in S \mid s \models \Phi \}$$

The "states that satisfy  $\Phi$ "

CTL model checking problem can be solved by:

- 1. Computing  $Sat(\Phi)$  set for relevant CTL state formula
- 2. Checking whether  $S_0 \subseteq Sat(\Phi)$

Then: how do we compute  $Sat(\Phi)$ ?

Simple recursive algorithm

#### Reminder: Existential Normal Form

#### Recall from last lecture:

- · Existential Normal Form formulae have negations "pushed in"
- Only use a subset of modalities
- ullet Theorem: every CTL state formula  $\Phi$  has an equivalent ENF formula

In this lecture, we work only with ENF formulae (fewer cases to cover)

To extend our algorithm implementations to full CTL:

- · Wrap them in another function accepting a CTL formula,
- · Use translation hidden in constructive proof of theorem above,
- · Call the algorithm on this translated formula

## Characterising $Sat(\Phi)$

Suppose  $\Phi$  is ENF formula

Take a step back:

- We aim to algorithmically compute  $Sat(\Phi)$  in order to check  $s \models \Phi$  for  $s \in S_0$
- But what is this set?

Need to first characterise  $Sat(\Phi)$  to understand whether algorithm correct

#### Characterising $Sat(\Phi)$ : the 'easy' cases

For 
$$\mathcal{M} = \langle S, S_0, \rightarrow, \mathcal{L} \rangle$$
, we have:

$$Sat(\top) = S$$
  
 $Sat(p) = \{s \mid p \in \mathcal{L}(s)\}$   
 $Sat(\neg \Phi) = Sat(\Phi)$   
 $Sat(\Phi \land \Psi) = Sat(\Phi) \cap Sat(\Psi)$ 

Here:  $S - Sat(\Phi)$  is relative complement

Note, per setwise reasoning, we have  $Sat(\Phi \vee \Psi) = Sat(\Phi) \cup Sat(\Psi)$ 

Other derived connectives similarly map onto setwise operations

#### Characterising $Sat(\Phi)$ : the $\exists \bigcirc \Phi$ case

For 
$$\mathcal{M}=\langle S,S_0,\to,\mathcal{L}\rangle$$
, we have: 
$$Sat(\exists\bigcirc\Phi)= \qquad \{s\in S\mid Post(s)\cap Sat(\Phi)\neq \{\}\}$$
 Here,  $Post(s)=\{s'\mid s\to s'\}$ 

#### Characterising $Sat(\Phi)$ : the $\exists (\Phi \text{ UNTIL } \Psi)$ case

For  $\mathcal{M} = \langle S, S_0, \rightarrow, \mathcal{L} \rangle$ , we have:

 $Sat(\exists (\Phi \ \mathtt{UNTIL} \ \Psi))$  is the smallest  $T\subseteq S$ , such that:

- 1.  $Sat(\Psi) \subseteq T$ ,
- 2. If  $s \in Sat(\Phi)$  with  $Post(s) \cap T \neq \{\}$  then  $s \in T$

Here, "smallest" is interpreted with respect to set inclusion order

## Correctness of characterisation of $Sat(\exists (\Phi \text{ UNTIL } \Psi))$ (1)

Suppose 
$$T=Sat(\exists(\Phi\ \mathtt{UNTIL}\ \Psi))$$
 
$$\exists(\Phi\ \mathtt{UNTIL}\ \Psi)\ \mathtt{satisfies}\ \mathtt{an}\ \text{``expansion law''}:$$
 
$$\exists(\Phi\ \mathtt{UNTIL}\ \Psi)\equiv\Psi\vee(\Phi\wedge\exists\bigcirc\exists(\Phi\ \mathtt{UNTIL}\ \Psi))$$
 
$$T=Sat(\exists(\Phi\ \mathtt{UNTIL}\ \Psi))$$

$$\begin{split} T &= Sat(\exists(\Psi \ \mathsf{UNTIL} \ \Psi)) \\ &= Sat(\Psi \lor (\Phi \land \exists \bigcirc \exists(\Phi \ \mathsf{UNTIL} \ \Psi))) \\ &= Sat(\Psi) \cup (Sat(\Phi) \cap \{s \in S \mid Post(s) \cap Sat(\exists(\Phi \ \mathsf{UNTIL} \ \Psi)) \neq \{\}\}) \\ &= Sat(\Psi) \cup (Sat(\Phi) \cap \{s \in S \mid Post(s) \cap T \neq \{\}\}) \end{split}$$

So:

- 1.  $Sat(\Psi) \subseteq T$
- 2.  $s \in Sat(\Phi)$  with  $Post(s) \cap T \neq \{\}$  implies  $s \in T$

#### Correctness of characterisation of $Sat(\exists (\Phi \cup \Psi))$ (2)

Suppose *T* satisfies:

- 1.  $Sat(\Psi) \subseteq T$ ,
- 2. If  $s \in Sat(\Phi)$  with  $Post(s) \cap T \neq \{\}$  then  $s \in T$

 $\mathrm{Aim}\;\mathrm{to}\;\mathrm{show}\;Sat(\exists(\Phi\;\mathrm{UNTIL}\;\Psi))\subseteq T$ 

Suppose  $s \in Sat(\exists (\Phi \ \mathtt{UNTIL} \ \Psi))$ 

Work by cases on whether  $s \in Sat(\Psi)$ 

One case is easy:

If  $s \in Sat(\Psi)$  then  $s \in T$  per (1) above

#### Correctness of characterisation of $Sat(\exists (\Phi \cup \Psi))$ (3)

Otherwise suppose  $s \notin Sat(\Psi)$ 

Note  $\pi=s_0,s_1,s_2,\ldots$  exists where  $s=\pi[0]$  and  $\pi\models\Phi$  UNTIL  $\Psi$ 

Let n > 0 be such  $\pi[n] \models \Psi$  and  $\pi[i] \models \Phi$  for  $0 \le i < n$ 

Then  $\pi[n] \in Sat(\Psi)$  and therefore  $\pi[n] \in T$  per (1) above

Then  $\pi[n-1] \in Sat(\Phi)$  and  $\pi[n-1] \in T$  since  $\pi[n] \in Post(\pi[n-1]) \cap T$ 

Then  $\pi[n-2] \in Sat(\Phi)$  and  $\pi[n-2] \in T$  since  $\pi[n-1] \in Post(\pi[n-2]) \cap T$ 

..

Then  $\pi[0] \in Sat(\Phi)$  and  $\pi[0] \in T$  since  $\pi[1] \in Post(\pi[0]) \cap T$ 

Therefore  $s = \pi[0] \in T$ , as required

#### Characterising $Sat(\Phi)$ : the $\exists(\Box\Phi)$ case

For  $\mathcal{M} = \langle S, S_0, \rightarrow, \mathcal{L} \rangle$ , we have:

 $Sat(\exists(\Box\Phi))$  is the largest  $T\subseteq S$ , such that:

- 1.  $T \subseteq Sat(\Phi)$
- 2. If  $s \in T$  then  $Post(s) \cap T \neq \{\}$

Here, "largest" is interpreted with respect to set inclusion order

## Correctness of characterisation of $Sat(\exists \Box \Phi)$ (1)

Suppose 
$$T = Sat(\exists \Box \Phi)$$

 $\exists \Box \Phi$  also satisfies an "expansion law":

$$\exists \Box \Phi \equiv \Phi \land \exists \bigcirc \exists \Box \Phi$$

$$\begin{split} T &= Sat(\exists \Box \Phi) \\ &= Sat(\Phi \land \exists \bigcirc \exists \Box \Phi) \\ &= Sat(\Phi) \cap \{s \in S \mid Post(s) \cap Sat(\exists \Box \Phi) \neq \{\}\} \\ &= Sat(\Phi) \cap \{s \in S \mid Post(s) \cap T \neq \{\}\} \end{split}$$

So:

- 1.  $Sat(\exists \Box \Phi) \subseteq Sat(\Phi)$
- 2.  $s \in T$  implies  $Post(s) \cap T \neq \{\}$

#### Correctness of characterisation of $Sat(\exists \Box \Phi)$ (2)

Suppose T satisfies:

- 1.  $T \subseteq Sat(\Phi)$
- 2.  $s \in T$  implies  $Post(s) \cap T \neq \{\}$

Aim to show  $T \subseteq Sat(\exists \Box \Phi)$ 

Suppose  $s \in T$  (for T non-empty), define  $\pi$ :

$$\pi[0] = s \in T$$

 $\pi[1]$  is some state  $s_1 \in Post(s_0) \cap T$ , which exists as  $s_0 \in T$  per (2)

 $\pi[2]$  is some state  $s_2 \in Post(s_1) \cap T$ , which exists as  $s_1 \in T$  per (2)

..

Hence  $\pi[i] \in T \subseteq Sat(\Phi)$  for all  $i \geq 0$  and  $\pi \models \Box \Phi$  and  $s \in Sat(\exists \Box \Phi)$ 

As this applies to any  $s \in T$ , we have  $T \subseteq Sat(\exists \Box \Phi)$  as required

#### Recursive labelling algorithm

```
Pseudocode:
  function SAT(\Phi):
       case \top: return S
            case p: return \{s \in S \mid p \in \mathcal{L}(s)\}
            case \neg \Psi: return S - Sat(\Psi)
            case \Psi \wedge \Xi: return Sat(\Psi) \cap Sat(\Xi)
            case \exists \bigcirc \Psi: return \{s \in S \mid Post(s) \cap Sat(\Psi) \neq \{\}\}
            case \exists (\Psi \text{ UNTIL } \Xi): return SatExistsUntil(\Psi, \Xi)
            case \exists (\Box \Psi): return SatExistsSquare(\Psi)
  end function
```

#### Subprocedure SatExistsUntil

```
Pseudocode for SatExistsUntill: function \  \, \text{SatExistsUntil}(\Phi, \Psi): \\ T \leftarrow Sat(\Psi) \\ \text{while } \{s \in Sat(\Phi) - T \mid Post(s) \cap T \neq \{\}\} \neq \{\} \  \, \text{do:} \\ s \leftarrow \text{ some state from } \{s \in Sat(\Phi) - T \mid Post(s) \cap T \neq \{\}\} \\ T \leftarrow T \cup \{s\} \\ \text{end while} \\ \text{return T} \\ \text{end function}
```

#### Subprocedure SatExistsSquare

```
Pseudocode for SatExistsSquare: function \ \text{SatExistsSquare}(\Phi): \\ T \leftarrow Sat(\Phi) \\ \text{while } \{s \in T \mid Post(s) \cap T = \{\}\} \neq \{\} \ \text{do} \\ s \leftarrow \text{ some state from } \{s \in T \mid Post(s) \cap T = \{\}\} \\ T \leftarrow T - \{s\} \\ \text{ end while} \\ \text{return T} \\ \text{end function}
```

#### Correctness of recursive labelling algorithm (1)

Recall  $Sat(\exists (\Phi \text{ UNTIL } \Psi))$  is smallest  $T \subseteq S$ :

$$Sat(\Psi) \subseteq T \qquad s \in Sat(\Phi) \text{ and } Post(s) \cap T \neq \{\} \text{ implies } s \in T$$

This suggests an iterative procedure for computing  $Sat(\exists (\Phi \ \mathtt{UNTIL} \ \Psi))$ :

$$T_0 = Sat(\Psi)$$
  
 $T_{1+i} = T_i \cup \{s \in Sat(\Phi) \mid Post(s) \cap T_i \neq \{\}\}$ 

Iterate until fixed point is reached

 $T_i$  states can reach  $\Psi$ -state in at most i steps along  $\Phi$ -path SatExistsUntil implements this idea

## Correctness of recursive labelling algorithm (2)

Recall  $Sat(\exists \Box \Phi)$  is largest  $T \subseteq S$ :

$$T \subseteq Sat(\Phi)$$
  $s \in T \text{ implies } Post(s) \cap T \neq \{\}$ 

This suggests an iterative procedure for computing  $Sat(\exists \Box \Phi)$ :

$$T_0 = Sat(\Phi)$$
  

$$T_{1+i} = T_i \cap \{ s \in Sat(\Phi) \mid Post(s) \cap T_i \neq \{ \} \}$$

Iterate until fixedpoint is reached

SatExistsSquare implements this idea

#### CTL model checking as reachability

SatExistsUntil and SatExistsSquare are both "backwards searches"

In both cases:

- · We start with an initial "guess"
- $\cdot$  Move backwards along  $\rightarrow$  transitions, refining guess
- · Until we stop

CTL model checking can therefore be seen as a reachability problem Correctness of algorithm relies crucially on:

- · Finiteness of CTL models
- · Fixed-point characterisation of CTL

#### Computational complexity

Above algorithm is naïve

Can improve performance by considering only strongly connected components during SatExistsSquare

Do not consider this here

Complexity of optimised variant of above algorithm is  $O(\mid \Phi \mid \cdot (V+E))$ :

- $\cdot$  V is number of states in model
- $\cdot$  E is number of transitions in model
- $\cdot \mid \Phi \mid$  is "size" of formula being checked

#### Summary

- · CTL model checking is a reachability problem
- Can model check CTL formulae by computing Sat-set of ENF equivalent
- Satisfaction-set can be computed recursively using a "labelling algorithm"
- Correctness of algorithm depends on fixed-point characterisation of CTL formulae
- · Rely crucially on finite models for termination
- Variant of labelling algorithm is  $O(\mid \Phi \mid \cdot (V+E))$  complexity