

[[while B do C]] : State \rightarrow State

Operationally

while B do C \equiv if B then (C; while B do C) else skip.

So we want

$$\begin{aligned} \llbracket \text{while B do C} \rrbracket &= \llbracket \text{if B then (C; while B do C) else skip} \rrbracket \\ &= \lambda s. \text{if } (\llbracket B \rrbracket s, \llbracket \text{C; while B do C} \rrbracket s, \llbracket \text{skip} \rrbracket s) \\ &\stackrel{*}{=} \lambda s. \text{if } (\llbracket B \rrbracket s, \llbracket \text{while B do C} \rrbracket (\llbracket C \rrbracket s), s) \end{aligned}$$

Consider

$$f \llbracket B \rrbracket, \llbracket C \rrbracket : (\text{state} \rightarrow \text{state}) \rightarrow (\text{state} \rightarrow \text{state})$$

$f(\pi_B \gamma, \pi_C \gamma)$

$=^{\text{def}} \lambda W: \text{State} \rightarrow \text{State}$

$\lambda s: \text{State}.$

$\gamma(\pi_B \gamma s, W(\pi_C \gamma s), s)$

NB: We want $\pi_{\text{while } B \text{ do } C} \gamma$ satisfies the
equation $\pi_{\text{while } B \text{ do } C} \gamma \stackrel{\circledast}{=} f(\pi_B \gamma, \pi_C \gamma)(\pi_{\text{while } B \text{ do } C} \gamma)$

[?] Does there always exist a unique state transformer satisfying \textcircled{A} ?

[!] If so then we define $\llbracket \text{while } B \text{ do } C \rrbracket$ as the unique fixed point of $f(B, \cdot)$!

[ans] No! $\llbracket \text{while true do skip} \rrbracket$

$$\begin{aligned} f(\text{true}, \llbracket \text{skip} \rrbracket) &= \lambda W. \lambda s. \\ &\quad \text{if } (\text{true}, W(s), s) \\ &= \lambda W. \lambda s. W(s) \\ &= \text{the identity} \end{aligned}$$

NB: A fixed point of a function $h: A \rightarrow A$ is an element $a \in A$ s.t. $h(a) = a$

Every state transformer is a fixed point of $f(\text{true}, \text{[skip]})$, so how do we single out

the fixed point $\llbracket \text{while true do skip} \rrbracket$?

$: \text{State} \rightarrow \text{State}$
intuitively

$\llbracket \text{while true do skip} \rrbracket (s) \uparrow \quad \forall s \in \text{State}$

$\} \text{Notation for undefined}$

$\llbracket \text{while true do skip} \rrbracket = \perp$ the totally undefined function.

Amongst all fixed points of $f_{\bar{A}B\bar{Y}, \bar{A}C\bar{Y}}$ we want to
calculate the fixed point corresponding to
 $\llbracket \text{while } B \text{ do } C \rrbracket$!

(by approximation)

$$\llbracket \text{while } B \text{ do } C \rrbracket_0 = \perp$$

$$\llbracket \text{while } B \text{ do } C \rrbracket_1 = f_{\bar{A}B\bar{Y}, \bar{A}C\bar{Y}} (\llbracket \text{while } B \text{ do } C \rrbracket_0)$$

$$= \lambda s. \bar{y} (\bar{A}B\bar{Y}s, \uparrow, s)$$

$$= \lambda s. \begin{cases} s \\ \uparrow \end{cases}$$

$$\bar{A}B\bar{Y}(s) = \begin{cases} \text{false} \\ \text{other} \end{cases}$$

$$\llbracket \text{while } B \text{ do } C \rrbracket_2 = f_{\llbracket B \rrbracket, \llbracket C \rrbracket} (\llbracket \text{while } B \text{ do } C \rrbracket_1)$$

$$= \lambda s. \text{if } (\llbracket B \rrbracket(s), \llbracket \text{while } B \text{ do } C \rrbracket_1(\llbracket C \rrbracket(s), s))$$

$$= \lambda s. \begin{cases} s & \llbracket B \rrbracket(s) = \text{false} \\ \llbracket \text{while } B \text{ do } C \rrbracket_1(\llbracket C \rrbracket(s)) & \text{otherwise} \end{cases}$$

$$= \lambda s. \begin{cases} s & \text{if } \llbracket B \rrbracket(s) = \text{false} \\ \llbracket C \rrbracket(s) & \text{if } \llbracket B \rrbracket(s) = \text{true} \\ & \text{end } \llbracket B \rrbracket(\llbracket C \rrbracket(s)) \\ & = \text{false} \end{cases}$$

↑

otherwise

TWO KEY INGREDIENTS OF THE THEORY

Recap

$$\llbracket \text{while } B \text{ do } C \rrbracket_0 \stackrel{\text{def}}{=} \perp$$

$$\sqsubseteq \llbracket \text{while } B \text{ do } C \rrbracket_1 \stackrel{\text{def}}{=} f_{\llbracket B \rrbracket, \llbracket C \rrbracket}(\perp)$$

$$\sqsubseteq \llbracket \text{while } B \text{ do } C \rrbracket_2 \stackrel{\text{def}}{=} f_{\llbracket B \rrbracket, \llbracket C \rrbracket}^2(\perp)$$

$$\sqsubseteq \dots \llbracket \text{while } B \text{ do } C \rrbracket_n \sqsubseteq \dots$$

less information than

the join of all the information

$$\llbracket \text{while } B \text{ do } C \rrbracket \stackrel{\text{def}}{=} \bigsqcup_{n \geq 0}$$

$$\stackrel{\text{def}}{=} f_{\llbracket B \rrbracket, \llbracket C \rrbracket}^n(\perp)$$

$$f_{\llbracket B \rrbracket, \llbracket C \rrbracket}(\perp)$$

□ ? How come $\bigsqcup_{n \geq 0} f_{\bar{A}B\gamma}, \bar{A}C\gamma^n (\perp)$

is a fixed point of $f_{\bar{A}B\gamma}, \bar{A}C\gamma$?

That is,

$$\begin{aligned} f_{\bar{A}B\gamma}, \bar{A}C\gamma \left(\bigsqcup_{n \geq 0} f_{\bar{A}B\gamma}, \bar{A}C\gamma^n (\perp) \right) \\ = \bigsqcup_{n \geq 0} f_{\bar{A}B\gamma}, \bar{A}C\gamma^{n+1} (\perp) . \end{aligned}$$

Fixed point property of [[while B do C]]

$$\llbracket \text{while } B \text{ do } C \rrbracket = f_{\llbracket B \rrbracket, \llbracket C \rrbracket}(\llbracket \text{while } B \text{ do } C \rrbracket)$$

where, for each $b : \text{State} \rightarrow \{\text{true}, \text{false}\}$ and $c : \text{State} \rightarrow \text{State}$, we define

as $f_{b,c} : (\text{State} \rightarrow \text{State}) \rightarrow (\text{State} \rightarrow \text{State})$
 $f_{b,c} = \lambda w \in (\text{State} \rightarrow \text{State}). \lambda s \in \text{State}. \text{if } (b(s), w(c(s))), s).$

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- Why does $w = f_{\llbracket B \rrbracket, \llbracket C \rrbracket}(w)$ have a solution?
 - What if it has several solutions—which one do we take to be $\llbracket \text{while } B \text{ do } C \rrbracket$?

Approximating $\llbracket \text{while } B \text{ do } C \rrbracket$

$$f_{\llbracket B \rrbracket, \llbracket C \rrbracket}^n(\perp)$$

$$= \lambda s \in \text{State}.$$

$$\left\{ \begin{array}{l} \llbracket C \rrbracket^k(s) \quad \text{if } \exists 0 \leq k < n. \llbracket B \rrbracket(\llbracket C \rrbracket^k(s)) = \text{false} \\ \quad \text{and } \forall 0 \leq i < k. \llbracket B \rrbracket(\llbracket C \rrbracket^i(s)) = \text{true} \\ \uparrow \\ \text{if } \forall 0 \leq i < n. \llbracket B \rrbracket(\llbracket C \rrbracket^i(s)) = \text{true} \end{array} \right.$$

Partial order \leq on a set is a binary relation.
 That is: (reflexive) $x \leq x$, (transitive) $x \leq y \wedge y \leq z \Rightarrow x \leq z$
 $D \stackrel{\text{def}}{=} (\text{State} \rightarrow \text{State})$
 (antisymmetric) $x \leq y \wedge y \leq x \Rightarrow x = y$

• **Partial order \sqsubseteq on D :**

$w \sqsubseteq w'$ iff for all $s \in \text{State}$, if w is defined at s then
 so is w' and moreover $w(s) = w'(s)$.

iff the graph of w is included in the graph of w' .

• **Least element $\perp \in D$ w.r.t. \sqsubseteq :**

\perp = totally undefined partial function

= partial function with empty graph

(satisfies $\perp \sqsubseteq w$, for all $w \in D$).

Topic 2

Least Fixed Points

The way to single out the computationally meaningful fixpoints.

Thesis

E.g.

$$D = (\text{State} \rightarrow \text{State})$$

All domains of computation are partial orders with a least element.

E.g. $(A \rightarrow B)$
for A, B sets.

Thesis

All domains of computation are partial orders with a least element.

All computable functions are monotonic.

f monotonic

$$x \sqsubseteq y \Rightarrow f(x) \sqsubseteq f(y)$$

more information on the input gives more information on the output