



High dynamic range and tone mapping

Advanced Graphics

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Cornell Box: need for tone-mapping in graphics




Rendering
Photograph

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Real-world scenes are more challenging



- ▶ The match could not be achieved if the light source in the top of the box was visible
- ▶ The display could not reproduce the right level of brightness

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Dynamic range



Luminance

↓

max L

↑

min L

(for SNR>3)

Slide 4

Dynamic range (contrast)

- ▶ As ratio:

$$C = \frac{L_{\max}}{L_{\min}}$$
 - ▶ Usually written as C:1, for example 1000:1.
- ▶ As “orders of magnitude” or log₁₀ units:

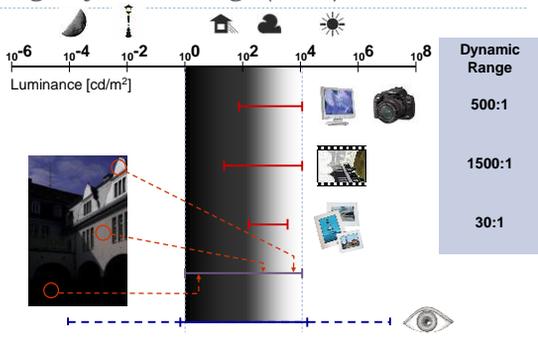
$$C_{10} = \log_{10} \frac{L_{\max}}{L_{\min}}$$
- ▶ As stops:

$$C_2 = \log_2 \frac{L_{\max}}{L_{\min}}$$

One stop is doubling of halving the amount of light

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High dynamic range (HDR)



Dynamic Range

500:1

1500:1

30:1

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HDR in products

- ▶ UltraHD + HDR
 - ▶ Because the resolution alone gives only small improvement in image quality
- ▶ HDR UltraHD broadcast
- ▶ Technicolor offers HDR color grading services
- ▶ Netflix & Amazon announce HDR content streaming
- ▶ HDR experimental short films
- ▶ Better pixels instead of more pixels
- ▶ HDR is universally accepted as „better“



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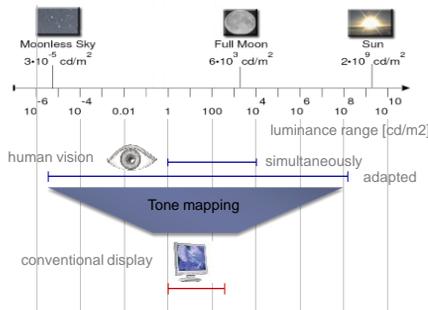
Visible colour gamut

- ▶ The eye can perceive more colours and brightness levels than
 - ▶ a display can produce
 - ▶ a JPEG file can store
- ▶ The premise of HDR:
 - ▶ Visual perception and not the technology should define accuracy and the range of colours
 - ▶ The current standards not fully follow to this principle



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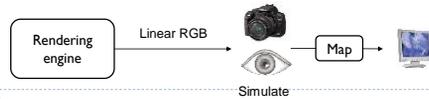
Tone-mapping problem



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Tone-mapping in rendering

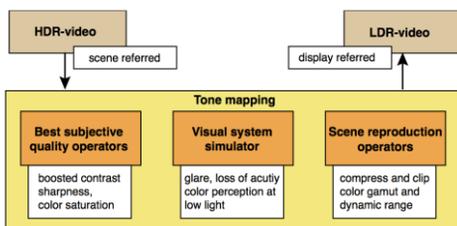
- ▶ Any physically-based rendering requires tone-mapping
- ▶ “HDR rendering” in games is pseudo-physically-based rendering
- ▶ Goal: to simulate a camera or the eye
- ▶ Greatly enhances realism



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Three intents of tone-mapping

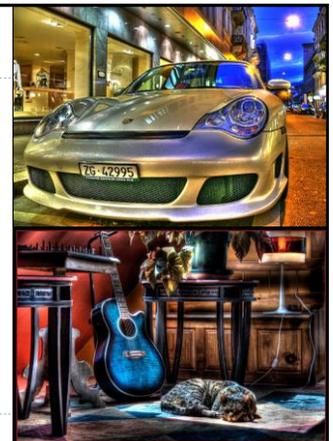
1. Scene reproduction operator
2. Visual system simulator
3. Best subjective quality



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Intent #1: Best subjective quality

- ▶ Often interactive
- ▶ Software
 - ▶ Photoshop
 - ▶ Lightroom
 - ▶ Photomatix
- ▶ Techniques
 - ▶ Color-grading
- ▶ Artistic intent



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Intent #2: Visual system simulator

The eye adapted to the display viewing conditions

Real-world / rendering

The eye adapted to the real-world viewing conditions

Display

Goal: match color appearance

Visual system simulator - example

▶ Simulation of glare

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Intent #3: Scene reproduction problem

Real-world

Display

Goal: map colors to a restricted color space

Mapping problem

Real-world

Display

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Techniques

- ▶ Arithmetic of HDR images
- ▶ Display model
- ▶ Tone-curve
- ▶ Color transfer
- ▶ Base-detail separation
- ▶ Glare
- ▶ Simulation of night vision

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Arithmetic of HDR images

- ▶ How does the basic arithmetic operations
 - ▶ Addition
 - ▶ Multiplication
 - ▶ Power function
- ▶ affect the appearance of an HDR image
- ▶ We work in the luminance space (NOT luma)
- ▶ The same operations can be applied to linear RGB
 - ▶ Or to luminance-only and the color can be transferred

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Multiplication – brightness change

Resulting luminance: $T(L_p) = B \cdot L_p$

Input luminance: L_p

Brightness change parameter: B

- ▶ Multiplication makes the image brighter or darker
- ▶ It does not change the dynamic range!

Power function – contrast change

Contrast change (gamma): c

Luminance of white: L_{white}

Equation: $T(L_p) = \left(\frac{L_p}{L_{white}} \right)^c$

- ▶ Power function stretches or shrinks image dynamic range
- ▶ It is usually performed relative to reference white
- ▶ Apparent brightness changes is the side effect of pushing tones towards or away from the white point

Addition – black level

Black level (flare, fog): F

Equation: $T(L_p) = L_p + F$

- ▶ Addition elevates black level, adds fog to an image
- ▶ It does NOT make the overall image brighter
- ▶ It reduces dynamic range

Techniques

- ▶ Arithmetic of HDR images
- ▶ **Display model**
- ▶ Tone-curve
- ▶ Color transfer
- ▶ Base-detail separation
- ▶ Glare
- ▶ Simulation of night vision

Two ways to do tone-mapping

Way 1: HDR image → Tone mapping A → LDR image

Way 2: HDR image → Tone mapping B → Inverse display model → LDR image

Labels: Luminance, linear RGB; Luma, „gamma corrected“ RGB, sRGB; Luminance, linear RGB; Sometimes known as „gamma“

- Display model can account for:
 - Display peak luminance
 - Display dynamic range (contrast)
 - Ambient light

Display model

▶ Tone-mapping needs to account for the physical model of the display

▶ How a display transforms pixel values into emitted light

(Forward) Display model

► GOG: Gain-Gamma-Offset

Luminance, Peak luminance, Gamma, Display black level, Screen reflections

$$L = (L_{peak} - L_{black}) V^\gamma + L_{black} + L_{refl}$$

Gain, Pixel value 0-1, Offset

Reflectance factor (0.01)

$$L_{refl} = \frac{k}{\pi} E_{amb}$$

Ambient illumination (in lux)

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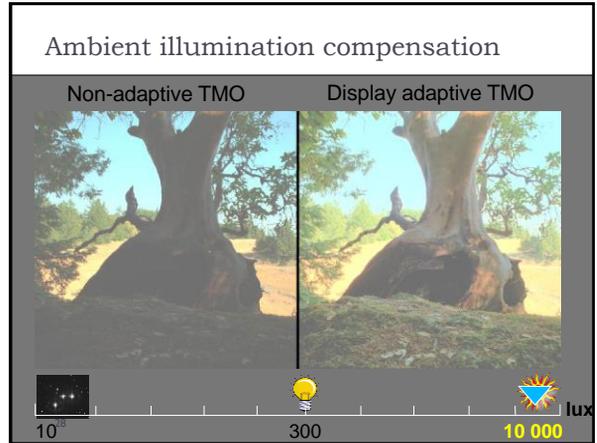
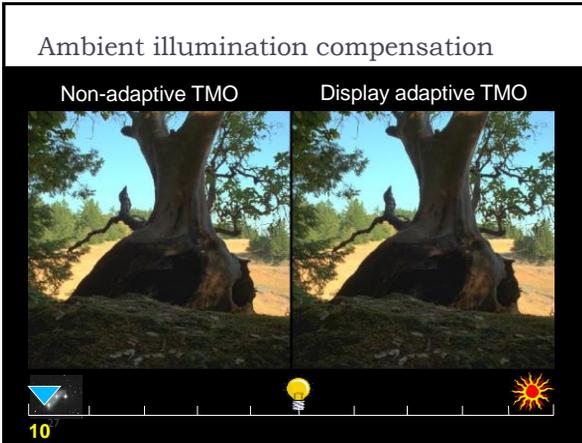
Inverse display model

Symbols are the same as for the forward display model

$$V = \left(\frac{L - L_{black} - L_{refl}}{L_{peak} - L_{black}} \right)^{1/\gamma}$$

Note: This display model does not address any colour issues. The same equation is applied to red, green and blue color channels. The assumption is that the display primaries are the same as for the sRGB color space.

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Example: Ambient light compensation

► We are looking at the screen in bright light

$L_{peak} = 100 [cd \cdot m^{-2}]$ $k = 0.005$ Modern screens have reflectivity of around 0.5%

$L_{black} = 0.1 [cd \cdot m^{-2}]$

$E_{amb} = 2000 [lux]$ $L_{refl} = \frac{0.005}{2\pi} 2000 = 1.59 [cd \cdot m^{-2}]$

► We assume that the dynamic of the input is 2.6 (=400:1)

$$r_{in} = 2.6 \quad r_{out} = \log_{10} \frac{L_{peak}}{L_{black} + L_{refl}} = 1.77$$

► First, we need to compress contrast to fit the available dynamic range, then compensate for ambient light

$$L_{out} = \left(\frac{L_{in}}{L_{peak}} \right)^{\frac{r_{out}}{r_{in}}} - L_{refl}$$

The resulting value is in luminance, must be mapped to display luma / gamma corrected values

Simplest, but not the best tone mapping

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Techniques

- Arithmetic of HDR images
- Display model
- **Tone-curve**
- Color transfer
- Base-detail separation
- Glare
- Simulation of night vision

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Tone-curve

Best tone-mapping is the one which does not do anything, i.e. slope of the tone-mapping curves is equal to 1.

Image histogram

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Tone-curve

But in practice contrast (slope) must be limited due to display limitations.

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Tone-curve

Global tone-mapping is a compromise between clipping and contrast compression.

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Sigmoidal tone-curves

- ▶ Very common in digital cameras
- ▶ Mimic the response of analog film
- ▶ Analog film has been engineered over many years to produce good tone-reproduction (given that the tone curve must not change)
- ▶ In practice - the most commonly used tone-mapping!

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Photoreceptor response

- ▶ Dynamic range reduction inspired by photoreceptor physiology
- ▶ [Reinhard & Devlin '05]

$$V = \frac{I}{I + \sigma(I_a)} V_{max}$$

$$\sigma(I_a) = (fI_a)^m$$

- ▶ From gamma to sigmoidal response:

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Photoreceptor TMO

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Results: photoreceptor TMO



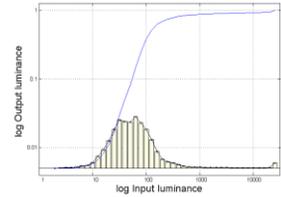
Histogram equalization

- 1. Compute cumulative image histogram

$$c(I) = \frac{1}{N} \sum_{i=0}^I h(i) = c(I-1) + \frac{1}{N} h(I)$$
 - For HDR, operate in the log domain
- 2. Use the cumulative histogram as a tone-mapping function

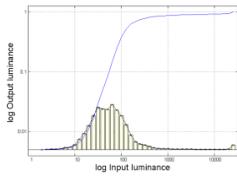
$$Y_{out} = c(Y_{in})$$

- For HDR, map the log-10 values to the $[d_{r_{out}}, 0]$ range
 - where $d_{r_{out}}$ is the target dynamic range (of a display)



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Histogram equalization



- ▶ Steepest slope for strongly represented bins
 - If many pixels have the same value - enhance contrast
 - Reduce contrast, if few pixels
- ▶ Histogram Equalization distributes contrast distortions relative to the "importance" of a brightness level

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Histogram adjustment with a linear ceiling

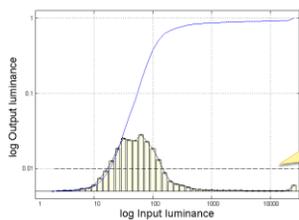
- ▶ [Larson et al. 1997, IEEE TVCG]



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Histogram adjustment with a linear ceiling

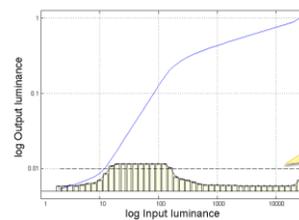
- ▶ Truncate the bins that exceed the ceiling;
- ▶ Distribute the removed counts to all bins;
- ▶ Repeat until converges



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Histogram adjustment with a linear ceiling

- ▶ Truncate the bins that exceed the ceiling;
- ▶ Distribute the removed counts to all bins;
- ▶ Repeat until converges



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Tone-curve as an optimization problem

Goal: Minimize the visual difference between the input and displayed images

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Techniques

- ▶ Arithmetic of HDR images
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- ▶ **Color transfer**
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- ▶ Simulation of night vision

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Colour transfer in tone-mapping

- ▶ Many tone-mapping operators work on luminance
 - ▶ For speed
 - ▶ To avoid colour artefacts
- ▶ Colours must be transferred later from the original image
- ▶ Colour transfer in the linear RGB colour space:

$$R_{out} = \left(\frac{R_{in}}{L_{in}} \right)^s \cdot L_{out}$$

Labels for the equation: R_{in} is the input red channel, L_{in} is the input luminance, s is the saturation parameter, and L_{out} is the resulting luminance.

- ▶ The same formula applies to green (G) and blue (B) linear colour values.

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Colour transfer: out-of-gamut problem

- ▶ Colours often fall outside the colour gamut when contrast is compressed

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Colour transfer: alternative method

- ▶ Colour transfer in linear RGB will alter resulting luminance
- ▶ Colours can be also transferred and saturation adjusted using CIE u'v' chromatic coordinates

Chroma of the white

- ▶ To correct saturation:

$$u'_{out} = (u'_{in} - u'_w) \cdot s + u'_w \quad u'_w = 0.1978$$

$$v'_{out} = (v'_{in} - v'_w) \cdot s + v'_w \quad v'_w = 0.4683$$

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Techniques

- ▶ Arithmetic of HDR images
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Illumination & reflectance separation

Input \rightarrow Illumination \times Reflectance

$$Y = I \times R$$

Labels: Image, Illumination, Reflectance

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Illumination and reflectance

<p>Reflectance</p> <ul style="list-style-type: none"> White $\approx 90\%$ Black $\approx 3\%$ Dynamic range $< 100:1$ Reflectance critical for object & shape detection 	<p>Illumination</p> <ul style="list-style-type: none"> Sun $\approx 10^9 \text{ cd/m}^2$ Lowest perceivable luminance $\approx 10^{-6} \text{ cd/m}^2$ Dynamic range 10,000:1 or more Visual system partially discounts illumination
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Reflectance & Illumination TMO

- Hypothesis: Distortions in reflectance are more apparent than the distortions in illumination
- Tone mapping could preserve reflectance but compress illumination

$$L_d = R \times T(I)$$

Labels: Tone-mapped image, Reflectance, Tone-mapping, Illumination

- for example:

$$L_d = R \cdot (I / L_{white})^c \cdot L_{white}$$

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How to separate the two?

- (Incoming) illumination – slowly changing
 - except very abrupt transitions on shadow boundaries
- Reflectance – low contrast and high frequency variations

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Gaussian filter

$$f(x) = \frac{1}{2\pi\sigma_s^2} e^{-\frac{x^2}{2\sigma_s^2}}$$

- First order approximation

- Blurs sharp boundaries
- Causes halos

Tone mapping result

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Bilateral filter

$$I_p \approx \frac{1}{k_s} \sum_{t \in \Omega} f(p-t) g(L_p - L_t) L_p$$

- Better preserves sharp edges

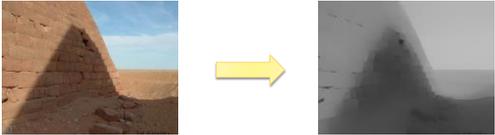
- Still some blurring on the edges
- Reflectance is not perfectly separated from illumination near edges

Tone mapping result

55 [Durand & Dorsey, SIGGRAPH 2002]

Weighted-least-squares (WLS) filter

- ▶ Stronger smoothing and still distinct edges



Tone mapping result

- ▶ Can produce stronger effects with fewer artifacts
- ▶ See image processing lecture

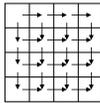
[Farbman et al., SIGGRAPH 2008]

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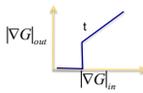
Retinex

- ▶ Retinex algorithm was initially intended to separate reflectance from illumination [Land 1964]
- ▶ There are many variations of Retinex, but the general principle is to eliminate from an image small gradients, which are attributed to the illumination

1st step: compute gradients in log domain



2nd step: set to 0 gradients less than the threshold



3rd step: reconstruct an image from the vector field

$$\nabla^2 I = \text{div } G$$

For example by solving the Poisson equation

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Retinex examples

From: <http://dragon.larc.nasa.gov/retinex757/>



Original



After Retinex

From: http://www.ipol.im/pub/algol/imps_retinex_poisson_equation/#ref_1



original image



Retinex result with t=3



Retinex result with t=5



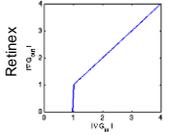
Retinex result with t=10

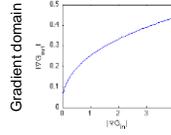
Gradient domain HDR compression

[Fattal et al., SIGGRAPH 2002]



- ▶ Similarly to Retinex, it operates on log-gradients
- ▶ But the function amplifies small contrast instead of removing it





- Contrast compression achieved by global contrast reduction
 - Enhance reflectance, then compress everything

▶

Techniques

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- ▶ Glare
- ▶ Simulation of night vision

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Glare



Alan Wake © Remedy Entertainment

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Glare Illusion

Photography Painting

Computer Graphics
HDR rendering in games

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Scattering of the light in the eye

From: Sekuler, R., and Blake, R. Perception, second ed. McGraw- Hill, New York, 1990

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Ciliary corona and lenticular halo

From: Spencer, G. et al. 1995. Proc. of SIGGRAPH. (1995)

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Examples of simulated glare

[From Ritschel et al, Eurographics 2009]

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Temporal model of glare (low level)

- The model assumes that glare is mostly caused by diffraction and scattering
- Can simulate temporal effects

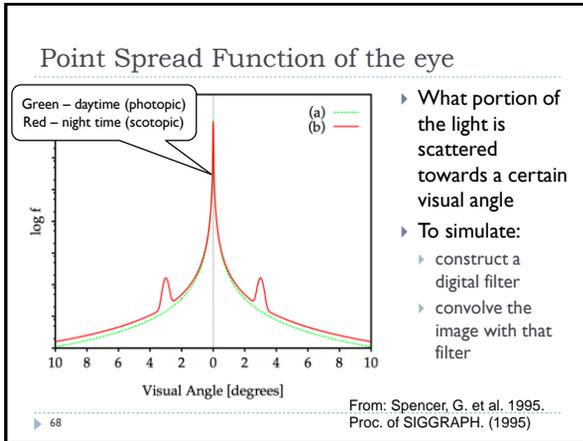
[From Ritschel et al, Eurographics 2009]

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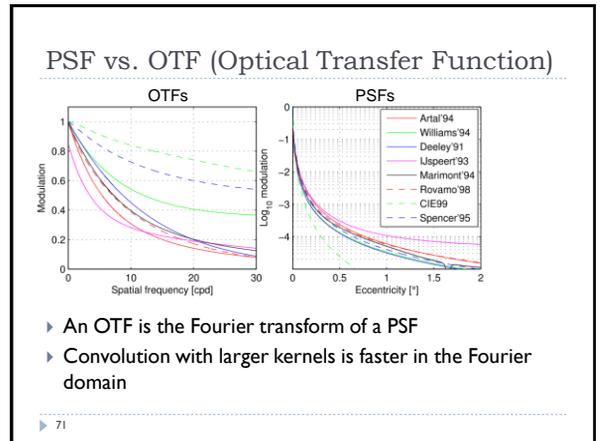
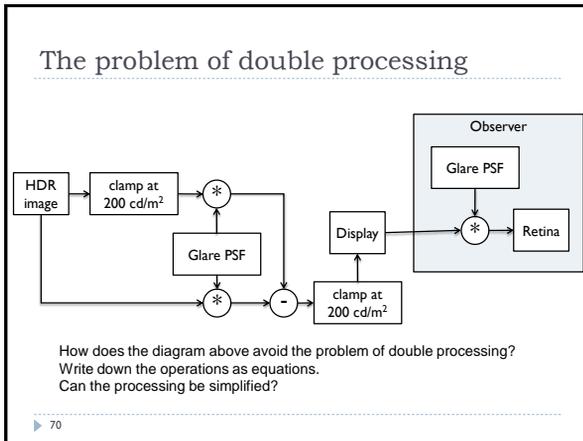
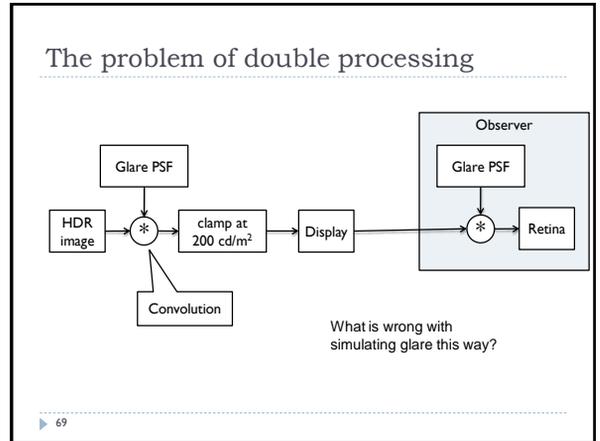
Temporal glare

Dynamic glare

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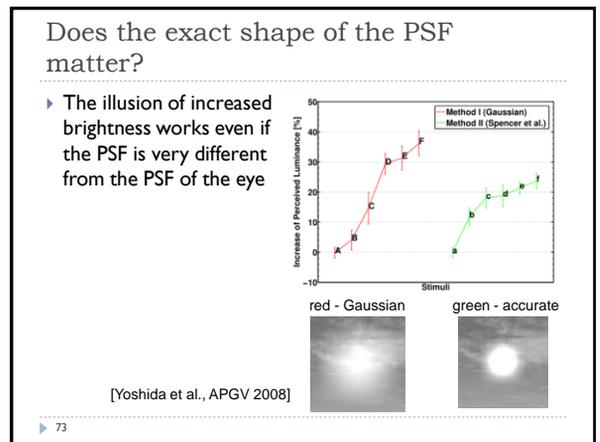


- ▶ What portion of the light is scattered towards a certain visual angle
- ▶ To simulate:
 - ▶ construct a digital filter
 - ▶ convolve the image with that filter



Glare (or bloom) in games

- ▶ Convolution with large, non-separable filters is too slow
- ▶ The effect is approximated by a combination of Gaussian filters
 - ▶ Each filter with different "sigma"
- ▶ The effect is meant to look good, not be accurate model of light scattering
- ▶ Some games simulate camera rather than the eye



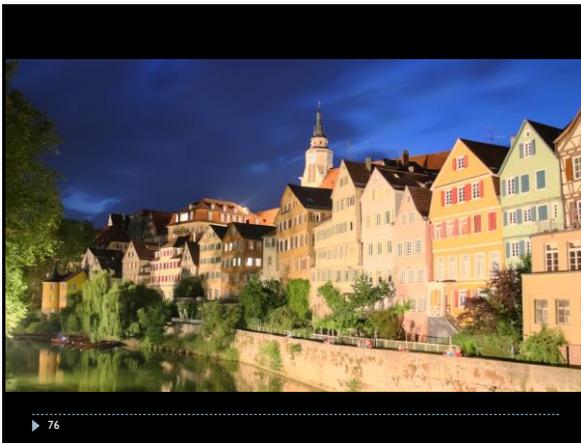
HDR rendering – motion blur

74 From LDR pixels From HDR pixels

Techniques

- ▶ Arithmetic of HDR images
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What changes at low illumination?

0.1 -> 100 cd/m²

- ▶ Global contrast
 - ▶ Relative brightness
- ▶ Local contrast
 - ▶ Visibility of small details
- ▶ Color
 - ▶ Purkinje shift
 - ▶ Saturation

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Brightness reduction – tone-curve

- ▶ Perceptually-based night-vision tone-curve
 - ▶ [Wanat et al. 2014]
 - ▶ Requires rather complex optimization
- ▶ Empirical approach (not perceptual)

$$y_{out} = b \cdot y_{in}^a + f$$

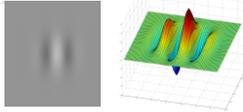
Reduce brightness Reduce contrast

Add „fog“

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Local contrast

- ▶ Gabor patch
 - ▶ basic contrast stimulus
 - ▶ the shape matches the response pattern of the receptive fields on the retina

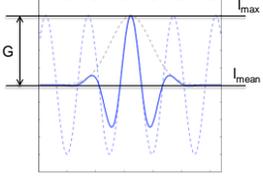


$$G = I_{\max} - I_{\text{mean}}$$

Contrast

Max log luminance

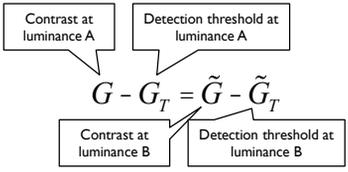
Mean log luminance

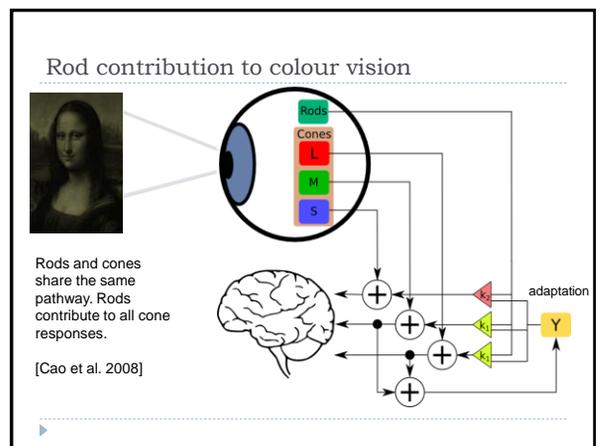
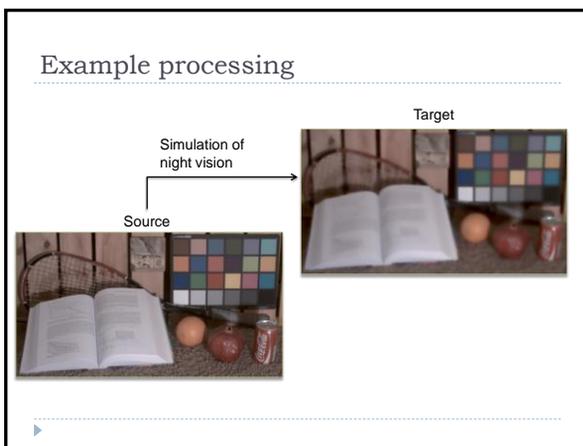
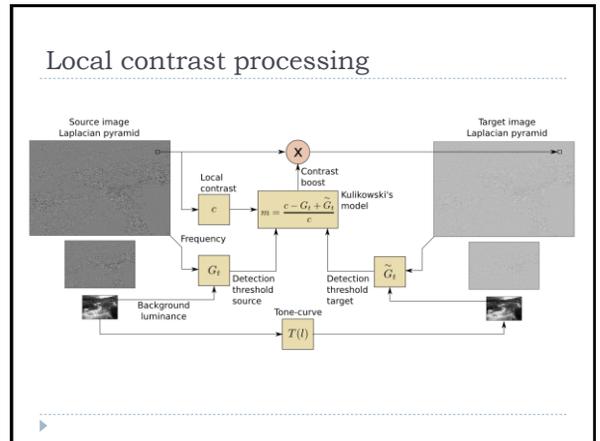
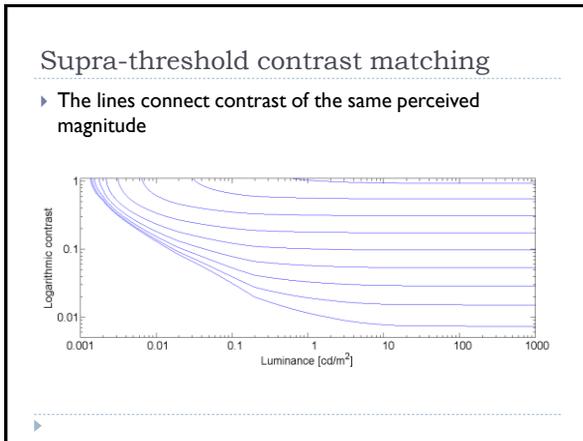


Supra-threshold contrast matching

- ▶ Kulikowski's model of matching contrast [Kulikowski 1976]
 - ▶ Contrast is perceived the same at different luminance levels when the physical contrast reduced by the corresponding detection threshold is equal at those luminance levels

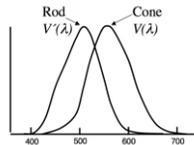
The detection thresholds can be predicted by the contrast sensitivity function



$$G - G_T = \tilde{G} - \tilde{G}_T$$


Purkinje shift (effect)

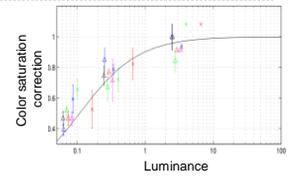
- ▶ A shift in spectral sensitivity associated with the transition of cone to rod vision
- ▶ Blue appears brighter and red appears darker in twilight
- ▶ And the reverse is observed in daylight
- ▶ The shift to bluish hues is sometimes attributed to the Purkinje effect
- ▶ In practice the blue-shift is very subtle
- ▶ Much more pronounced in movies



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Loss of colour saturation with luminance

- Cones become less sensitive at low light
- Colours become less saturated
- Empirical formula [Wanat 2014]



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Age-adaptive night vision

Video 4

Rivoli
Simulation of age-adaptive night vision

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References

- ▶ **Comprehensive book on HDR Imaging**
 - ▶ E. Reinhard, W. Heidrich, P. Debevec, S. Pattanaik, G. Ward, and K. Myszkowski, High Dynamic Range Imaging: Acquisition, Display, and Image-Based Lighting, 2nd edition. Morgan Kaufmann, 2010.
- ▶ **Overview of HDR imaging & tone-mapping**
 - ▶ http://www.cl.cam.ac.uk/~rkm38/hdri_book.html
- ▶ **Review of recent video tone-mapping**
 - ▶ A comparative review of tone-mapping algorithms for high dynamic range video Gabriel Eilertsen, Rafal K. Mantiuk, Jonas Unger, Eurographics State-of-The-Art Report 2017.
- ▶ **Selected papers on tone-mapping:**
 - ▶ G.W. Larson, H. Rushmeier, and C. Piato, "A visibility matching tone reproduction operator for high dynamic range scenes," IEEE Trans. Vis. Comput. Graph., vol. 3, no. 4, pp. 291–306, 1997.
 - ▶ R. Wanat and R. K. Mantiuk, "Simulating and compensating changes in appearance between day and night vision," ACM Trans. Graph. (Proc. SIGGRAPH), vol. 33, no. 4, p. 147, 2014.
 - ▶ Spencer, G. et al. 1995. Physically-Based Glare Effects for Digital Images. Proceedings of SIGGRAPH, (1995), 325–334
 - ▶ Ritschel, T. et al. 2009. Temporal Glare: Real-Time Dynamic Simulation of the Scattering in the Human Eye. Computer Graphics Forum, 28, 2 (Apr. 2009), 183–192
 - ▶ ...

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