

# Arrows and Reagents

“KC” Sivaramakrishnan  
Advanced Functional Programming  
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# Arrows

```
module type Arrow =
sig
  type ('a, 'b) t
  val arr    : ('a -> 'b) -> ('a, 'b) t
  val (">>>>") : ('a, 'b) t -> ('b, 'c) t -> ('a, 'c) t
  val first : ('a, 'b) t -> ('a * 'c, 'b * 'c) t
end
```

## Laws

$$\text{arr } f \ggg \text{arr } g \equiv \text{arr } (\text{compose } g f)$$

$$(f \ggg g) \ggg h \equiv f \ggg (g \ggg h)$$

$$\text{arr } \text{id} \ggg f \equiv f$$

... ...

# Functions as Arrows

“If we think of a library as defining a domain specific '**language**', whose constructions are represented as **combinators**, then the idea is to implement the language via a combination of a **static analysis** and **an optimised dynamic semantics**.”

John Huges, “Generalising Monads to Arrows”

```
val (>>) : 'a Monad.t -> ('a -> 'b Monad.t) -> 'b Monad.t
val (>>) : ('a, 'b) Arrow.t -> ('b, 'c) Arrow.t -> ('a, 'c) Arrow.t
```

**Functions with cost  
as  
Arrows**

# Reagents

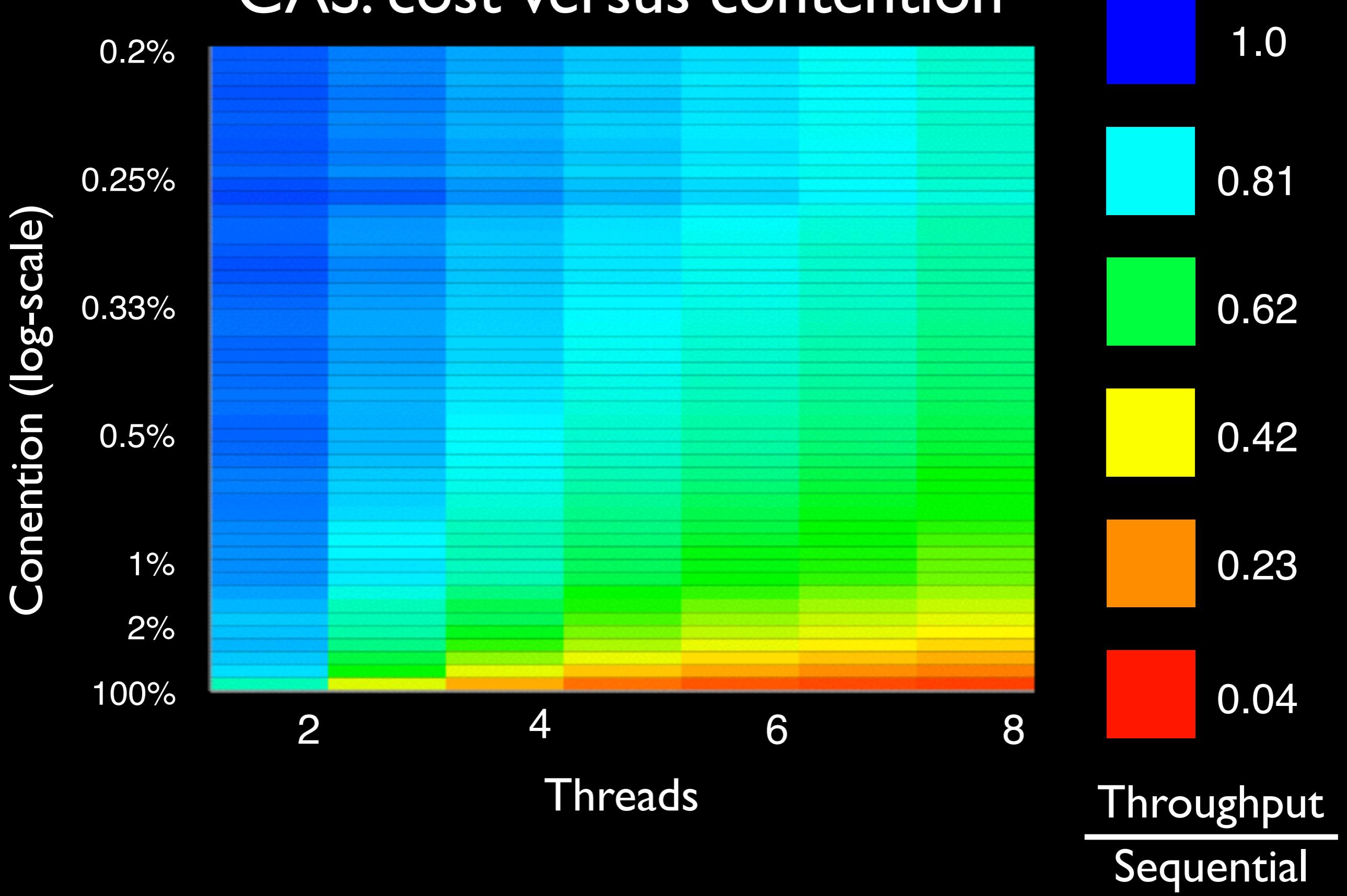
- DSL for *expressing* and *composing* fine-grained concurrency libraries
- Aaron Turon, “Reagents: expressing and composing fine-grained concurrency”, PLDI 2012
- Based on Arrows
  - Enable dynamic optimisations
  - Built on **k**-compare-and-swap abstraction

# Compare-and-swap (CAS)

```
module CAS : sig
  val cas : 'a ref -> expect:'a -> update:'a -> bool
end = struct
  (* atomically... *)
  let cas r ~expect ~update =
    if !r = expect then
      (r := update; true)
    else false
end
```

- Implemented *atomically* by processors
  - x86: **CMPXCHG** and friends
  - arm: **LDREX**, **STREX**, etc.
  - ppc: **lwarx**, **stwcx**, etc.

# CAS: cost versus contention



# java.util.concurrent

## Synchronization

Reentrant locks

Semaphores

R/W locks

Reentrant R/W locks

Condition variables

Countdown

Cyclic

Pla

Exchangers

## Data

Queues

Blocking

Blocking (array & list)

Synchronous

Priority, nonblocking

Priority, blocking

Deques

Sets

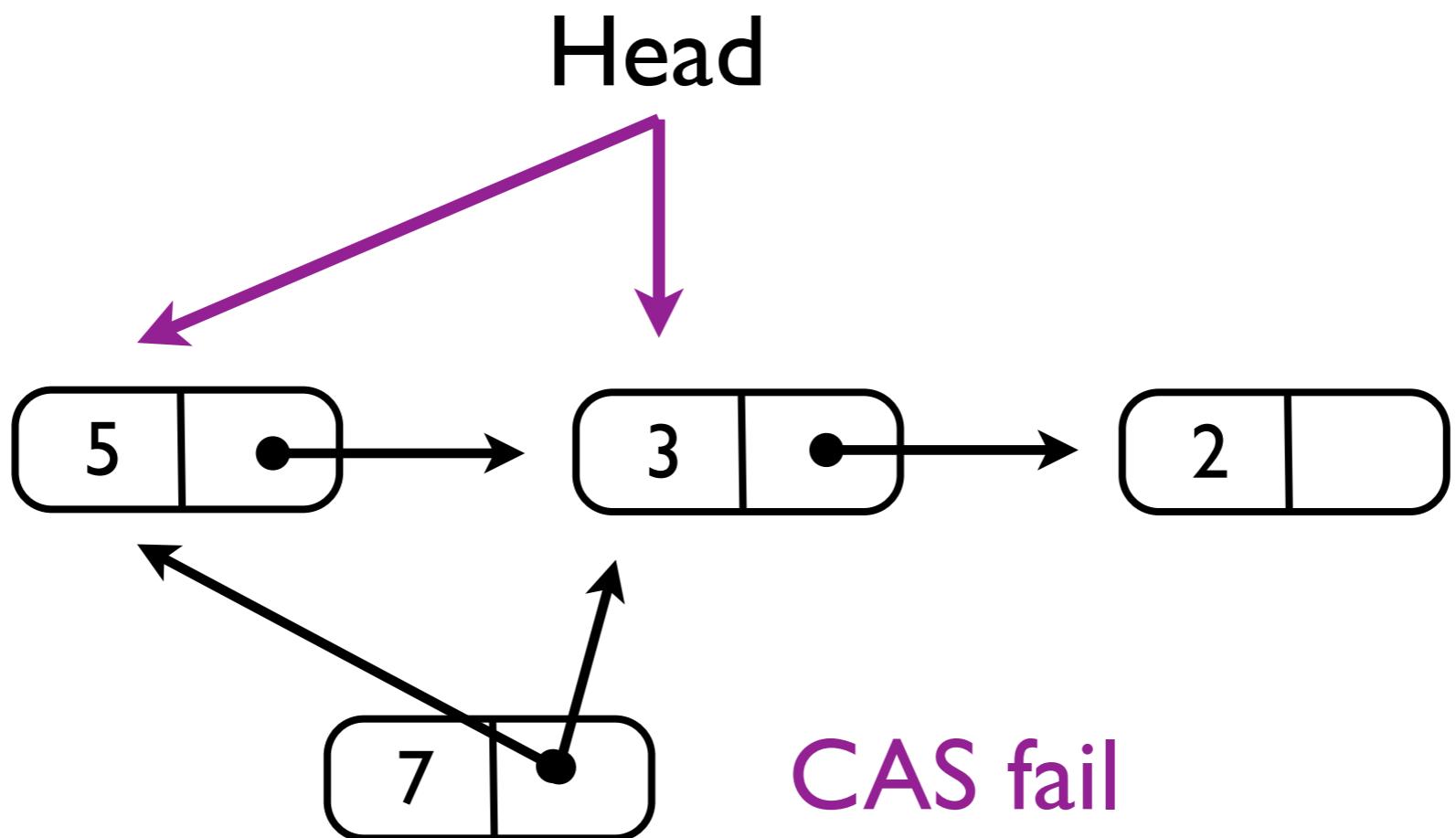
Maps (hash & skip list)

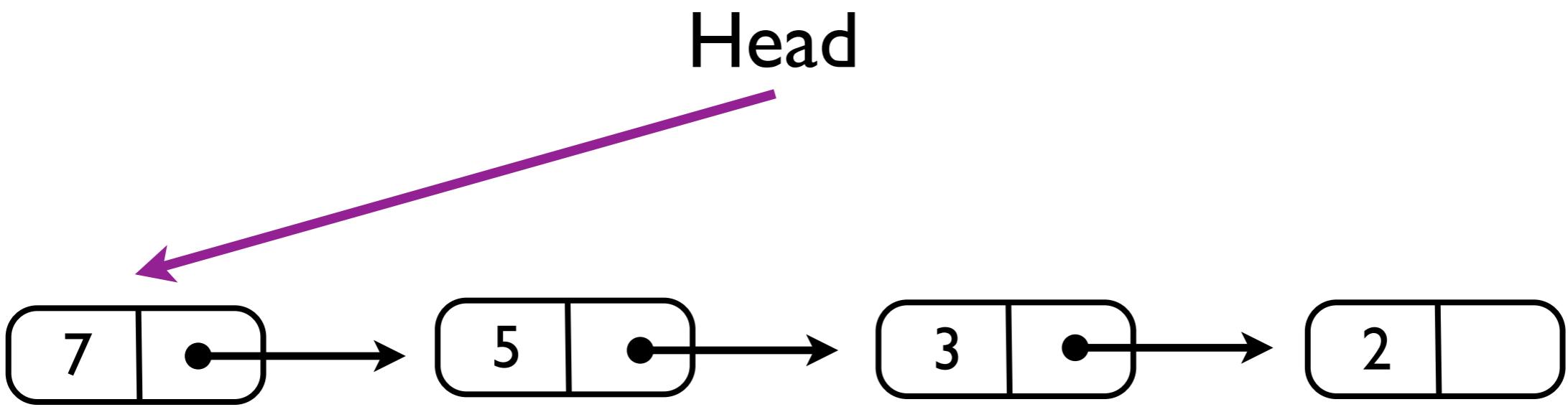
**Not Composable**

```
module type TREIBER_STACK = sig
  type 'a t
  val push : 'a t -> 'a -> unit
  ...
end
```

```
module Treiber_stack : TREIBER_STACK =
struct
  type 'a t = 'a list ref

  let rec push s t =
    let cur = !s in
    if CAS.cas s cur (t::cur) then ()
    else (backoff (); push s t)
end
```





```

module type TREIBER_STACK = sig
  type 'a t
  val push    : 'a t -> 'a -> unit
  val try_pop : 'a t -> 'a option
end

module Treiber_stack : TREIBER_STACK =
struct
  type 'a t = 'a list ref

  let rec push s t = ...

  let rec try_pop s =
    match !s with
    | [] -> None
    | (x::xs) as cur ->
        if CAS.cas s cur xs then Some x
        else (backoff O; try_pop s)
end

```

# The Problem:

Concurrency libraries are  
**indispensable**, but hard to  
**build** and **extend**

```
let v = Treiber_stack.pop s1 in  
Treiber_stack.push s2 v
```

is not ***atomic***

# The Proposal:

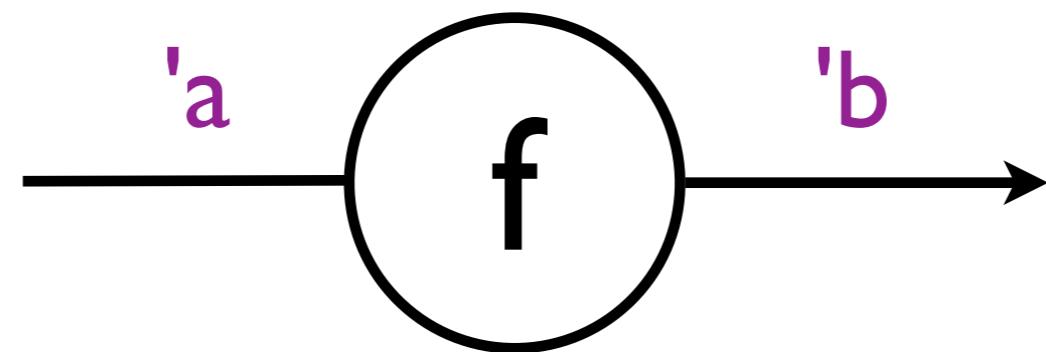
Scalable concurrent algorithms  
can be built and extended using  
abstraction and composition

```
Treiber_stack.pop s1 >>> Treiber_stack.push s2
```

is *atomic*

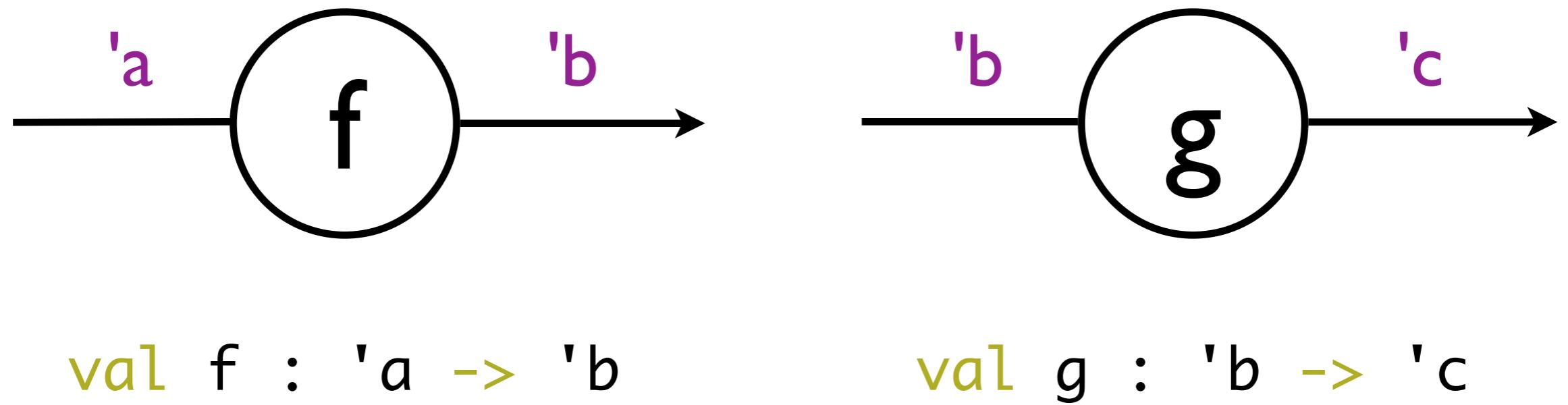
# Design

# Lambda: the ultimate abstraction

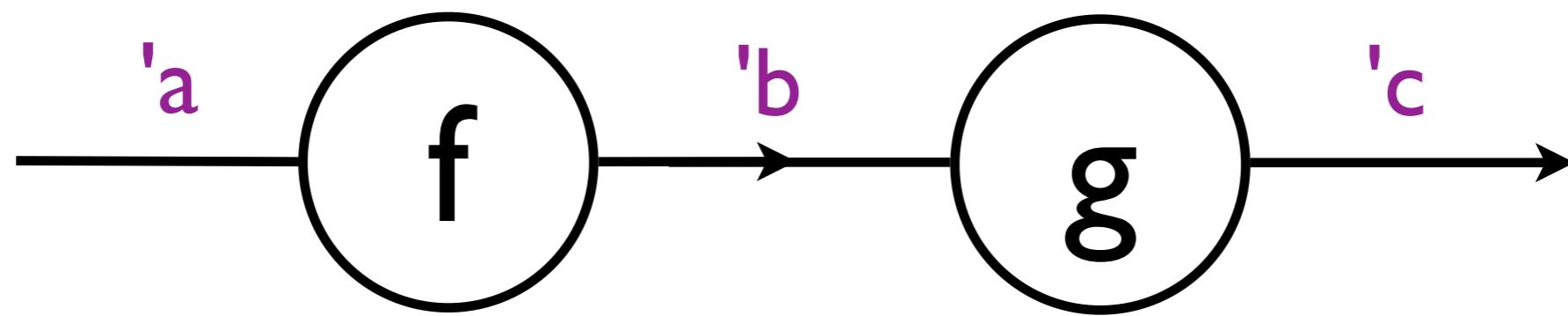


`val f : 'a -> 'b`

# Lambda: the ultimate abstraction

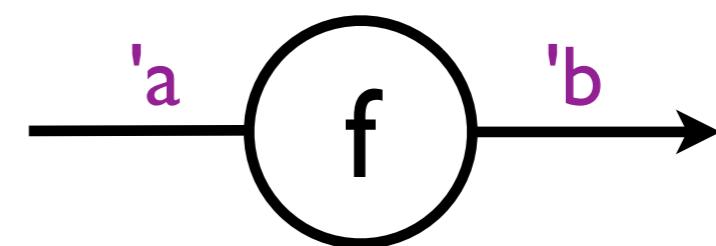


# Lambda: the ultimate abstraction

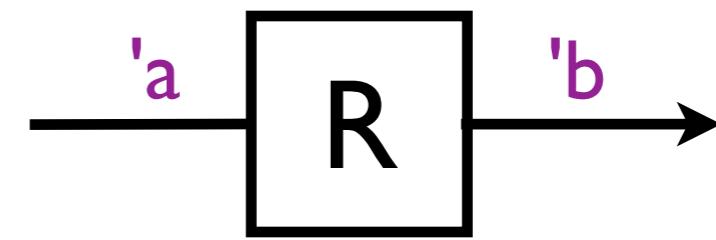


(compose g f): ' $a \rightarrow c$ '

Lambda abstraction:



Reagent abstraction:



( $'a$ ,  $'b$ ) Reagent.t

# Reagent combinators

```
module type Reagents = sig
  type ('a, 'b) t
  val never      : ('a, 'b) t
  val constant   : 'a -> ('b, 'a) t
  val (">>>>)  : ('a, 'b) t -> ('b, 'c) t -> ('a, 'c) t

  module Ref : Ref.S with type ('a, 'b) reagent = ('a, 'b) t
  module Channel : Channel.S with type ('a, 'b) reagent = ('a, 'b) t

  val run        : ('a, 'b) t -> 'a -> 'b
  ...
end
```

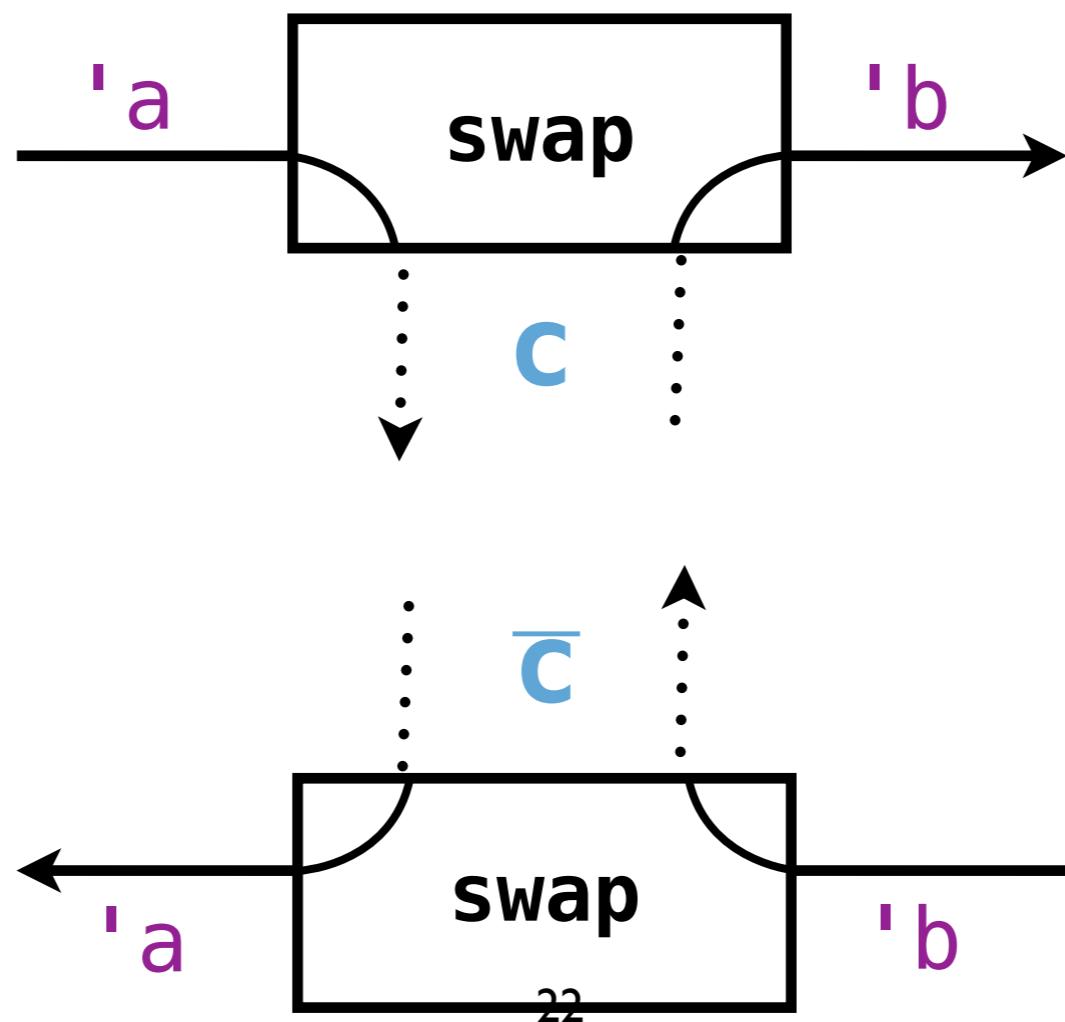
```

module type Channel = sig
  type ('a, 'b) endpoint
  type ('a, 'b) reagent

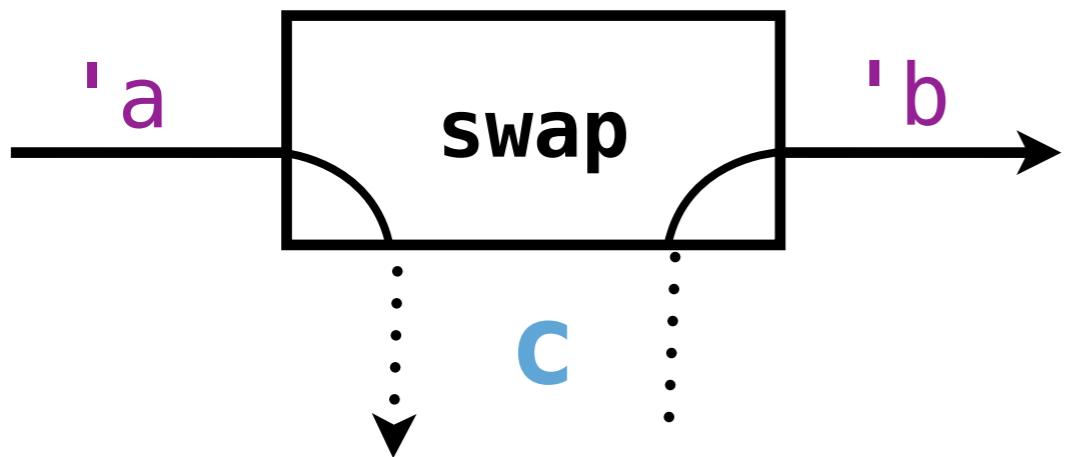
  val mk_chan : unit -> ('a, 'b) endpoint * ('b, 'a) endpoint
  val swap     : ('a, 'b) endpoint -> ('a, 'b) reagent
end

```

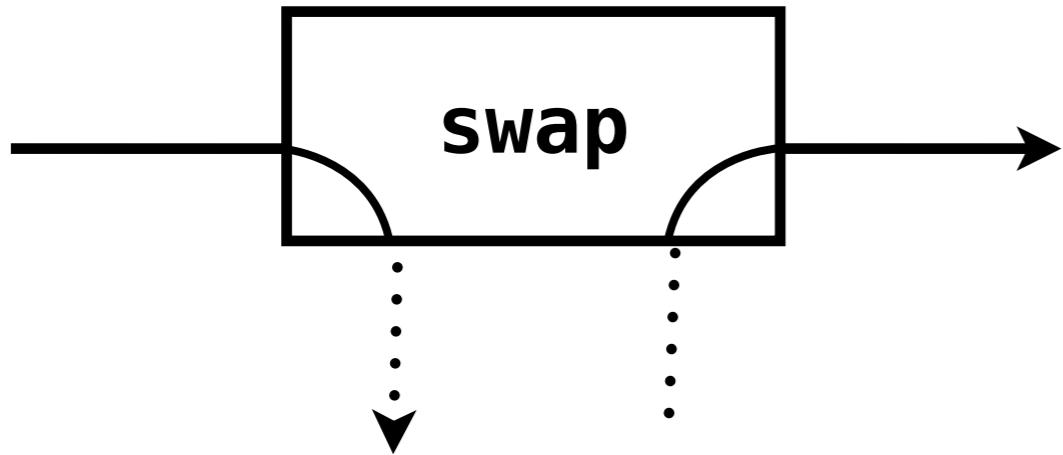
**c: ('a, 'b) endpoint**



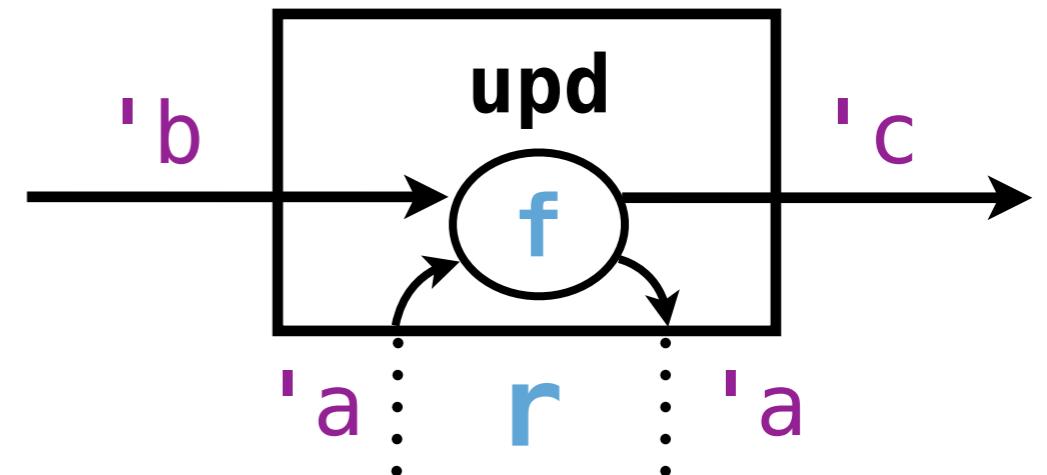
**c:** ('a, 'b) endpoint



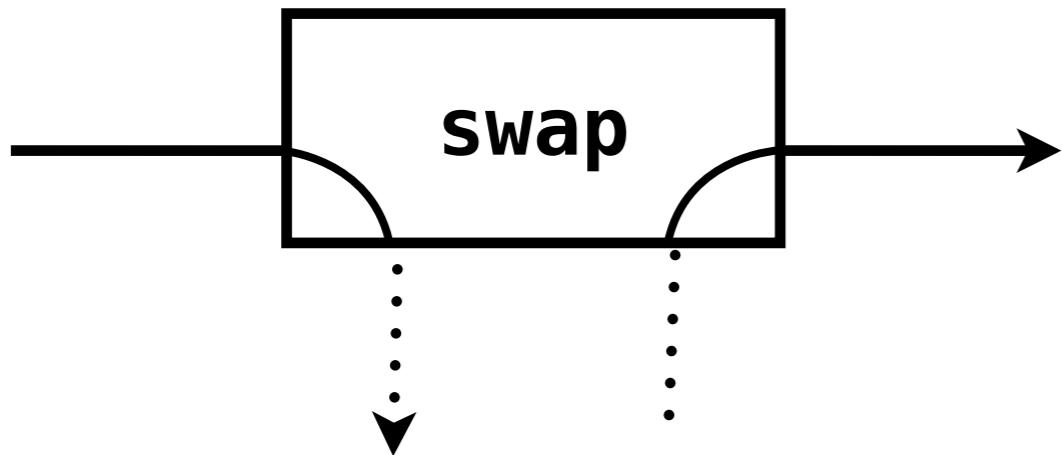
# Message passing



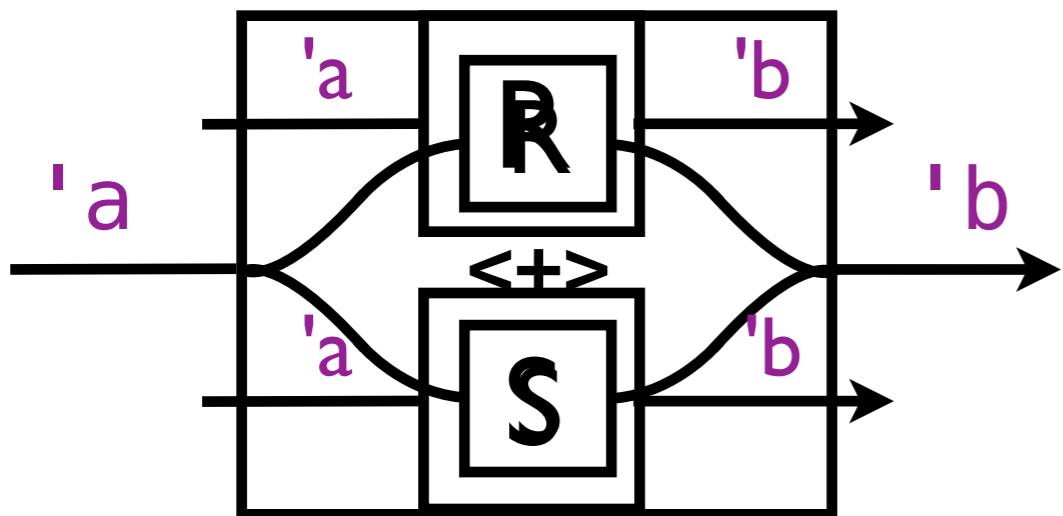
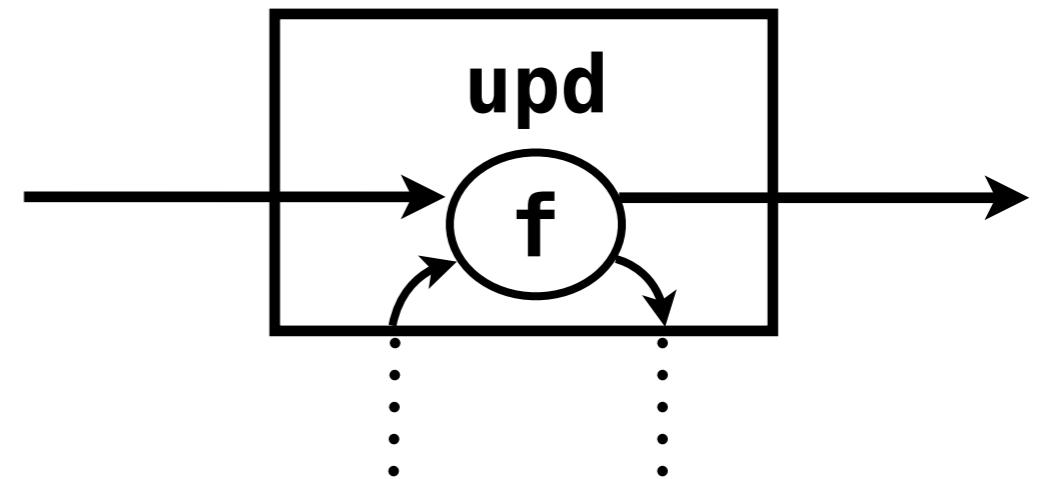
```
type 'a ref
val upd : 'a ref
  -> f:('a -> 'b -> ('a * 'c) option)
  -> ('b, 'c) Reagent.t
```



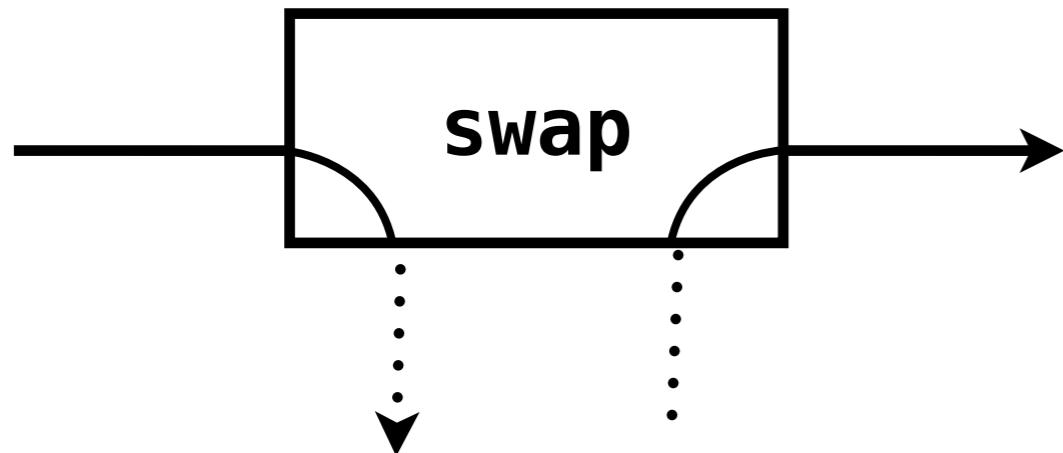
# Message passing



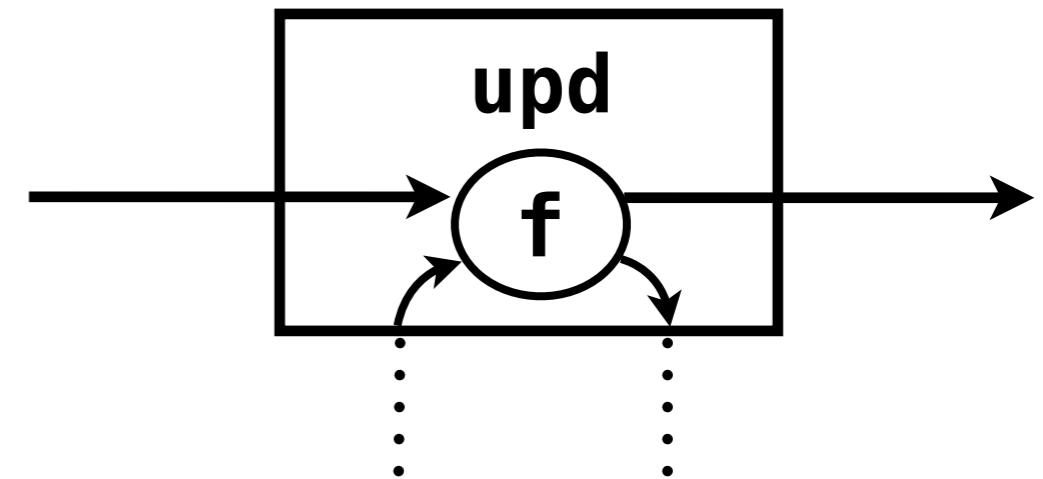
# Shared state



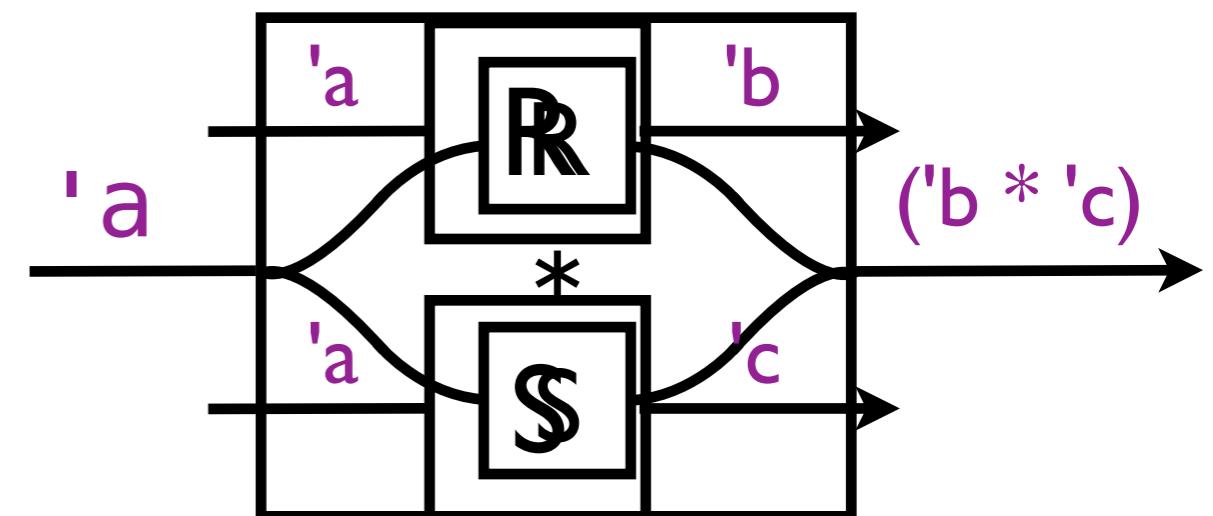
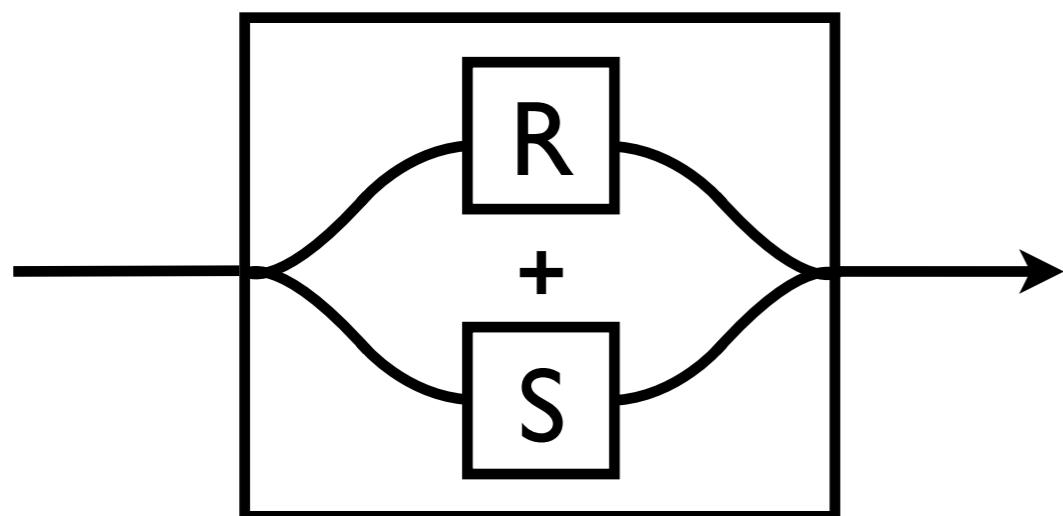
## Message passing



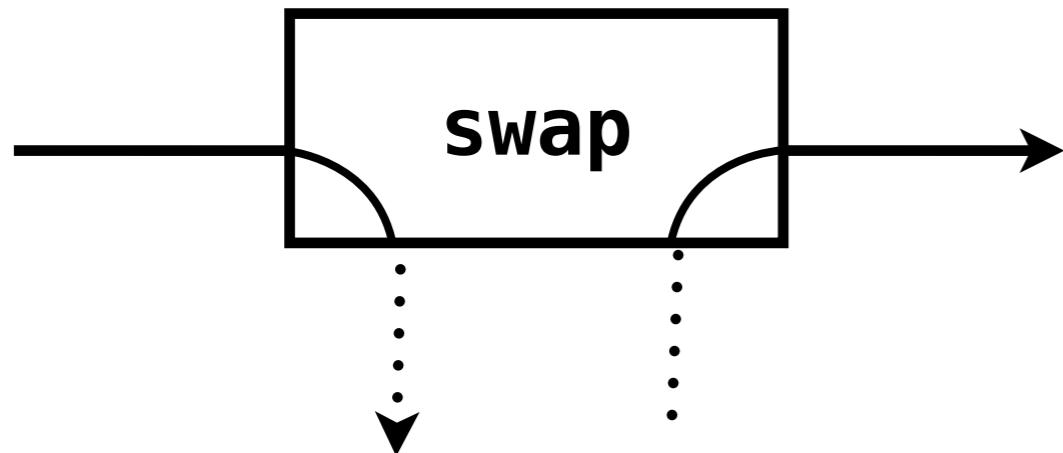
## Shared state



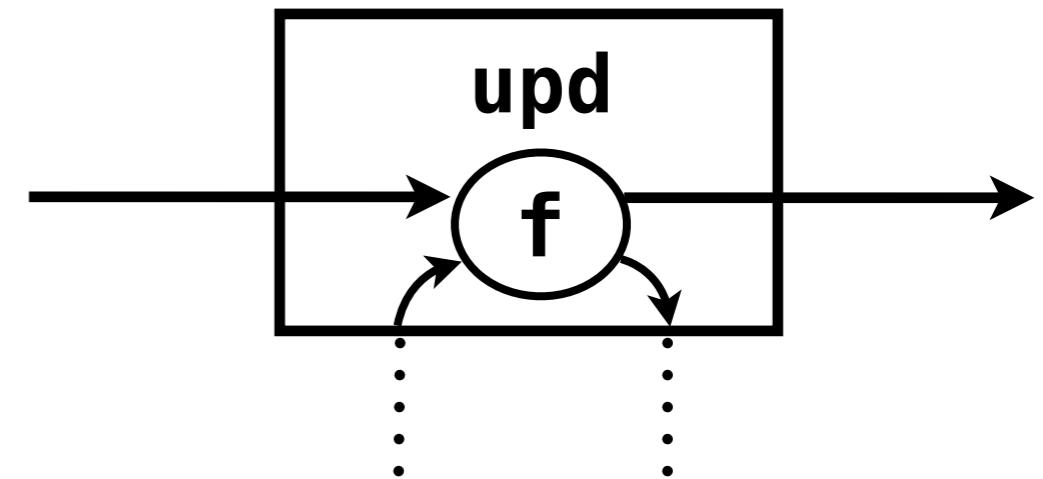
## Disjunction



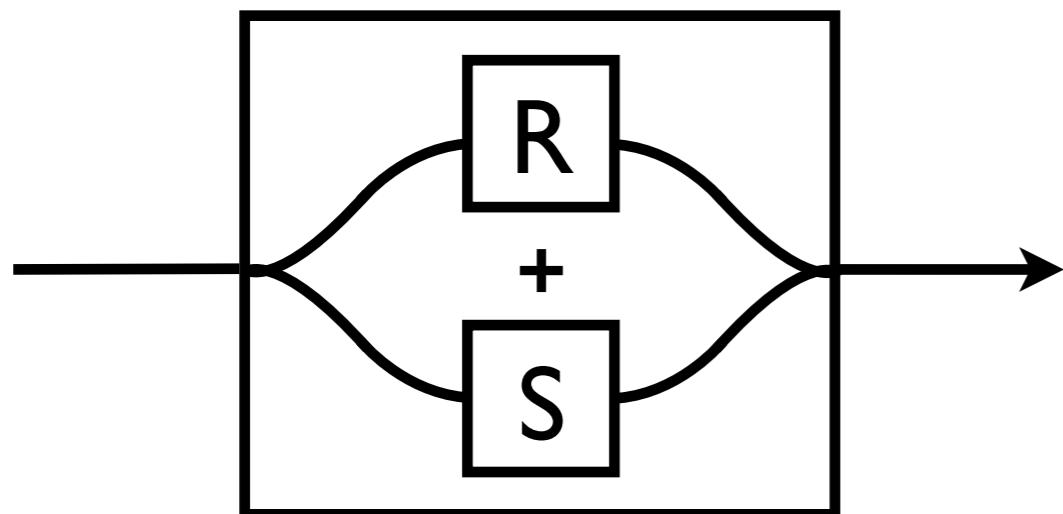
## Message passing



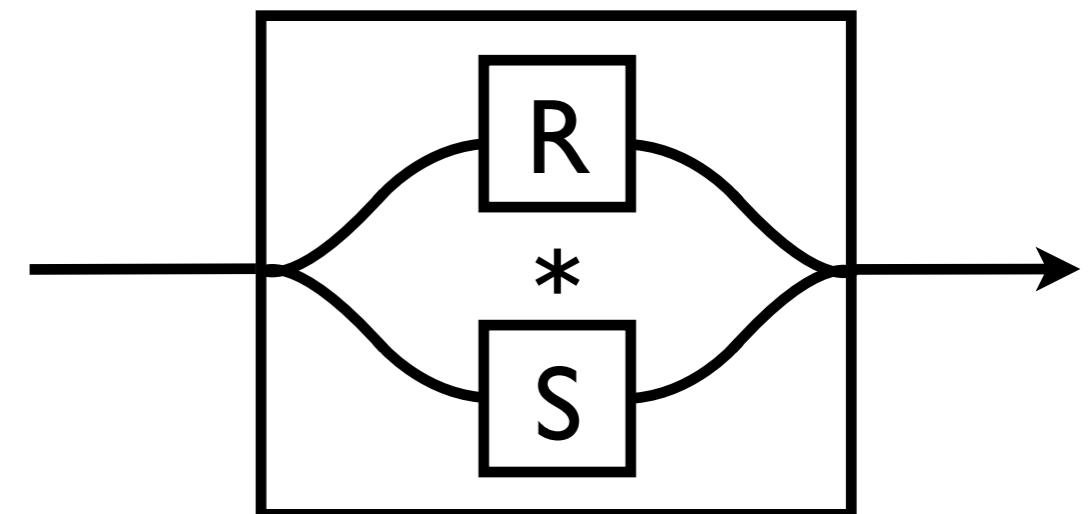
## Shared state



## Disjunction



## Conjunction



```

module type TREIBER_STACK = sig
  type 'a t
  val create : unit -> 'a t
  val push   : 'a t -> ('a, unit) Reagent.t
  val pop    : 'a t -> (unit, 'a) Reagent.t
  val try_pop : 'a t -> (unit, 'a option) Reagent.t
end

module Treiber_stack : TREIBER_STACK = struct
  type 'a t = 'a list Ref.ref

  let create () = Ref.mk_ref []

  let push r x = Ref.upd r (fun xs x -> Some (x::xs, ()))

  let try_pop r = Ref.upd r (fun l () ->
    match l with
    | [] -> Some ([], None)
    | x::xs -> Some (xs, Some x))

  let pop r = Ref.upd r (fun l () ->
    match l with
    | [] -> None
    | x::xs -> Some (xs,x))
end

```

# Composability

Transfer elements atomically

`Treiber_stack.pop s1 >>> Treiber_stack.push s2`

Consume elements atomically

`Treiber_stack.pop s1 <*> Treiber_stack.pop s2`

Consume elements from either

`Treiber_stack.pop s1 <+> Treiber_stack.pop s2`



```
type fork =
  {drop : (unit,unit) endpoint;
   take : (unit,unit) endpoint}
```

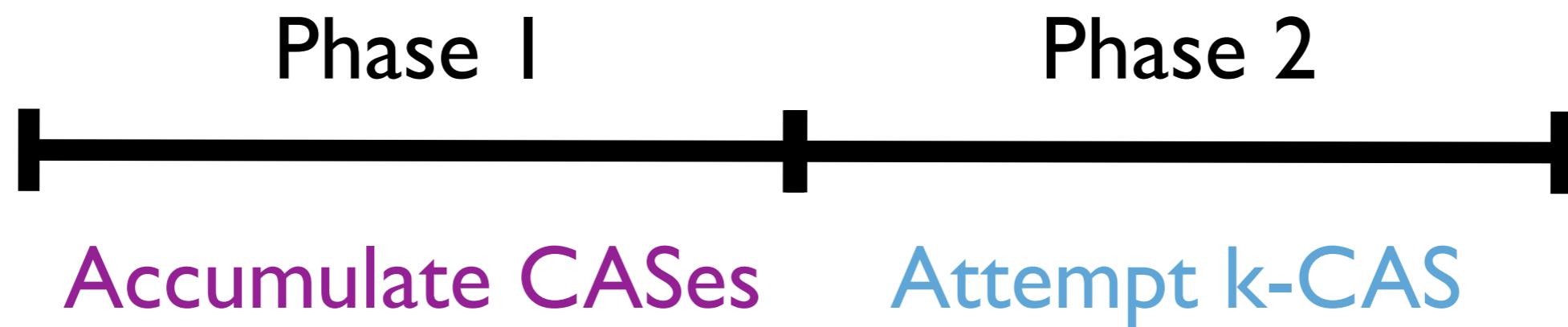
```
let mk_fork () =
  let drop, take = mk_chan () in
  {drop; take}
```

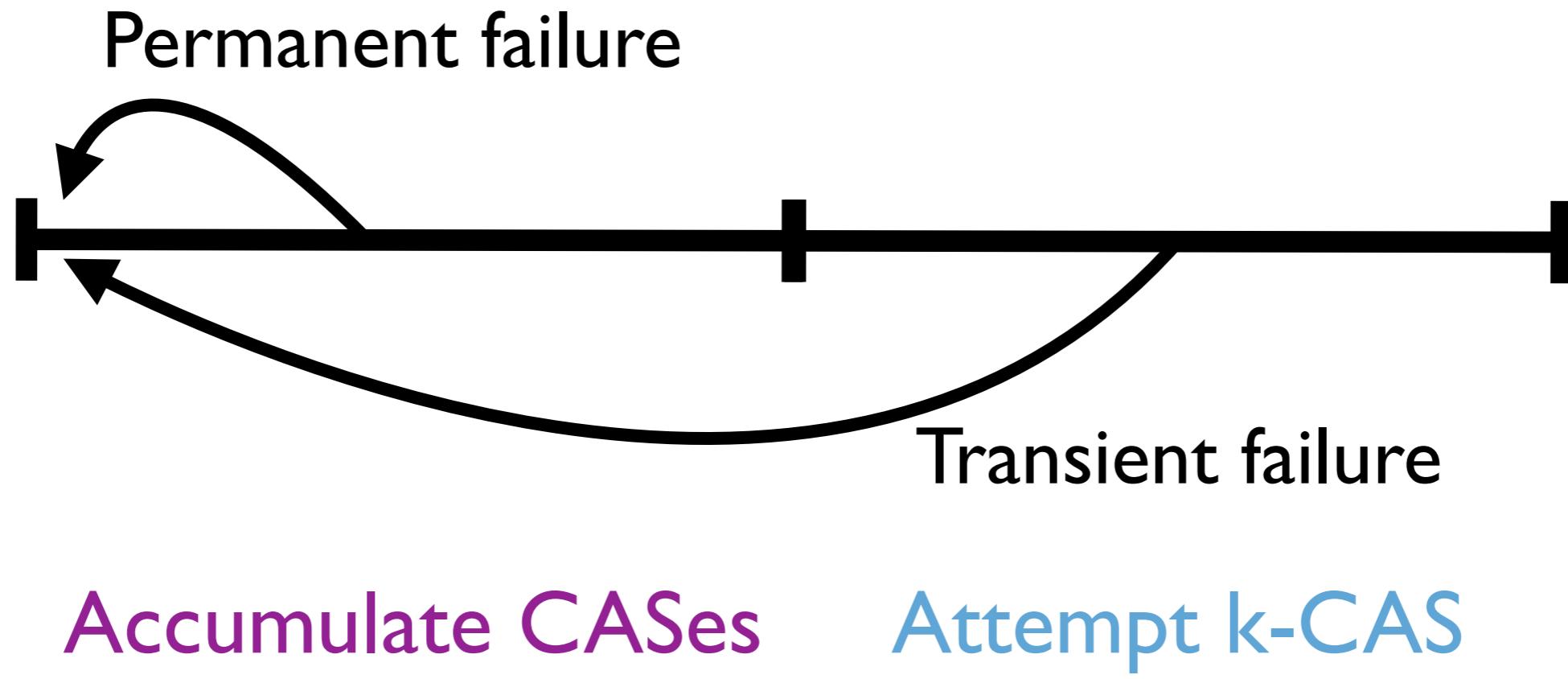
```
let drop f = swap f.drop
let take f = swap f.take
```

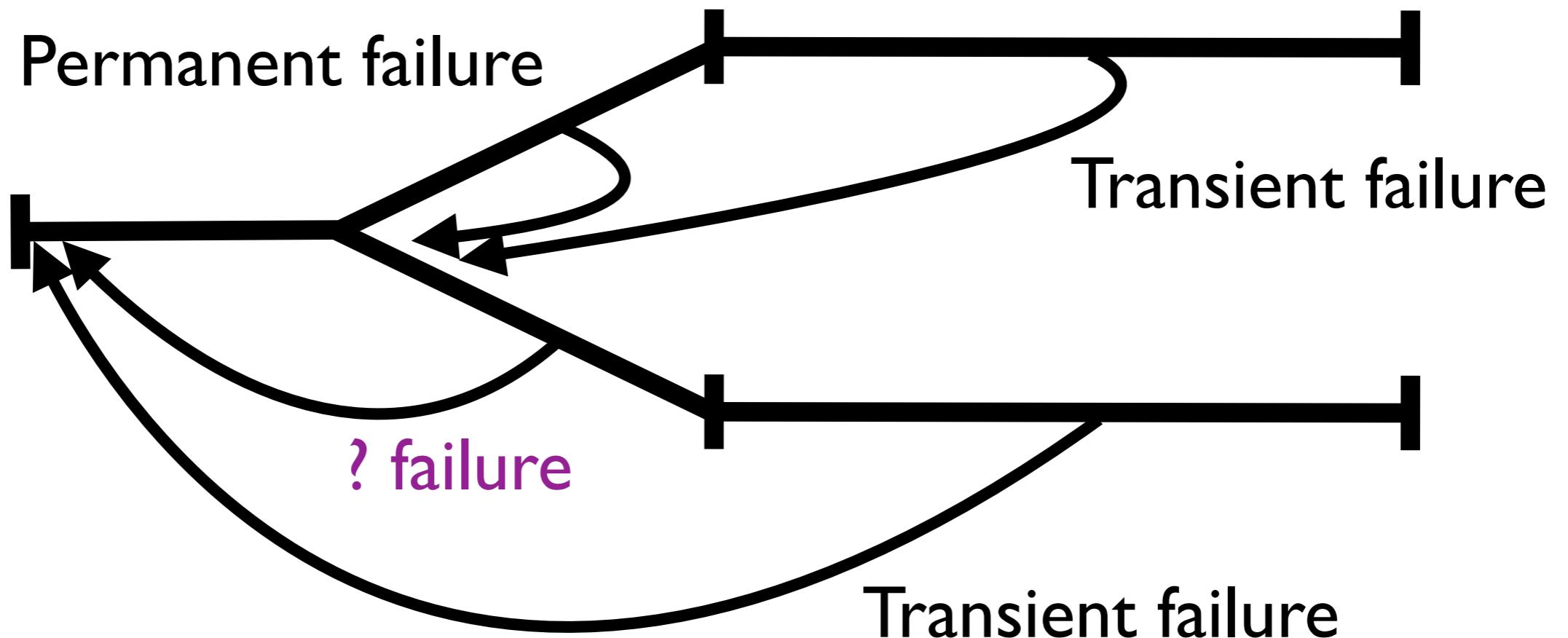
```
let init forks =
  List.iter (fun fork ->
    Thread.spawn @@ run (drop fork)) forks
```

```
let eat l_fork r_fork =
  run (take l_fork <*> take r_fork) ();
  (* ...
   * eat
   * ... *)
  run (drop l_fork) ();
  run (drop r_fork) ()
```

# Implementation







$$P \& P = P$$

$$T \& T = T$$

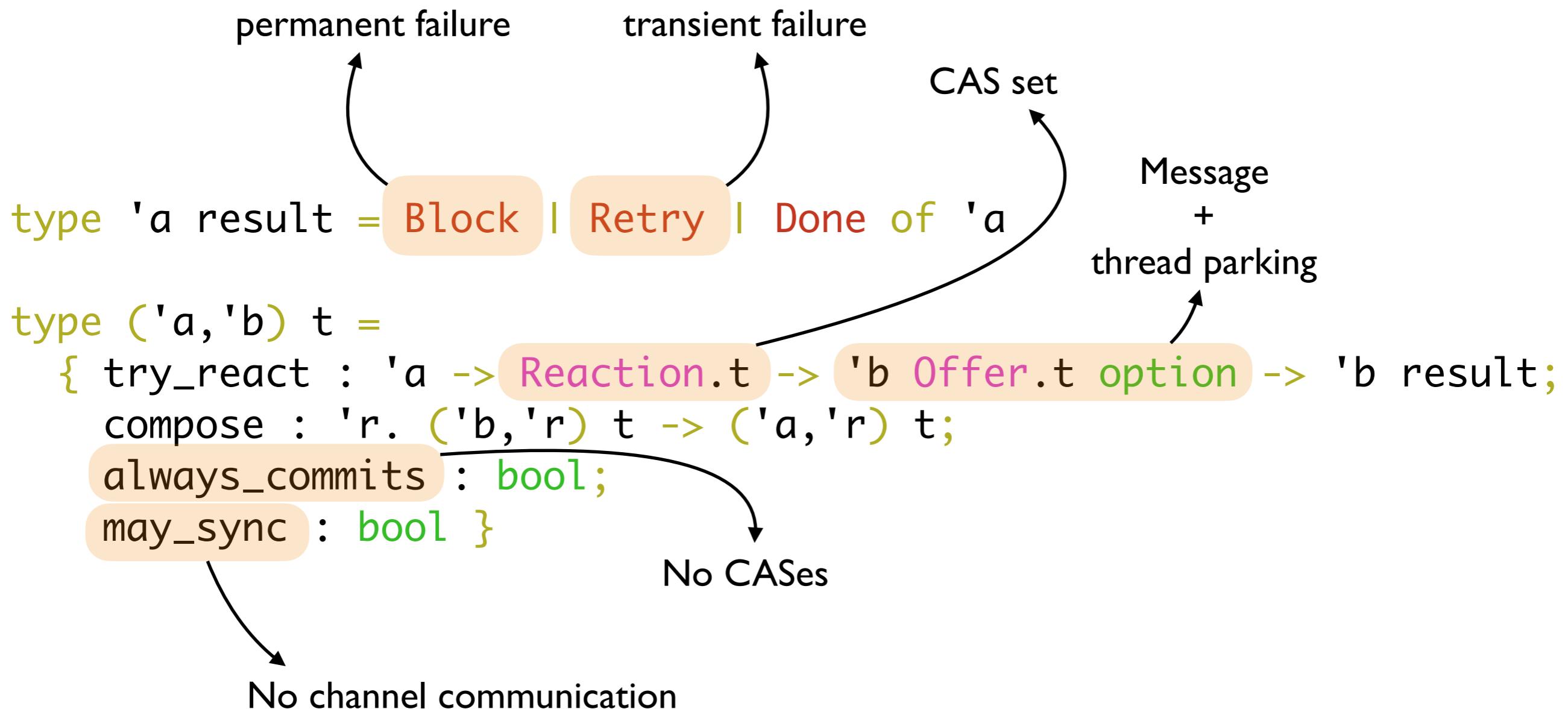
$$P \& T = T$$

$$T \& P = T$$

# Trouble with k-CAS

- Most processors do not support k-CAS
- Implemented as a multi-phase protocol
  1. Sort refs
  2. Lock refs in order (CAS); rollback if conflicts.
  3. Commit refs
- Additional book-keeping required
  - CAS list, messages to be consumed, post-commit actions, etc.
- Common case is *just a single CAS*
  - *Identify and optimise with Arrows*

# Reagent type



```

let rec never : 'a 'b. ('a,'b) t =
{ try_react = (fun _ _ _ -> Block);
may_sync = false;
always_commits = false;
compose = fun _ -> never }

```

```

let rec constant : 'a 'b 'r. 'a -> ('a,'r) t -> ('b, 'r) t =
fun x k (* continuation *) ->
{ may_sync = k.may_sync;
always_commits = k.always_commits;
try_react = (fun _ rx o -> k.try_react x rx o);
compose = (fun next -> constant x (k.compose next)) }

```

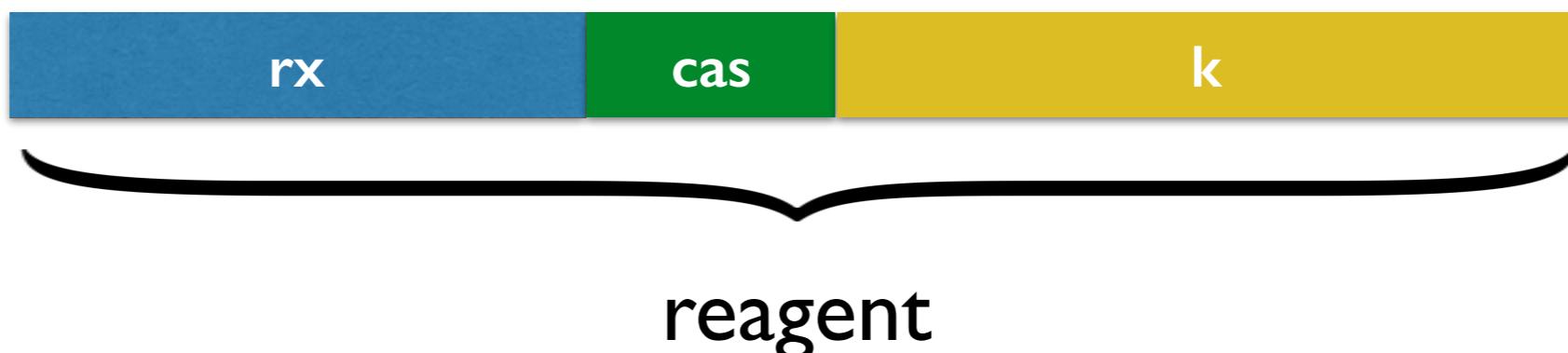
```

let rec <+> : 'a 'b 'r. ('a,'b) t -> ('a,'b) t -> ('a,'b) t =
fun r1 r2 ->
{ always_commits = r1.always_commits && r2.always_commits;
may_sync = r1.may_sync || r2.may_sync;
...

```

# Specialising k-CAS

```
let rec cas r ~expect ~update k =
  let try_react () rx o =
    if Reaction.has_no_cas rx &&
       k.always_commits then
      if CAS.cas r.data expect update then
        (k.try_react () rx o) (* Will succeed! *)
      else Retry
    else
      (* slow path with bookkeeping *)
in
  ...
```



# Optimising Transient Failures

```
let rec without_offer pause r v =
  match r.try_react v Reaction.empty None with
  | Done res -> res
  | Retry ->
    ( pause ();
      if r.may_sync
      then with_offer pause r v
      else without_offer pause r v)
  | Block -> with_offer pause r v

let run r v =
  let b = Backoff.create () in
  let pause () = Backoff.once b in
  without_offer pause r v
```