Topics in Concurrency

Lecture 7

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27 February 2015

CTL: Computation tree logic

A logic based on paths

$$A ::= At \mid A_0 \wedge A_1 \mid A_0 \vee A_1 \mid \neg A \mid T \mid F \mid$$

EX $A \mid EG A \mid E[A_0 \cup A_1]$

A path from state s is a maximal sequence of states

$$\pi = (\pi_0, \pi_1, \ldots, \pi_i \ldots)$$

such that $s = \pi_0$ and $\pi_i \to \pi_{i+1}$ for all i.

$$s \models \mathsf{EX} \ A$$
 iff Exists a path from s along which the neXt state satisfies A

$$s \models \mathsf{EG}\ A$$
 iff Exists a path from s along which Globally each state satisfies A

$$s \models E[A \cup B]$$
 iff Exists a path from s along which A holds Until B holds

Derived assertions

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AX B \equiv \neg EX \neg B
EF B \equiv E[T \cup B]
AG B \equiv \neg EF \neg B
AF B \equiv \neg EG \neg B
A[B \cup C] \equiv \neg E[\neg C \cup \neg B \land \neg C] \land \neg EG \neg C
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The *U*ntil operator is strict

From CTL to $\boldsymbol{\mu}$

Want a modal- μ assertion equivalent to EG A.

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Begin by writing a fixed point equation:

$$X = \varphi(X)$$
 where $\varphi(X) = A \wedge ([-]F \vee \langle - \rangle X)$

Least or greatest fixed point? Consider:

$$A \longrightarrow A \longrightarrow A$$

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$$\begin{array}{ccc}
A & & \mu X.A \wedge ([-]F \vee \langle - \rangle X) = \emptyset \\
s & & t
\end{array}$$

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Alternatively, consider the approximants for finite-state systems.

A translation into modal- μ

$$\begin{array}{rcl} \mathsf{EX} \ a & \equiv & \langle - \rangle A \\ \mathsf{EG} \ a & \equiv & \nu Y.A \wedge ([-]F \vee \langle - \rangle Y) \\ \mathsf{E}[a \cup b] & \equiv & \mu Z.B \vee (A \wedge \langle - \rangle Z) \end{array}$$

Based on this, we get a translation of CTL into the modal- μ calculus.

Proposition

$$s \models \nu Y.A \land ([-]F \lor \langle - \rangle Y)$$

in a finite-state transition system iff there exists a path π from s such that $\pi_i \models A$ for all i.

Proof:

Take
$$\varphi(Y) \stackrel{\text{def}}{=} A \wedge ([-]F \vee \langle - \rangle Y)$$
.

$$\nu Y.\varphi(Y) = \bigcap_{n \in \omega} \varphi^n(T)$$
 where $T \supseteq \varphi(T) \supseteq \cdots$

since φ is monotonic and \bigcap -continuous due to the set of states being finite

By induction, for $n \ge 1$

- $s \models \varphi^n(T)$ iff there is a path of length $\leq n$ from s along which all states satisfy A and the final state has no outward transition
 - or there is a path of length *n* from *s* along which all states satisfy *A* and the final state has some outward transition

Assuming the number of states is k, we have

$$\varphi^k(T) = \varphi^{k+1}(T)$$

and hence
$$\nu Y.\varphi(Y) = \varphi^k(T)$$
.

$$s \models \nu Y. \varphi(Y)$$
 iff $s \models \varphi^k(T)$

or there exists a necessarily looping A path of length k from s

iff there exists a maxmial A path of length $\leq k$ from s

Model checking modal- μ

Assume processes are finite-state

- Brute force (+ optimizations) computes each fixed point
- Local model checking [Larsen, Stirling and Walker, Winskel]

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$$p \in \nu X. \varphi(X) \iff p \in \varphi(\nu X. \qquad \varphi(X))$$

Model checking modal- μ

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 Reduction Lemma

$$p \in \nu X.\varphi(X) \iff p \in \varphi(\nu X.\{p\} \vee \varphi(X))$$

Modal- μ for model checking

Extend the syntax with defined basic assertions and adapt the fixed point operator:

Semantics identifies assertions with subsets of states:

- *U* is an arbitrary subset of states
- T = S
- F = Ø
- $\neg A = S \setminus A$
- $A \wedge B = A \cap B$
- $A \vee B = A \cup B$
- $\langle a \rangle A = \{ p \in \mathcal{S} \mid \exists q. p \xrightarrow{a} q \land q \in A \}$
- $\langle \rangle A = \{ p \in \mathcal{S} \mid \exists q, a.p \xrightarrow{a} q \land q \in A \}$
- $\nu X\{p_1,\ldots,p_n\}.A=\bigcup\{U\subseteq S\mid U\subseteq A[U/X]\}$

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$$A ::= U \mid T \mid F \mid \neg A \mid A \land B \mid A \lor B \mid \langle a \rangle A \mid \langle - \rangle A \mid \nu X \{p_1, \dots, p_n\}.A$$

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As before, $\mu X.A \equiv \neg \nu X. \neg A[\neg X/X]$ and now

$$\nu X.A = \nu X\{\}.A$$

The reduction lemma

Lemma

Let
$$\varphi: \mathcal{P}(\mathcal{S}) \to \mathcal{P}(\mathcal{S})$$
 be monotonic. For all $U \subseteq \mathcal{S}$,

$$\longleftrightarrow U \subseteq \nu X. \varphi(X) \\ \longleftrightarrow U \subseteq \varphi(\nu X. (U \cup \varphi(X)))$$

In particular,

$$p \in \nu X. \varphi(X)$$

$$\iff p \in \varphi(\nu X. (\{p\} \cup \varphi(X))).$$

Model checking algorithm

Given a transition system and a set of basic assertions $\{U, V, \ldots\}$:

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\begin{array}{lll} p \vdash U & \longrightarrow & \mathrm{true} & \mathrm{if} \ p \in U \\ p \vdash U & \longrightarrow & \mathrm{false} & \mathrm{if} \ p \notin U \\ p \vdash T & \longrightarrow & \mathrm{true} \\ p \vdash F & \longrightarrow & \mathrm{false} \\ p \vdash \neg B & \longrightarrow & \mathrm{not}(p \vdash B) \\ p \vdash A \land B & \longrightarrow & p \vdash A \ \mathrm{and} \ p \vdash B \\ p \vdash A \lor B & \longrightarrow & p \vdash A \ \mathrm{or} \ p \vdash B \\ p \vdash \langle a \rangle B & \longrightarrow & q_1 \vdash B \ \mathrm{or} \ \ldots \ \mathrm{or} \ q_n \vdash B \\ p \vdash \nu X\{\vec{r}\}.B & \longrightarrow & \mathrm{true} & \mathrm{if} \ p \in \{\vec{r}\} \\ p \vdash \nu X\{\vec{r}\}.B & \longrightarrow & p \vdash B[\nu X\{p,\vec{r}\}.B/X] & \mathrm{if} \ p \notin \{\vec{r}\} \end{array}
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