



# Alias and Points-to Analysis

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## Lecture 13a[may be updated for 2012]



## Points-to analysis, parallelisation etc.

Consider an MP3 player containing code:

```
for (channel = 0; channel < 2; channel++)
    process_audio(channel);
```

or even

```
process_audio_left();
process_audio_right();
```

Can we run these two calls in parallel?



## Points-to analysis, parallelisation etc. (2)

Multi-core CPU: *probably* want to run these two calls in parallel.

```
#pragma omp parallel for // OpenMP
for (channel = 0; channel < 2; channel++)
    process_audio(channel);
```

or

```
spawn process_audio_left(); // e.g. Cilk, X10
process_audio_right();
sync;
```

or

```
par { process_audio_left() // language primitives
      ||| process_audio_right()
    }
```

Question: when is this transformation *safe*?



## Can we know what locations are read/written?

Basic parallelisation criterion: parallelise only if neither call writes to a memory location read or written by the other.

So, we want to know (at compile time) what locations a procedure might write to at run time. Sounds hard!



## Can we know what locations are read/written?

Non-address-taken variables are easy, but consider:

```
for (i = 0; i < n; i++) v[i]->field++;
```

Can this be parallelised? Depends on knowing that each cell of  $v[]$  points to a distinct object (i.e. there is no *aliasing*).

So, given a pointer value, we are interested in finding a *finite description* of what locations it *might* point to – or, given a procedure, a description of what locations it might read from or write to.

If two such descriptions have empty intersection then we can parallelise.



## Can we know what locations are read/written?

For simple variables, even including address-taken variables, this is moderately easy (we have done similar things in “ambiguous *ref*” in LVA and “ambiguous *kill*” in Avail). Multi-level pointers, e.g.

```
int a, *b, **c;
b=&a;
c=&b;
```

make the problem more complicated here.

What about **new**, especially in a loop?

Coarse solution: treat all allocations done at a single program point as being aliased (as if they all return a pointer to a single piece of memory).



## Andersen’s points-to analysis

An  $O(n^3)$  analysis – underlying problem same as 0-CFA.

We’ll only look at the intra-procedural case.

First assume program has been re-written so that all *pointer-typed* operations are of the form

- $x := \mathbf{new}_\ell$   $\ell$  is a program point (label)
- $x := \mathbf{null}$  optional, can see as variant of **new**
- $x := \&y$  only in C-like languages, also like **new** variant
- $x := y$  copy
- $x := *y$  field access of object
- $*x := y$  field access of object

Note: no pointer arithmetic (or pointer-returning functions here). Also fields conflated (but ‘field-sensitive’ is possible too).



## Andersen’s points-to analysis (2)

Get set of abstract values  $V = \text{Var} \cup \{\mathbf{new}_\ell \mid \ell \in \text{Prog}\} \cup \{\mathbf{null}\}$ .

Note that this means that all **new** allocations at program point  $\ell$  are conflated – makes things finite but loses precision.

The *points-to* relation is seen as a function  $pt : V \rightarrow \mathcal{P}(V)$ . While we might imagine having a different *pt* at each program point (like liveness) Andersen keeps one per function.

Have type-like constraints (one per source-level assignment)

$$\frac{}{\vdash x := \&y : y \in pt(x)} \qquad \frac{}{\vdash x := y : pt(y) \subseteq pt(x)}$$

$$\frac{z \in pt(y)}{\vdash x := *y : pt(z) \subseteq pt(x)} \qquad \frac{z \in pt(x)}{\vdash *x := y : pt(y) \subseteq pt(z)}$$

$x := \mathbf{new}_\ell$  and  $x := \mathbf{null}$  are treated identically to  $x := \&y$ .

### Andersen's points-to analysis (3)



Alternatively, the same formulae presented in the style of 0-CFA (this is only stylistic, it's the same constraint system, but there are no obvious deep connections between 0-CFA and Andersen's points-to):

- for command  $x := \&y$  emit constraint  $pt(x) \supseteq \{y\}$
- for command  $x := y$  emit constraint  $pt(x) \supseteq pt(y)$
- for command  $x := *y$  emit constraint implication  $pt(y) \supseteq \{z\} \implies pt(x) \supseteq pt(z)$
- for command  $*x := y$  emit constraint implication  $pt(x) \supseteq \{z\} \implies pt(z) \supseteq pt(y)$

### Andersen's points-to analysis (4)



Flow-insensitive – we only look at the assignments, not in which order they occur. Faster but less precise – syntax-directed rules all use the same set-like combination of constraints ( $\cup$  here).

Flow-insensitive means property inference rules are essentially of the form:

$$\begin{aligned} (\text{ASS}) & \frac{}{\vdash x := e : \dots} & (\text{SEQ}) & \frac{\vdash C : S \quad \vdash C' : S'}{\vdash C; C' : S \cup S'} \\ (\text{COND}) & \frac{\vdash C : S \quad \vdash C' : S'}{\vdash \text{if } e \text{ then } C \text{ else } C' : S \cup S'} \\ (\text{WHILE}) & \frac{\vdash C : S}{\vdash \text{while } e \text{ do } C : S} \end{aligned}$$

### Andersen: example



[Example taken from notes by Michelle Mills Strout of Colorado State University]

command	constraint	solution
$a = \&b;$	$pt(a) \supseteq \{b\}$	$pt(a) = \{b, d\}$
$c = a;$	$pt(c) \supseteq pt(a)$	$pt(c) = \{b, d\}$
$a = \&d;$	$pt(a) \supseteq \{d\}$	$pt(b) = pt(d) = \{ \}$
$e = a;$	$pt(e) \supseteq pt(a)$	$pt(e) = \{b, d\}$

Note that a flow-sensitive algorithm would instead give  $pt(c) = \{b\}$  and  $pt(e) = \{d\}$  (assuming the statements appear in the above order in a single basic block).

### Andersen: example (2)



command	constraint	solution
$a = \&b;$	$pt(a) \supseteq \{b\}$	$pt(a) = \{b, d\}$
$c = \&d;$	$pt(c) \supseteq \{d\}$	$pt(c) = \{d\}$
$e = \&a;$	$pt(e) \supseteq \{a\}$	$pt(e) = \{a\}$
$f = a;$	$pt(f) \supseteq pt(a)$	$pt(f) = \{b, d\}$
$*e = c;$	$pt(e) \supseteq \{z\} \implies pt(z) \supseteq pt(c)$	
(generates)	$pt(a) \supseteq pt(c)$	

### Points-to analysis – some other approaches



- Steensgaard's algorithm: treat  $e := e'$  and  $e' := e$  identically. Less accurate than Andersen's algorithm but runs in almost-linear time.
- shape analysis (Sagiv, Wilhelm, Reps) – a program analysis with elements being abstract heap nodes (representing a family of real-world heap nodes) and edges between them being *must* or *may* point-to. Nodes are labelled with variables and fields which may point to them. More accurate but abstract heaps can become very large.

Coarse techniques can give poor results (especially inter-procedurally), while more sophisticated techniques can become very expensive for large programs.

### Points-to and alias analysis



"Alias analysis is undecidable in theory and intractable in practice."

It's also very discontinuous: small changes in program can produce global changes in analysis of aliasing. Potentially bad during program development.

So what can we do?

Possible answer: languages with type-like restrictions on where pointers can point to.

- Dijkstra said (effectively): spaghetti *code* is bad; so use structured programming.
- I argue elsewhere that spaghetti *data* is bad; so need language primitives to control aliasing ("structured data").