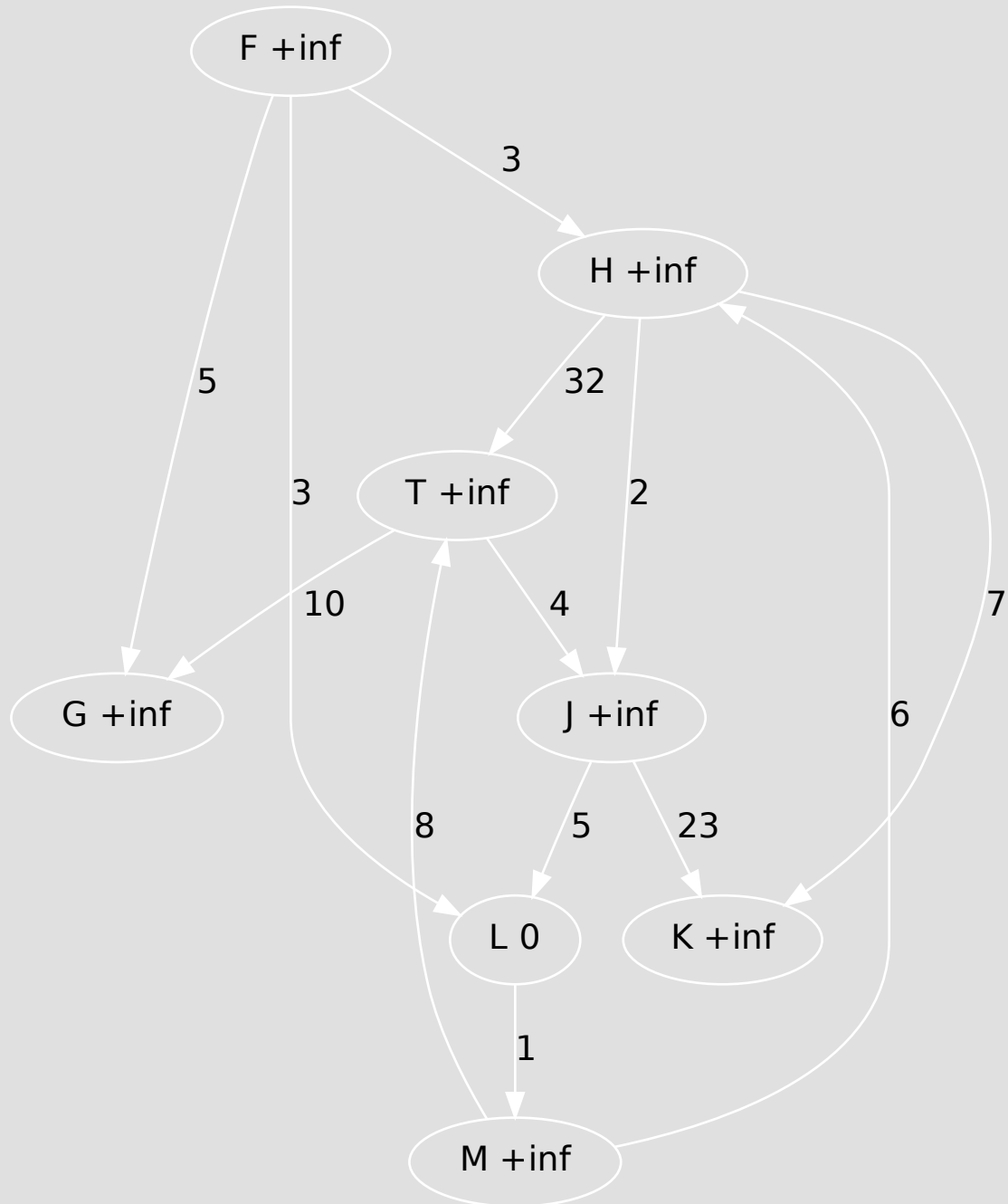


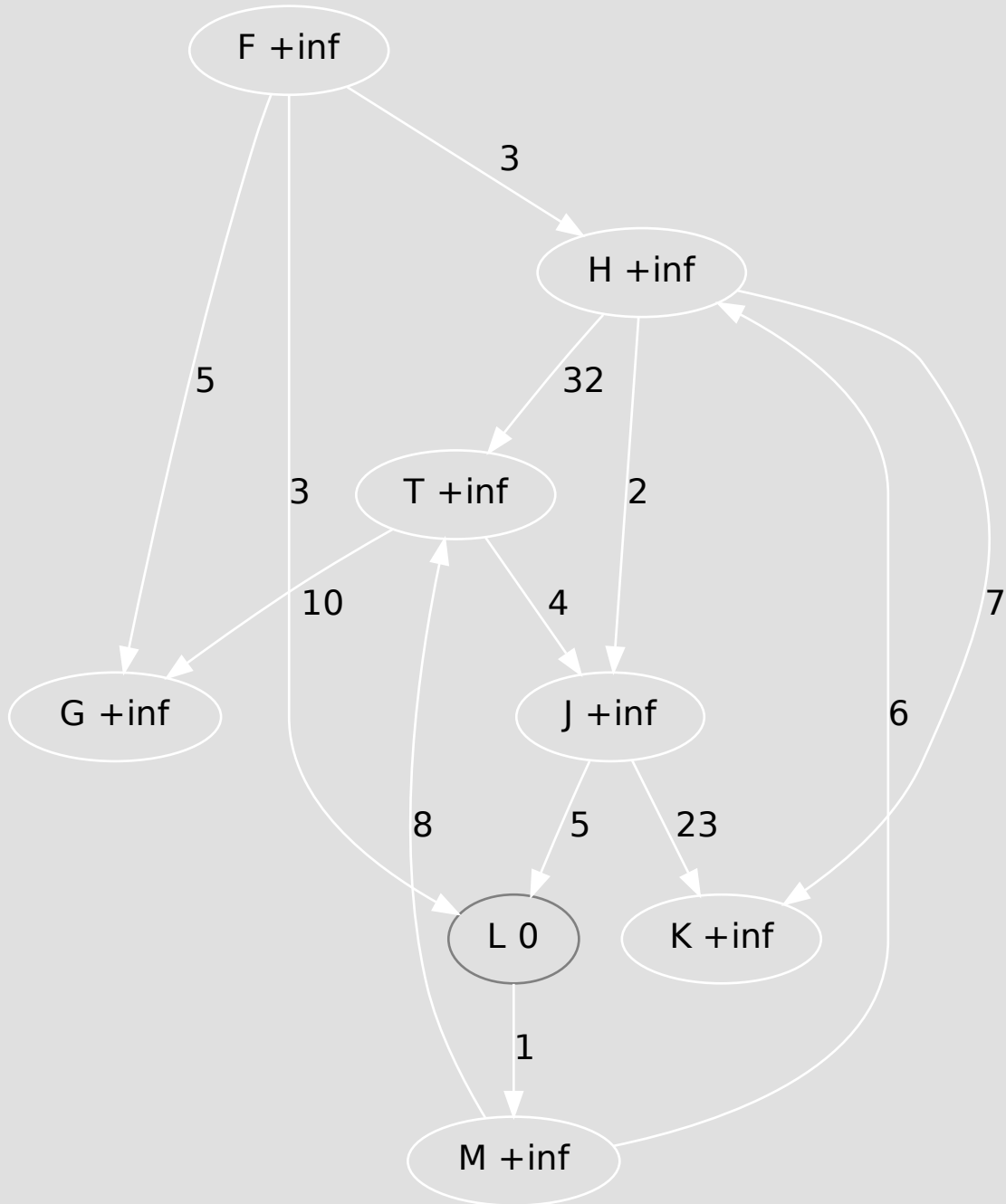
Dijkstra single-source shortest paths. Source = L.

Priority queue = [L 0, H +inf, F +inf, T +inf, J +inf, G +inf, M +inf, K +inf]

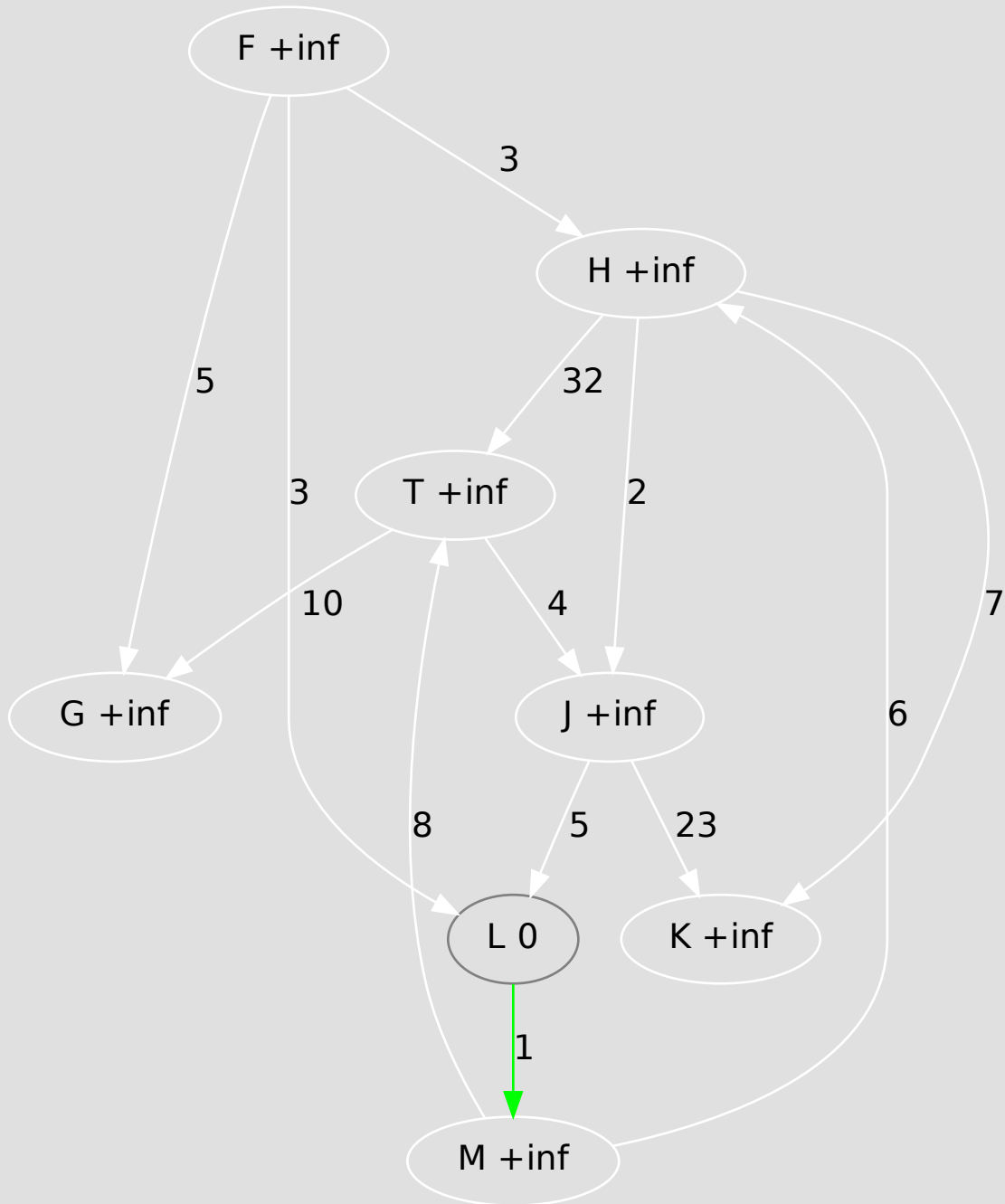


extractMin() -> L.

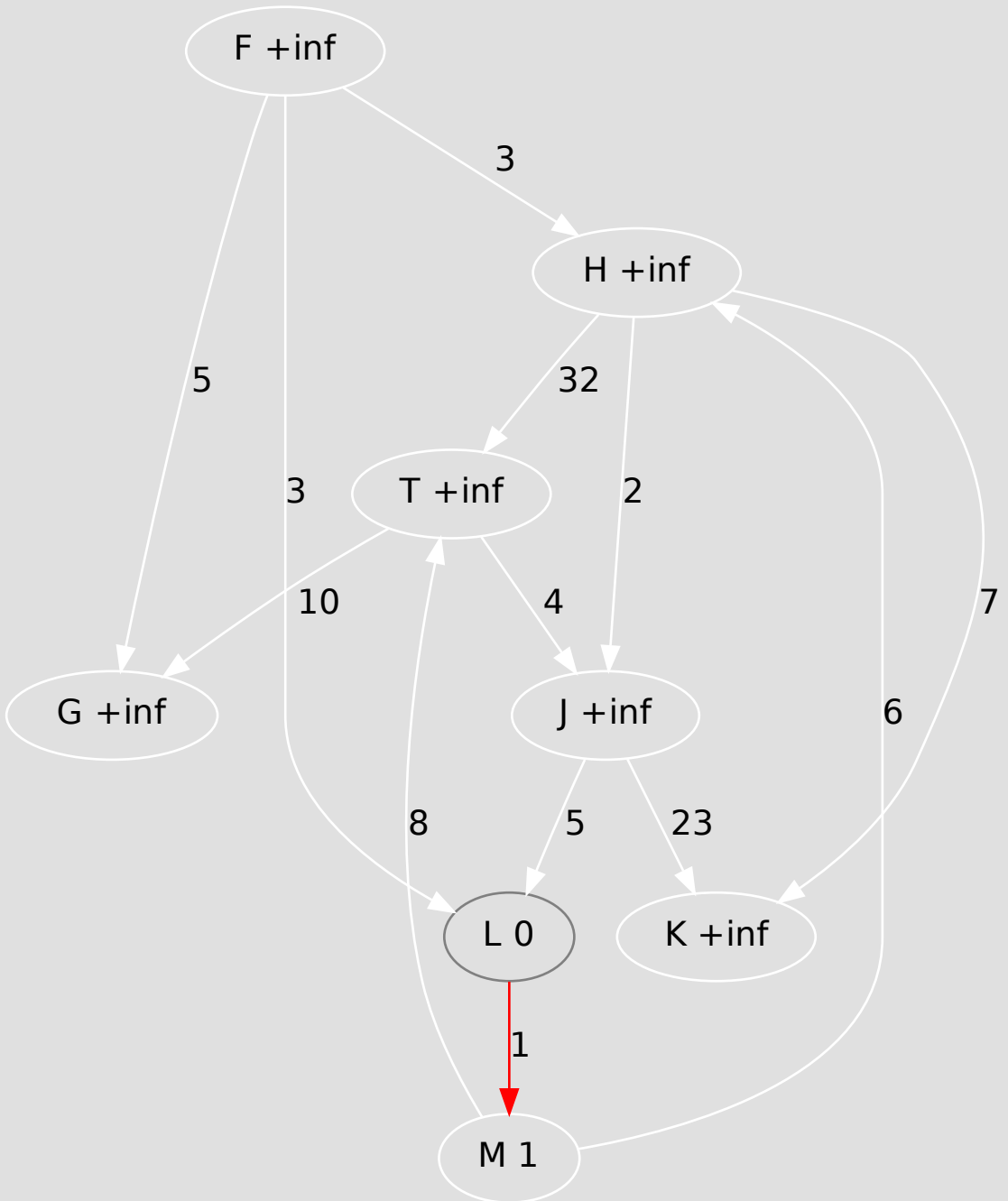
Priority queue = [H +inf, F +inf, T +inf, J +inf, G +inf, M +inf, K +inf]



Relaxing the edges from L. Considering edge (L, M), leading to M.
Priority queue = [H +inf, F +inf, T +inf, J +inf, G +inf, M +inf, K +inf]

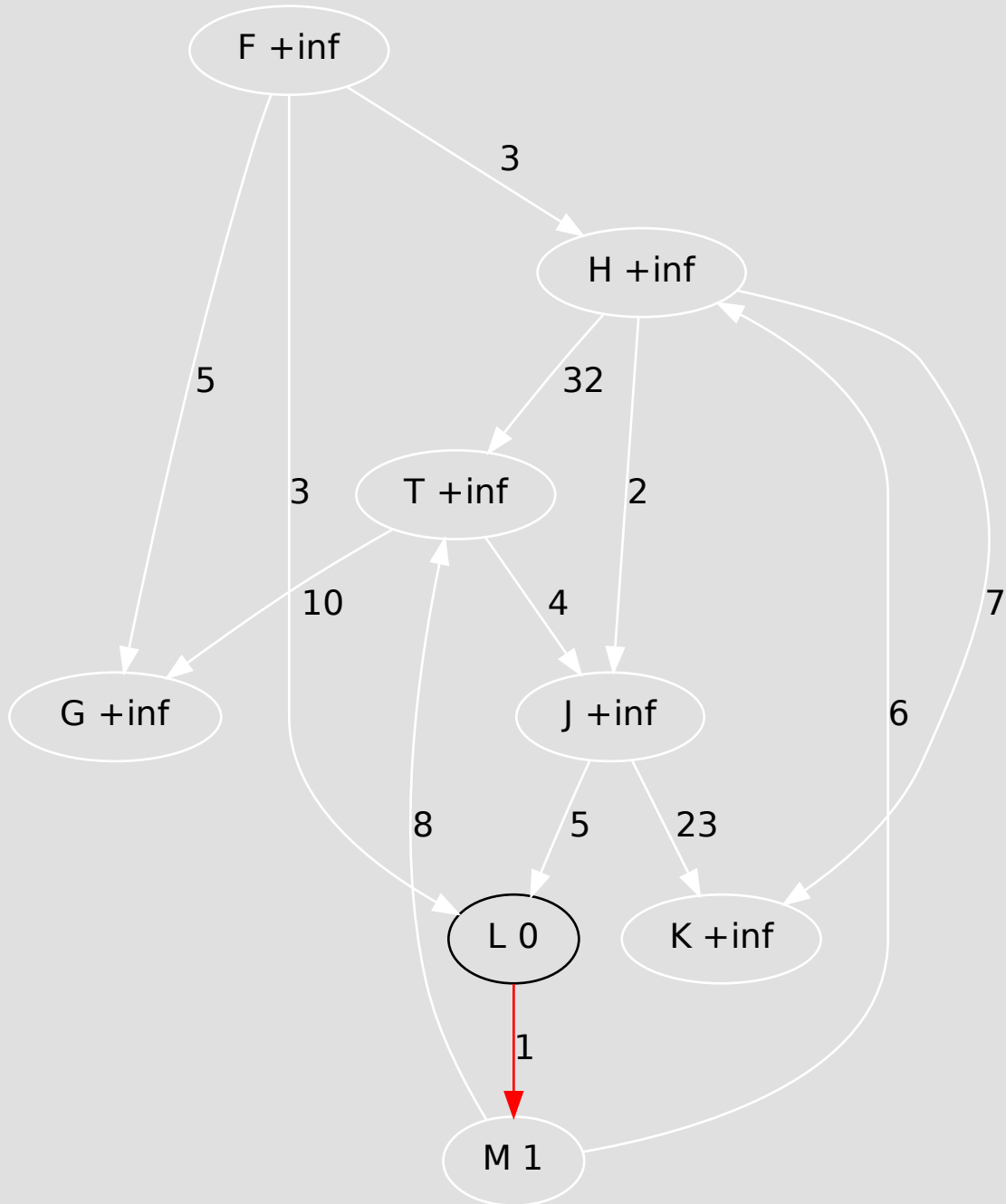


$0 + 1 < +\text{inf}$. Edge (L, M) relaxed.



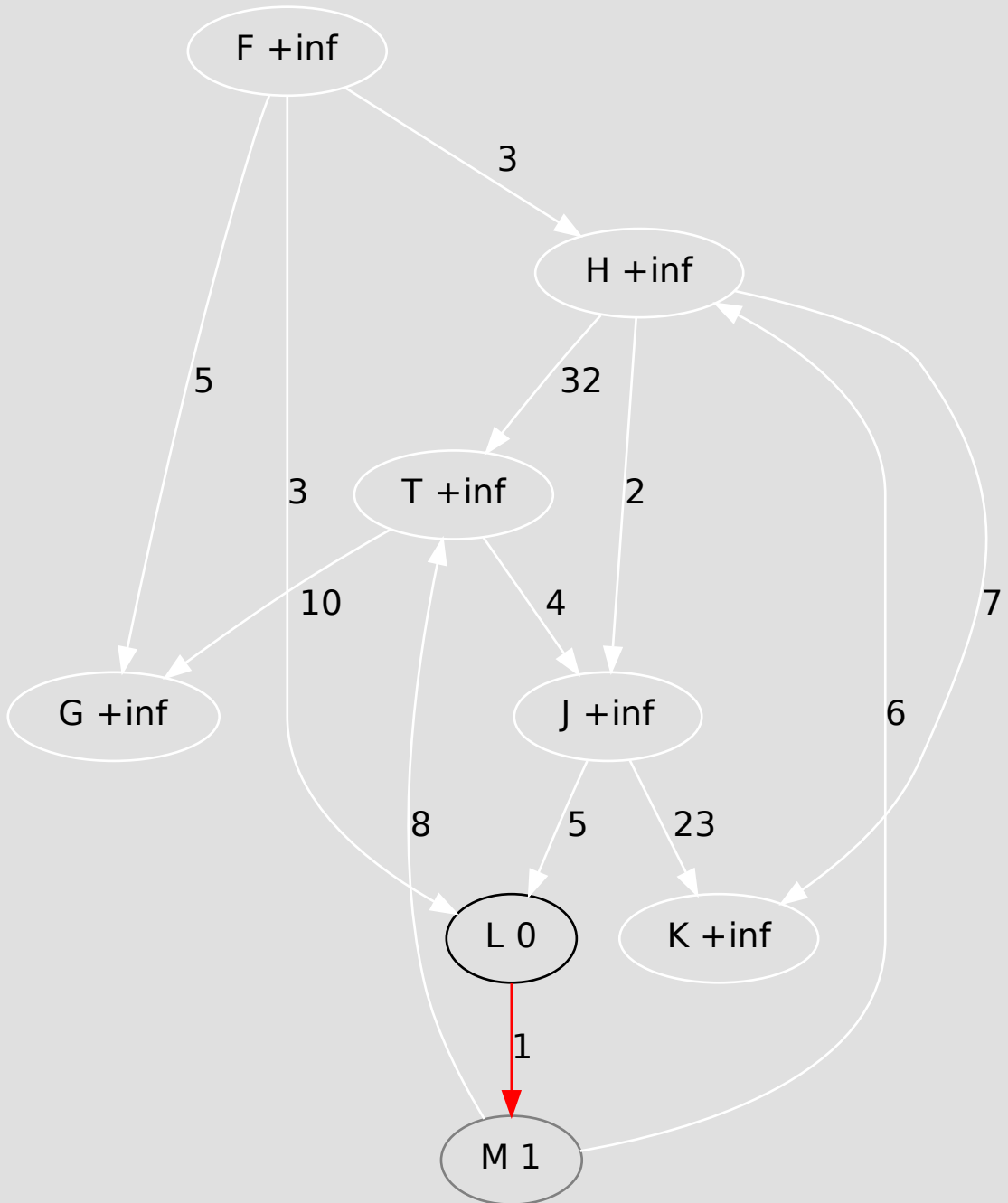
Finished with L.

Priority queue = [M 1, H +inf, F +inf, T +inf, J +inf, G +inf, K +inf]

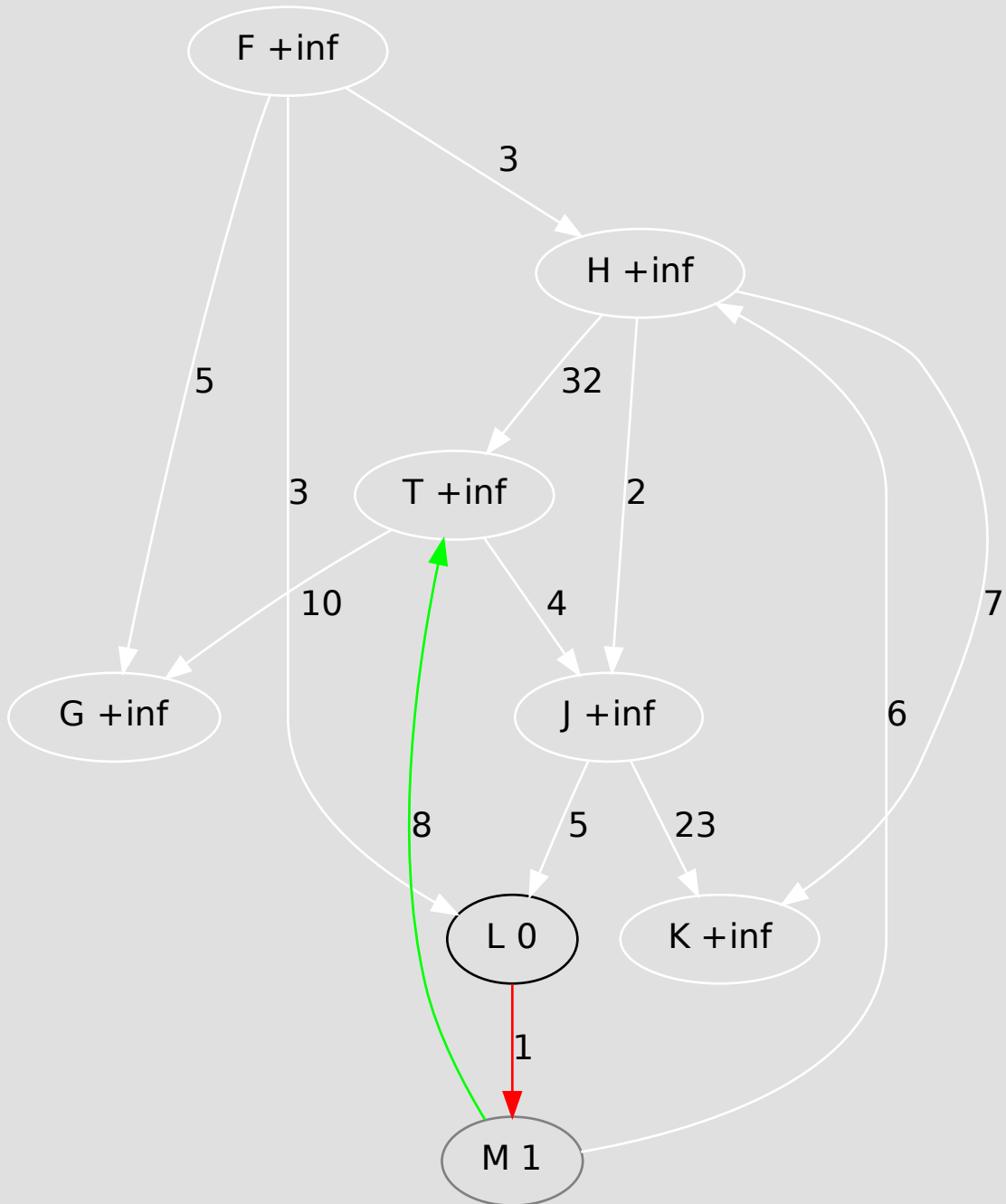


extractMin() -> M.

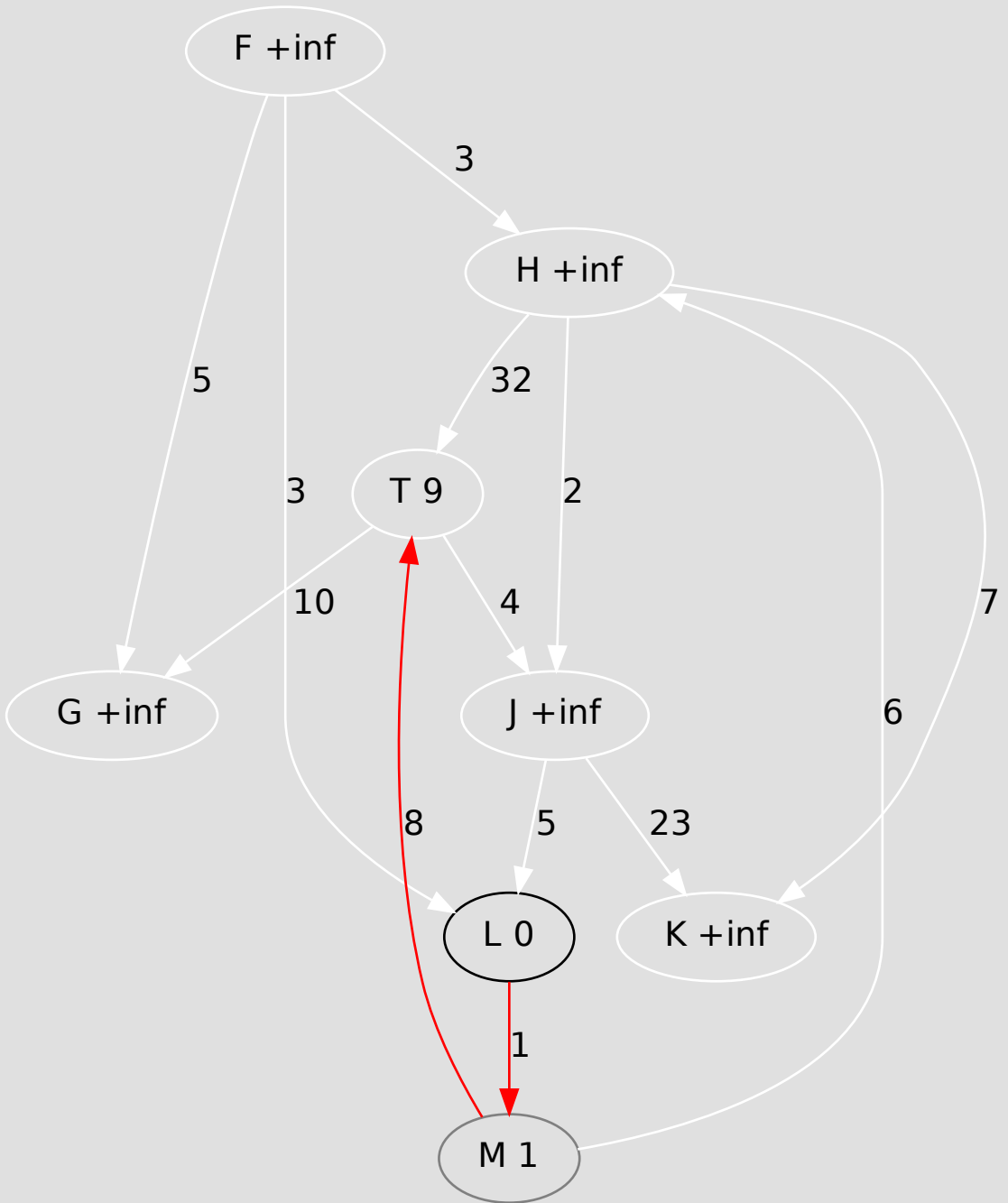
Priority queue = [H +inf, F +inf, T +inf, J +inf, G +inf, K +inf]



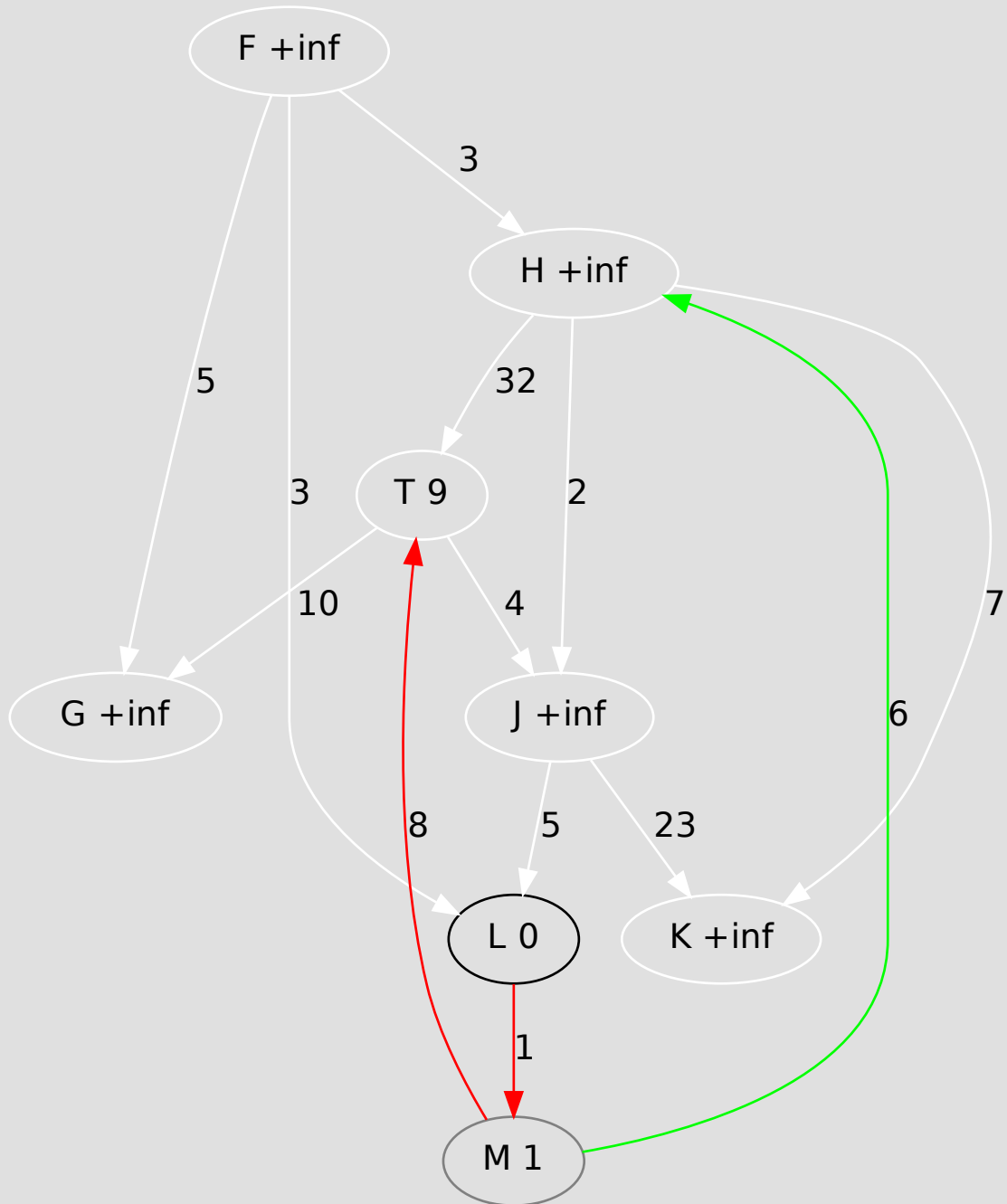
Relaxing the edges from M. Considering edge (M, T), leading to T.
Priority queue = [H +inf, F +inf, T +inf, J +inf, G +inf, K +inf]



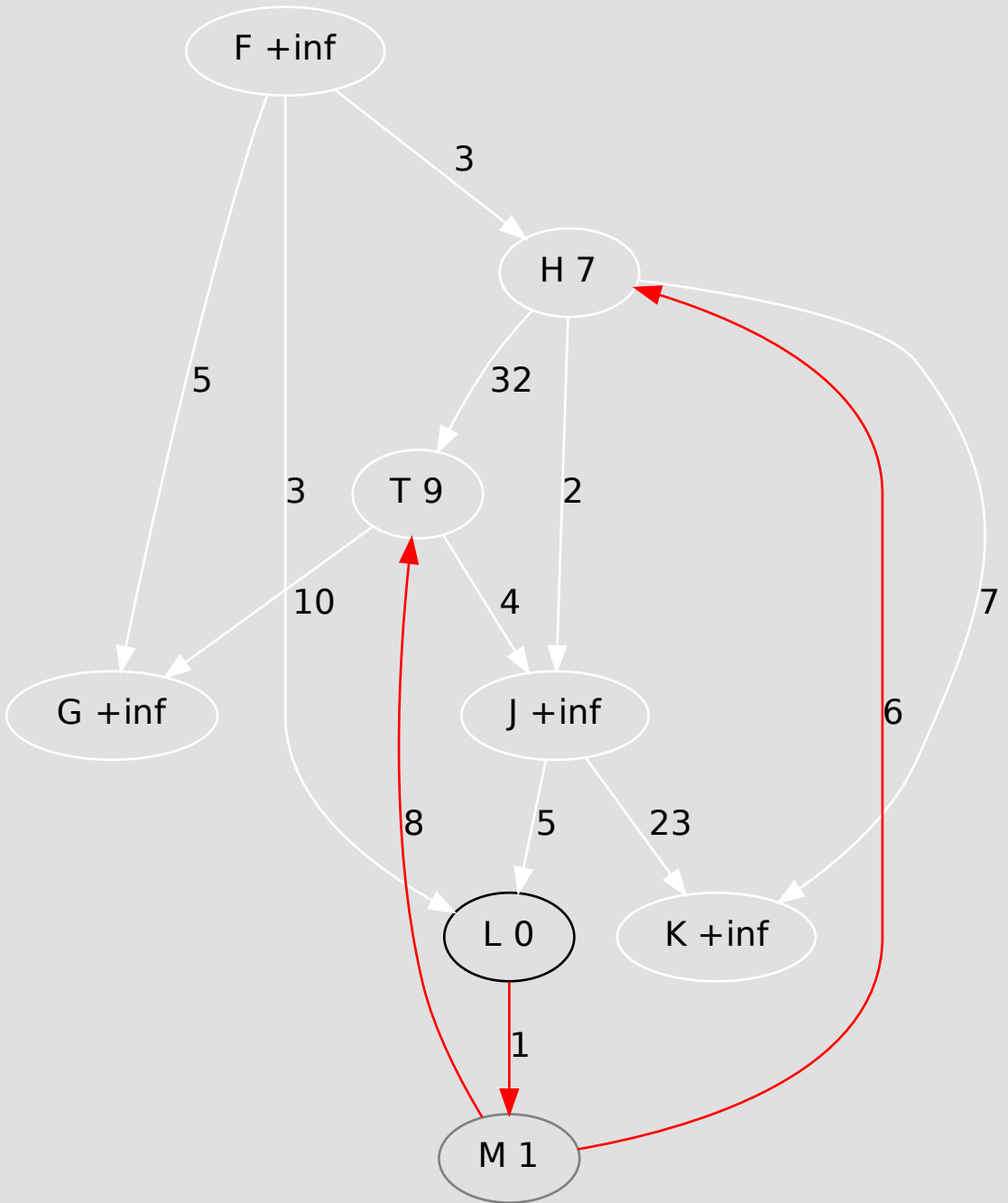
1 + 8 < +inf. Edge (M, T) relaxed.



Relaxing the edges from M. Considering edge (M, H), leading to H.
Priority queue = [T 9, H +inf, F +inf, J +inf, G +inf, K +inf]

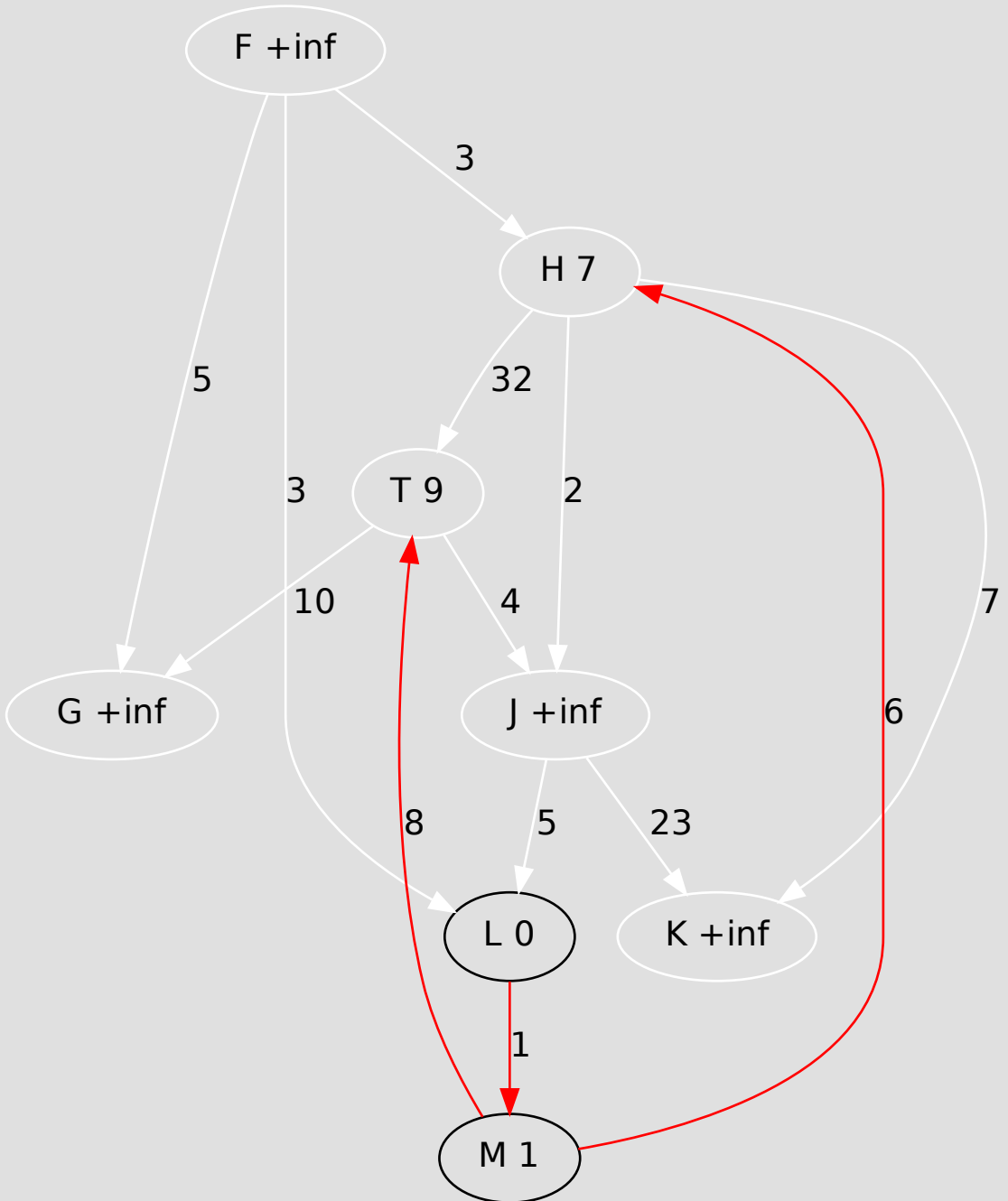


1 + 6 < +inf. Edge (M, H) relaxed.



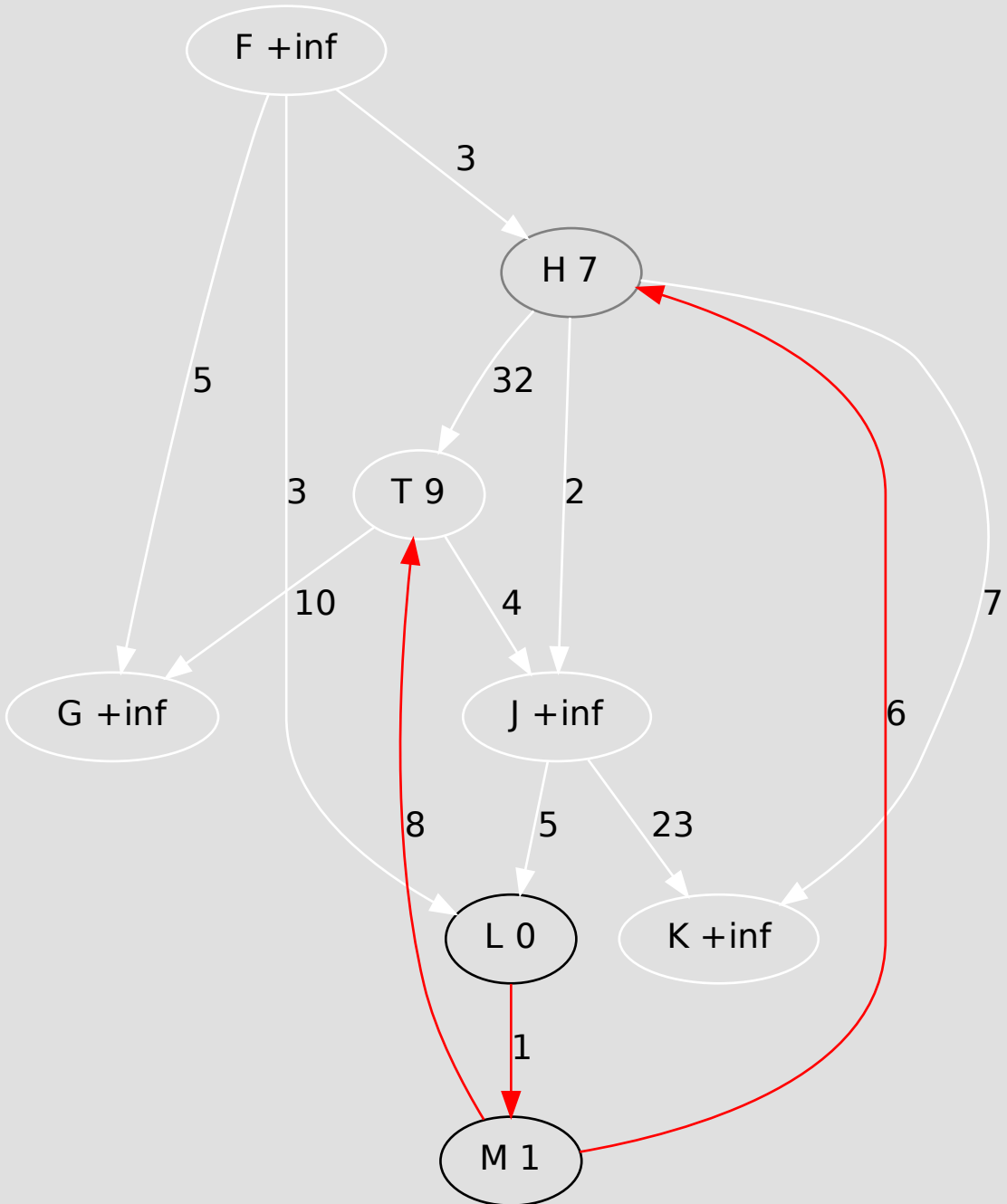
Finished with M.

Priority queue = [H 7, T 9, F +inf, J +inf, G +inf, K +inf]

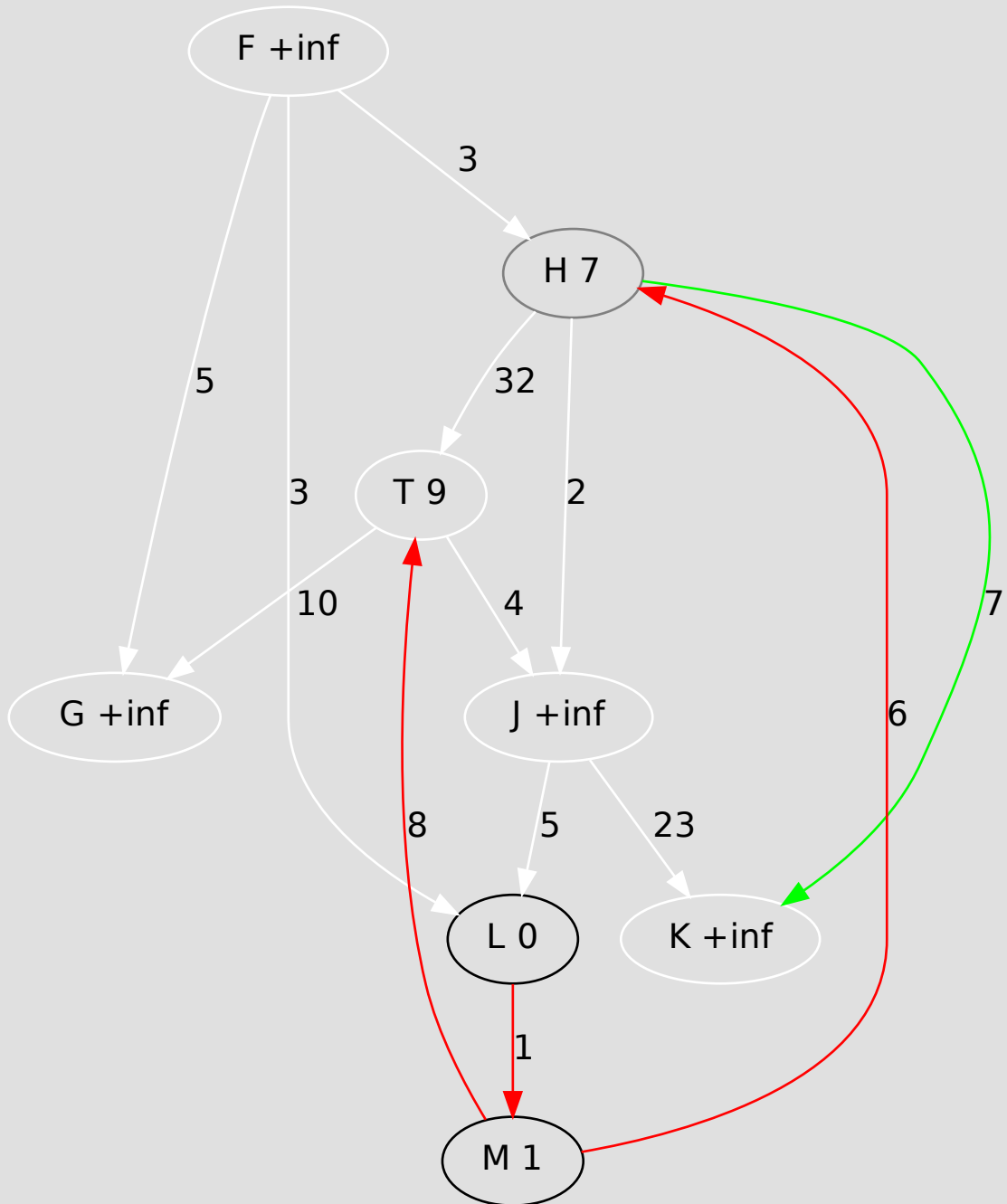


extractMin() -> H.

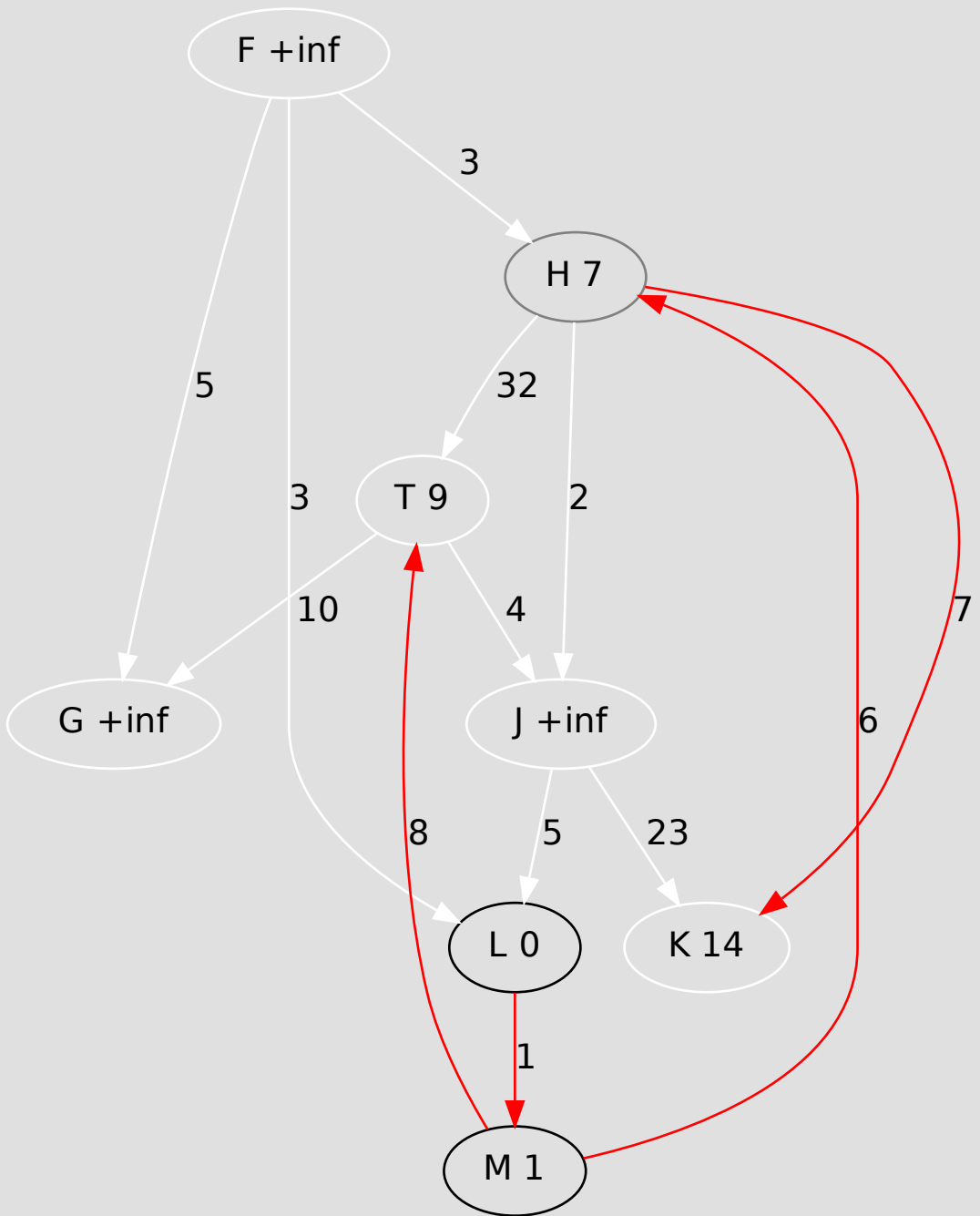
Priority queue = [T 9, F +inf, J +inf, G +inf, K +inf]



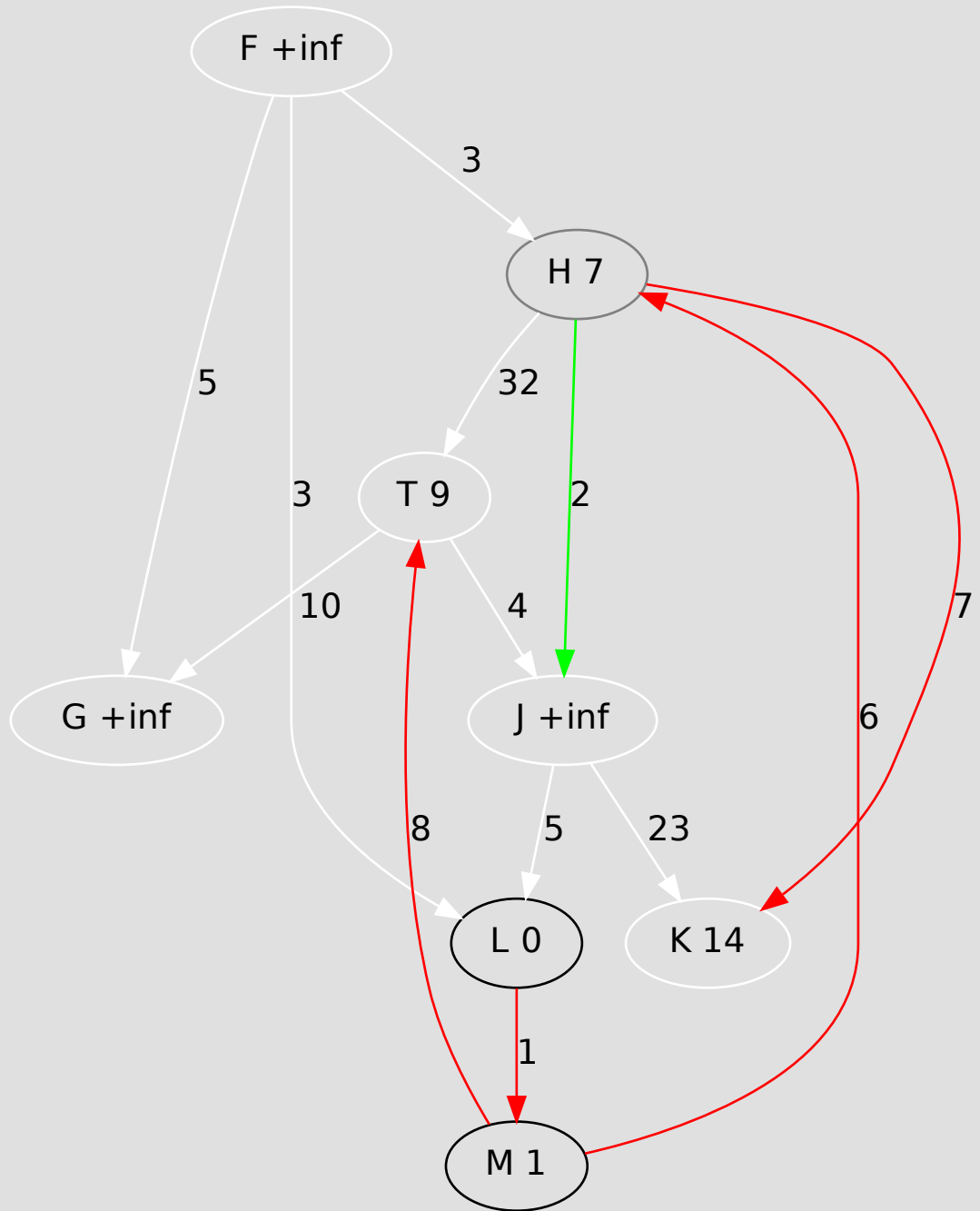
Relaxing the edges from H. Considering edge (H, K), leading to K.
Priority queue = [T 9, F +inf, J +inf, G +inf, K +inf]



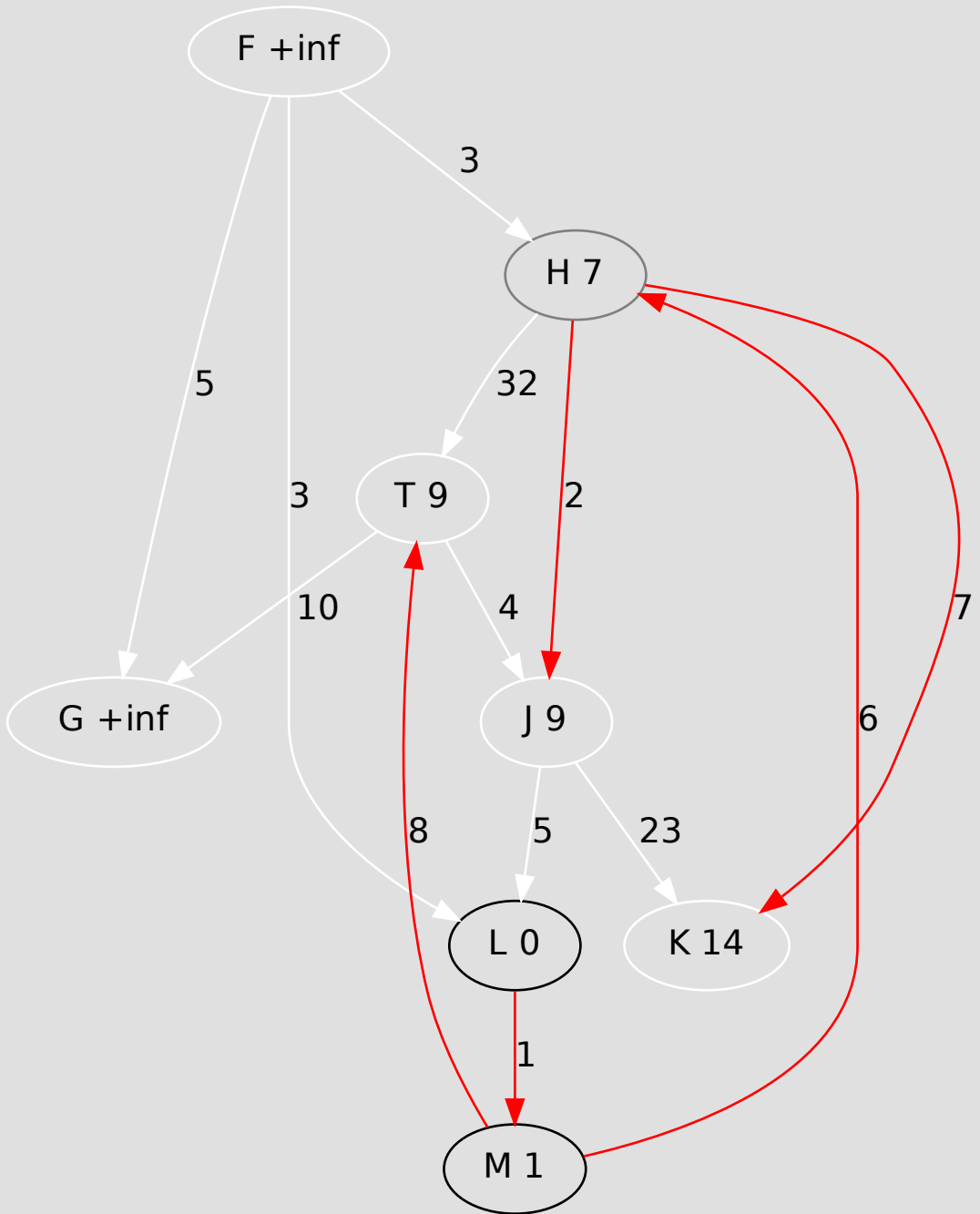
$7 + 7 < +\text{inf}$. Edge (H, K) relaxed.



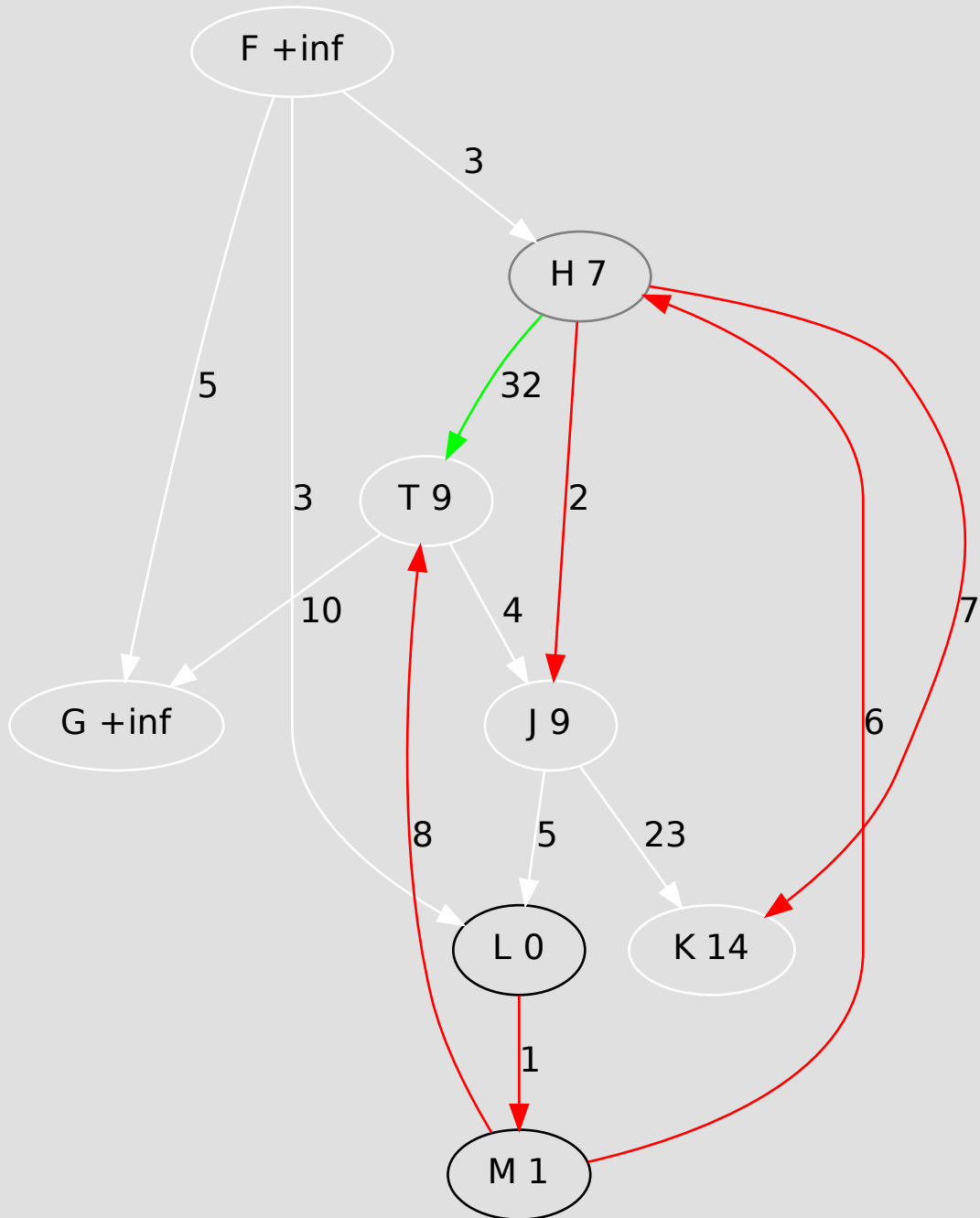
Relaxing the edges from H. Considering edge (H, J), leading to J.
Priority queue = [T 9, K 14, F +inf, J +inf, G +inf]



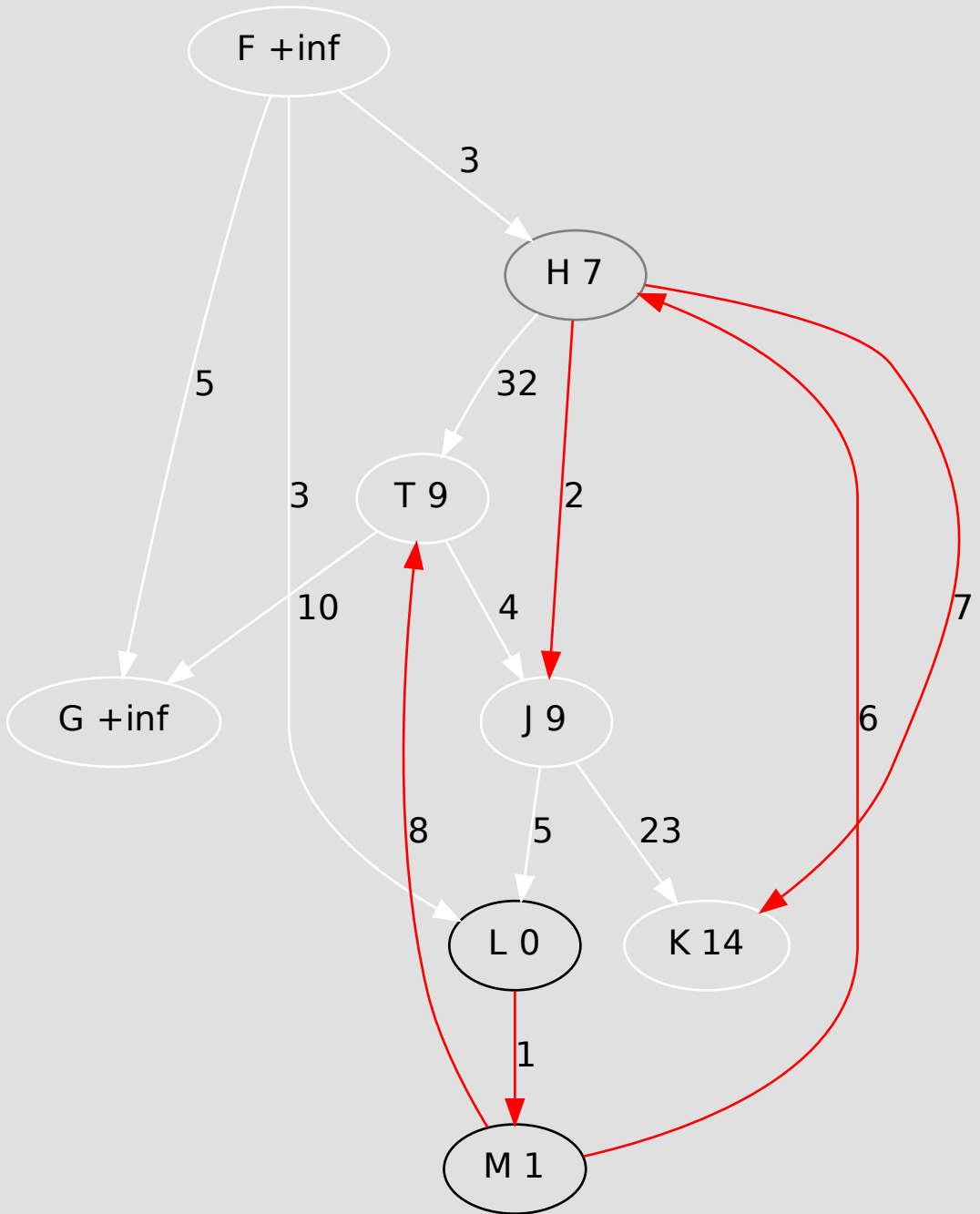
$7 + 2 < +\text{inf}$. Edge (H, J) relaxed.



Relaxing the edges from H. Considering edge (H, T), leading to T.
Priority queue = [T 9, J 9, K 14, F +inf, G +inf]

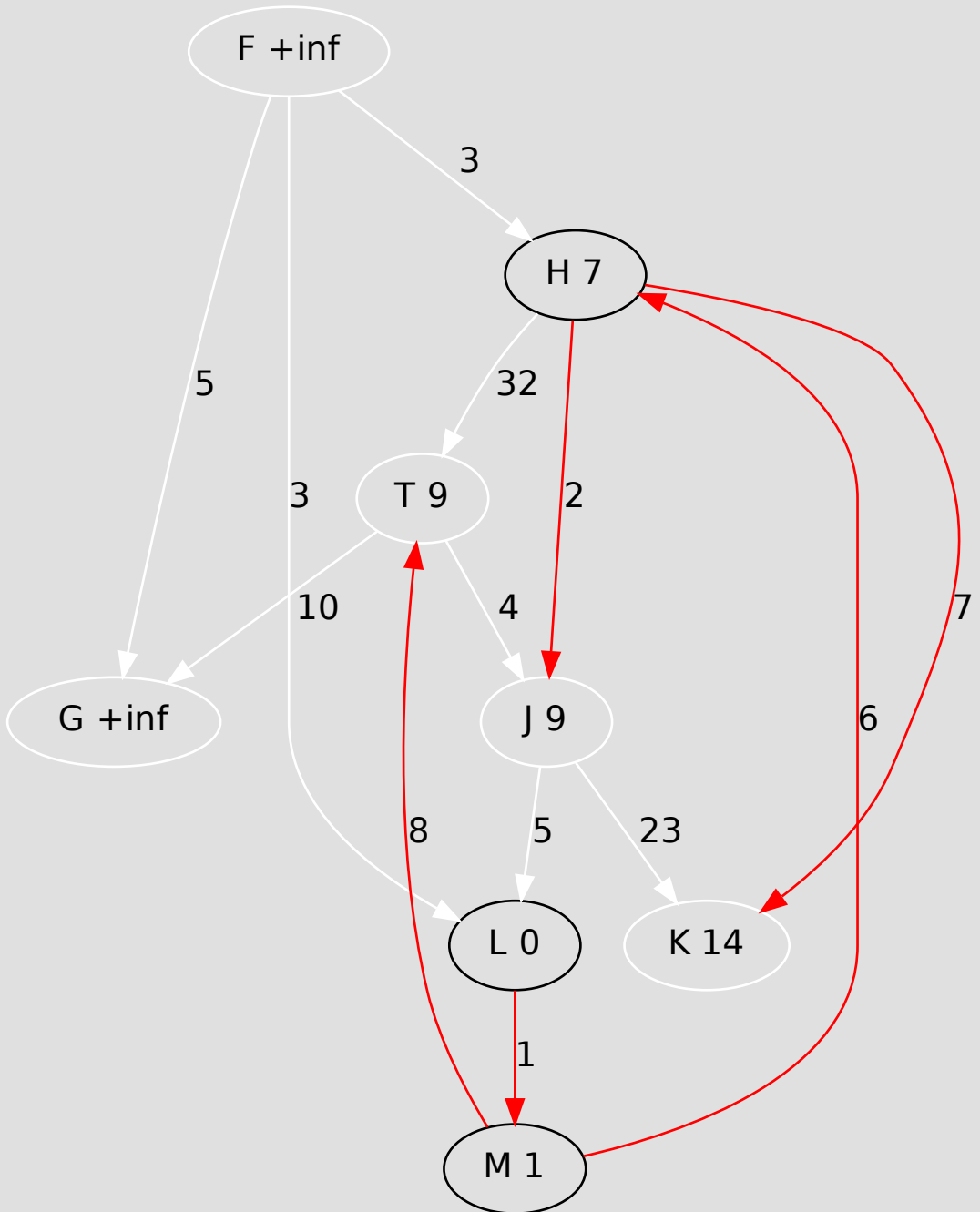


7 + 32 is not < 9. Edge (H, T) not relaxed.

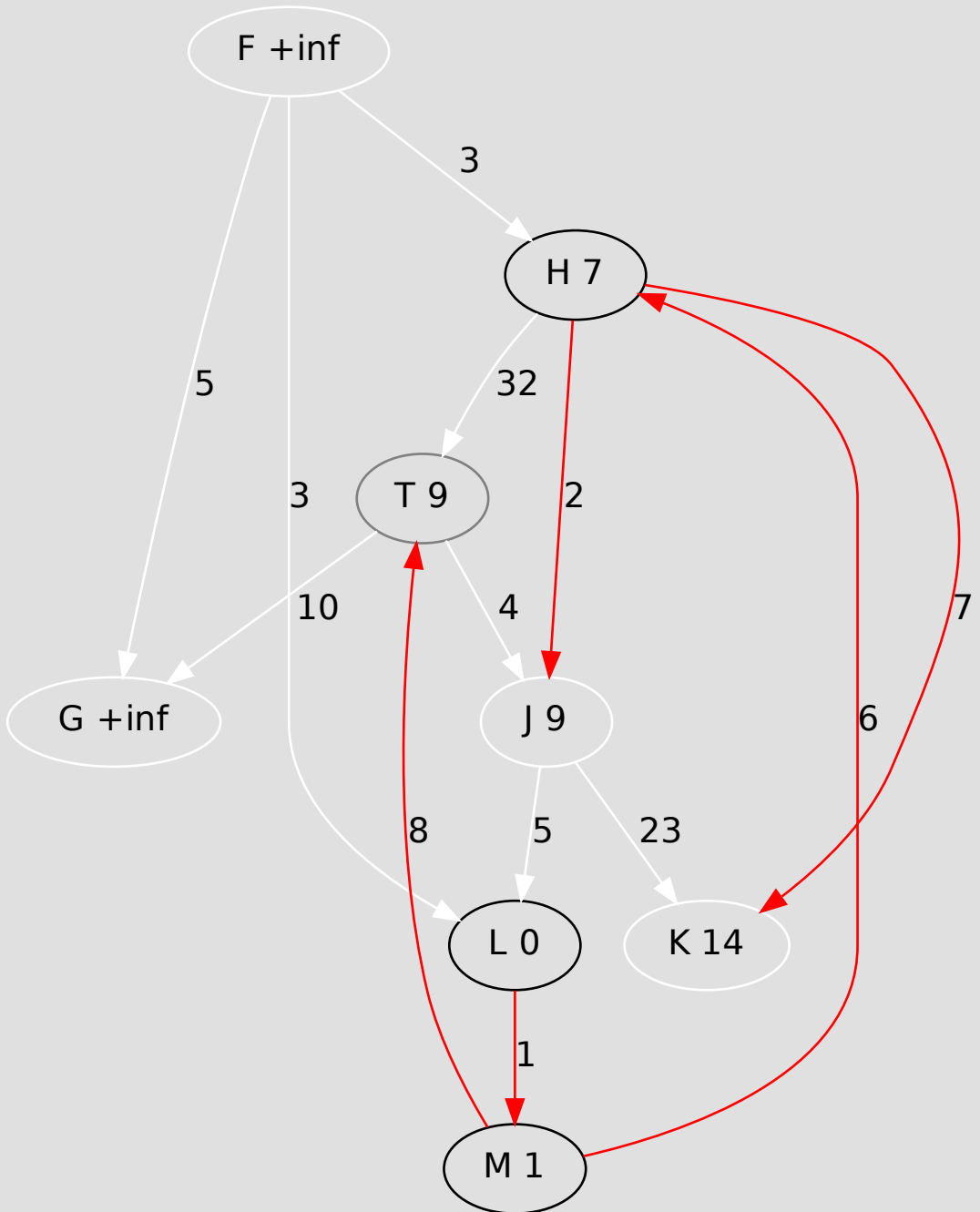


Finished with H.

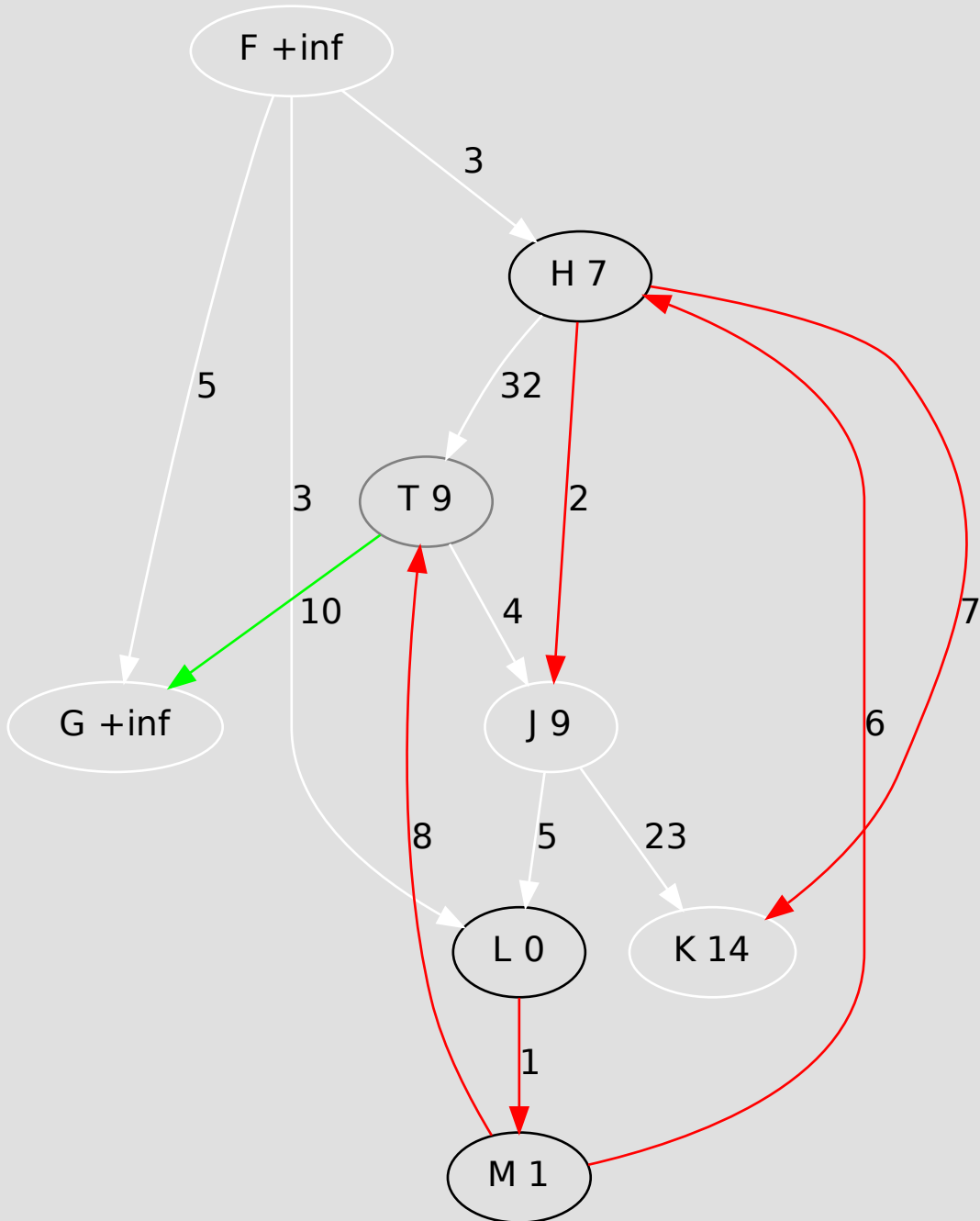
Priority queue = [T 9, J 9, K 14, F +inf, G +inf]



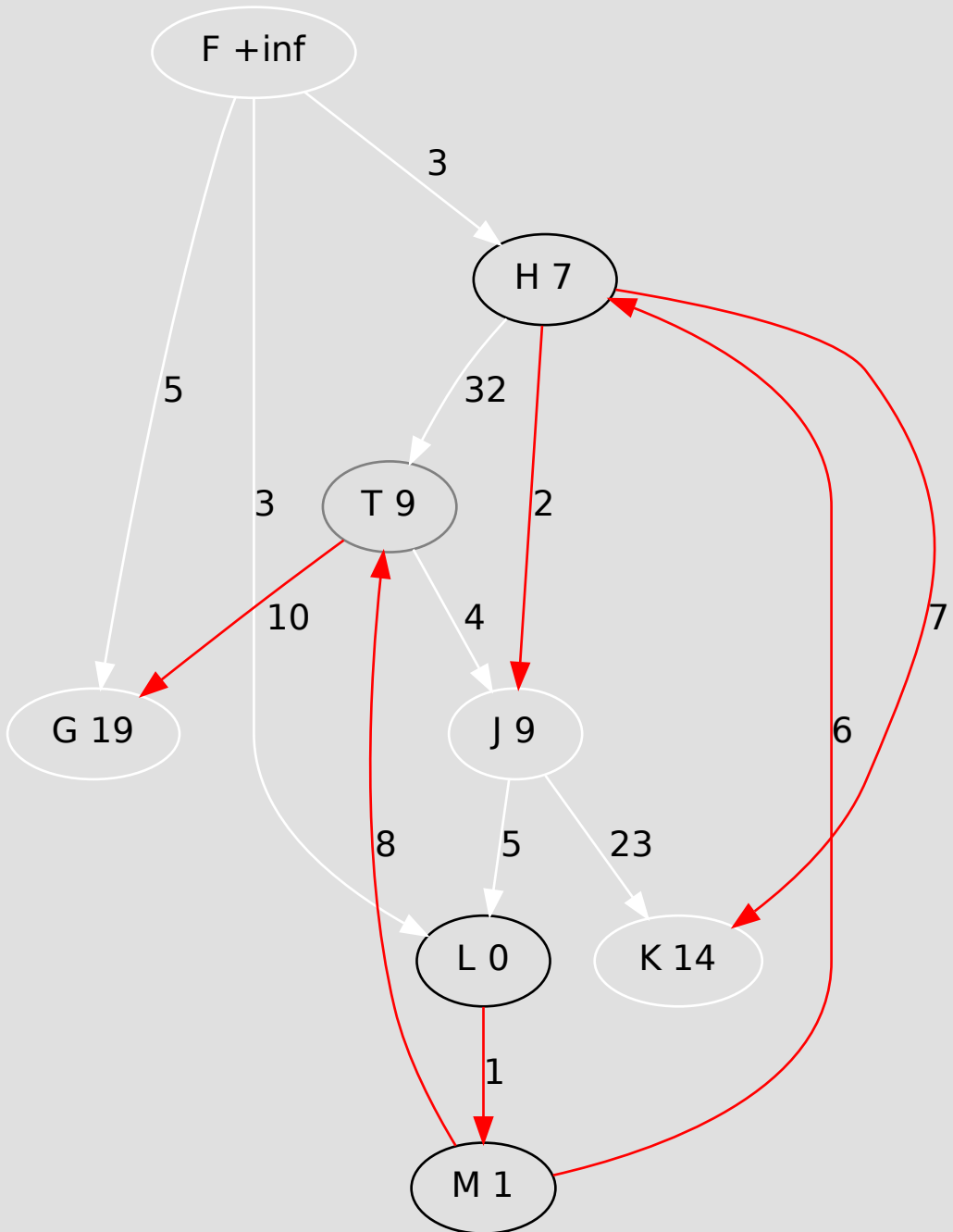
extractMin() -> T.
Priority queue = [J 9, K 14, F +inf, G +inf]



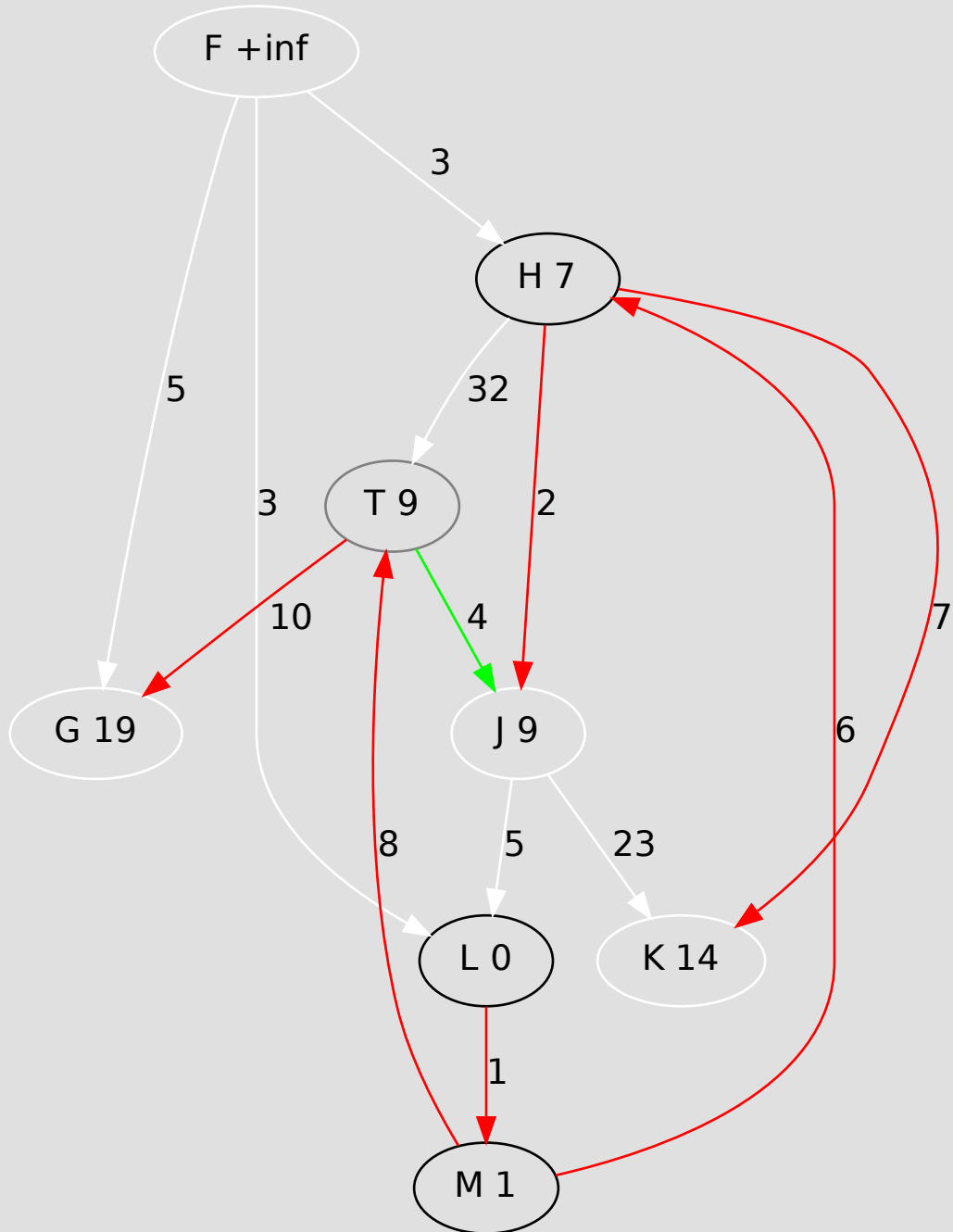
Relaxing the edges from T. Considering edge (T, G), leading to G.
Priority queue = [J 9, K 14, F +inf, G +inf]



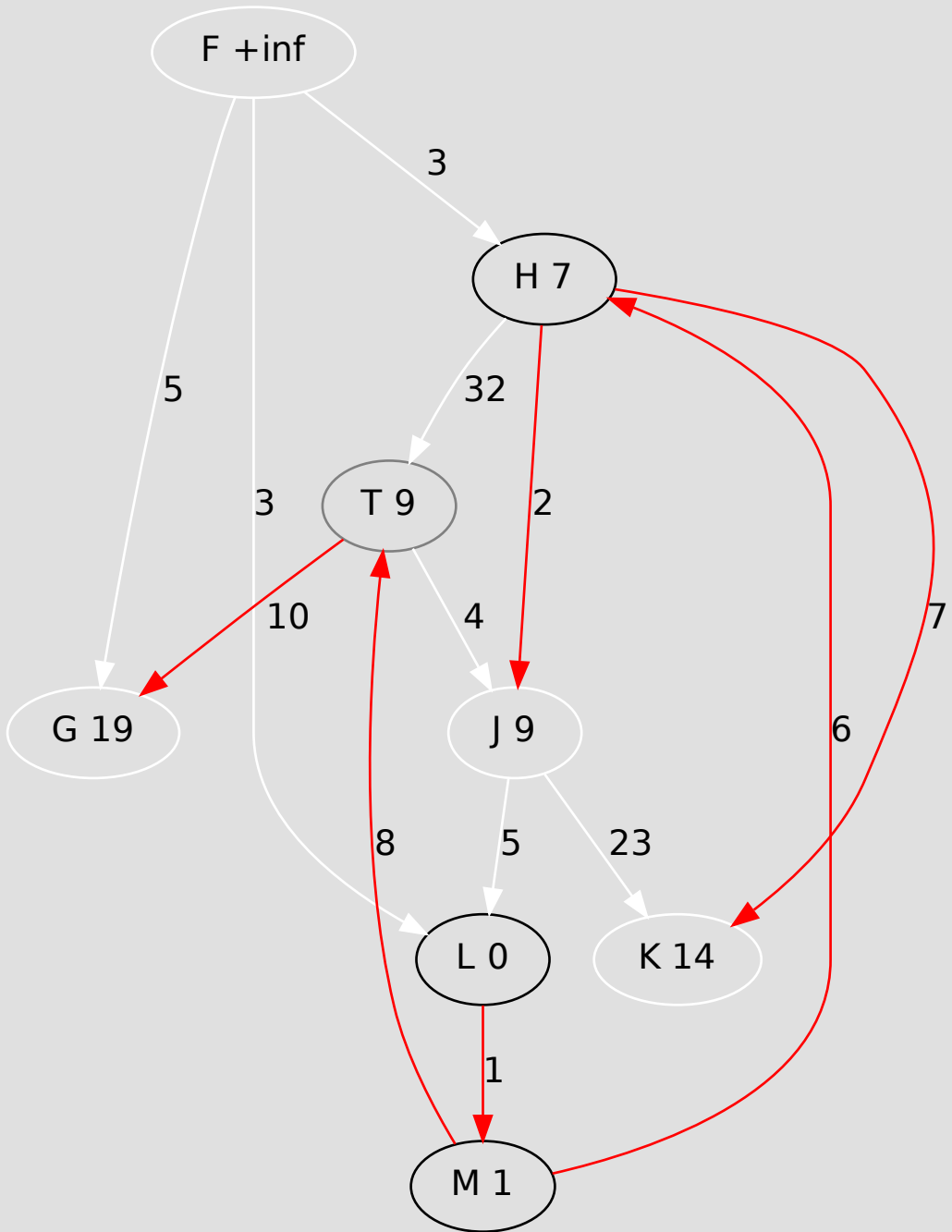
$9 + 10 < +\text{inf}$. Edge (T, G) relaxed.



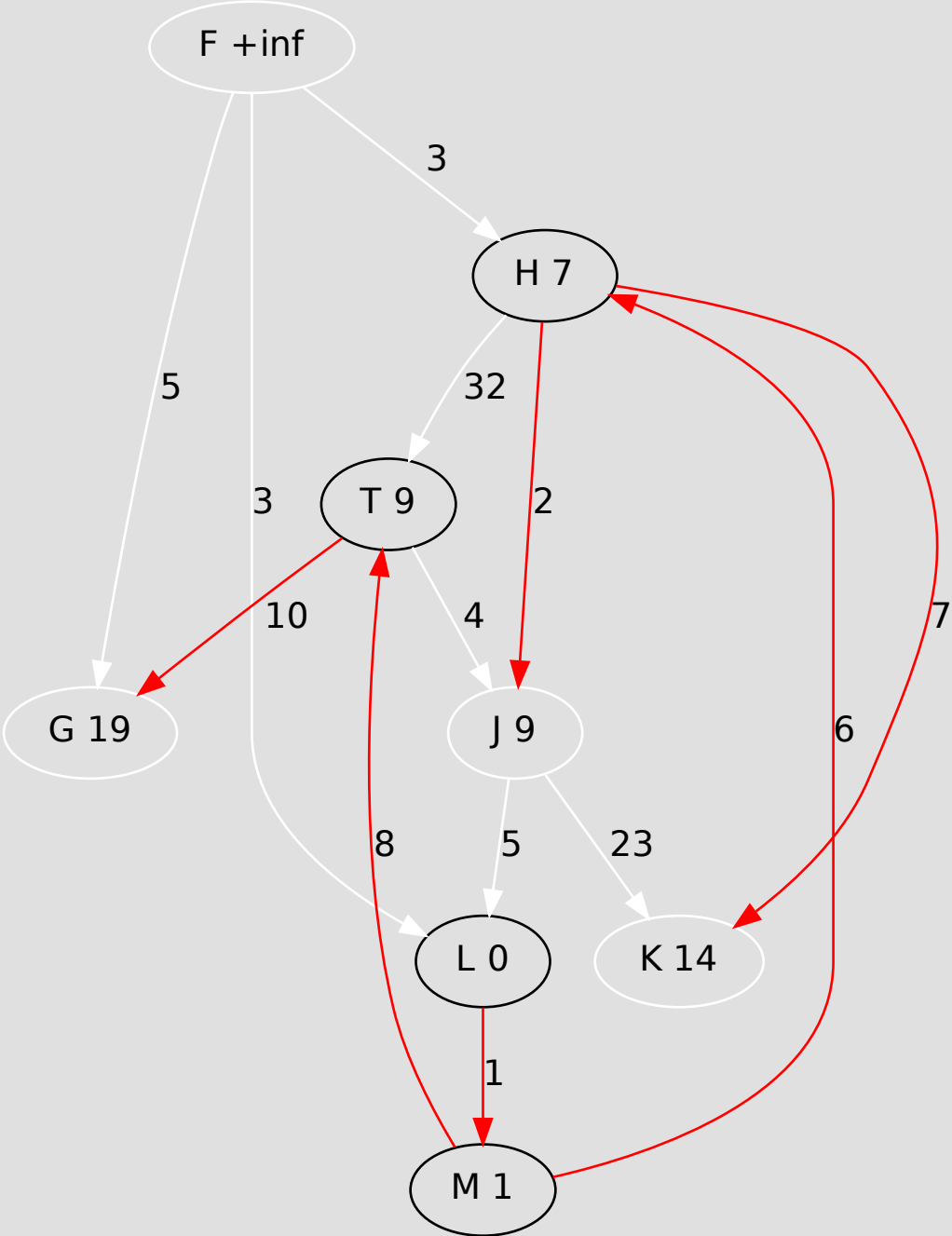
Relaxing the edges from T. Considering edge (T, J), leading to J.
Priority queue = [J 9, K 14, G 19, F +inf]



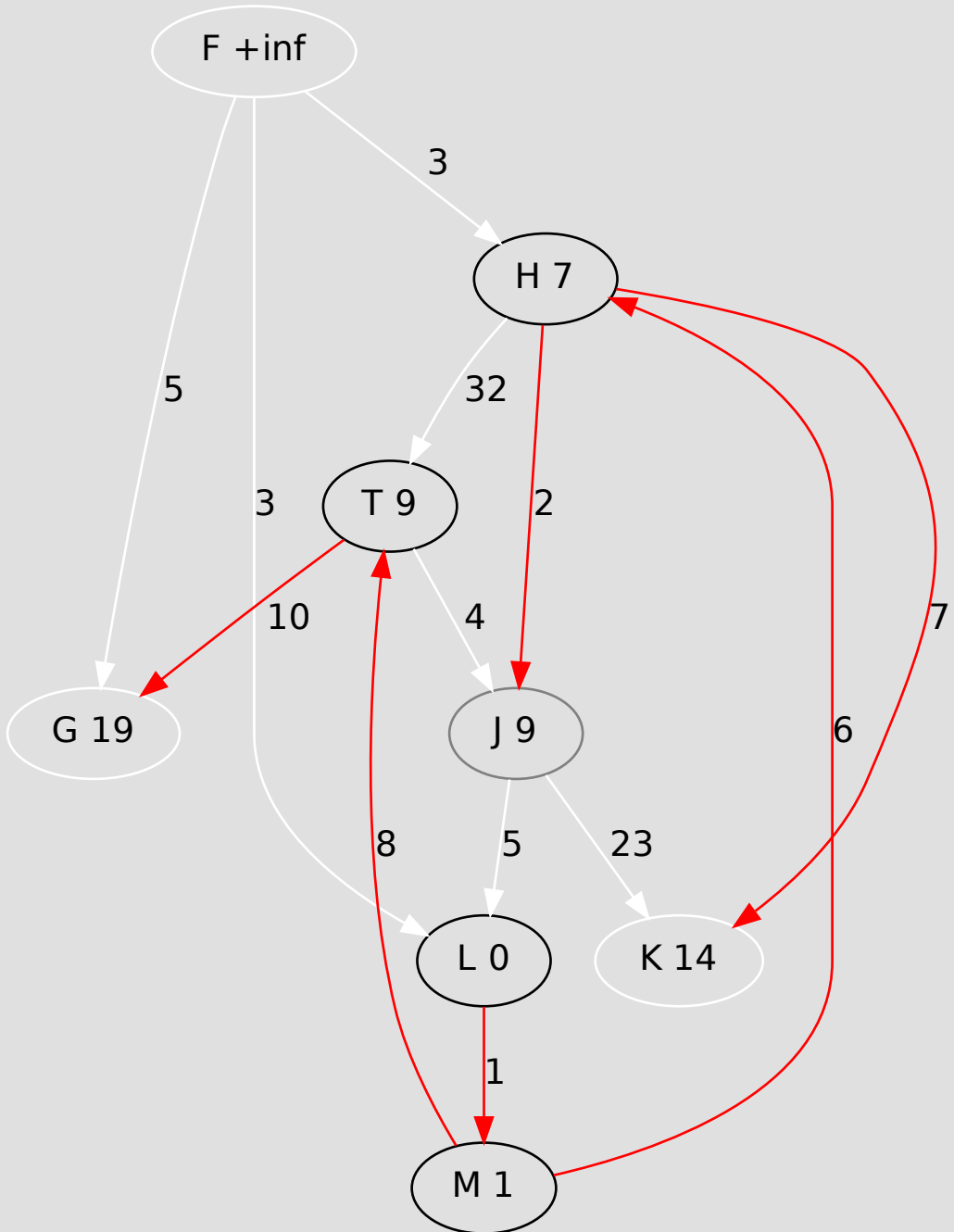
9 + 4 is not < 9. Edge (T, J) not relaxed.



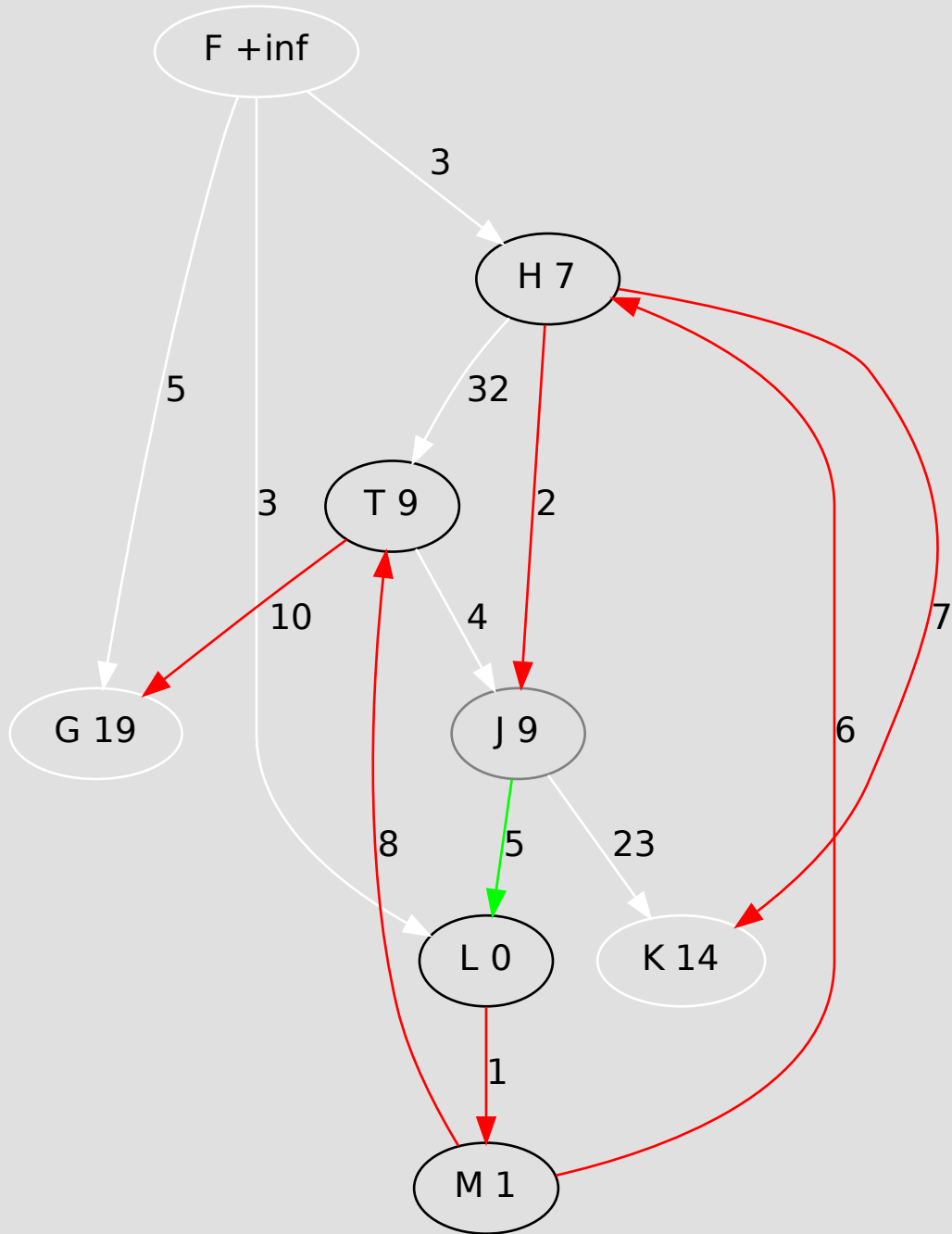
Finished with T.
Priority queue = [J 9, K 14, G 19, F +inf]



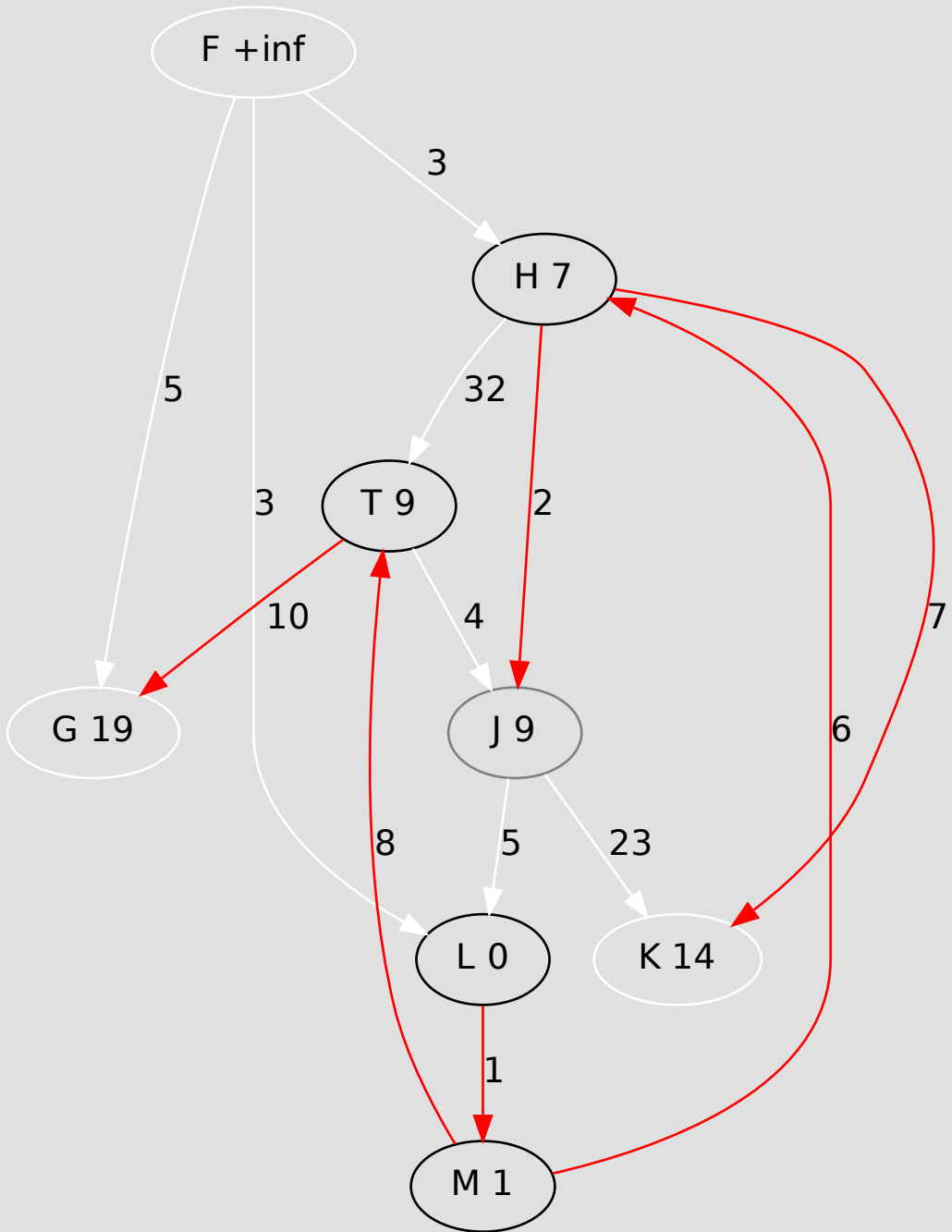
extractMin() -> J.
Priority queue = [K 14, G 19, F +inf]



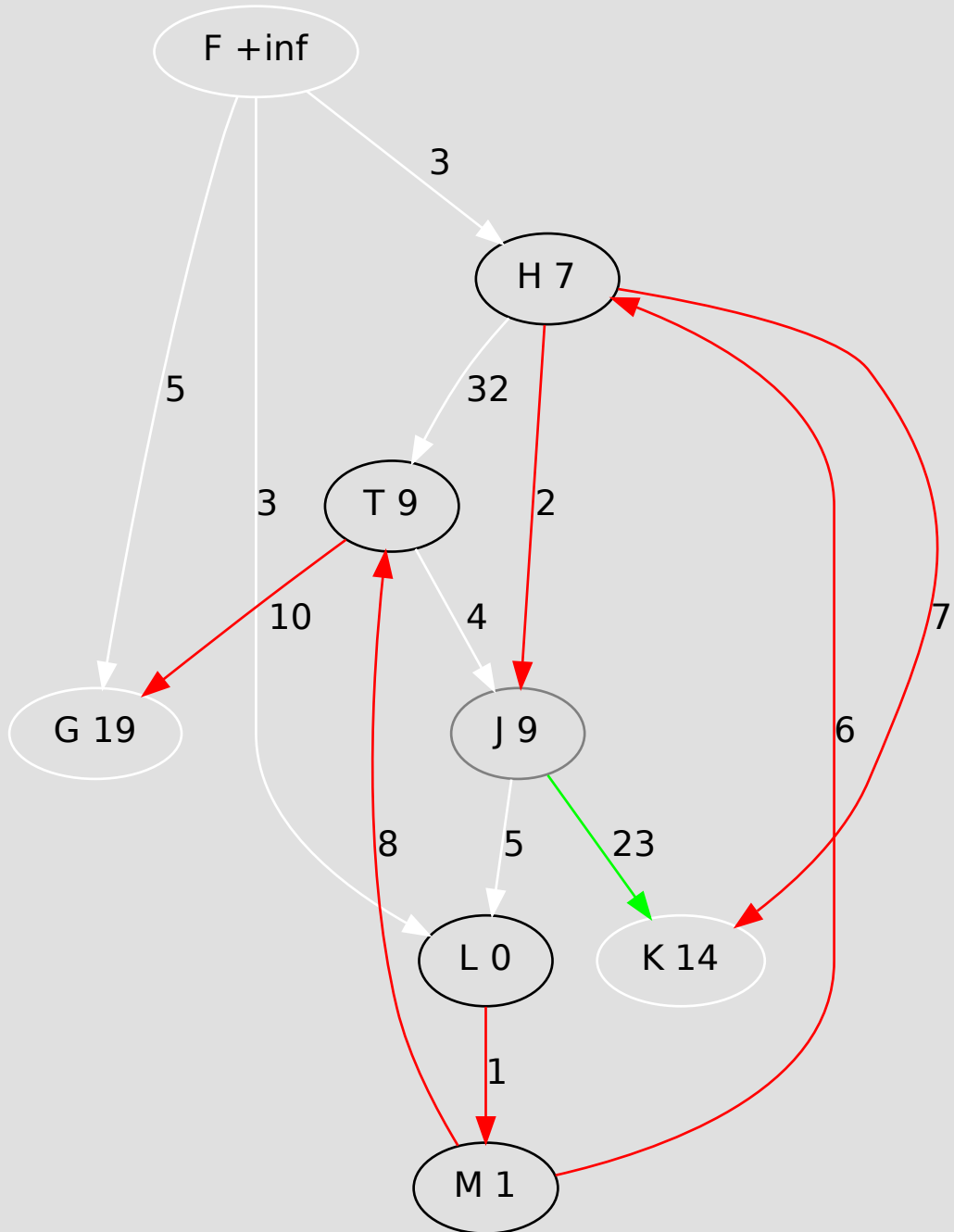
Relaxing the edges from J. Considering edge (J, L), leading to L.
Priority queue = [K 14, G 19, F +inf]



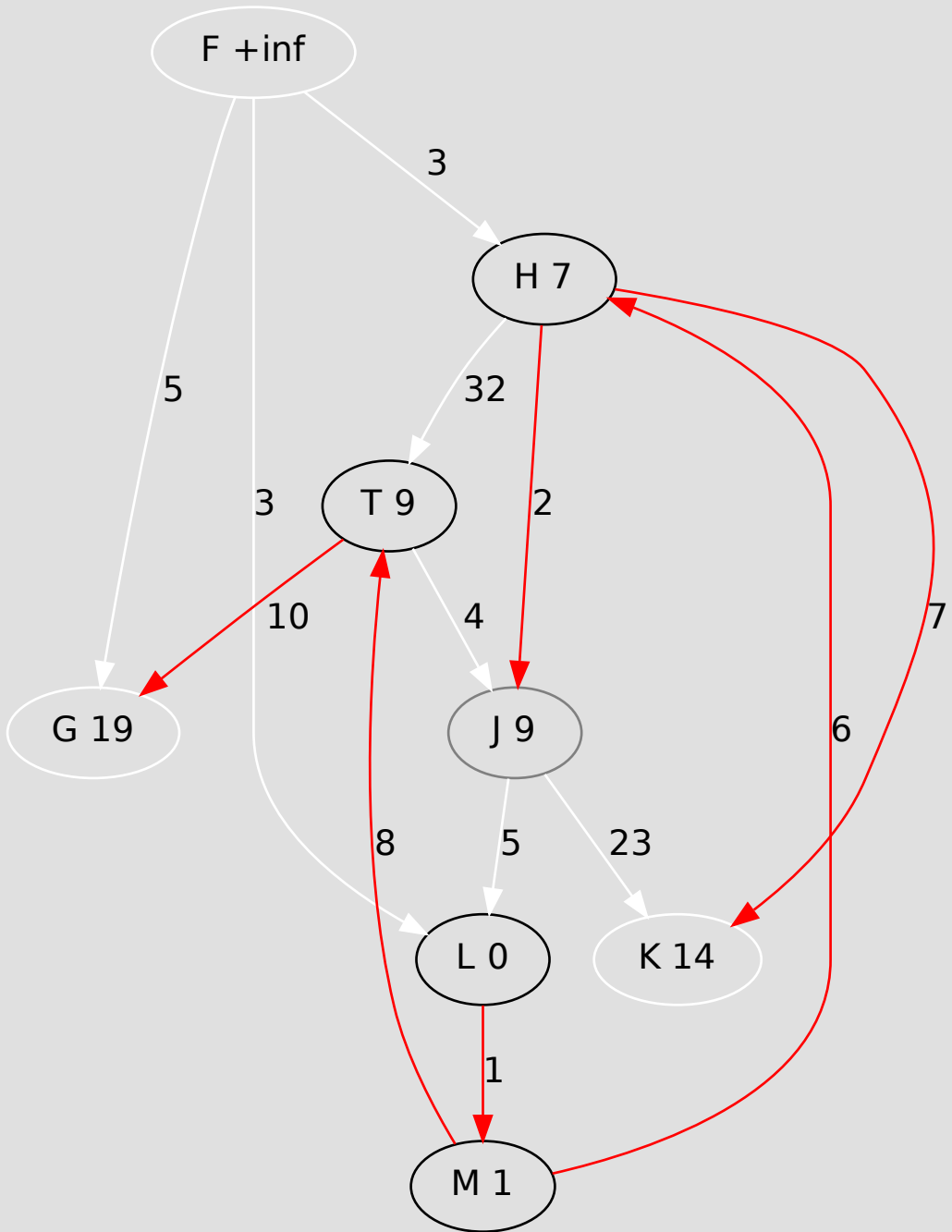
9 + 5 is not < 0. Edge (J, L) not relaxed.



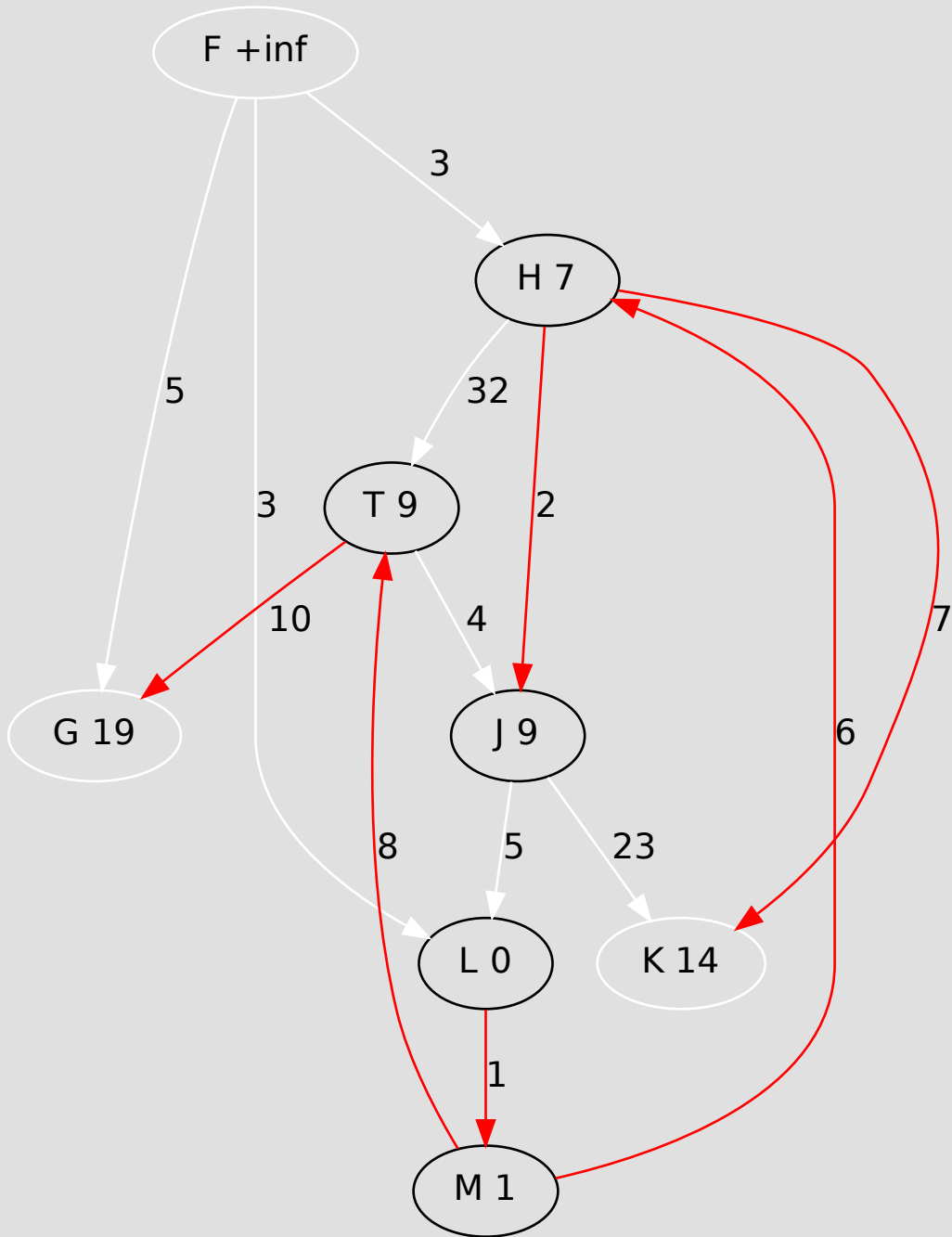
Relaxing the edges from J. Considering edge (J, K), leading to K.
Priority queue = [K 14, G 19, F +inf]



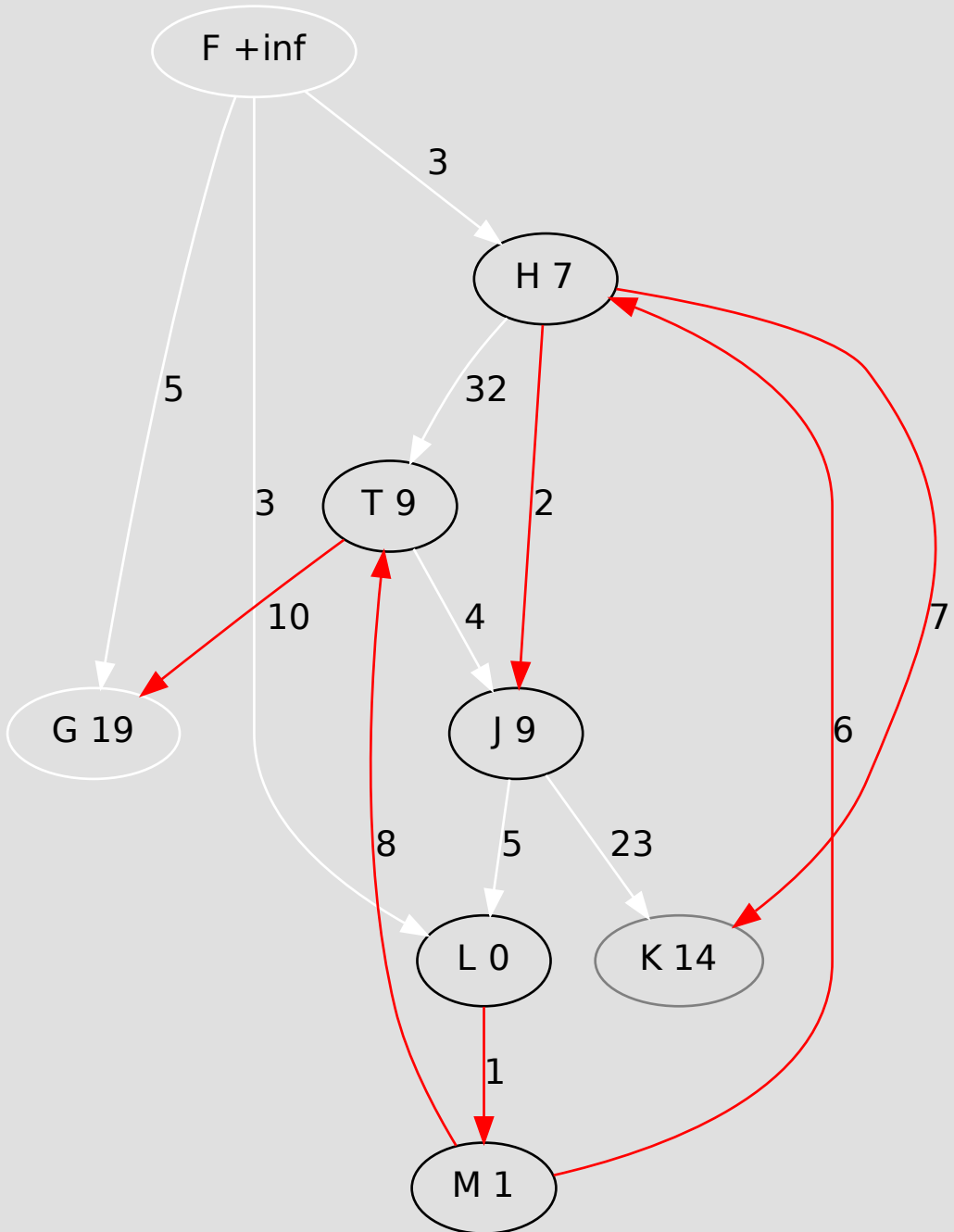
9 + 23 is not < 14. Edge (J, K) not relaxed.



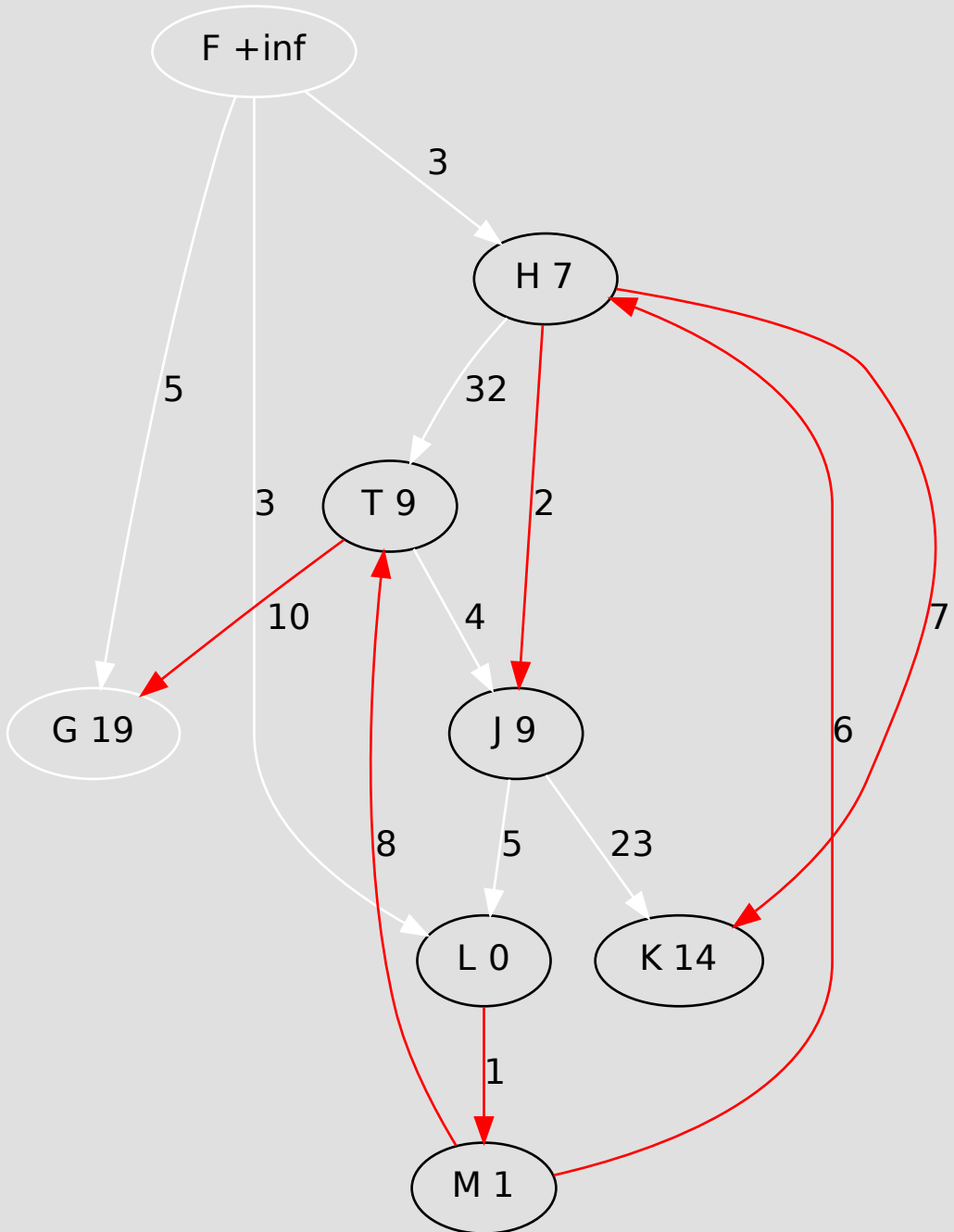
Finished with J.
Priority queue = [K 14, G 19, F +inf]



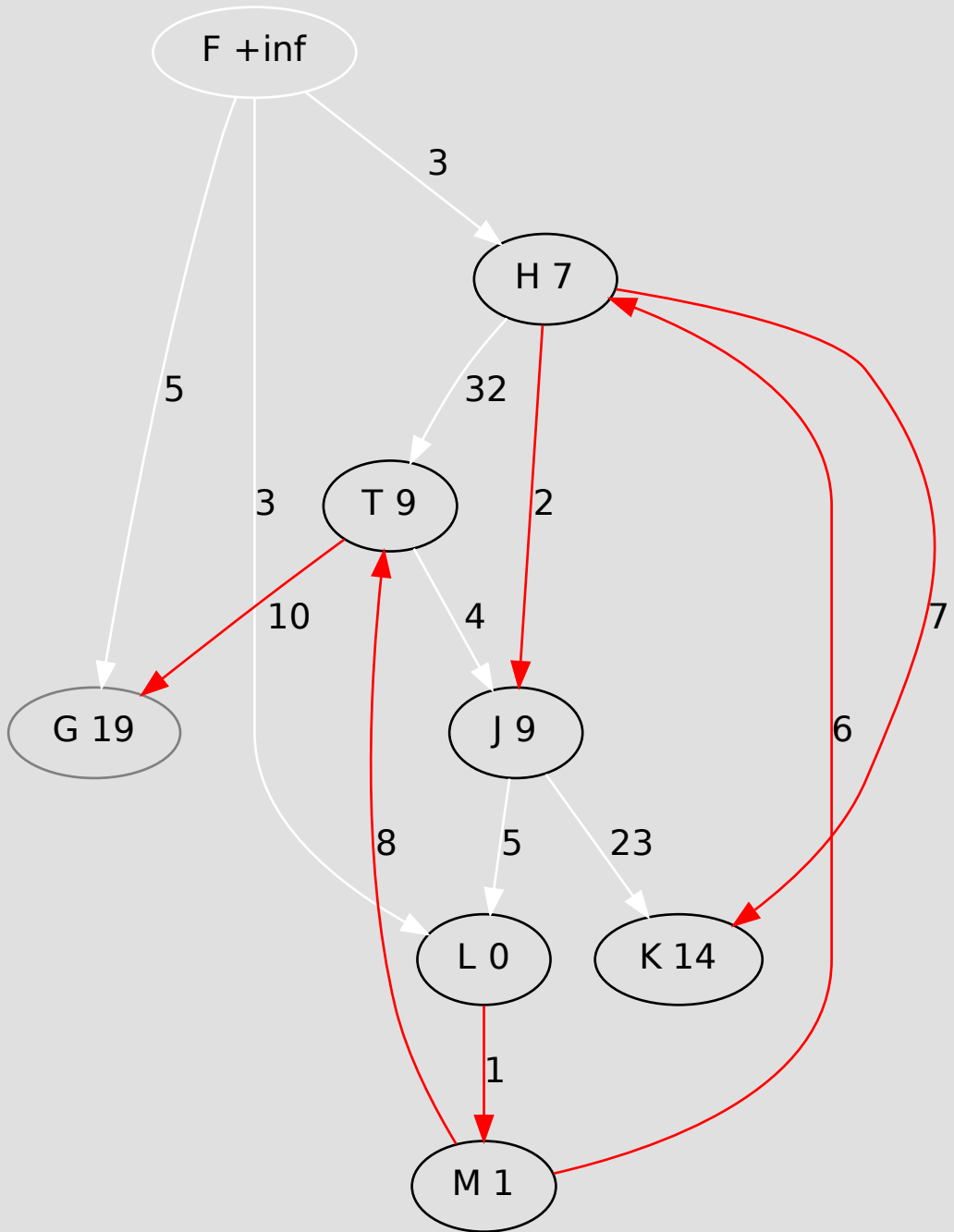
extractMin() -> K.
Priority queue = [G 19, F +inf]



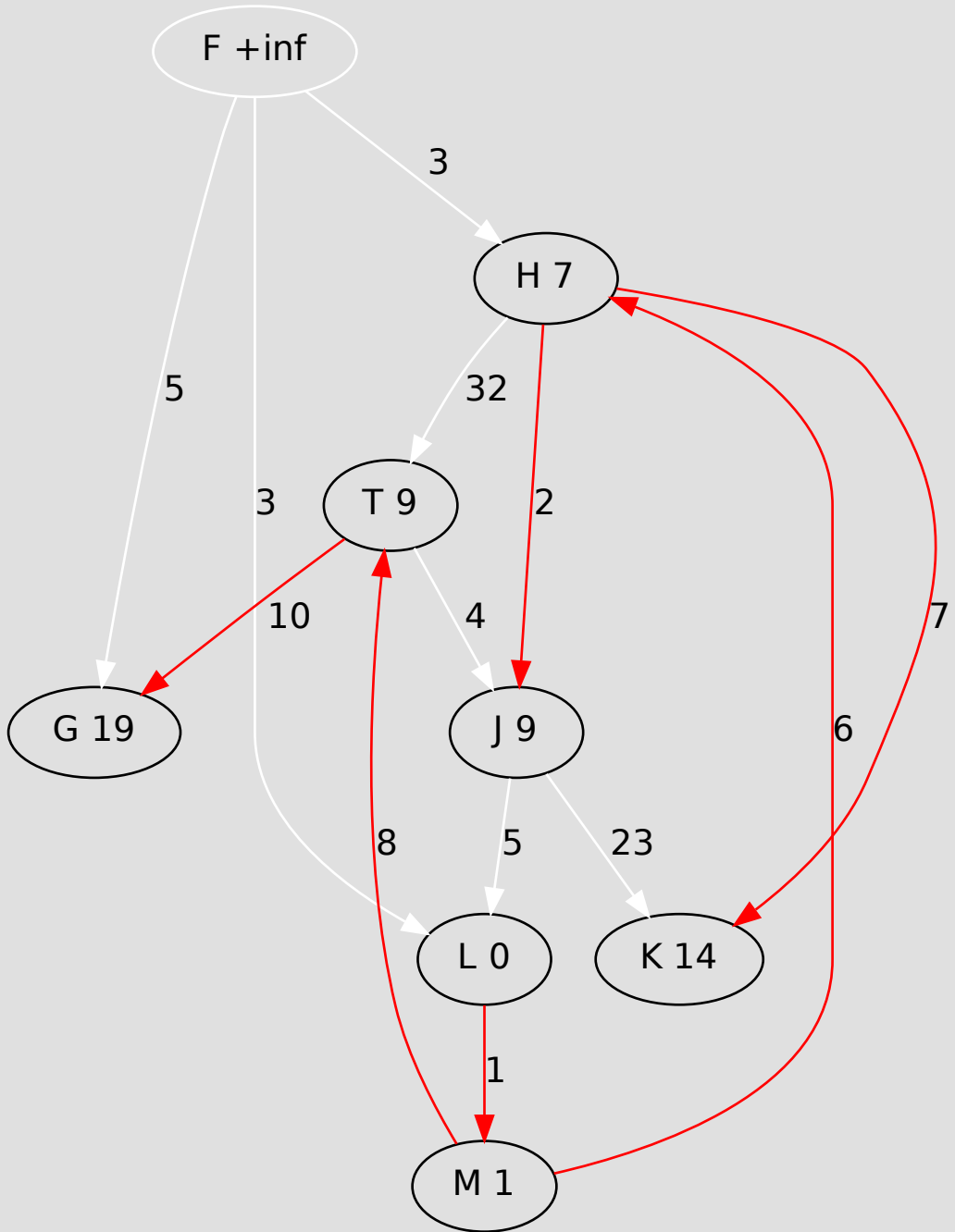
Finished with K.
Priority queue = [G 19, F +inf]



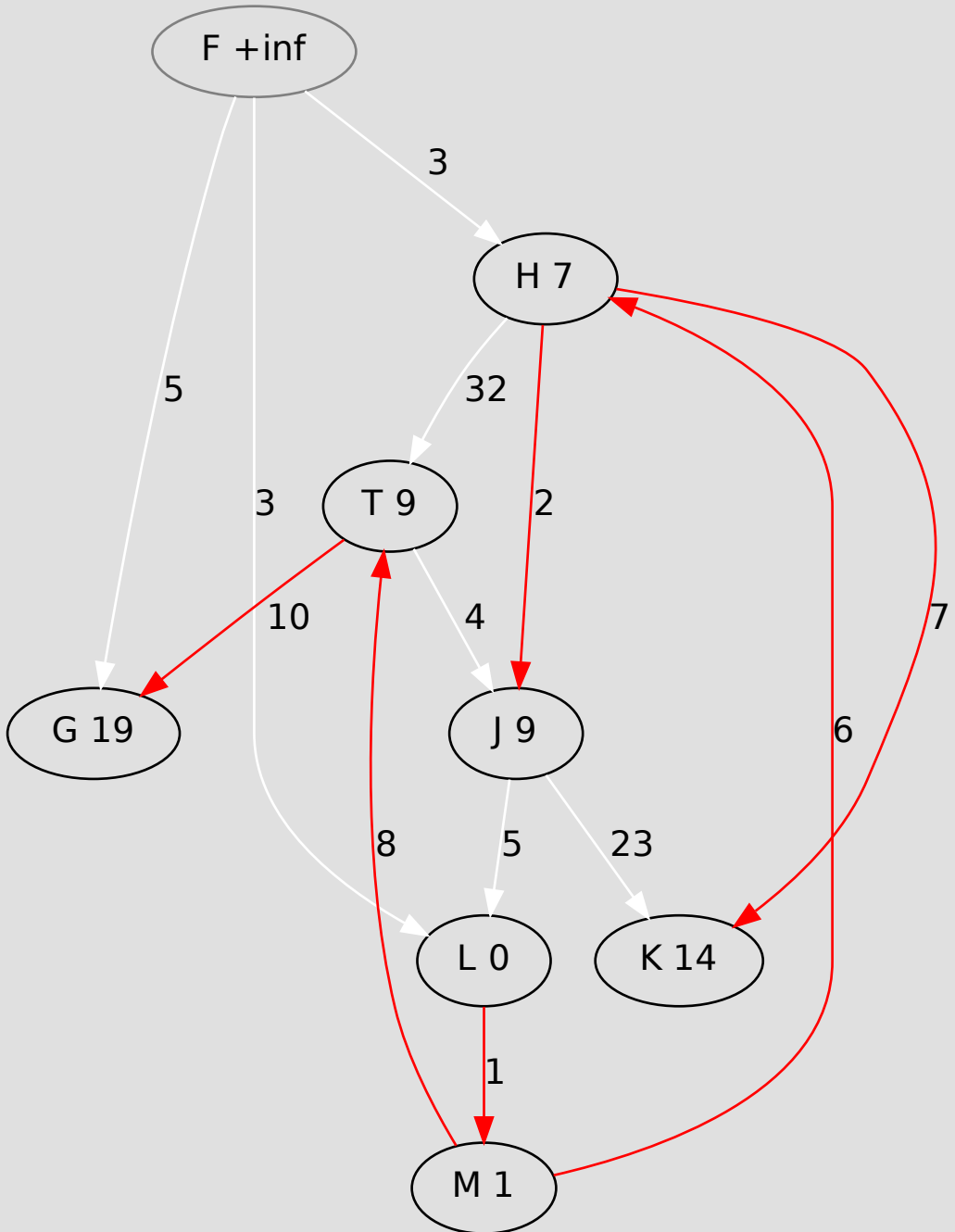
extractMin() -> G.
Priority queue = [F +inf]



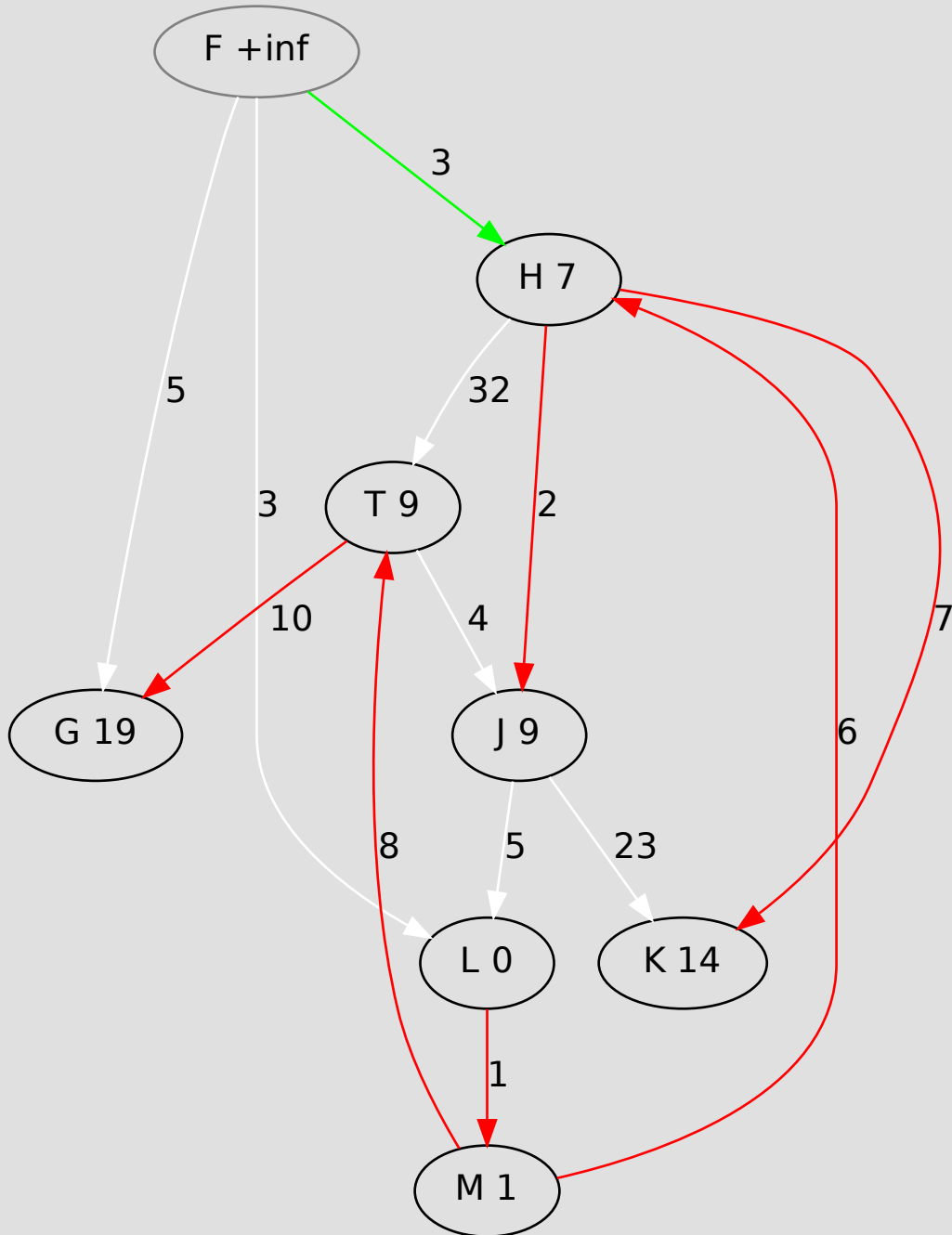
Finished with G.
Priority queue = [F +inf]



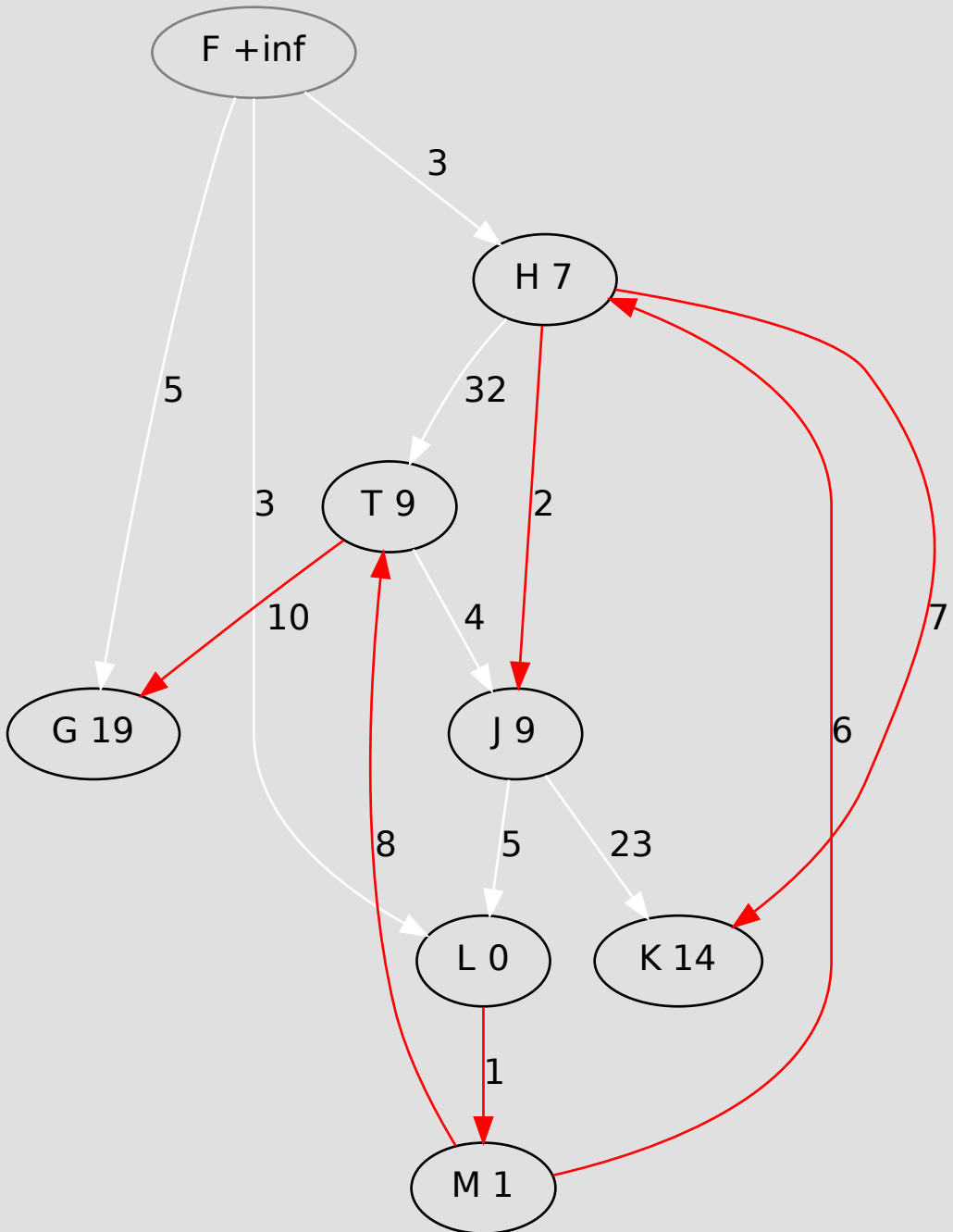
extractMin() -> F.
Priority queue = []



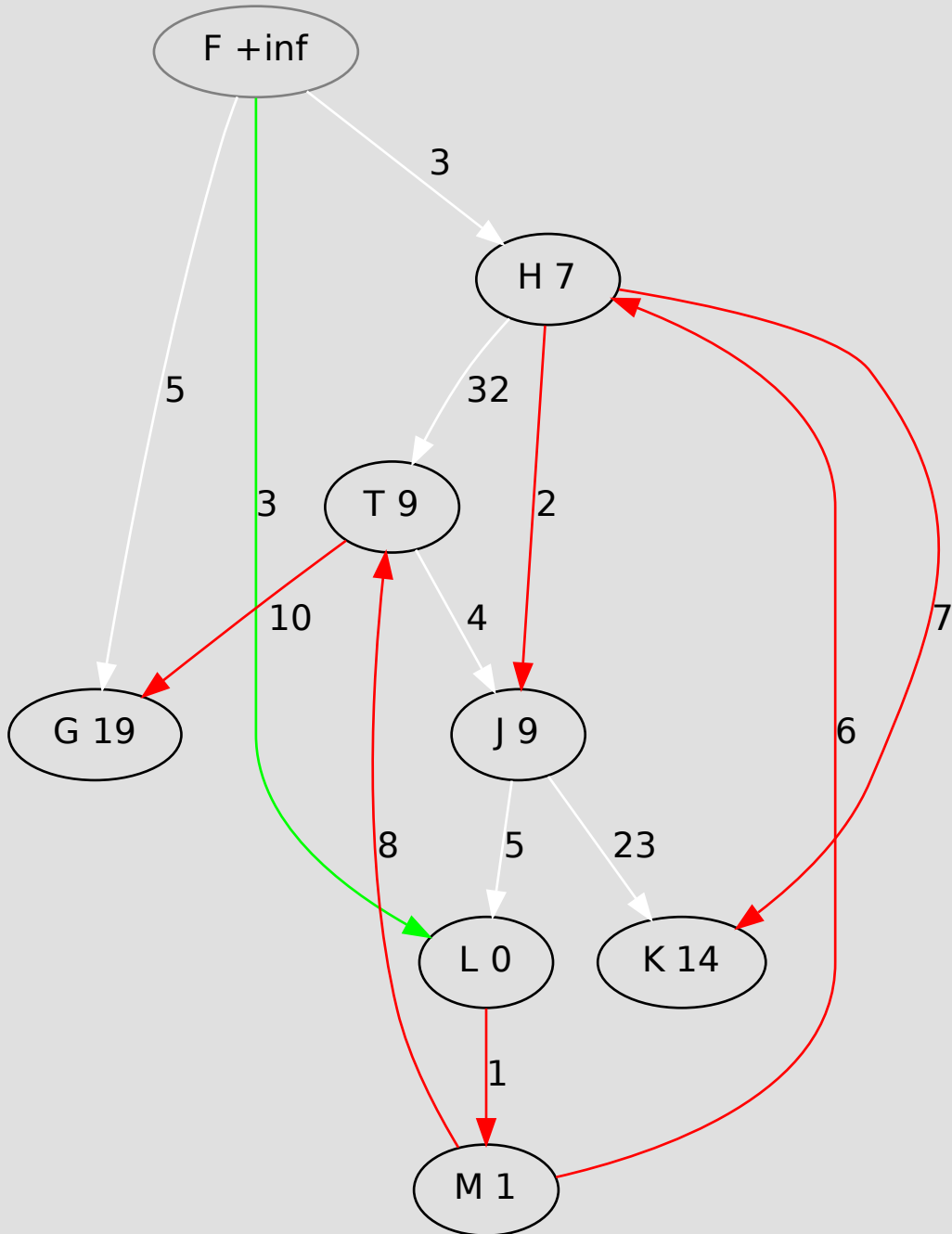
Relaxing the edges from F. Considering edge (F, H), leading to H.
Priority queue = []



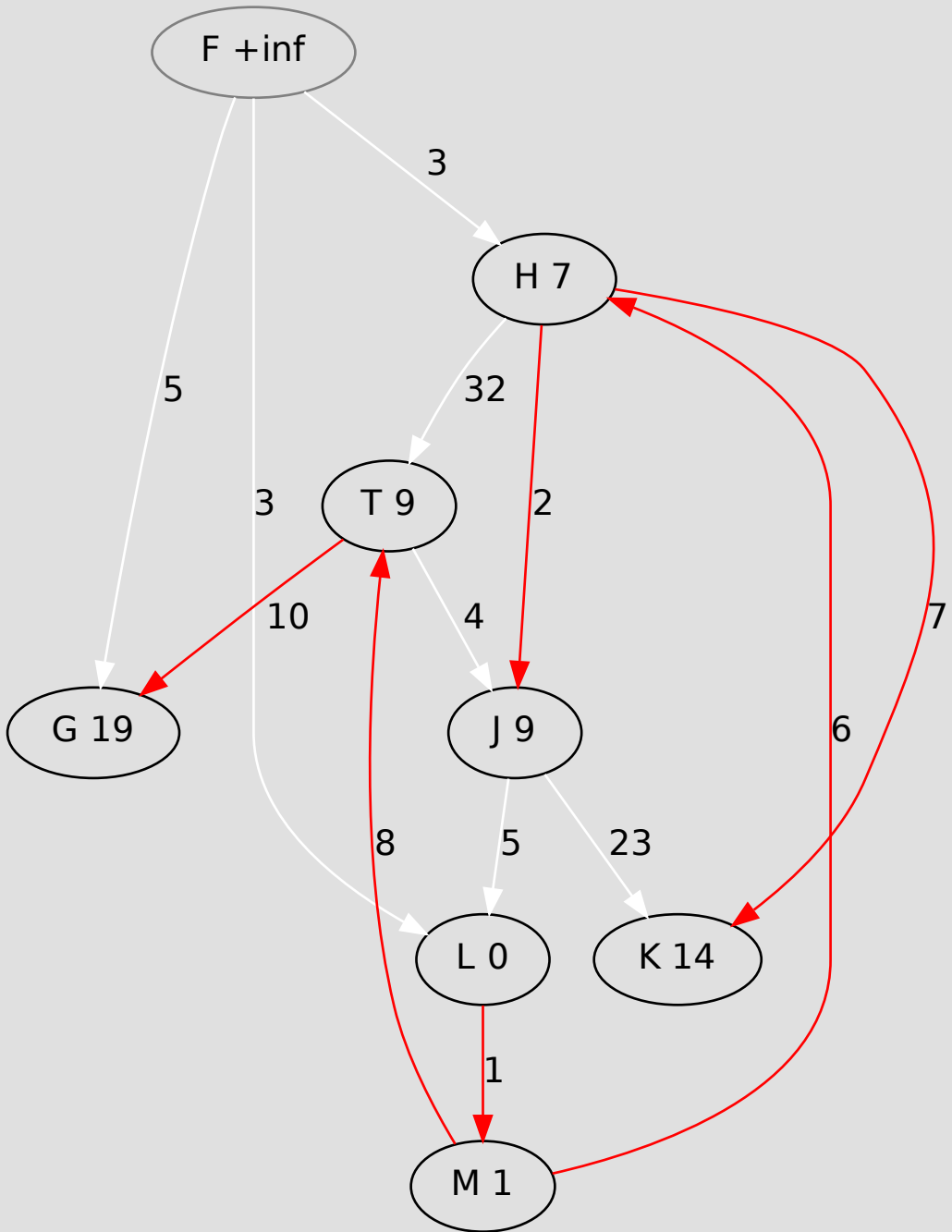
+inf + 3 is not < 7. Edge (F, H) not relaxed.



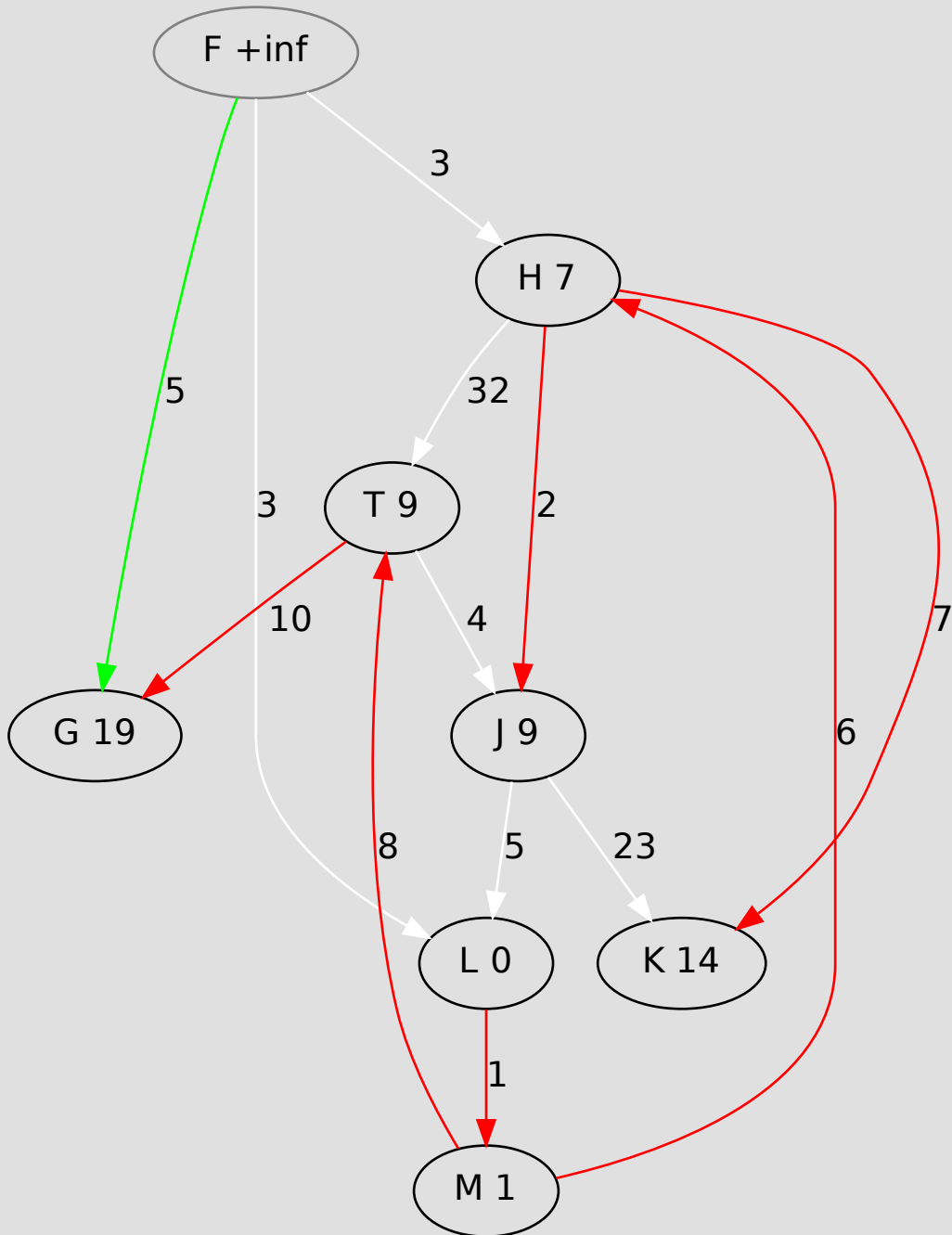
Relaxing the edges from F. Considering edge (F, L), leading to L.
Priority queue = []



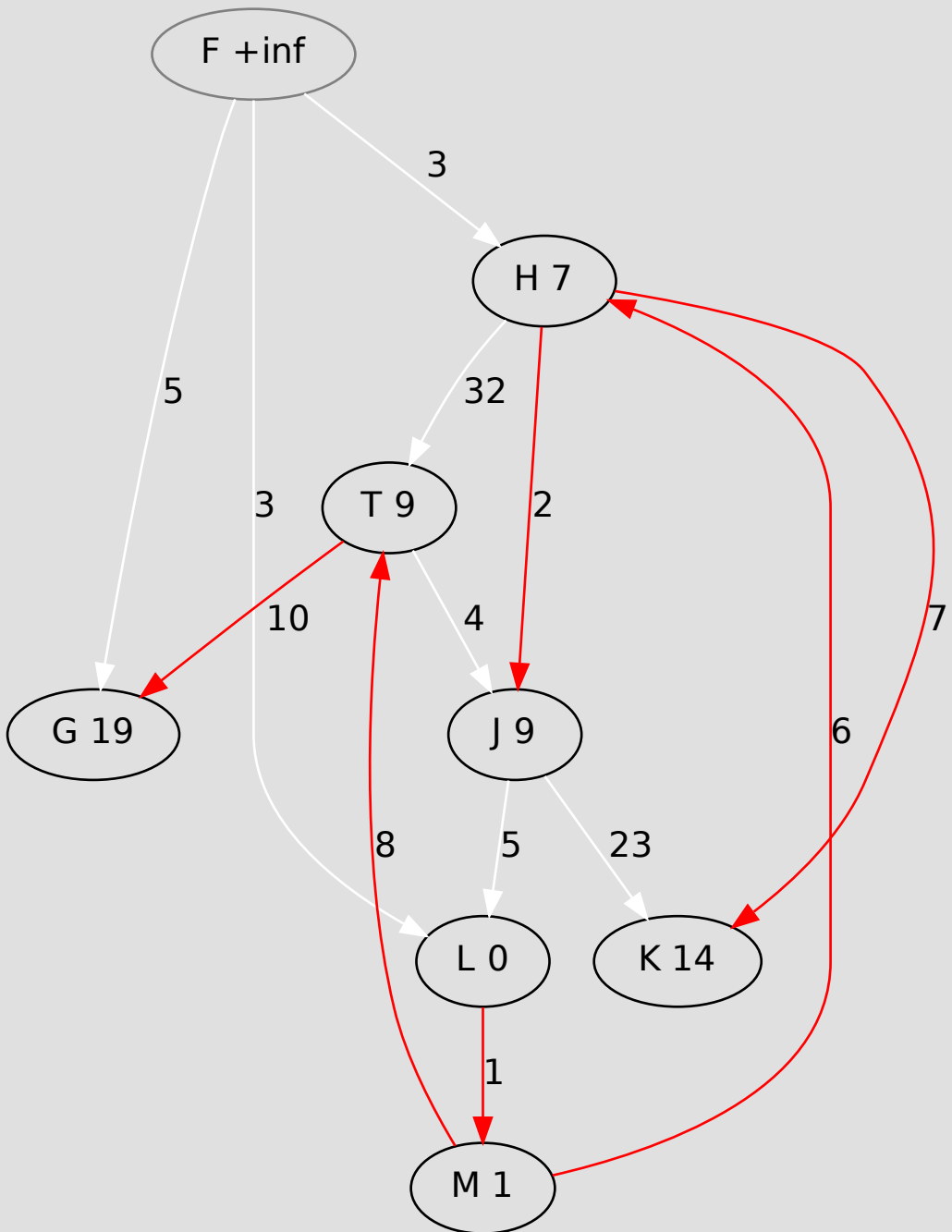
$+\text{inf} + 3$ is not < 0 . Edge (F, L) not relaxed.



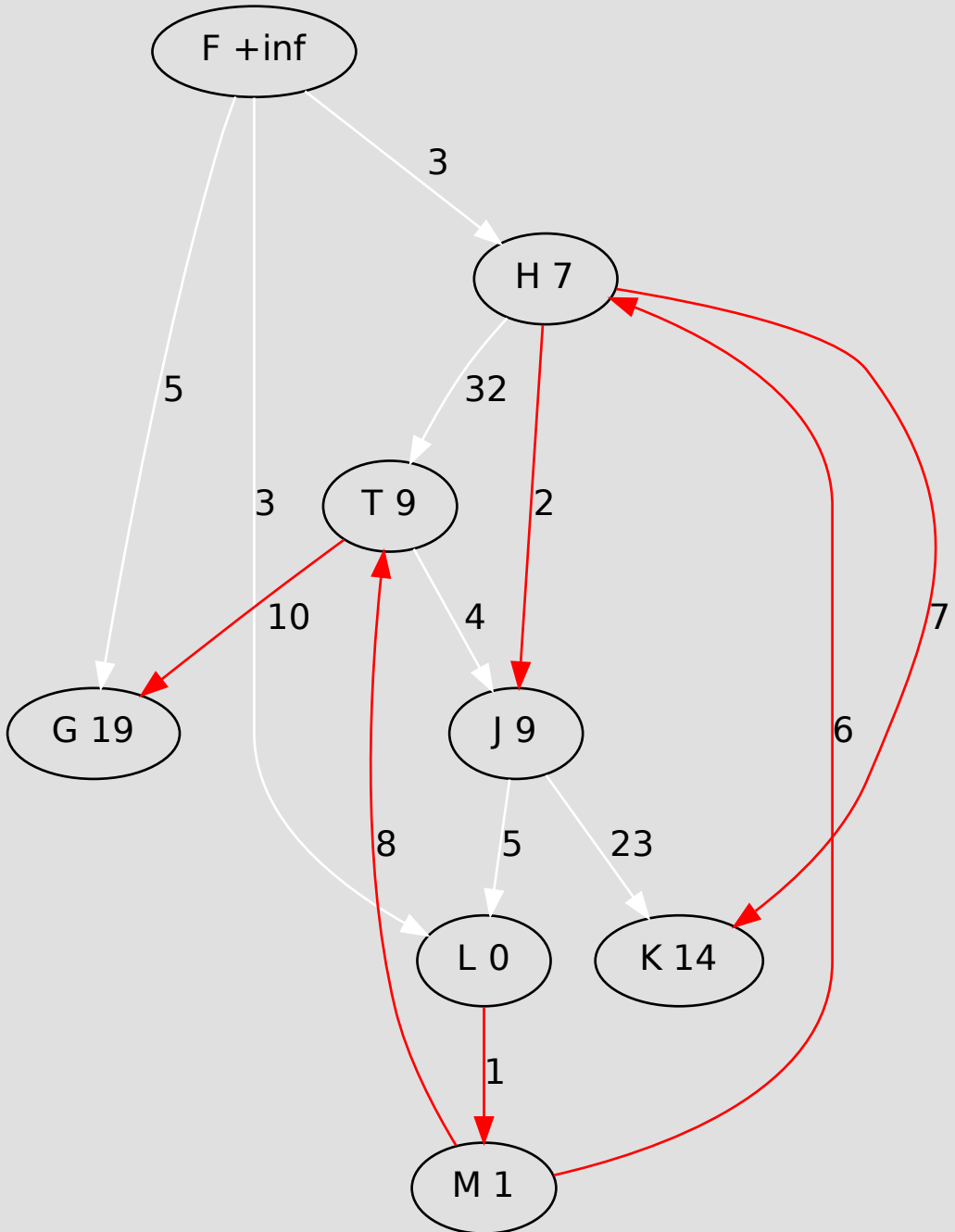
Relaxing the edges from F. Considering edge (F, G), leading to G.
Priority queue = []



+inf + 5 is not < 19. Edge (F, G) not relaxed.



Finished with F.
Priority queue = []



Dijkstra single-source shortest paths

Generated by \$Id: dijkstra.py 99 2010-11-18 10:48:22Z fms27 \$

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