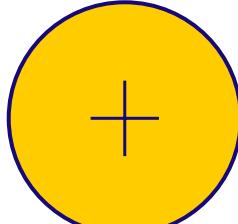


Introduction to Implicit Surfaces

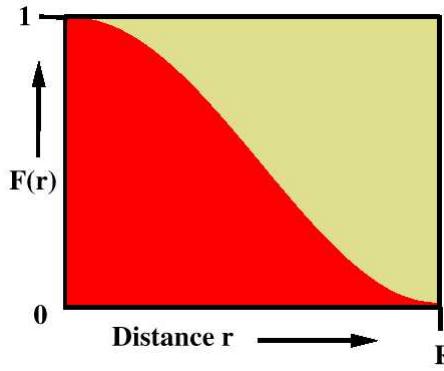
BlobTree

<p>Implicit Definition</p> $f(x,y) = x^2 + y^2 - r^2 = 0$ <p>e.g. $r = 1$</p> $f(0,0) = 0 + 0 - 1 < 0 \text{ inside}$ $f(0,0) = 1 + 1 - 1 > 0 \text{ outside}$ <p>implies search space to find x,y to satisfy: $f(x,y) = 0$</p> <p>iso-surface: $f(x,y) - c = 0$</p>	<p>Parametric Definition</p> $x = r \sin(\alpha)$ $y = r \cos(\alpha)$ $0 \leq \alpha \leq 2\pi$ 
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The Geoff Function

BlobTree

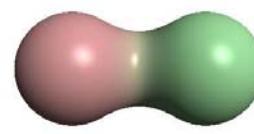


 Blend

Proximity Blending:

Add contributions from generating skeletal elements in the neighbourhood

Field Function

$$F(r) = 1 - \frac{(4/9) \frac{r^6}{R^6} + (17/9) \frac{r^4}{R^4} - (22/9) \frac{r^2}{R^2}}{1}$$


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Blending and The Soft Train

BlobTree

Polygonizer Info.

Warp Info.

$$\mathbf{F}_{\text{total}}(\mathbf{P}) = \sum_{i=1}^{i=n} c_i \mathbf{F}_i(\mathbf{r}_i)$$

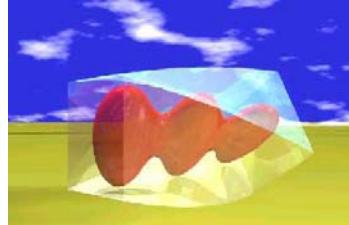
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Polygonization Algorithm

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Warping *BlobTree*

$$\mathbf{F}_{\text{total}}(\mathbf{P}) = \sum c_i \mathbf{F}_i(|\mathbf{P} - \mathbf{Q}_i|)$$


Warp function w:

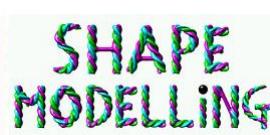
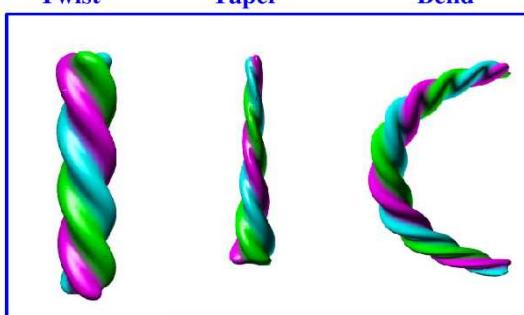
$$\mathbf{F}_{\text{total}}(\mathbf{P}) = \sum c_i \mathbf{F}_i(|w(\mathbf{P}) - \mathbf{Q}_i|)$$

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Barr Operators *BlobTree*

The Barr operators:

Twist Taper Bend



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Constructive Solid Geometry (CSG) **BlobTree**

Primitives are combined using boolean set operations:
Union, Intersection, Difference. Each primitive represents a half space,
ie the set of points defining the half space

E.g.

Sphere Cylinder Plane

Boolean expression (u= union, d= difference, i= intersection)
 $d(\text{sphere}, \text{cylinder}) = u(\text{sphere}, i(\text{cylinder}, \text{plane1}), \text{plane2}))$

The cylinder is infinite in extent
it is first intersected with two
half space planes.

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CSG Tree **BlobTree**

CSG Implementation

Boolean Expressions are
usually represented as a
binary tree.

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CSG Intersections with Voxels

BlobTree

The diagram illustrates the intersection of a cube with a curved surface. On the right, a 2D cross-section shows the intersection curve and points A, B, P₁, P₂, C₁, and C₂. Below this are two 1D interval diagrams representing the intersection regions for object 1 and object 2, and their difference. The intervals are labeled 'in' and 'out' at the ends.

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CSG Intersection Value

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Boolean Operations

Union and intersection of primitives, A and B may be respectively defined as a composition of the field values, F_A , F_B

$$F_A \cup F_B = \max(F_A, F_B)$$

$$F_A \cap F_B = \min(F_A, F_B)$$

Difference use $-\min(F_A, F_B)$
 (- in this case inverts inside and outside)

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CSG - Min and Max

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Union

$f_{A|B}(p_0) = \text{Max}(f_A(p_0), f_B(p_0))$
Depending on position of p_0

$f_A(p_1) = \text{Max}(f_A(p_1), f_B(p_1))$

$f_B(p_2) = \text{Max}(f_A(p_2), f_B(p_2))$

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CSG - Min

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Intersection

$f_{A|B}(p_0) = \text{Min}(f_A(p_0), f_B(p_0))$
Depending on position of p_0

$f_B(p_1) = \text{Min}(f_A(p_1), f_B(p_1)) = 0$

$f_A(p_2) = \text{Min}(f_A(p_2), f_B(p_2)) = 0$

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CSG - Min

BlobTree

Difference

$\text{Min}(f_A(p_0), f_B(p_0)) = 1 - f_{A|B}(p_0)$
Depending on position of p_0

$\text{Min}(f_A(p_1), 1 - f_B(p_1)) = f_A(p_1)$

$\text{Min}(f_A(p_2), 1 - f_B(p_2)) = 0$

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