# Advanced Systems Topics Part I of III

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6 lectures of 15 for CST II

#### **Course Aims**

This course aims to help students develop and understand complex systems and interactions, and to prepare them for emerging systems architectures.

It will cover a selection of topics including:

- operating systems,
- database systems,
- peer-to-peer systems, and
- parallel and distributed systems.

On completing the course, students should be able to

- describe three techniques supporting extensibility
- argue for or against distributed virtual memory
- describe how to build effective concurrency-control primitives for a modern computer
- compare and contrast various self-organising distributed lookup schemes
- architect a basic peer-to-peer application

#### **Course Outline**

- Part I: Advanced Operating Systems [SMH, 6L]
  - Distributed & Persistent Virtual Memory
  - Capability Systems & The CAP Computer
  - Microkernels & Virtual Machine Monitors
  - Extensibile Operating Systems
  - Database & Distributed Storage [2L]
- Part II: Scalable Synchronization [KAF, 4L]
  - Introduction (systems with 10K threads)
  - Architectures and Algorithms
  - Implementing Mutual Exclusion
  - Programming without Locks
- Part III: Peer-to-Peer Systems [JAC, 5L]
  - P2P Intro, Case Studies and Applications [3L]
  - Internet Coordinate Systems (Guest Lecture)
  - Structured v Unstructured P2P (Guest Lecture)

# **Recommended Reading**

- Singhal M and Shivaratris N
   Advanced Concepts in Operating Systems
   McGraw-Hill, 1994
- Stonebraker M and Shivaratri N
   Readings in Database Systems
   Morgan Kaufmann (3rd ed.), 1998
- Wilkes M V and Needham R M
   The Cambridge CAP Computer and its Operating System
   North Holland, 1979
- Hennessy J and Patterson D
   Computer Architecture: a Quantitative Approach
   (Chapter 6 in particular)
   Morgan Kaufmann (3rd ed.), 2003
- Bacon J and Harris T
   Operating Systems, Addison Wesley, 2003
- Peer-to-Peer Systems and the Grid
   www.cl.cam.ac.uk/~jac22/out/grid-p2p-paper.pdf
- Additional links and papers (via course web page)
   www.cl.cam.ac.uk/Teaching/current/AdvSysTop/

## **Memory Models**

Memory models for concurrent/parallel programs:

- Shared memory model:
  - collection of 'threads' sharing address space
  - reads/writes on memory locations implicitly and immediately globally visible
  - e.g. x := x + 1
- Message passing model:
  - collection of 'processes' (private address spaces)
  - explicit coordination through messages, e.g.

Processor 1	Processor 2
send_message("fetch(x)")	receive message
	send_message("x")
$tmp := recv\_message(P2)$	
tmp := tmp + 1	
send_message( "tmp" )	$x: = recv_message(P1)$

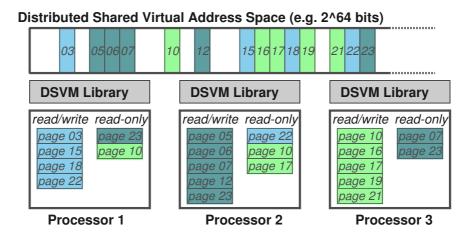
- Message passing: control, protection, performance
- Shared memory:
  - ease of use
  - transparency & scalability
  - but: race conditions, synchronisation, cost

# **Recap: Demand Paged Virtual Memory**

- Run-time mapping from logical to physical addresses performed by special h/w (the MMU).
- Variants: segmentation, capabilities, paging.
- Typically use demand paging:
  - create process address space (setup page tables)
  - mark PTEs as either "invalid or "non-resident"
  - add PCB to scheduler.
- Then whenever we receive a page fault:
  - 1. check PTE to determine if "invalid" or not
  - 2. if an invalid reference  $\Rightarrow$  kill process;
  - 3. otherwise 'page in' the desired page:
    - find a free frame in memory (may require direct or asynchronous page replacement)
    - initiate disk I/O to read in the desired page
    - when I/O is finished modify the PTE for this page to show that it is now valid
    - restart the process at the faulting instruction

Seems fairly straightforward for uniprocessors...

# **Distributed Shared Virtual Memory**



- Memory model typically dictated by hardware:
  - shared memory on tightly-coupled systems,
  - message passing on loosely-coupled systems
- Radical idea: provide shared memory on clusters!
  - each page has a "home" processor
  - can be mapped into remote address spaces
  - on read access, page in across network
  - on write acess, sort out ownership. . .
- OS/DSVM library responsible for:
  - tracking current ownership
  - copying data across network
  - setting access bits to ensure coherence

# Implementing DSVM (1)

- Simple case: centralized page manager
  - runs on a single processor
  - maintains two data structures per-page:
    - \* owner(p) = the processor P that created or which last wrote to page p
    - \* copyset(p) = all processors with a copy of p
  - can store copyset as bitmap to save space
- Then on read fault need four messages:
  - contact manager; manager forwards to owner;
  - owner sends page; requester acks to manager;
- On write fault, need a bit more work:
  - contact manager; manager *invalidates* copyset;
  - manager conacts owner; owner relinquishes page;
  - requester acks to manager;
- Load-balance: manager(p) is (p % # processors)
- Reduce messages: manager(p) = owner(p):
  - broadcast to find manager(p) ?
  - or keep per-processor hint: probOwner(p) ?
  - update probOwner(p) on forwarding or invalidate

# Implementing DSVM (2)

- Still potentially expensive, e.g. false-sharing:
  - P1 owns p, P2 just has read-access
  - P1 writes  $p \Rightarrow$  copies to P2
  - but P2 doesn't care about this change
- Reduce traffic by using weaker memory consistency:
  - so far assumed sequential consistency:
    - \* every read sees latest write
    - \* easy to use, but expensive
  - instead can do e.g. release consistency:
    - \* reads and writes occur locally
    - \* explicit acquire & release for synch
    - \* analogy with memory barriers in MP
- Best performance by doing *type-specific* coherence:
  - private memory  $\Rightarrow$  ignore
  - write-once ⇒ just service read faults
  - read-mostly ⇒ owner broadcasts updates
  - producer-consumer  $\Rightarrow$  live at P, ship to C
  - write-many ⇒ release consistency & buffering
  - synchronization ⇒ strong consistency

#### **DSVM: Evolution & Conclusions**

- mid 1980's: IVY at Princeton (Li)
  - sequential consistency (used probOwner(), etc)
  - some nice results for parallel algorithms with large data sets
  - overall: too costly
- early 1990's: Munin at Rice (Carter)
  - type-specific coherence
  - release consistency (when appropriate)
  - allows optimistic multiple writers
  - almost as fast as hand-coded message passing
- mid 1990's: Treadmarks at Rice (Keleher)
  - introduced "lazy release consistency"
  - update not on release, but on next acquire
  - reduced messages, but higher complexity
- On clusters:
  - can always do better with explicit messages
  - complexity argument fails with complex DSVM
- On non-ccNUMA multiprocessors: sounds good!

#### **Persistence**

Why is *virtual* memory volatile?

- virtual memory means memory is (or at least may be) backed by non-volatile storage.
- why not make this the default case?
  - ⇒ no more distinction between files and memory
  - ⇒ programmatic access to file system or DB bases:
    - \* is easier (e.g. linked structures)
    - \* can benefit from type system

#### Some definitions:

- Persistence of data = length of time it exists
- Orthogonal Persistence = manner in which data is accessed is independent of how long it persists

Two main options for implementation:

- Functional/interpreted languages ⇒ can 'fake out' in language runtime.
- Imperative/compiled languages:
  - prescribe way to access data (e.g. pure OO), or
  - use the power of virtual memory. . .

# The Multics Virtual Memory

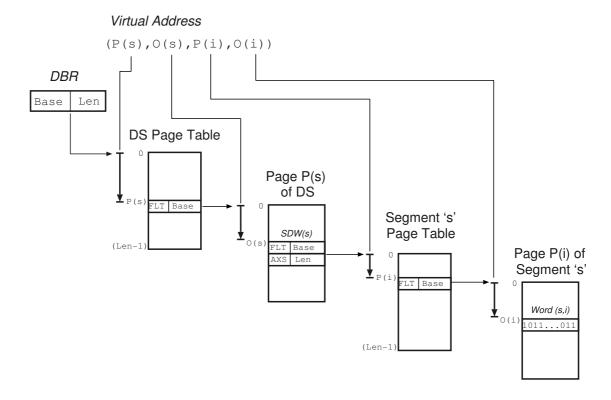
Unifying VM and non-volatile storage is *old*:

- Developed 1964- by MIT, GE and AT&T Bell Labs
- Many (8–64) concentric rings of privilege.
- No filesystem per se; user saw large number of orthogonal linear regions ("segments") of virtual address space, each backed by a secondary store.
- Segments were created and named by users, and remained available until explicitly deleted.
- Tree of directories and non-directories, a la Unix
- Directories contains a set of **branches** ( $\sim$  inodes)
- A branch contains a set of attributes for a segment:
  - Unique Segment ID (assigned by FS)
  - An access control list (ACL) for each UID
  - A ring bracket and limit:
    - \* ACL applies only within bracket
    - \* bracket is a pair  $(b1 \le b2)$ , limit is  $l \ge b2$
  - A list of gates = procedure entry points
- Flexible security: processes "jump" through gates

#### **Problems with Multics**

A victim of complexity. . .

• e.g. GE 645 hardware for paged segments



- e.g. translating "names" to usable segments:
  - access via pathnames or reference names
  - separate "known" and "active" concepts:
    - \* per proc "known" segments (KST)
    - \* per system "active" segments (AST)
  - segment fault handlers, page fault handlers
- good security ⇒ harder to do stuff!

# **Persistent Virtual Memory**

Increasing secondary storage  $\Rightarrow$  persistence tricky:

- cannot safely name (refer to) all data
- e.g. consider limitations of mmap()
- possible soln via pointer swizzling, e.g. Texas
  - portable C++ library
  - can allocate objects on persistent heap
  - data in persistent pages canonically addressed by special 64-bit persistent pointers (PPtrs)
  - ensure PPtrs are never directly accessed:
    - \* mark any resident persistent page as invalid
    - \* trap on access and for every PPtr  $\hat{p}$ 
      - $\cdot$  allocate a new page P and mark it invalid
      - $\cdot$  swizzle (rewrite)  $\hat{p}$  to refer to P
      - · unprotect original page and resume
- Recent 64-bit address spaces mean virtual addresses can directly serve as unique names:
  - $\Rightarrow$  can have a  $single \ address \ space \ OS \ (SASOS)$ 
    - many SASOSes (e.g. Opal, Mungi) have PVM
    - can also combine with DSVM: smart?

## **Recoverable Virtual Memory**

- RVM refers to a region of virtual memory on which transactional semantics apply.
- Building block for filesystems, DBs, applications.
- Best known work: lightweight RVM (Satya et al, SOSP '93, ACM TOCS '94)
  - full transaction semantics too expensive
  - ⇒ just consider atomicity and [some] durability
    - processes map regions of external segments into their virtual address space and then:
      - \* Start with t = begin\_transaction(rmode)
      - \* Invoke set\_range(t, base\_addr, nbytes)
        - normally LRVM copies range when notified and adds to undo  $log \Rightarrow on abort$ , can restore old values.
        - · elide if rmode is "no-restore"
      - \* Finally end\_transaction(t, cmode):
        - LVRM synchronously writes all ranges to redo log.
        - · (lazy write if cmode is "no-flush")
    - Redo log gets full  $\Rightarrow$  reflect log contents to external segments and truncate log.
- Can build full transaction semantics on top of LRVM (see paper for details).

## Making RVM Faster

LVRM is faster than full transaction system but:

- up to three copies of data (undo, redo, truncate)
- expensive synchronous disk writes

Can we do better?

- Controversial Rio Vista proposed SOSP '97
- Uses Rio, a persistent (NVRAM) file cache:
  - on map, just mmap region of NVRAM
  - on set\_range() copy to undo log in NVRAM
  - all updates immediately durable  $\Rightarrow$  no redo log.
- Authors report performance wins up to 2000x since:
  - no synchronous disk writes required
  - no redo  $log \Rightarrow avoid two copies$
- So what if the machine crashes?
  - early in reboot, flush NVRAM contents to disk
  - on map, lazily undo any transactions which had not committed at time of crash.
- Q: performance if DB doesn't fit in NVRAM?

# **Capability-based addressing**

A capability is a protected name for an object.

- possession is necessary and sufficient for access
- supplied by system and must be unforgeable
- can be manipulated in a defined and restricted set of ways (e.g. passed as param, refined, etc)

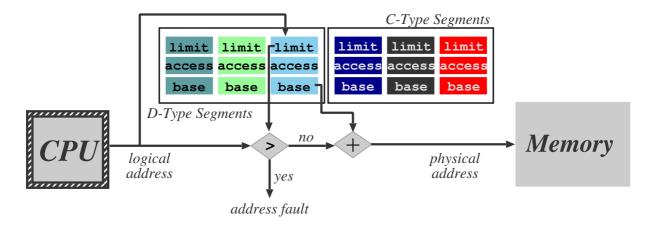
Can implement in software (crypto) or in hardware.

# The Cambridge CAP Computer

Developed here starting in 1970 (Needham, Wilkes, Wheeler, Richards, Moody, Johnson, Herbert, . . . )

- Recognises need for hardware memory protection on a fine grained level.
- The CAP controlled what can be written to registers, not who can write to them.
- Base-limit registers and their contents become capability registers and capabilities
- A capability consists of three values:
  - base, limit and access code

# **Capability Architectures**



- Protection relies on unforgeable capabilities
  - data (and code) are stored in different segment type from capabilities
  - D-type (data-type) segments: words may be transferred to/from arithmetic registers
  - C-type (capability-type) segments: words may be transferred to/from capability registers
- Need some highly trusted system procedure with both C- and D-type capability for same segment
- Also need way to load capabilities into registers:
  - e.g. Plessey system 250 had explicit instructions
  - by contrast, in CAP, loading is implicit whenever a capability is referred to (c/f TLB)

# Control of Privilege in the CAP

- In conventional systems, all control lies with OS designer (i.e. coarse grained)
- Rings of protection: more flexible as long as OS remains at the centre of the set of rings
- CAP: no problem with giving access to facilities to a subsystem designer which are identical to those used by main system
- Nothing hierarchical about capabilities
- Note that hierarchies are useful in organisation of flow of control, but are unnecessarily restrictive for protection

# **Analogy with Structured Programming**

- The CAP is to hardware what scoping is to programming
- Further advantages are being able to more easily debug programs and even to prove correctness!

#### **Domains of Protection**

- This is the set of capabilities to which a process has access (i.e. can cause to be loaded into the capability registers)
- Special instruction needed to change domain of protection (ENTER)
- Need to be careful when leaving a protection domain – cannot leave capabilities lying about in capability registers
- ENTER and RETURN give rise to a hierarchy of control but not of protection

#### **Protection of Processes**

- Necessary to support multiprogramming
- Also need to give one process privileges which differ from another – define a protection environment for process
- "Kernel" (co-ordinator) ENTERs user process;
   control RETURNs on process trap, or interrupt
- Requires specific hardware support (in microcode)

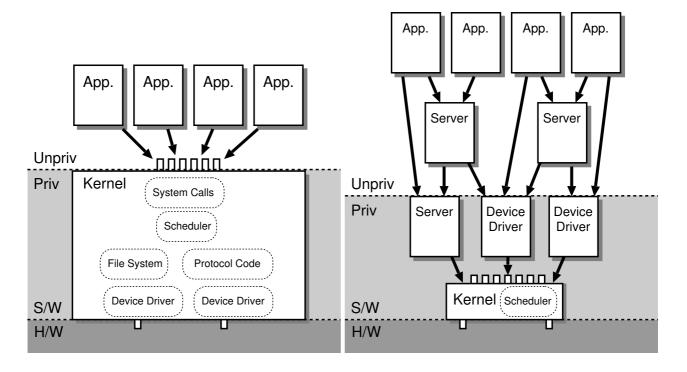
## **Relative Capabilities**

- Capabilities defined previously have a segement base which is an absolute address in memory;
- i.e. a capability selects subset of entire memory
- Relative Capabilites allow the base to be relative to the base of some other segment
- Now capability is:
  - (base, limit, access code, reference)
  - reference is { capability | whole memory }
- This allows us to evaluate a chain of references
- Furthermore, a process can now 'hand on' a subset of memory access privileges to its sub-processes
- In the CAP operating system:
  - "kernel" (co-ordinator) capabilities live in a segment called the  $master\ resource\ list\ (MRL)$
  - each process has  $process\ resource\ list\ (PRL)$  with capabilities relative to those in MRL
  - Can recurse. . .

# **Summary: The CAP & Capabilities**

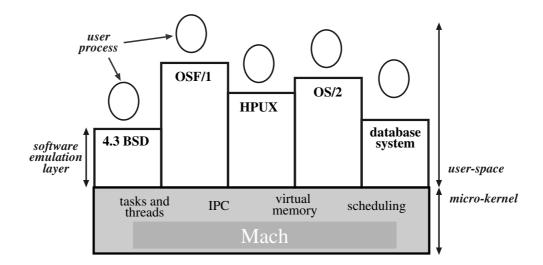
- The CAP was an architectural innovation and extremely successful – for details see the book
- Key features include:
  - Segment swapping.
  - Local naming.
  - Flexible control of sub-processes:
- CAP enforces high degree of modularity on programs ⇒ easy to modify OS and programs
- Minimum privilege: each process runs with minimum degree of required privileges
- Similar ideas used in Hydra (CMU), IBM System 38, Intel i432, CAP II/III
- But:
  - hardware complex and expensive
  - systems often slow in practice
  - and the killer: security vs. usability
- So although technically cool, capabilities and the CAP – didn't win (although see EROS later. . . )

# Microkernel Operating Systems



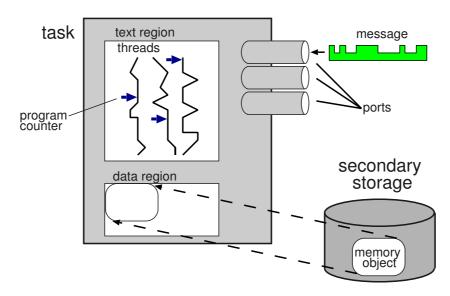
- New concept in early 1980's:
  - "kernel" scheme (Ihs) considered complex
  - $\Rightarrow$  try to simplify kernel, build modular system
  - support multiprocessors, distributed computing
- Re-engineered OS structure (*rhs*)
  - move functions to user-space servers
  - access servers via some interprocesscommunication (IPC) system
  - increase modularity  $\Rightarrow$  more robust, scalable. . .

#### The Mach Microkernel



- Mach developed at CMU (Rashid, Bershad, . . . )
- Evolved from BSD 4.2
- Provided compatibility with 4.3 BSD, OS/2, . . .
- Design goals:
  - support for diverse architectures, including multiprocessors (SMP, NUMA, NORMA)
  - scale across network speeds
  - distributed operation:
    - \* heterogeneous machine types
    - \* memory management & communications
- (NB: above diagram shows Mach 3.0)

#### **Mach Abstractions**



- Tasks & threads:
  - a task is an execution environment
  - a thread is the unit of execution
- IPC based on *ports* and *messages*:
  - port = generic reference to a 'resource'
  - implemented as buffered comms channels
  - messages are the unit of communication
    - $\Rightarrow$  IPC is message passing between threads
  - also get port sets (share a message queue)
- Also get *memory objects*:
  - memory object is a 'source' of memory
  - e.g. memory manager, or a file on a file server

# L3/L4: Making Microkernels Perform

- Perceived problems with microkernels:
  - many kernel crossings ⇒ expensive
  - e.g. Chen (SOSP'93) compared Mach to Ultrix:
    - \* worse locality (jumping in/out of Mach)
    - \* more large block copies
- Basic dilemma:
  - if too much in  $\mu$ -kernel, lose benefits (and microkernels often "grow" quite a bit)
  - if too little in  $\mu$ -kernel, too costly
- Liedtke (SOSP'95) claims that to fix you:
  - 1. minimise what should be in kernel
  - 2. make those primitives really fast.
- The L3 (and L4, SOSP'97) systems provided just:
  - recursive construction of address spaces
  - threads
  - IPC
  - unique identifier support
- (Cynical question: is this an operating system?)

# L3/L4 Design and Implementation

- Address spaces support by three primitives:
  - 1. Grant: give pages to another address space
  - 2. Map: share pages with another address space
  - 3. Flush: take back mapped or granted pages
- Threads execute with address space:
  - characterised by set of registers
  - $\mu$ -kernel manages thread $\leftrightarrow$ address space binding
- IPC is message passing between address spaces:
  - highly optimised for i486 (3 $\mu$ s vs Mach's 18 $\mu$ s)
  - interrupts handled as messages too
- Does it work? '97 paper getpid() comparison:

System	Time	Cycles
Linux	$1.68 \mu$ s	223
$L^4Linux$	$3.95 \mu$ s	526
MkLinux (Kernel)	$15.41 \mu$ s	2050
MkLinux (User)	$110.60 \mu$ s	14710

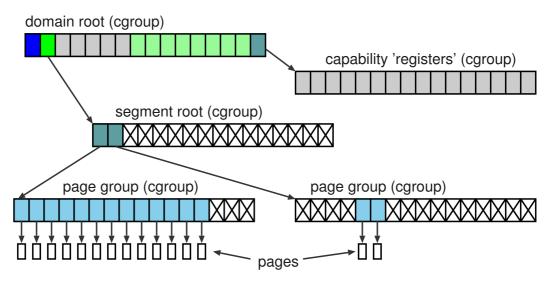
- Q: are these micro-benchmarks useful?
- Q: what about portability?

# **Extremely Reliable Operating System**

EROS: a persistent software capability microkernel.

- Why revisit capabilities?
  - reliability requires system decomposition
  - decomposition → access delegation (flexibility)
  - ability to restrict information and access right transmission (security, confinement)
  - access policy is a run time problem
  - persistence simplifies applications, improves I/O
  - 'active agent' (applet/servlet/cgi) confinement
  - mutually suspicious users
- But surely:
  - capabilities are slow ?
  - microkernels are (must be?) slow ?
  - capabilities can't support discretionary access control (just pass them on)?
  - capability systems are complex ?
- EROS set out to challenge the above. . .

# Software Capabilities in EROS



- Two disjoint "spaces" (as per CAP):
  - 1. data space
    - set of pages: each holds 4096 bytes
    - read and write data to/from data registers
  - 2. capability space:
    - set of cgroups: each holds 16 capabilities
    - read and write to/from capability registers
- Each capability is (type, oid, authority):
  - basic types are page, cgroup, number, schedule
  - complex types include segment and domain
- Segments correspond to address spaces.
- Domains correspond to processes.

# Making EROS Fast & Persistent

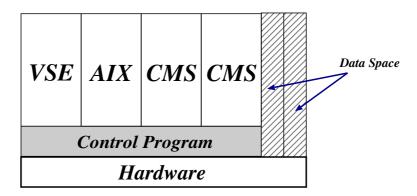
- Persistence achieved by flushing objects to disk:
  - circular log used for checkpointing
  - eventually log entries migrate to home location
- Before using capabilities, they must be *prepared* 
  - if necessary bring object referred to into memory
  - modify capability to point to object table
  - mark capability as prepared
- Only unprepared capabilities written to disk.
- Get run-time speed by caching a page-table representation of segment tree:
  - update on any write to segment tree
  - update if capabilities or pages paged out
- Fast capability-based IPC scheme:
  - invocation names capability to be invoked,
     operation code, four capabilities, and some data
  - call, return and send operations
  - threads migrate with call & return
  - hand-coded for L4-style speed

### **Virtual Machine Monitors**

Forget microkernels: take a different approach.

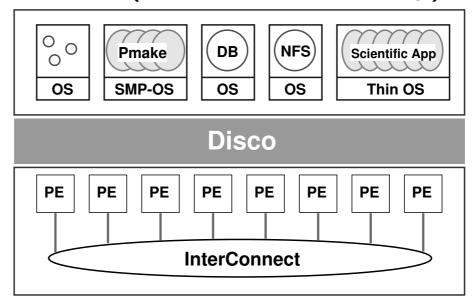
- Use a "hypervisor" (beyond supervisor, i.e. beyond a normal OS) to multiplex multiple OSes.
- (NB: hypervisor  $\equiv$  virtual machine monitor)
- Made popular by IBM's VM/CMS (1970's)
- Idea regained popularity in mid 90's:
  - e.g. Disco uses a VMM to make it easier to write operating systems for ccNUMA machines.
  - e.g. VMWare allows you to run Windows on Linux, or vice versa.
  - e.g. Denali lets you run 10,000 web servers
  - e.g. XenoServers allow you to run whatever you want, wherever you want.
- Virtual Machine Monitors somewhat similar to but not the same as the JVM (Java Virtual Machine)

# IBM's VM/CMS



- 60's: IBM researchers propose VM for System/360
- 70's: implemented on System/370
- 90's: VM/ESA for ES/9000
- Control program provides each OS with:
  - virtual console
  - virtual processor
  - virtual memory
  - virtual I/O devices
- Complete virtualisation: can even run another VM!
- Performance good since most instructions run direct on hardware.
- Success ascribed to extreme flexibility.

# **Disco (Stanford University)**



- Motivation: run commodity OS on ccNUMA:
  - existing commodity OS do badly on NUMA
  - tricky to modify them successfully
  - writing from scratch a lot of work
- Also hope to get:
  - fault tolerance between operating systems
  - ability to run special-purpose OSes
  - reasonable sharing between OSes
- OSes mostly unaware of VMM:
  - CPU looks like real MIPS R10000: privileged insts (including TLB fill) trap and are emulated.

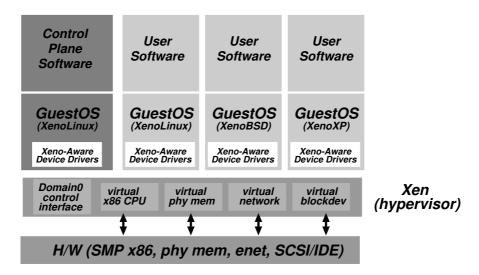
#### **VMWare**

- Startup founded 1998 by Stanford Disco dudes
- Basic idea: virtual machines for x86
- One major problem to overcome:
  - x86 not fully virtualizable: 17 instructions have different user/kernel semantics, but do not trap
  - ⇒ cannot emulate them!
- VMWare solution: perform binary rewriting to manually insert traps (extremely hairy)
- (explains why only certain guest OSes supported)
- "Physical" to machine address mapping realized by using shadow page tables.
- Second big problem: performance
  - no longer research prototype ⇒ must run at a reasonable speed
  - but no source code access to make small effective modifications (as with Disco)
- VMWare address this by writing special device drivers (e.g. display) and other low-level code

# Denali (Univ. Washington)

- Motivation: new application domains:
  - pushing dynamic content code to caches, CDNs
  - application layer routing (or peer-to-peer)
  - deploying measurement infstructures
- Use VMM as an isolation kernel
  - security isolation: no sharing across VMs
  - performance isolation: VMM supports fairness mechanisms (e.g. fair queueing and LRP on network path), static memory allocation
- Overall performance by para-virtualization
  - full x86 virtualization needs gory tricks
  - instead invent "new" x86-like ISA
  - write/rewrite OS to deal with this
- Work in progress:
  - Yakima isolation kernel based on Flux OSKit
  - Ilwaco single-user guest OS comprises user-space
     TCP/IP stack plus user-level threads package
  - No SMP, no protection, no disk, no QoS

# XenoServers (Cambridge)

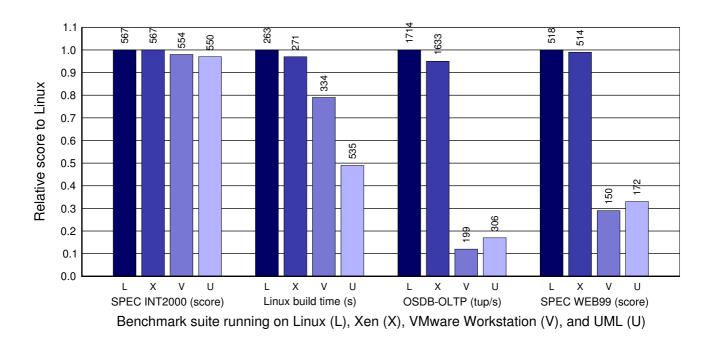


- Vision: XenoServers scattered across globe, usable by anyone to host services, applications, . . .
- Use Xen hypervisor to allow the running of arbitrary untrusted code (including OSes)
- Crucial insight:
  - use SRT techniques to guarantee resources in time and space, and then charge for them.
  - share and protect CPU, memory, network, disks
- Sidestep Denali of Service (DOS:-)
- Use paravirtualization, but real operating systems

### Xen Implementation

- Xen based on low-level parts of linux ⇒ don't need to rewrite 16-bit startup code.
- Includes device drivers for timers (IOAPICs), network cards, IDE & SCSI.
- Special guest OS (Domain 0) started at boot time:
  - special interface to Xen
  - create, suspend, resume or kill other domains
- Physical memory allocated at start-of-day:
  - guest uses buffered page-table updates to make changes or create new address spaces
  - aware of 'real' addresses ⇒ bit awkward
- Interrupts converted into *events*:
  - write to event queue in domain
  - domain 'sees' events only when activated
- Guest OSes run own scheduler off either virtual or real-time timer facility.
- Asynchronous queues used for network and disk

## Xen: Comparative Performance



- Attempt to measure overall system performance:
  - SPEC INT2000: CPU intensive, no OS
     ⇒ expect all systems to perform well
  - Linux build: more  $I/O \Rightarrow$  potentially larger hit
  - Final pair (DB workload, Web workload) exercise all parts of OS  $\Rightarrow$  can get huge overhead
- Ongoing work in migration, I/O, . . .
- More info from http://www.cl.cam.ac.uk/xeno/xen

### **VMMs:** Conclusions

- Old technique having recent resurgence:
  - really just 1 VMM between 1970 and 1995
  - now at least 10 under development
- Why popular today?
  - OS static size small compared to memory
  - (sharing can reduce this anyhow)
  - security at OS level perceived to be weak
  - flexibility as desirable as ever
- Emerging applications:
  - Internet suspend-and-resume:
    - \* run all applications in virtual machine
    - \* at end of day, suspend VM to disk
    - \* copy to other site (e.g. conference) & resume
  - Multi-level secure systems
    - \* many people run VPN from home to work
    - \* but machine shared for personal use ⇒ risk of viruses, information leakage, etc
    - \* instead run VM with only VPN access
  - Data-center management & beyond. . .

## **Extensibility**

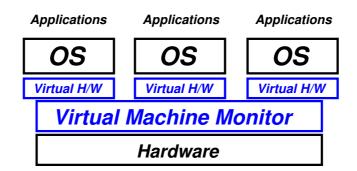
#### What's it about?

- Fixing mistakes.
- Supporting new features (or hardware).
- Efficiency, e.g.
  - packet filters
  - run-time specialisation
- Individualism, e.g.
  - per-process thread scheduling algorithms.
  - customizing replacement schemes.
  - avoiding "shadow paging" (DBMS).

### How can we do it?

- 1. give everyone their own machine.
- 2. allow people to modify the OS.
- 3. allow some of the OS to run outside.
- 4. reify separation between protection and abstraction.

### **Low-Level Techniques**



Have just seen one way to provide extensibility: give everyone their own [virtual] machine:

- Lowest level s/w provides
  - a) virtual hardware, and
  - b) some simple secure multiplexing.
    - $\Rightarrow$  get N pieces of h/w from one.
- ullet Then simply run OS on each of these N:
  - can pick and choose operating system.
  - users can even recompile and "reboot" OS without logging off!
  - Q: how big is a sensible value for N?
  - what about layer violations?
- Examples: VM, VMWare, Disco, XenoServers, . . .

# Kernel-Level Schemes (1)

Often don't require entirely new OS:

- Just want to replace/modify some small part.
- Allow portions of OS to be dynamically [un]loaded.
- e.g. Linux kernel modules
  - requires dynamic relocation and linking.
  - once loaded must register.
  - support for [un]loading on demand.
- e.g. NT/2K/XP services and device drivers
  - well-defined entry / exit routines.
  - can control load time & behaviour.
- However there are some problems, e.g.
  - requires clean [stable?] interfaces
  - specificity: usually rather indiscriminate.
- . . . and the big one: security.
  - who can you trust?
  - who do you rate?

# Kernel-Level Schemes (2)

Various schemes exist to avoid security problems:

- Various basic techniques:
  - Trusted compiler [or CA] + digital signature.
  - Proof carrying code
  - Sandboxing:
    - \* limit [absolute] memory references to per-module [software] segments.
    - \* use trampolines for other memory references.
    - \* may also check for certain instructions.
- e.g. SPIN (U. Washington)
  - based around Modula-3 & trusted compiler
  - allows "handlers" for any event.
- Still problems with dynamic behaviour (consider handler while(1);) ⇒ need more.
- e.g. Vino (Harvard)
  - uses "grafts" = sandboxed C/C++ code.
  - timeouts protect CPU hoarding.
  - in addition supports per-graft resource limits and transactional "undo" facility.

# **Proof Carrying Code (PCC)**

- Take code, *check it*, and run iff checker says it's ok.
- "Ok" means cannot read, write or execute outside some logical fault domain (subset of kernel VAS)
- Problem: how do we check the code?
  - generating proof on fly tricky + time-consuming.
  - and anyway termination not really provable
- So expect proof *supplied* and just check proof.
- Overall can get very complex, e.g. need:
  - formal specification language for safety policy
  - formal semantics of language for untrusted code
  - language for expressing proofs (e.g. LF)
  - algorithm for validating proofs
  - method for generating safety proofs
- Possible though, see e.g.
  - Necula & Lee, Safe Kernel Extensions without Run-time Checking, OSDI 1996
  - Necula, Proof Carring Code, PPOPL 1997
  - SafetyNet Project (Univ. Sussex)

## Sandboxing

- PCC needs a lot of theory and a lot of work
- Sandboxing takes a more direct approach:
  - take untrusted code as input
  - transform it to make it safe
  - run transformed code
- E.g. Software Fault Isolation (SFI, Wahbe et al)
  - Assume logical fault domain once more
  - Scan code and look for memory accesses
  - Insert instructions to perform bounds checking:

```
cmp r1, $0x4000; blt fault; ldr r0, [r1] \rightarrow cmp r1, $0x5000; bgt fault; ldr r0, [r1]
```

Better if restrict and align LFD:

```
bic r1, $0x03ff; ldr r0, [r1] \rightarrow cmp r1, $0x4000; bne fault; ldr r0, [r1]
```

- Can handle indirect jumps similarly.
- Problem: ret, int, variable length instructions, . . .
- Problem: code expansion
  - Trusted optimizing compiler?

## The SPIN Operating System

- Allow extensions to be downloaded into kernel.
- Want performance comparable with procedure call
   ⇒ use language level (compiler checked) safety:
- SPIN kernel written (mostly) in Modula-3
  - Type-safe, and supports strong interfaces & automatic memory managent.
  - (some low-level kernel stuff in C/assembly)
- Kernel resources referenced by capabilities
  - capability = unforgeable reference to a resource
  - in SPIN, capabilities are Modula-3 pointers
  - protection domain is enforced by language name space (not virtual addressing)
- Extensions somewhat ungeneral:
  - define events and handlers
  - applications register handlers for specific events
  - e.g. handler for "select a runnable thread"
  - what about unforseen needs?
- Problems: trusted compiler, locks, termination. . .

## The VINO Operating System

Set out to overcome perceived problems with SPIN

- Download *grafts* into kernel.
- Grafts written in C or C++
  - free access to most kernel interfaces
  - safety acheived by SFI (sandboxing)
  - (must use trusted compiler)
- Prevent quantitative resource abuse (e.g. memory hogging) by resource quotas and accounting
- Prevent resource starvation by timeouts
  - grafts must be preemptible ⇒ kernel threads
  - decide "experimentally" how long graft can hold certain resources (locks, ipl (?), cpu (?))
  - if graft exceeds limits, terminate.
- Safe graft termination "assured" by transactions:
  - wrapper functions around grafts
  - all access to kernel data via accessors
  - two-phase locking + in-memory undo stack

### **User-Level Schemes**

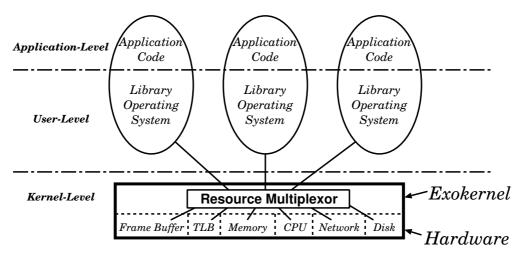
Kernel-level schemes can get very complex  $\Rightarrow$  avoid complexity by putting extensions in user-space:

- e.g.  $\mu$ -kernels + IDL (Mach, Spring)
- still need to handle timeouts / resource hoarding.

Alternatively reconsider split between protection and abstraction: only former need be trusted.

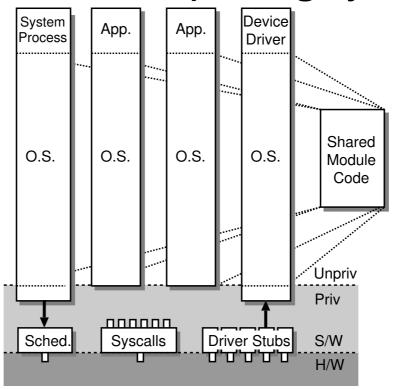
- e.g. Exokernel:
  - run most of OS in user-space library.
  - leverage DSL/packet filters for customization.
  - can get into a mess (e.g. UDFs).
- e.g. Nemesis:
  - guarantee each application share of physical resources in both space and time.
  - use IDL to allow user-space extensibility.
  - still requires careful design. . .
- Is this the ultimate solution?

### The Exokernel



- Separate concepts of protection and abstraction  $\Rightarrow$  get extensibility, accountability & performance.
- Why are abstractions bad?
  - deny application-specific optimizations
  - discourage innovation
  - impose mandatory costs
- Still need some "downloading":
  - describe packets you wish to receive using DPF;
     exokernel compiles to fast, unsafe, machine code
  - Untrusted Deterministic Functions (UDFs) allow exokernel to sanity check block allocations.
- Lots of cheezy performance hacks (e.g. Cheetah)

## The Nemesis Operating System



- Design to support soft real-time applications
  - isolation: explicit guarantees to applications
  - exposure: multiplex real resources
  - responsibility: applications must do data path
- Parallel development to exokernel:
  - similar overall structure (though leaner no device drivers, DPFs, UDFs, etc, in NTSC)
  - but: strongly typed IDL, module name space
  - but: "temporal protection" built in

## **Extensibility: Conclusions**

- Extensibility is a powerful tool.
- More than just a "performance hack"
  - Simplifies system monitoring.
  - Enables dynamic system tuning.
  - Provides potential for better system/application integration.
- Operating system extensibility is a good design paradigm for the future:
  - Allow extensible applications to take advantage
  - Do operating system modifications "on-the-fly"
- Lots of ways to achieve it:
  - virtual machine monitors (everyone gets own operating system)
  - downloading untrusted code (and checking it?)
  - punting things to user space (fingers crossed)
  - pushing protection boundary to rock bottom

### **Database Storage**

- Recall relational databases from Part IB
- Why not just store relations and directories in ASCII format in standard files, e.g.

#### Store relation R1 in /usr/db/R1

#### Store directory file in /usr/db/directory

```
Moody # 123 # CUCL
Kelly # 231 # DPMMS
Bacon # 432 # CUCL
.....
```

```
R1# Name #STR #Id #INT # Dept#STR
R2# Id#INT #CRSId#STR
.....
```

- To do select \* from R where condition:
  - read directory to get R attributes
  - for each line in file containing R:
    - \* check condition
    - \* if OK, display line
- To do select \* from R,S where condition:
  - read directory to get R, S attributes
  - read file containing R, for each line:
    - \* for each line in file containing S
      - · create join tuple
      - check condition
      - · display if OK

## What's Wrong with This?

- Tuple layout on disk
  - change 'Bacon' to 'Ham' ⇒ must rewrite file
  - ASCII storage expensive
  - deletions expensive
- Search expensive no indexes
  - cannot quickly find tuple with key
  - always have to read entire relation
- Brute force query processing
  - select \* from R,S where R.A = S.A and S.B > 10
  - do select first? more efficient join?
- No reliability
  - can lose data
  - can leave operations half done
- No security
  - file-system is insecure
  - file-system security is coarse
- No buffer management, no concurrency control

## **Disk Storage Issues**

- What block size?
  - large blocks  $\Rightarrow$  amortise I/O costs
  - but large blocks mean may read in more useless stuff, and read itself takes longer.
- Need efficient use of disk
  - e.g. sorting data on disk (external sorting)
  - I/O costs likely to dominate
    - $\Rightarrow$  design algorithms to reduce I/O
- Need to maximise concurrency
  - e.g. use (at least) double buffering
  - more generally, use asynchronous I/O and a database-specific buffer manager
  - care needed with replacement strategy
- Need to improve reliability
  - need to deal with failures mid transaction
     ⇒ use write-ahead log
  - recall transactions from Part IB CSAA

## Representing Records

- Record = collection of related data ("fields"):
  - can be fixed or variable format
  - can be fixed or variable length
- Fixed format  $\Rightarrow$  use schema:
  - schema holds #fields, types, order, meaning
  - records interpretable only using schema
  - e.g. fixed format and length

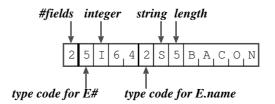
#### Employee Record (Schema)

E#, 2 byte integer
E.name, 10 char
Dept, 2 byte code

#### Actual Employee Records

64	В	А	С	0	Ν		ı	ı	ı	02
77	В	Ι	Ε	R	М	Α	N	J <sub>L</sub>	_	02

- Variable format  $\Rightarrow$  record "self describing".
  - e.g. variable format and length



- More generally get hybrid schemes
  - e.g. record header with schema id, length
  - e.g. fixed record with variable suffix

## Storing Records in Blocks

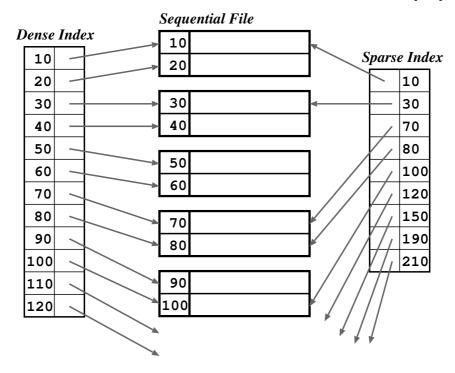
- Ultimately storage device provided blocks
- Could store records directly in blocks:

#### Fixed Size Disk Block



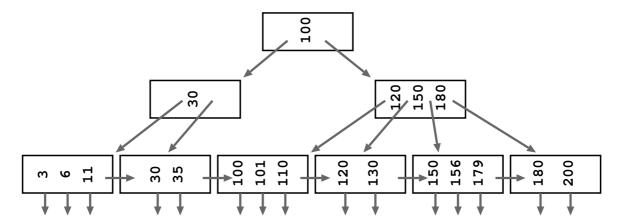
- fixed size recs: no need to separate
- variable length ⇒ separation marker?
- better: offsets in block header
- What about spanning multiple blocks?
  - may need if variable length record grows
  - certainly need if |record| > |block|
  - can impl with pointers at end of blocks
- Should we mix record types within a block?
  - clustering benefit for related records
  - usually too messy  $\Rightarrow$  just co-locate
- In which order should we store records?
  - often want sequential within block (and 'file')
  - (makes e.g. merge-join easier)

# Efficient Record Retrieval (1)



- Assume have sequential file ordered by key.
- Can build dense or sprase index:
  - sparse: smaller  $\Rightarrow$  more of index in memory
  - dense: existence check without accessing fils
  - sparse better for inserts
  - dense needed for secondary indexes
  - multi-level sparse also possible
- Can use block pointers (< record pointers)</li>
- If file actually contiguous, can omit!
- But: insertions and deletions get messy. . .

# **Efficient Record Retrieval (2)**



- Eschew sequentiality focus on balance
- Good example is a B+-Tree
  - All nodes have n keys and n+1 pointers
  - In non-leaf nodes, each pointer points to nodes with key values < right key,  $\ge$  left key
  - In leaves, point direct to record (or across)
- Balanced tree (i.e. all leaves same depth):
  - keep  $\geq \lceil (n+1)/2 \rceil$  in non-leaves
  - keep  $\geq \lfloor (n+1)/2 \rfloor$  data pointers in leaves
- Search is easy and fast:
  - binary search at each level  $O(\log(n))$
  - with N records, height  $\log_n N$

### More on B+-Trees

- Insertion fairly straightforward:
  - space in leaf  $\Rightarrow$  sorted
  - if no space somewhere  $\Rightarrow$  split
  - if root split ⇒ new root (and new height)
- Deletion a bit hairy:
  - if min bounds not violated ⇒ easy
  - otherwise need to either:
    - \* redistribute keys (and propagate upward), or
    - \* coalesce siblings
  - many implementation don't coalesce. . .
- Buffering: is LRU a good idea?
  - No! Keep root (and higher levels) in memory
- Can we do better?
  - also get B-Tree: avoid key duplication
  - i.e. interior nodes also point to records
  - smaller, & faster lookup (at least in theory)
  - but: deletion even more difficult
  - but: leaf and non-leaf nodes different sizes

# **Aside: Spatial Indexes**

- Spatial data pertains to the space occupied by objects (e.g. points, lines, surfaces, volumes)
- Real life: roads, cities, countries, internet
- Challenging for conventional DBMS:
  - inherently highly dimensional (and may be continuous) ⇒ cannot simply store as relation.
  - want to express spatial queries (e.g. close to, encompasses, intersects)
- How can we index such data?
  - B-tree cannot handle high dimensionality
  - hashing cannot handle range queries
- Two main approaches:
  - balanced trees in spatial occupancy (R-trees)
  - multi-dimensional ∼hashing (grid files)
- Detailed discussion beyond scope of this course;
   see papers on web page for more info.

### **Postgres DBMS**

- Postgres: developed at UCB between 1989 19991
- Postgres motivation:
  - Old DBMS data management only (fixed format records, traditional transactions & queries)
  - New need for 'object' management (bitmaps, vector graphics, free text, etc)
  - e.g. CAD, general knowledge management
- Postgres used set-oriented Postquel:
  - small number of concepts ⇒ simple for users
  - embedded directly in programming language.
- variable persistence, standard control flowbig memory footprint
- Handles base types, ADTs, composite types, complex objects, and path expressions
- Used some novel techniques in backend design and implementation.

### **Postgres Implementation**

- Every previous system used a write-ahead log
- Postgres wanted to do something different:
  - "no-overwrite" storage manager
  - i.e. leave old version of record in data base
  - 'log' now just 2-bits per transaction stating if in progress, committed, or aborted
- Benefits of this approach:
  - abort is very cheap (nothing to undo)
  - recovery is very cheap (same reason)
  - "time-travel": support historic queries
- But there are a few (!) problems:
  - must flush new records to disk on commit
  - may need multiple indices (or R-trees?)
  - disk fills up  $\Rightarrow$  flush to write-once media
  - but 'cleaner' didn't run under load :-(
  - time travel queries hard to express
- 1995 saw Postgresql (SQL version):
  - some improvements to storage manager
  - free and useful system for small databases

# **Operating Systems and Databases (1)**

OSes not suited to DBMS (Stonebraker CACM '81):

- Extra data copies to/from disk
- Buffer replacement:
  - most OSes use LRU but DBMS accesses are:
    - 1. sequential access to blocks without re-reference (build hash table, sort)
    - 2. sequential access to blocks with cyclic reference (inner loop of nested join)
      - this kills LRU
    - 3. random access to blocks without re-reference (should discard immediately)
    - 4. random access to blocks with non-zero probability of re-reference
  - only case 4. works ok with LRU
  - but DBMS knows all of this
- (similar arguments apply to prefetching)
- No support for synchronous reorder barriers
- ⇒ DBMSes end up doing their own buffer pool management in user space

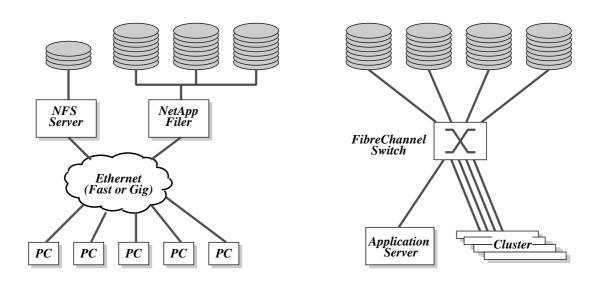
# **Operating Systems and Databases (2)**

- Problems with user-space buffer management:
  - want extents, not variable byte-length files
  - buffer pool in virtual memory ⇒ poss poor interaction with VM system ("double paging")
- Other problems noted in paper:
  - multiple trees (directory, inode, B-trees) wasteful
  - multi-process DBMS can suffer from priority inversion if have user-space locks in DBMS
  - but single process DBMS more complex and cannot benefit from multiprocessors.
- Stonebraker suggests OS accept 'hint' from DBMS
- So where have we got in 20+ years?
  - Not very far. . .
  - Some OS give DBMS raw disk/partition access
  - NTFS directly supports [infinite] write-ahead log.
  - Some extensibility research in this area (e.g. page-replacement or buffer cache callbacks)
- Overall: still serious engineering effort to get good DBMS perf without tight OS integration.

## **Distributed Storage**

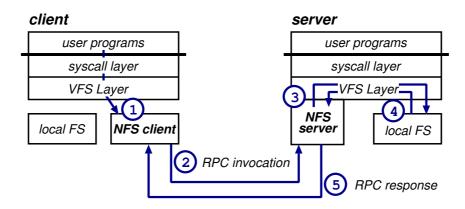
- Filesystems/DBMS want big, fast, reliable disks.
- Cheaply achieve this using multiple disks, e.g.
  - RAID = Redundant Array of Inexpensive Disks
  - better performance through striping
  - more reliable via redundancy:
    - \* simple mirroring
    - \* generalised parity (Reed-Solomon)
    - \* variable length erasure codes (IDA)
  - key benefits: scalability, fault tolerance
- Even better: make storage distributed i.e. separate data management from apps / servers
- Why is this a good idea?
  - centralised data management
  - even more scalability
  - location fault tolerance
  - mobility (for access)
- What are the options here?

### NAS versus SAN



- Two basic architectures:
  - Ihs: Network Attached Storage (NAS)
  - rhs: Storage Area Networks (SANs)
- NAS distributes storage at the FS/DB level:
  - runs over TCP/IP (or NetBIOS) network
  - exports NFS, CIFS, SQL, . . .
- ullet SAN distributes storage at the block level:
  - runs over fibre channel
  - accessed via encapsulated SCSI
  - filesystem/DBMS run on hosts
- NAS better general purpose, SAN more specialised

## **Network File-Systems**



- NAS normally accessed by network file-system:
  - client-server (e.g. NFS, SMB/CIFS, etc)
  - mostly RPC-based at some level
- NFS originally (V2, 1989) designed to be stateless:
  - no record of clients or open files
  - no implicit arguments to requests
  - no write-back caching on server
  - requests idempotent where possible
  - only hard state is on [server] local filesystem
- Statelessness good for recovery, but:
  - synchronous disk write on server sucks
  - cannot help client caching
- More recent NFS versions are an improvement. . .

### **NFS** Evolution

NFS V3 (1995) brings mostly minor enhancements:

- scalability:
  - remove limits on path and file name lengths,
  - support 64-bit file offsets
  - allow large (>8KB) transfer size negotiation
- explict asynchrony:
  - server can do asynchronous writes
  - client sends commit after some # of writes;
     must keep cached copy until successful commit
- enhanced operations (symlink, readdirplus)

NFS V4 (RFC3530, April 2003) a major rethink:

- single, **stateful** protocol (including mount, lock)
- TCP or at least reliable transport only
- explicit open and close operations
- share reservations (file level revocable 'locks')
- delegation (sever gives client revocable autonomy)
- arbitrary compound operations

Actual success yet to be seen. . .

### **AFS** and Coda

- AFS (1983+) developed concurrently with NFS:
  - purely remote: even local access via client
  - persistent client caching with delegation on a directory basis through callbacks
  - increment file version # on every change
  - live replication and relocation of volumes
- Free 'OpenAFS' implementation available.
- Coda (1987+):
  - descendant of AFS (based on AFS2)
  - support for disconnected operation
  - Venus cache manager operates in 1 of 3 modes:
    - \* *hoarding*: when connected tries to cache copies of "working set" for user
    - \* *emulating*: when disconnected, services what it can and notes any updates in LRVM
    - \* reintegrating: when reconnected, performs (assisted) conflict resolution
- Extensions to Coda support weakly connected –
   e.g. wireless operation (Satya et al, SOSP 95)

### LBFS: An Alternative for Wide Area

LBFS (SOSP 01) addresses network file system access over low-bandwidth (wide area, wireless) networks.

- more and more people have laptops
- remote CIFS or NFS (even V4) pretty suckful
- key idea: aggressive compression on wire/air.

How can we compress an order of magnitude better?

- don't just look at individual blocks / files
- maintain persistent cache on client
- ⇒ huge amount of shared information!

In a bit more detail:

- server divides its files into chunks, and for each chunk computes a secure (SHA-1) hash
- client does the same
- if e.g. client wants to write a (portion of) a file, actually just transfers hashes for relevant chunks
- if server already has chunks, can avoid transfer; replies requesting missing chunks (if any)
- reads proceed in an similar fashion

## LBFS: Exploiting Inter-File Similarities

- As described, LBFS clearly going to work, but performance gains may not be huge:
  - e.g. consider edits in place
  - e.g. consider fetch of file never seen before
- So here's the clever bit:
  - file chunk boundaries chosen based on contents
  - compute Rabin fingerprint over every overlapping 48-byte region of every file
  - if low-order 13 bits match a magic value, deem this to be a chunk boundary
  - assuming uniformity, expected chunk size is 8K
  - use low (2K) and high (64K) thresholds to deal with pathological cases
- Now we get 'hits' if contents appear anywhere in any file that we know about
- Tested on fairly realistic workloads:
  - up to 20% redundancy between unrelated files
  - LBFS 10x better than NFS / CIFS / AFS
- Q: what about hash collisions?

# Serverless File-Systems

- Modern trend towards serverless file-systems:
  - no discrimnated "server"
  - all nodes hold some data
  - (think P2P in the local area)
- e.g. xFS (Berkeley):
  - have clients, cleaners, managers, storage servers
  - any machine can be [almost] any subset of above
  - to read file:
    - \* lookup manager in globally-replicated map
    - \* contact manager with request
    - \* manager redirects to cache or disk (imap)
  - to write file:
    - \* obtain write token from manager
    - st append all changes to log
    - st when hit threshhold, flush to  $stripe\ group$
- xFS approx 10x better than NFS. Why?
  - co-operative caching
  - parallelism via software RAID (striping)
  - avoid read-modify-write by using log-structure
  - managers replicated for fault tolerance

# JetFile: Serverless Internet Storage

- The Jetfile distributed FS (OSDI 99) aimed to:
  - support shared personal file access in heterogeneous Internet (LAN and WAN)
  - provide approx performance of local file system
- Basic implementation:
  - uses scalable reliable multicast (SRM):
    - \* receiver driven: multicast request for data, receive (hopefully!) 1 or few responses.
    - \* version numbers on all data ⇒ receiver can retry to guarantee eventual delivery
  - files named by (org, vol, fileID, version):
    - \* hash first three to get file address
    - \* to retrieve file first multicast data\_request
    - \* pick reponse and use unicast for remainder.
  - updates handled by versioning
    - \* write-on-close semantics (bumps version)
    - \* client now 'server' for new version
    - \* explicit version requests, plus "current table" multicast over per-volume channel
- Overall: approx local FS (if warm cache. . . )

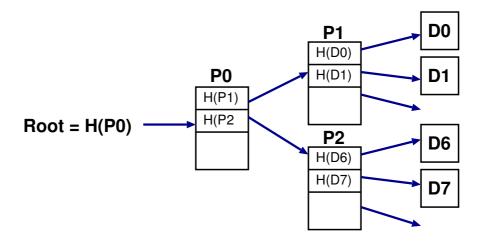
## File-systems for SANs

- Recall: SAN has pool of disks accessed via iSCSI
- With multiple clients ⇒ need coordination
- Two ways to build a shared disk file system (SDFS)
  - 1. asymmetric: add a metadata manager:
    - exclusive access to metadata disk[s]
    - clients access data disks directly
  - 2. symmetric:
    - clients access data and metadata directly
    - distributed locking used for synchronisation
- Asymmetric simpler, but less scalable/fault-tolerant
- Symmetric systems becoming mature:
  - e.g. GFS, open source project for linux
  - bottom half: network storage pool driver:
    - \* combines all disks into single 'address space'
    - \* supports striping for performance/reliability
  - top half: file-system
    - \* almost standard unix structure (inodes, etc)
    - \* device locks and global locks for synch
- NASD work (CMU) tries to make SDFS easier. . .

### **Network Attached Secure Disks**

- Basic idea: a less stupid SAN.
- Still have network attached disks, but:
  - disks export variable-length object interface:
    - \* create, read, write, etc
    - \* can use to store e.g. files or DBMS tables
    - \* disk manages block allocation and layout
  - integrity/privacy available on transfers
  - access checks on disk:
    - \* disk and file manager share secret key
    - st after file-system-specific checks, file manager issues derived capabilities to clients
    - ⇒ clients can securely access disk directly.
- Middle ground between regular 'dumb' network attached disks and network file systems
- Advantages:
  - data path operations fast and secure
  - offloads work from file manager: e.g. NFS server using NASD requires 10x CPU cycles.
  - multiple NASDs can be accessed in parallel
- But: less allocation control, key mgt, enoexist

## Venti: Distributed Archival Storage



- Archival storage typically on tape / optical
- Venti (FAST 02) considers using magnetic disk:
  - cheap, ubiquitous, fast
  - but: subject to overwrite. . .
- ullet So use software to provide immutable storage
  - every file update a new version
  - c/f Plan-9 in lb, Elephant (SOSP 99)
  - but: what about directories?
- Key idea: use content hashes to access everything
  - file contents are a set of blocks
  - inode is table/tree of block content hashes
  - directories map names to inode content hashes

# Venti (Continued)

- Gives you some nice properties:
  - if e.g. a file changes in leaf directory, then some or all its block hashes change ⇒ inode changes
  - hence inode content hash changes, and so some directory block(s) change
  - and so on all the way up the tree
- So root hash uniquely captures filesystem snapshot!
- Same applies to arbitrary subdir: can build a very cheap 'tar' replacement (just store hash in text file)
- Not without design/implementation challenges:
  - all addressing now via hashes ⇒ need some way to map from hash to actual block location
  - Venti uses log-based (append-only) storage:
    - \* store blocks sequentially in an arena, each with a header including its fingerprint (hash)
    - \* trailer on arena points back to blocks
    - \* simple, but doesn't help with hash search
    - ⇒ build index to map hashes to block headers
  - index can be a bottleneck, so also add a index cache plus a regular block cache

# **Summary & Outlook**

We've seen a selection of systems topics:

- Distributed and persistent virtual memory
- Capability systems
- Microkernels (Mach, L3/L4, [EROS])
- Virtual machine monitors (VM/CVS, Disco, VMWare, Denali, Xen)
- Extensible operating systems (SPIN, Vino, Exokernel, Nemesis)
- Database storage & retrieval (issues, consistency, records, blocks, indices, Postgres, OS issues)
- Distributed storage and filesystems (NAS, SANs, NFS, LBFS, xFS, NASD, etc)

Lots more research ongoing in most of above areas.

Next section of course: scalable synchronization.