Privacy-preserving datagram delivery for ubiquitous systems

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May 21, 2008
Outline

1. Introduction

2. Our approach

3. Evaluation

4. Conclusions
1. Introduction
The Problem

- Many useful ubiquitous (and transport) applications are context-aware
- Context-aware applications build models of the world
- These models contain information about people
- People worry about... 
  - Where this information is stored
  - Who gets to see it
  - How it is used
Datagrams Are Desirable

- Defer retransmission strategy to applications
- Applications with sensors have to handle missing data anyway
- Improved privacy properties compared to streams
Anonymous Datagrams

- Lots of work on anonymous comms (Mixminion, I2P, Tor, …)
- Work supports either high latency (for, e.g., email) or TCP or is written by d00dz (I2P)
- Goal: build a real (albeit toy) anonymous datagram service and evaluate its performance
2. Our approach
What We Did

- Modified Tor to support UDP
- Only ingress and egress nodes need modification
- Intermediate nodes can’t tell whether they are forwarding UDP or TCP traffic
A SOCKS Primer

1. Application requests a *datagram association*
2. Server evaluates the request and responds
3. Application sends its first datagram
4. Server sets up state to forward the datagram and any replies
5. Application tears down the association
Tor Terminology

Circuit  A path through the overlay network from ingress to egress nodes
Stream   The state an ingress node needs to forward data
UDP With Tor

- Beefed up SOCKS support to handle UDP
- Map each datagram association to a “pseudo-stream”
- Use the forwarding internals without change
Tor’s Congestion Control

- Aims to protect both the underlying and overlay networks
- Uses transmission windows per stream and per circuit
- Drop datagrams if the circuit window would close
- No congestion control of pseudo-streams
3. Evaluation
Request-response time

Mean = 5681 µs
Request-response time

Mean = 124.9 µs
Percentage packet loss

![Graph showing the relationship between percentage of datagrams lost and inter-datagram delay (μs). The x-axis represents inter-datagram delay in microseconds, ranging from 0 to 400. The y-axis represents the percentage of datagrams lost, ranging from 0 to 80. The graph includes data points indicated by '±' symbols, with error bars showing variability. The general trend shows a decrease in the percentage of datagrams lost as the inter-datagram delay increases.]
One-way delay, replication one
One-way delay, replication two
One-way delay, replication three
One-way delay, replication three
4. Conclusions
Contributions

- Argued that anonymous datagrams are useful for a spectrum of ubiquitous applications
- Provided and evaluated a toy implementation that is incrementally deployable
- Illustrated that the cost may not be all that high
- A more clever solution would have to be justified
The Future

- Better implementation (improved administration, *etc.*)
- Better guarantees that datagrams are good citizens
- Use of non-interactive key exchange protocols for circuit building
- Incorporation into TIME