

13th International Conference on Relational and Algebraic Methods in Computer Science (RAMiCS 13)

Relation Algebras, Matrices, and Multi-Valued Decision Diagrams

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13th International Conference on Relational and Algebraic Methods in Computer Science
(RAMiCS 13)

September 20, 2012

Presentation Outline

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Problems and Motivations

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Summary And Conclusion

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Concrete Relation Algebra

Definition

A concrete relation R between two sets A and B is a subset of the Cartesian product $A \times B$, where

$$A \times B = \{(a, b) : a \in A, b \in B\}$$

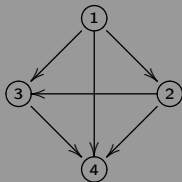
[3] [1]

Example

Let $A = \{1, 2, 3, 4\}$ and let R be a relation defined on A such that $R = \{(a, b) \mid a < b\}$, then the relation can be visualized as set given by:

$R = \{(1, 2), (1, 3), (1, 4), (2, 3), (2, 4), (3, 4)\}$.

R can also be visualized as a graph, a table or a boolean matrix as shown in the figures below:



R	1	2	3	4
1		x	x	x
2			x	x
3				x
4				

$$\begin{array}{c}
 1 \ 2 \ 3 \ 4 \\
 \begin{pmatrix}
 1 & (0 & 1 & 1 & 1) \\
 2 & (0 & 0 & 1 & 1) \\
 3 & (0 & 0 & 0 & 1) \\
 4 & (0 & 0 & 0 & 0)
 \end{pmatrix}
 \end{array}$$

RelView System

"RELVIEW, developed in Kiel (formerly in Munich). RELVIEW is an interactive tool for computer-supported manipulation of relations represented as Boolean matrices or directed graphs, especially for prototyping relational specifications and programs " [2].

- ▶ RELVIEW implements relation in the form of boolean matrices using Ordered Binary Decision Diagrams (OBDDs).
- ▶ OBDDs are an efficient data structure used to implement very large Boolean functions.
- ▶ The first versions of RELVIEW were implemented using only arrays.
- ▶ A BDD is a directed acyclic graph (DAG) with decision nodes and two terminal nodes (0 and 1). Each decision node is labeled by a Boolean variable and has two child nodes (low child and high child).
- ▶ A BDD is called 'ordered' if different variables appear in the same order on all paths from the root to the leaf node. A BDD is said to be 'reduced' if there is no isomorphic subgraphs .

Heterogeneous relation algebras

A variant of the theory of relation which originated from category theory is called heterogeneous relation algebras. In this approach, relations have different source and target.

Definition

A (heterogeneous abstract) relation algebra is a locally small category \mathcal{R} consisting of a class $Obj_{\mathcal{R}}$ of objects and a set $\mathcal{R}[A, B]$ of morphisms for all $A, B \in Obj_{\mathcal{R}}$. The morphisms are usually called relations. Composition is denoted by “;”, identities are denoted by $\mathbb{I} \in \mathcal{R}[A, B]$, conversion

$\smile_{AB}: \mathcal{R}[A, B] \rightarrow \mathcal{R}[B, A]$

The operations satisfy the following rules:

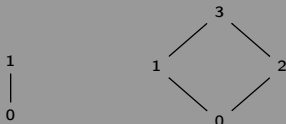
1. Every set $\mathcal{R}[A, B]$ carries the structure of a complete atomic boolean algebra with operations, \sqcup_{AB} , \sqcap_{AB} , \overline{AB} , zero element \perp_{AB} , universal element \top_{AB} , and inclusion ordering \subseteq_{AB} .
2. The Schröder equivalences

$$Q; R \subseteq_{AC} S \iff Q \smile; \overline{S} \subseteq_{BC} \overline{R} \iff \overline{S}; R \smile \subseteq_{AB} \overline{Q}$$

holds for all relations $Q: A \rightarrow B$, $R: B \rightarrow C$ and $S: A \rightarrow C$.

Example of Heterogeneous Relation Algebras

- Two Boolean algebra \mathcal{L}_2 and \mathcal{L}_4 with 2 and 4 elements.



▶

Identity	
A	1
B	1

Bottom	
A, A	0
B, B	0
B, A	0
A, B	0

Top	
A, A	3
B, B	3
B, A	1
A, B	1

- Similarly, we can produce the tables for meet, composition, converse and complement.

- Union Operation

A, B	0	1
0	0	1
1	1	1

B, A	0	1
0	0	1
1	1	1

A, A	0	1	2	3
0	0	1	2	3
1	1	1	3	3
2	0	3	2	3
3	3	3	3	3

B, B	0	1	2	3
0	0	1	2	3
1	1	1	3	3
2	0	3	2	3
3	3	3	3	3

Problems and Motivations

1. Splittings exist in matrix algebras
2. Standard and Non-Standard models of relation algebras
 - ▶ (Point axiom) For every relation $R \neq \perp$ there exist two points x, y such that $xy^{\sim} \subseteq R$
 - ▶ Concrete relations between sets form the standard model of relation algebras. But the theory has non-standard models.
 - ▶ RELVIEW works with the standard model. This system cannot visualize computations in non-standard models of the abstract theory of heterogeneous relations
 - ▶ That is, not all relation algebras can be represented as the algebra of Boolean matrices.

Example

- ▶ The relation $\perp; \perp = \perp$ is always true in RELVIEW since it uses the standard model. These properties might not be true in some non-standard models, hence RELVIEW is not a complete system for relation algebra.
- ▶ An advanced example is given by the relationship between the power set of a disjoint union of two sets A and B and the product of the power set of A and the power set of B . In the standard model both constructions lead to isomorphic objects, while this might not be the case in certain non-standard models. ($P(A) \times P(B) \cong P(A + B)$)

Matrix Algebras

Definition

Let \mathcal{R} be a relation algebra. The algebra \mathcal{R}^+ of the matrices with coefficients from \mathcal{R} is defined by:

- ▶ The class of objects of \mathcal{R}^+ is the collection of all functions from an arbitrary set I to $Obj_{\mathcal{R}}$.
- ▶ For every pair $f : I \rightarrow Obj_{\mathcal{R}}, g : J \rightarrow Obj_{\mathcal{R}}$ of objects from \mathcal{R}^+ , the set of morphisms $\mathcal{R}^+[f, g]$ is the set of all functions $R : I \times J \rightarrow Mor_{\mathcal{R}}$ such that $R(i, j) \in \mathcal{R}[f(i), g(j)]$ holds.
- ▶ For $R \in \mathcal{R}^+[f, g]$ and $S \in \mathcal{R}^+[g, h]$ composition is defined by $(R; S)(i, k) := \sqcup R(i, j); S(j, k)$.
- ▶ For $R \in \mathcal{R}^+[f, g]$ conversion and negation is defined by $R^\sim(j, i) := (R(i, j))^\sim, \overline{R}(i, j) = \overline{R(i, j)}$
- ▶ For $R, S \in \mathcal{R}^+[f, g]$ union and intersection is defined by $(R \sqcup S)(i, j) = R(i, j) \sqcup S(i, j), (R \sqcap S)(i, j) = R(i, j) \sqcap S(i, j)$
- ▶ The identity, zero and universal elements are defined by

$$\mathbb{I}f(i_1, i_2) := \begin{cases} \mathbb{I}f(i_1)f(i_2) & : i_1 \neq i_2 \\ \mathbb{I}f(i_1) & : i_1 = i_2 \end{cases}$$

$$\mathbb{I}fg(i, j) := \mathbb{I}f(i)g(j), \quad \mathbb{I}fg(i, j) := \mathbb{I}f(i)g(j)$$

[3].

A Pseudo Representation Theorem

Lemma

\mathfrak{R}^+ is a relation algebra

Definition

An object A of a relation algebra is called integral iff $\perp_{AA} \neq \top_{AA}$ and for all $Q, R \in \mathcal{R}[A, A]$, the equation $Q; R = \perp_{AA}$ implies either $Q = \perp_{AA}$ or $R = \perp_{AA}$.

Definition

Let $\{A_i | i \in I\}$ be a set of objects indexed by a set I . An object $\sum_{i \in I} A_i$, together with relations $\iota_j \in \mathcal{R}[A_j, \sum_{i \in I} A_i]$ for all $j \in I$ is called a relational sum of $\{A_i | i \in I\}$ iff for all $i, j \in I$ with $i \neq j$ the following holds: $\iota_i; \tilde{\iota}_i = \perp_{A_i}$, $\iota_i; \tilde{\iota}_j = \perp_{A_i A_j}$, $\bigsqcup_{i \in I} \iota_i; \tilde{\iota}_i = \perp_{\sum_{i \in I} A_i}$

Theorem

Let \mathcal{R} be a relation algebra with relational sums and subobjects and \mathcal{B} be the basis of \mathcal{R} . Then \mathcal{R} and \mathcal{B}^+ are equivalent [7].

Definition

Let $\Xi \in \mathcal{R}[A, A]$ be a partial equivalence relation. An object B together with a relation $\psi \in \mathcal{R}[B, A]$ is called a splitting of Ξ iff

$$\psi; \psi^{\sim} = \mathbb{I}_B, \quad \psi^{\sim}; \psi = \Xi.$$

A relation algebra has splittings iff for all partial equivalence relations a splitting exists.

Definition

Let \mathcal{R} be a relation algebra. An object $\mathcal{P}(A)$, together with a relation $\varepsilon_A : A \rightarrow \mathcal{P}(A)$ is called a relational power of A iff

$$\text{syQ}(\varepsilon_A, \varepsilon_A) \subseteq \mathbb{I}_{\mathcal{P}(A)} \quad \text{and} \quad \text{syQ}(R, \varepsilon_A) \text{ is total}$$

for all relations $R : B \rightarrow A$. \mathcal{R} has relational powers iff the relational power for any object exists.

Theorem

If \mathcal{R} is small, then \mathcal{R}^+ has pre-powers.

- ▶ We call an object B a pre-power of A if there is a relation $T : A \rightarrow B$ so that $\text{syQ}(R, T)$ is total for all relations $R : C \rightarrow A$, i.e., a relational power is a pre-power with the additional requirement $\text{syQ}(T, T) \subseteq \mathbb{I}$. If \mathcal{R} has splittings, then we obtain a relational power of A from a pre-power by splitting the equivalence relation $\text{syQ}(T, T)$

Theorem

Let \mathcal{R} be relation algebra with splittings. Then \mathcal{R}^+ has splittings.

Example

Let $M : f \rightarrow f$ be a partial equivalence relation in \mathcal{R}^+ of size α , and let $R_\beta : A_\beta \rightarrow f(\beta)$ be a splitting of Ξ_β in \mathcal{R} . Define $g : \alpha \rightarrow \text{Obj}\mathcal{R}$ and $N : g \rightarrow f$ by

$$g(\beta) = A_\beta,$$

$$N(\beta, \gamma) = \begin{cases} R_\beta; M(\beta, \gamma) & \text{iff } \beta \leq \gamma, \\ \perp_{A_\beta f(\gamma)} & \text{otherwise,} \end{cases}$$

For our example we consider the object $[B_{abc}, B_{abc}, B_{abc}, B_{abc}]$ and following partial equivalence relation in matrix form:

$$M = \begin{matrix} & B_{abc} & B_{abc} & B_{abc} & B_{abc} \\ \begin{matrix} B_{abc} \\ B_{abc} \\ B_{abc} \\ B_{abc} \end{matrix} & \begin{pmatrix} ab & 0 & b & 0 \\ 0 & ab & 0 & a \\ b & 0 & bc & 0 \\ 0 & a & 0 & a \end{pmatrix} \end{matrix}$$

Example

we obtain the following four partial equivalence relations $\Xi : B_{abc} \rightarrow B_{abc}$.

$$\Xi_1 := ab,$$

$$\Xi_2 := ab \cap \overline{0 \cap 0} = ab \cap abc = ab,$$

$$\Xi_3 := bc \cap \overline{b \cap b} \cap \overline{0 \cap 0} = bc \cap ac \cap abc = c,$$

$$\Xi_4 := a \cap \overline{0 \cap 0} \cap \overline{a \cap a} \cap \overline{0 \cap 0} = a \cap abc \cap bc \cap abc = 0.$$

The splittings for each of those relations is given by

$$R_1 = R_2 := ab : B_{ab} \rightarrow B_{abc}, \quad R_3 := c : B_c \rightarrow B_{abc}, \quad R_4 := 0 : B_0 \rightarrow B_{abc}.$$

Notice that the source object of each of those relations is different from B_{abc} . We obtain the matrix N as:

$$N = \begin{matrix} & B_{abc} & B_{abc} & B_{abc} & B_{abc} \\ \begin{matrix} B_{ab} \\ B_{ab} \\ B_c \\ B_0 \end{matrix} & \begin{pmatrix} ab & 0 & b & 0 \\ 0 & ab & 0 & a \\ 0 & 0 & c & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \end{matrix}$$

Objectives

- ▶ The proposed system will work with both standard and non-standard model.
- ▶ It will implement relation algebras in the form of matrix algebras.
- ▶ Make available a library to aid researchers to manipulate relations in their own programs.
- ▶ The proposed structure will be implemented in a packaged using C which can be imported into other programs and/or languages. A specific focus will be on a suitable module for the programming language Haskell.
- ▶ Understand how relations represented as matrices could be implemented using MDDs.

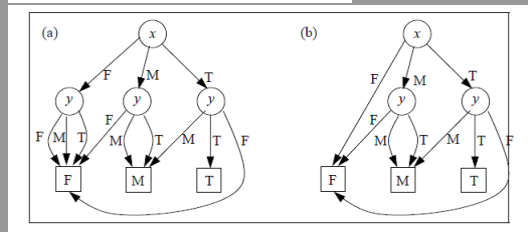
MDDs

- ▶ A multiple-valued decision diagram (MDD) is a natural extension of the reduced ordered binary decision diagrams (ROBDDs) to the multiple-valued case
- ▶ MDDs are considered to be more efficient and require smaller memory size than the ROBDDs.
- ▶ Let V be a set of finite size r . An r -valued function f is a function mapping V^n for some n to V . We will identify the n input values of f using a set of variables $X = \{x_0, x_1, \dots, x_n\}$. Each x_i as well as $f(X)$ is r -valued, i.e., it represents an element from V . The function f can be represented by a multi-valued decision diagram. Such a decision diagram is directed acyclic graph (DAG) with up to r terminal nodes each labeled by a distinct value from V . Every non-terminal node is labeled by an input variable x_i and has r outgoing edges
- ▶ An MDD is ordered (OMDD) if there is an order on the set of variables X so that for every path from the root to a leave node all variables appear in that order.
- ▶ MDD is called reduced if the graph does not contain isomorphic subgraphs and no nodes for which all r children are isomorphic (i.e. there is no redundant nodes in which two edges leaving a node points to the same next node within the graph).

Example MDDs

Let f be a multiple valued logic defined over the truth values T, M, F such that T = True, M = Maybe and F = False.

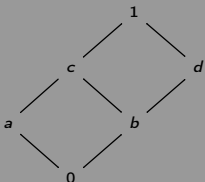
\wedge	F	M	T	\vee	F	M	T
F	F	F	F	F	F	M	T
M	F	M	M	M	M	M	T
T	F	M	T	T	T	T	T



$f = y \wedge x$ (a)MDD; (b)ROMDD

Implementation

- Heyting algebra \mathcal{L}



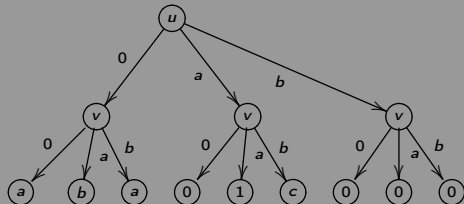
$$\begin{matrix}
 & 0 & a & b & c & d & 1 \\
 0 & \left(\begin{matrix} a & b & a & 0 & 0 & 0 \end{matrix} \right) \\
 a & \left(\begin{matrix} 0 & 1 & c & 0 & 0 & 0 \end{matrix} \right) \\
 b & \left(\begin{matrix} 0 & 0 & 0 & 0 & 0 & 0 \end{matrix} \right) \\
 c & \left(\begin{matrix} 0 & 0 & 0 & 0 & 0 & 0 \end{matrix} \right) \\
 d & \left(\begin{matrix} 0 & 0 & 0 & 0 & 0 & 0 \end{matrix} \right) \\
 1 & \left(\begin{matrix} 0 & 0 & 0 & 0 & 0 & 0 \end{matrix} \right)
 \end{matrix}$$

u	v	$f_R(u, v)$
0	0	a
0	a	b
0	b	a
a	0	0
a	a	1
a	b	c
		0

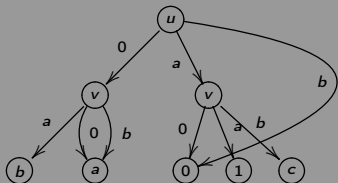
- Example: $c \sqcap d = b$, $a \sqcap b = 0$, $a \sqcap c = a$, $1 \sqcup b = 1$, and $a \sqcup b = c$

$$R = \begin{pmatrix} a & b & a \\ 0 & 1 & c \end{pmatrix} \quad S = \begin{pmatrix} a & a & 1 \\ 0 & b & d \end{pmatrix}$$

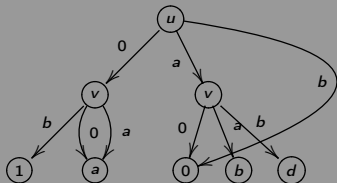
$$T := R \sqcap S = \begin{pmatrix} a & 0 & a \\ 0 & b & b \end{pmatrix}$$



Implementation



- ▶ Similarly, we construct the ROMDD for S :



- ▶ apply on ROMDDs: This operation applies a function to a leaf node of R and the corresponding leaf node of S . Corresponding leaf nodes are determined by the same path from the root to the leaf in both graphs.
- ▶ Another version of the apply operation applies a unary function to a each leaf node of a single ROMDD
- ▶ abstraction operation: This operation applies a function to all elements of an entire row or column of a matrix

RelMDD-A Library for Manipulating Relations Based on MDDs

- ▶ RelMDD is an arbitrary relation algebra manipulator library written in C programming language.
- ▶ It is a package that implements relation algebra using the matrix algebra approach and can be imported by other programs and/or languages such as Java and Haskell when programming or manipulating arbitrary relations.
- ▶ We implemented RelMDD using the matrix algebra over a suitable basis approach, hence it is capable of manipulating both the class of standard and the non-standard models of relation algebra.
- ▶ It has an XML interface for loading the basis of relations into memory.
- ▶ It has several function for performing basic operations.
- ▶ The implementation is currently restricted to the basic operations of relation algebras, i.e., union, intersection, composition, converse, and complement.
- ▶ In our implementation MDDs were implemented using algebraic decision diagrams [2]. By taking this approach we were able to use a well-known package for these diagrams called CUDD [5].

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Summary and Conclusion

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- ▶ Relation algebra is made up of standard and non-standard models
- ▶ Relation algebra are Matrix algebra, hence we can implement relation algebra in a form of matrix algebra (not restricting ourselves to only boolean matrix.)
- ▶ In order to implement a complete system for relation algebra we used a more advance representation of functions using ROMDDs.

Future Work And Suggestions

- ▶ This work would be extended by creating a suitable module for the programming language Haskell or Java.
- ▶ Extending the this system into a programming language for relations
- ▶ Integrating the package into the RELVIEW System.
- ▶ A future project will add further operations such as sums and splittings.

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Thank You

