

Bisimulation equivalence: general idea

- ▶ M, M' bisimilar if they have 'corresponding executions'
 - ▶ to each step of M there is a corresponding step of M'
 - ▶ to each step of M' there is a corresponding step of M
- ▶ Bisimilar models satisfy same CTL* properties
- ▶ Bisimilar: same truth/falsity of model properties
- ▶ Simulation gives property-truth preserving abstraction (see later)

Bisimulation relations

- ▶ Let $R : S \rightarrow S \rightarrow \mathbb{B}$ and $R' : S' \rightarrow S' \rightarrow \mathbb{B}$ be transition relations
- ▶ B is a **bisimulation relation** between R and R' if:
 - ▶ $B : S \rightarrow S' \rightarrow \mathbb{B}$
 - ▶ $\forall s s'. B s s' \Rightarrow \forall s_1 \in S. R s s_1 \Rightarrow \exists s'_1. R' s' s'_1 \wedge B s_1 s'_1$
(to each step of R there is a corresponding step of R')
 - ▶ $\forall s s'. B s s' \Rightarrow \forall s'_1 \in S'. R' s' s'_1 \Rightarrow \exists s_1. R s s_1 \wedge B s_1 s'_1$
(to each step of R' there is a corresponding step of R)

Bisimulation equivalence: definition and theorem

- ▶ Let $M = (S, S_0, R, L)$ and $M' = (S', S'_0, R', L')$
- ▶ $M \equiv M'$ if:
 - ▶ there is a bisimulation B between R and R'
 - ▶ $\forall s_0 \in S_0. \exists s'_0 \in S'_0. B s_0 s'_0$
 - ▶ $\forall s'_0 \in S'_0. \exists s_0 \in S_0. B s_0 s'_0$
 - ▶ there is a bijection $\theta : AP \rightarrow AP'$
 - ▶ $\forall s s'. B s s' \Rightarrow L(s) = L'(s')$
- ▶ Theorem: if $M \equiv M'$ then for any CTL* state formula ψ :
 $M \models \psi \Leftrightarrow M' \models \psi$
- ▶ See Q14 in the Exercises

Abstraction

- ▶ Abstraction creates a simplification of a model
 - ▶ separate states may get merged
 - ▶ an abstract path can represent several concrete paths
- ▶ $M \preceq \bar{M}$ means \bar{M} is an abstraction of M
 - ▶ to each step of M there is a corresponding step of \bar{M}
 - ▶ atomic properties of M correspond to atomic properties of \bar{M}
- ▶ Special case is when \bar{M} is a subset of M such that:
 - ▶ $\bar{M} = (\bar{S}_0, \bar{S}, \bar{R}, \bar{L})$ and $M = (S_0, S, R, L)$
 - $\bar{S} \subseteq S$
 - $\bar{S}_0 = S_0$
 - $\forall s s' \in \bar{S}. \bar{R} s s' \Leftrightarrow R s s'$
 - $\forall s \in \bar{S}. \bar{L} s = L s$
 - ▶ \bar{S} contain all reachable states of M
 - $\forall s \in \bar{S}. \forall s' \in S. R s s' \Rightarrow s' \in \bar{S}$
- ▶ All paths of M from initial states are \bar{M} -paths
 - ▶ hence for all CTL formulas $\psi: \bar{M} \models \psi \Rightarrow M \models \psi$

Recall JM1

Thread 1

```
0: IF LOCK=0 THEN LOCK:=1;
1: X:=1;
2: IF LOCK=1 THEN LOCK:=0;
3:
```

Thread 2

```
0: IF LOCK=0 THEN LOCK:=1;
1: X:=2;
2: IF LOCK=1 THEN LOCK:=0;
3:
```

- ▶ Two program counters, state: $(pc_1, pc_2, lock, x)$

$$S_{JM1} = [0..3] \times [0..3] \times \mathbb{Z} \times \mathbb{Z}$$

$$\begin{array}{l|l} R_{JM1}(0, pc_2, 0, x) & (1, pc_2, 1, x) \\ R_{JM1}(1, pc_2, lock, x) & (2, pc_2, lock, 1) \\ R_{JM1}(2, pc_2, 1, x) & (3, pc_2, 0, x) \end{array} \quad \Bigg| \quad \begin{array}{l} R_{JM1}(pc_1, 0, 0, x) & (pc_1, 1, 1, x) \\ R_{JM1}(pc_1, 1, lock, x) & (pc_1, 2, lock, 2) \\ R_{JM1}(pc_1, 2, 1, x) & (pc_1, 3, 0, x) \end{array}$$

- ▶ Assume $\text{NotAt11} \in L_{JM1}(pc_1, pc_2, lock, x) \Leftrightarrow \neg((pc_1 = 1) \wedge (pc_2 = 1))$
- ▶ Model $M_{JM1} = (S_{JM1}, \{(0, 0, 0, 0)\}, R_{JM1}, L_{JM1})$
- ▶ S_{JM1} not finite, but actually $lock \in \{0, 1\}, x \in \{0, 1, 2\}$
- ▶ Clear by inspection that $M_{JM1} \preceq \bar{M}_{JM1}$ where:

$$\bar{M}_{JM1} = (\bar{S}_{JM1}, \{(0, 0, 0, 0)\}, \bar{R}_{JM1}, \bar{L}_{JM1})$$

- ▶ $\bar{S}_{JM1} = [0..3] \times [0..3] \times [0..1] \times [0..3]$
- ▶ \bar{R}_{JM1} is R_{JM1} restricted to arguments from \bar{S}_{JM1}
- ▶ $\text{NotAt11} \in \bar{L}_{JM1}(pc_1, pc_2, lock, x) \Leftrightarrow \neg((pc_1 = 1) \wedge (pc_2 = 1))$
- ▶ \bar{L}_{JM1} is L_{JM1} restricted to arguments from \bar{S}_{JM1}

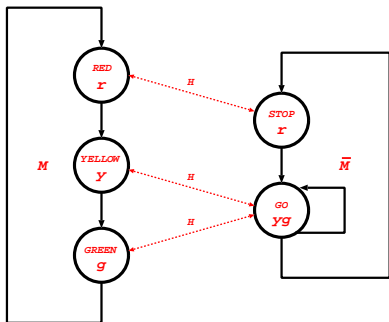
Simulation relations

- ▶ Let $R : S \rightarrow S \rightarrow \mathbb{B}$ and $\bar{R} : \bar{S} \rightarrow \bar{S} \rightarrow \mathbb{B}$ be transition relations
- ▶ H is a **simulation relation** between R and \bar{R} if:
 - ▶ H is a relation between S and \bar{S} – i.e. $H : S \rightarrow \bar{S} \rightarrow \mathbb{B}$
 - ▶ to each step of R there is a corresponding step of \bar{R} – i.e.:
 $\forall s \bar{s}. H s \bar{s} \Rightarrow \forall s' \in S. R s s' \Rightarrow \exists \bar{s}' \in \bar{S}. \bar{R} \bar{s} \bar{s}' \wedge H s' \bar{s}'$
- ▶ Also need to consider abstraction of atomic properties
 - ▶ $H_{AP} : AP \rightarrow \bar{AP} \rightarrow \mathbb{B}$
 - ▶ details glossed over here

Simulation preorder: definition and theorem

- ▶ Let $M = (S, S_0, R, L)$ and $\bar{M} = (\bar{S}, \bar{S}_0, \bar{R}, \bar{L})$
- ▶ $M \preceq \bar{M}$ if:
 - ▶ there is a simulation H between R and \bar{R}
 - ▶ $\forall s_0 \in S_0. \exists \bar{s}_0 \in \bar{S}_0. H s_0 \bar{s}_0$
 - ▶ $\forall s \bar{s}. H s \bar{s} \Rightarrow L(s) = \bar{L}(\bar{s})$
- ▶ ACTL is the subset of CTL without **E**-properties
 - ▶ e.g. **AG AF** p – from anywhere can always reach a p -state
- ▶ Theorem: if $M \preceq \bar{M}$ then for any ACTL state formula ψ :
 $\bar{M} \models \psi \Rightarrow M \models \psi$
- ▶ If $\bar{M} \models \psi$ fails then cannot conclude $M \models \psi$ false

Example (Grumberg)



H a simulation

$H \text{ RED STOP} \quad \wedge$

$H \text{ YELLOW GO} \quad \wedge$

$H \text{ GREEN GO}$

$H_{AP} : \{r, y, g\} \rightarrow \{r, yg\} \rightarrow \mathbb{B}$

$H_{AP} r r \wedge$

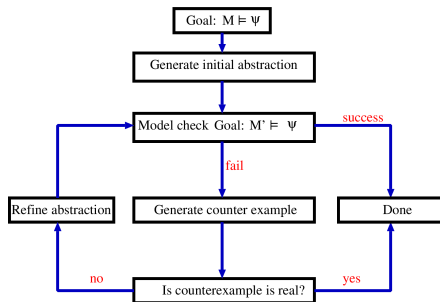
$H_{AP} y yg \wedge$

$H_{AP} g yg$

- ▶ $\bar{M} \models \mathbf{AG AF} \neg r$ hence $M \models \mathbf{AG AF} \neg r$
- ▶ but $\neg(\bar{M} \models \mathbf{AG AF} r)$ doesn't entail $\neg(M \models \mathbf{AG AF} r)$
 - ▶ $\llbracket \mathbf{AG AF} r \rrbracket_{\bar{M}}(\text{STOP})$ is false
(consider \bar{M} -path π' where $\pi' = \text{STOP.GO.GO.GO} \dots$)
 - ▶ $\llbracket \mathbf{AG AF} r \rrbracket_M(\text{RED})$ is true
(abstract path π' doesn't correspond to a real path in M)

CEGAR

- ▶ Counter Example Guided Abstraction Refinement



- ▶ Lots of details to fill out (several different solutions)
 - ▶ how to generate abstraction
 - ▶ how to check counterexamples
 - ▶ how to refine abstractions
- ▶ Microsoft SLAM driver verifier is a CEGAR system

Temporal Logic and Model Checking – Summary

- ▶ Various property languages: LTL, CTL, PSL (Prior, Pnueli)
- ▶ Models abstracted from hardware or software designs
- ▶ Model checking checks $M \models \psi$ (Clarke et al.)
- ▶ Symbolic model checking uses BDDs (McMillan)
- ▶ Avoid state explosion via simulation and abstraction
- ▶ CEGAR refines abstractions by analysing counterexamples
- ▶ Triumph of application of computer science theory
 - ▶ two Turing awards, McMillan gets 2010 CAV award
 - ▶ widespread applications in industry

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THE END