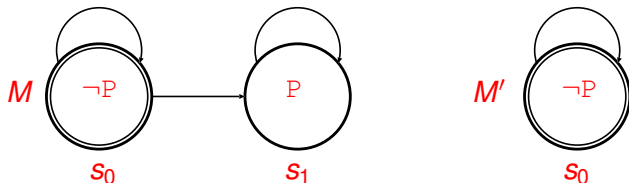


# A property not expressible in LTL

- ▶ Let  $AP = \{P\}$  and consider models  $M$  and  $M'$  below



$$M = (\{s_0, s_1\}, \{s_0\}, \{(s_0, s_0), (s_0, s_1), (s_1, s_1)\}, L)$$

$$M' = (\{s_0\}, \{s_0\}, \{(s_0, s_0)\}, L)$$

where:  $L = \lambda s. \text{if } s = s_0 \text{ then } \{\} \text{ else } \{P\}$

- ▶ Every  $M'$ -path is also an  $M$ -path
- ▶ So if  $\phi$  true on every  $M$ -path then  $\phi$  true on every  $M'$ -path
- ▶ Hence in LTL for any  $\phi$  if  $M \models \phi$  then  $M' \models \phi$
- ▶ Consider  $\phi_P \Leftrightarrow$  “can always reach a state satisfying  $P$ ”
  - ▶  $\phi_P$  holds in  $M$  but not in  $M'$
  - ▶ but in LTL can't have  $M \models \phi_P$  and not  $M' \models \phi_P$
- ▶ hence  $\phi_P$  not expressible in LTL

# CTL model checking

- ▶ For LTL path formulae  $\phi$  recall that  $M \models \phi$  is defined by:

$$M \models \phi \Leftrightarrow \forall \pi \text{ s. } s \in S_0 \wedge \text{Path } R \text{ s } \pi \Rightarrow \llbracket \phi \rrbracket_M(\pi)$$

- ▶ For CTL state formulae  $\psi$  the definition of  $M \models \psi$  is:

$$M \models \psi \Leftrightarrow \forall \text{ s. } s \in S_0 \Rightarrow \llbracket \psi \rrbracket_M(s)$$

- ▶  $M$  common; LTL, CTL formulae and semantics  $\llbracket \cdot \rrbracket_M$  differ
- ▶ CTL model checking algorithm:
  - ▶ compute  $\{s \mid \llbracket \psi \rrbracket_M(s) = \text{true}\}$  bottom up
  - ▶ check  $S_0 \subseteq \{s \mid \llbracket \psi \rrbracket_M(s) = \text{true}\}$
  - ▶ symbolic model checking represents these sets as BDDs

## CTL model checking: $p$ , $\mathbf{AX}\psi$ , $\mathbf{EX}\psi$

- ▶ For CTL formula  $\psi$  let  $\{\psi\}_M = \{s \mid \llbracket \psi \rrbracket_M(s) = \text{true}\}$
- ▶ When unambiguous will write  $\{\psi\}$  instead of  $\{\psi\}_M$
- ▶  $\{p\} = \{s \mid p \in L(s)\}$ 
  - ▶ scan through set of states  $S$  marking states labelled with  $p$
  - ▶  $\{p\}$  is set of marked states
- ▶ To compute  $\{\mathbf{AX}\psi\}$ 
  - ▶ recursively compute  $\{\psi\}$
  - ▶ marks those states all of whose successors are in  $\{\psi\}$
  - ▶  $\{\mathbf{AX}\psi\}$  is the set of marked states
- ▶ To compute  $\{\mathbf{EX}\psi\}$ 
  - ▶ recursively compute  $\{\psi\}$
  - ▶ marks those states with at least one successor in  $\{\psi\}$
  - ▶  $\{\mathbf{EX}\psi\}$  is the set of marked states

# CTL model checking: $\{\mathbf{E}[\psi_1 \mathbf{U} \psi_2]\}$ , $\{\mathbf{A}[\psi_1 \mathbf{U} \psi_2]\}$

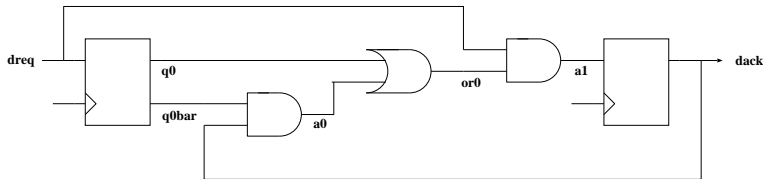
- ▶ To compute  $\{\mathbf{E}[\psi_1 \mathbf{U} \psi_2]\}$ 
  - ▶ recursively compute  $\{\psi_1\}$  and  $\{\psi_2\}$
  - ▶ mark all states in  $\{\psi_2\}$
  - ▶ mark all states in  $\{\psi_1\}$  with a successor state that is marked
  - ▶ repeat previous line until no change
  - ▶  $\{\mathbf{E}[\psi_1 \mathbf{U} \psi_2]\}$  is set of marked states
- ▶ More formally:  $\{\mathbf{E}[\psi_1 \mathbf{U} \psi_2]\} = \bigcup_{n=0}^{\infty} \{\mathbf{E}[\psi_1 \mathbf{U} \psi_2]\}_n$  where:
  - $\{\mathbf{E}[\psi_1 \mathbf{U} \psi_2]\}_0 = \{\psi_2\}$
  - $\{\mathbf{E}[\psi_1 \mathbf{U} \psi_2]\}_{n+1} = \{\mathbf{E}[\psi_1 \mathbf{U} \psi_2]\}_n \cup \{s \in \{\psi_1\} \mid \exists s' \in \{\mathbf{E}[\psi_1 \mathbf{U} \psi_2]\}_n. R s s'\}$
- ▶  $\{\mathbf{A}[\psi_1 \mathbf{U} \psi_2]\}$  similar, but with a more complicated iteration
  - ▶ details omitted (see Huth and Ryan)

## Example: checking **EF** $\rho$

- ▶ **EF** $\rho = \mathbf{E}[\mathbf{T} \ \mathbf{U} \ \rho]$ 
  - ▶ holds if  $\psi$  holds along some path
- ▶ Note  $\{\mathbf{T}\} = \mathcal{S}$
- ▶ Let  $\mathcal{S}_n = \{\mathbf{E}[\mathbf{T} \ \mathbf{U} \ \rho]\}_n$  then:
  - $\mathcal{S}_0 = \{\mathbf{E}[\mathbf{T} \ \mathbf{U} \ \rho]\}_0$ 
    - $= \{\rho\}$
    - $= \{s \mid \rho \in L(s)\}$
  - $\mathcal{S}_{n+1} = \mathcal{S}_n \cup \{s \in \{\mathbf{T}\} \mid \exists s' \in \{\mathbf{E}[\mathbf{T} \ \mathbf{U} \ \rho]\}_n. R \ s \ s'\}$ 
    - $= \mathcal{S}_n \cup \{s \mid \exists s' \in \mathcal{S}_n. R \ s \ s'\}$
- ▶ mark all the states labelled with  $\rho$
- ▶ mark all with at least one marked successor
- ▶ repeat until no change
- ▶ **{EF  $\rho$ }** is set of marked states

## Example: RCV

- ▶ Recall the handshake circuit:



- ▶ State represented by a triple of Booleans ( $dreq, q0, dack$ )
- ▶ A model of RCV is  $M_{RCV}$  where:

$$M = (S_{RCV}, S_{0_{RCV}}, R_{RCV}, L_{RCV})$$

and

$$R_{RCV} (dreq, q0, dack) (dreq', q0', dack') = \\ (q0' = dreq) \wedge (dack' = (dreq \wedge (q0 \vee dack)))$$

## RCV state transition diagram

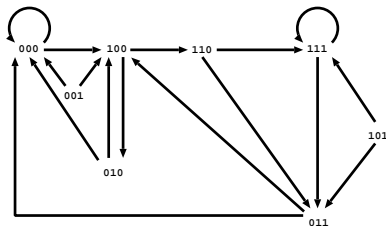
- ▶ Possible states for RCV:

$\{000, 001, 010, 011, 100, 101, 110, 111\}$

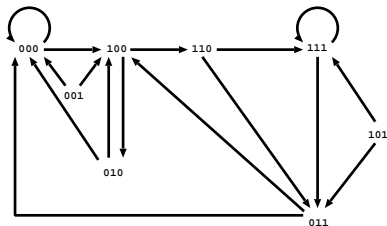
where  $b_2b_1b_0$  denotes state

$dreq = b_2 \wedge q0 = b_1 \wedge dack = b_0$

- ▶ Graph of the transition relation:



# Computing Reachable $M_{RCV}$



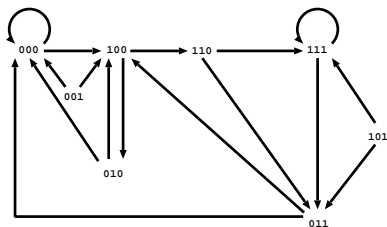
► Define:

$$\begin{aligned} S_0 &= \{b_2 b_1 b_0 \mid b_2 b_1 b_0 \in \{111\}\} \\ &= \{111\} \end{aligned}$$

$$\begin{aligned} S_{i+1} &= S_i \cup \{s' \mid \exists s \in S_i. R_{RCV} s s'\} \\ &= S_i \cup \{b'_2 b'_1 b'_0 \mid \\ &\quad \exists b_2 b_1 b_0 \in S_i. (b'_1 = b_2) \wedge (b'_0 = b_2 \wedge (b_1 \vee b_0))\} \end{aligned}$$



Computing  $\{EF_{At111}\}$  where  $At111 \in L_{RCV}(s) \Leftrightarrow s = 111$

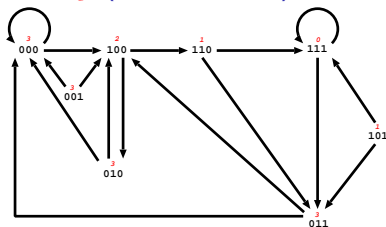


► Define:

$$\begin{aligned}
 \mathcal{S}_0 &= \{s \mid At111 \in L_{RCV}(s)\} \\
 &= \{s \mid s = 111\} \\
 &= \{111\}
 \end{aligned}$$

$$\begin{aligned}
 \mathcal{S}_{n+1} &= \mathcal{S}_n \cup \{s \mid \exists s' \in \mathcal{S}_n. \mathcal{R}(s, s')\} \\
 &= \mathcal{S}_n \cup \{b_2 b_1 b_0 \mid \\
 &\quad \exists b'_2 b'_1 b'_0 \in \mathcal{S}_n. (b'_1 = b_2) \wedge (b'_0 = b_2 \wedge (b_1 \vee b_0))\}
 \end{aligned}$$

# Computing $\{\mathbf{EF}_{\text{At111}}\}$ (continued)



► Compute:

$$S_0 = \{111\}$$

$$S_1 = \{111\} \cup \{101, 110\}$$

$$= \{111, 101, 110\}$$

$$S_2 = \{111, 101, 110\} \cup \{100\}$$

$$= \{111, 101, 110, 100\}$$

$$S_3 = \{111, 101, 110, 100\} \cup \{000, 001, 010, 011\}$$

$$= \{111, 101, 110, 100, 000, 001, 010, 011\}$$

$$S_n = S_3 \quad (n > 3)$$

►  $\{\mathbf{EF}_{\text{At111}}\} = \mathbb{B}^3 = S_{\text{RCV}}$

►  $M_{\text{RCV}} \models \mathbf{EF}_{\text{At111}} \Leftrightarrow S_{0\text{RCV}} \subseteq S$

# Symbolic model checking

- ▶ Represent sets of states with BDDs
- ▶ Represent Transition relation with a BDD
- ▶ If BDDs of  $\{\psi\}$ ,  $\{\psi_1\}$ ,  $\{\psi_2\}$  are known, then:
  - ▶ BDDs of  $\{\neg\psi\}$ ,  $\{\psi_1 \wedge \psi_2\}$ ,  $\{\psi_1 \vee \psi_2\}$ ,  $\{\psi_1 \Rightarrow \psi_2\}$  computed using standard BDD algorithms
  - ▶ BDDs of  $\{\mathbf{AX}\psi\}$ ,  $\{\mathbf{EX}\psi\}$ ,  $\{\mathbf{A}[\psi_1 \mathbf{U} \psi_2]\}$ ,  $\{\mathbf{E}[\psi_1 \mathbf{U} \psi_2]\}$  computed using straightforward algorithms (see textbooks)
- ▶ Model checking CTL generalises reachable states iteration

# History of Model checking

- ▶ CTL model checking due to Emerson, Clarke & Sifakis
- ▶ Symbolic model checking due to several people:
  - ▶ Clarke & McMillan (idea usually credited to McMillan's PhD)
  - ▶ Coudert, Berthet & Madre
  - ▶ Pixley
- ▶ SMV (McMillan) is a popular symbolic model checker:
  - <http://www.cs.cmu.edu/~modelcheck/smv.html> (original)
  - <http://www.kenmcmil.com/smv.html> (Cadence extension by McMillan)
  - <http://nusmv.first.itc.it/> (new implementation)
- ▶ Other temporal logics
  - ▶ CTL\*: combines CTL and LTL
  - ▶ Engineer friendly industrial languages: PSL, SVA

# Expressibility of CTL

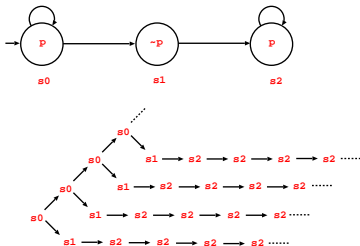
- ▶ Consider the property

*“on every path there is a point after which  $p$  is always true on that path”*

- ▶ Consider

$((\star)$  non-deterministically chooses  $T$  or  $F$ )

0:	$P := 1;$
$s_0$ 1:	WHILE $(\star)$ DO SKIP;
$s_1$ 2:	$P := 0;$
$s_2$ 3:	$P := 1;$
4:	WHILE $T$ DO SKIP;
5:	



- ▶ Property true, but cannot be expressed in CTL

- ▶ would need something like  $AF\psi$
- ▶ where  $\psi$  is something like “property  $p$  true from now on”
- ▶ but in CTL  $\psi$  must start with a path quantifier  $A$  or  $E$
- ▶ cannot talk about current path, only about all or some paths
- ▶  $AF(AG p)$  is false (consider path  $s_0 s_0 s_0 \dots$ )

# LTL can express things CTL can't

- ▶ Recall:

$$\llbracket \mathbf{F}\phi \rrbracket_M(\pi) = \exists i. \llbracket \phi \rrbracket_M(\pi \downarrow i)$$

$$\llbracket \mathbf{G}\phi \rrbracket_M(\pi) = \forall i. \llbracket \phi \rrbracket_M(\pi \downarrow i)$$

- ▶  $\mathbf{FG}\phi$  is true if there is a point after which  $\phi$  is always true

$$\llbracket \mathbf{FG}\phi \rrbracket_M(\pi) = \llbracket \mathbf{F}(\mathbf{G}(\phi)) \rrbracket_M(\pi)$$

$$= \exists m_1. \llbracket \mathbf{G}(\phi) \rrbracket_M(\pi \downarrow m_1)$$

$$= \exists m_1. \forall m_2. \llbracket \phi \rrbracket_M((\pi \downarrow m_1) \downarrow m_2)$$

$$= \exists m_1. \forall m_2. \llbracket \phi \rrbracket_M(\pi \downarrow (m_1 + m_2))$$

- ▶ LTL can express things that CTL can't express

- ▶ Note: it's tricky to prove CTL can't express  $\mathbf{FG}\phi$

# CTL can express things that LTL can't express

- ▶ **AG(EF p)** says:

*“from every state it is possible to get to a state for which p holds”*

- ▶ Can't say this in LTL (easy proof given earlier - slide 57)

- ▶ Consider disjunction:

*“on every path there is a point after which p is always true on that path*

*or*

*from every state it is possible to get to a state for which p holds”*

- ▶ Can't say this in either CTL or LTL!
- ▶ CTL\* combines CTL and LTL and can express this property

# CTL\*

- ▶ Both **state formulae** ( $\psi$ ) and **path formulae** ( $\phi$ )
  - ▶ state formulae  $\psi$  are true of a state  $s$  like CTL
  - ▶ path formulae  $\phi$  are true of a path  $\pi$  like LTL
- ▶ Defined mutually recursively

$\psi$	::=	$p$	(Atomic formula)
		$\neg\psi$	(Negation)
		$\psi_1 \vee \psi_2$	(Disjunction)
		<b>A</b> $\phi$	(All paths)
		<b>E</b> $\phi$	(Some paths)
$\phi$	::=	$\psi$	(Every state formula is a path formula)
		$\neg\phi$	(Negation)
		$\phi_1 \vee \phi_2$	(Disjunction)
		<b>X</b> $\phi$	(Successor)
		<b>F</b> $\phi$	(Sometimes)
		<b>G</b> $\phi$	(Always)
		$[\phi_1 \mathbf{U} \phi_2]$	(Until)

- ▶ CTL is CTL\* with **X**, **F**, **G**,  $[-\mathbf{U}-]$  preceded by **A** or **E**
- ▶ LTL consists of CTL\* formulae of form **A** $\phi$ , where the only state formulae in  $\phi$  are atomic



# CTL\* semantics

- ▶ Combines CTL state semantics with LTL path semantics:

$$\begin{aligned} \llbracket p \rrbracket_M(s) &= p \in L(s) \\ \llbracket \neg\psi \rrbracket_M(s) &= \neg(\llbracket \psi \rrbracket_M(s)) \\ \llbracket \psi_1 \vee \psi_2 \rrbracket_M(s) &= \llbracket \psi_1 \rrbracket_M(s) \vee \llbracket \psi_2 \rrbracket_M(s) \\ \llbracket \mathbf{A}\phi \rrbracket_M(s) &= \forall \pi. \text{Path } R \ s \ \pi \Rightarrow \phi(\pi) \\ \llbracket \mathbf{E}\phi \rrbracket_M(s) &= \exists \pi. \text{Path } R \ s \ \pi \wedge \llbracket \phi \rrbracket_M(\pi) \\ \\ \llbracket \psi \rrbracket_M(\pi) &= \llbracket \psi \rrbracket_M(\pi(0)) \\ \llbracket \neg\phi \rrbracket_M(\pi) &= \neg(\llbracket \phi \rrbracket_M(\pi)) \\ \llbracket \phi_1 \vee \phi_2 \rrbracket_M(\pi) &= \llbracket \phi_1 \rrbracket_M(\pi) \vee \llbracket \phi_2 \rrbracket_M(\pi) \\ \llbracket \mathbf{X}\phi \rrbracket_M(\pi) &= \llbracket \phi \rrbracket_M(\pi \downarrow 1) \\ \llbracket \mathbf{F}\phi \rrbracket_M(\pi) &= \exists m. \llbracket \phi \rrbracket_M(\pi \downarrow m) \\ \llbracket \mathbf{G}\phi \rrbracket_M(\pi) &= \forall m. \llbracket \phi \rrbracket_M(\pi \downarrow m) \\ \llbracket \phi_1 \mathbf{U} \phi_2 \rrbracket_M(\pi) &= \exists i. \llbracket \phi_2 \rrbracket_M(\pi \downarrow i) \wedge \forall j. j < i \Rightarrow \llbracket \phi_1 \rrbracket_M(\pi \downarrow j) \end{aligned}$$

- ▶ Note  $\llbracket \psi \rrbracket_M : \mathcal{S} \rightarrow \mathbb{B}$  and  $\llbracket \phi \rrbracket_M : (\mathbb{N} \rightarrow \mathcal{S}) \rightarrow \mathbb{B}$

## LTL and CTL as CTL\*

- ▶ As usual:  $M = (S, S_0, R, L)$
- ▶ If  $\psi$  is a CTL\* state formula:  $M \models \psi \Leftrightarrow \forall s \in S_0. \llbracket \psi \rrbracket_M(s)$
- ▶ If  $\phi$  is an LTL path formula then:  $M \models_{\text{LTL}} \phi \Leftrightarrow M \models_{\text{CTL}^*} \mathbf{A}\phi$
- ▶ If  $R$  is total ( $\forall s. \exists s'. R s s'$ ) then (exercise):  
 $\forall s s'. R s s' \Leftrightarrow \exists \pi. \text{Path } R s \pi \wedge (\pi(1) = s')$
- ▶ The meanings of CTL formulae are the same in CTL\*

$$\llbracket \mathbf{A}(\mathbf{X}\psi) \rrbracket_M(s)$$

$$= \forall \pi. \text{Path } R s \pi \Rightarrow \llbracket \mathbf{X}\psi \rrbracket_M(\pi)$$

$$= \forall \pi. \text{Path } R s \pi \Rightarrow \llbracket \psi \rrbracket_M(\pi \downarrow 1)$$

( $\psi$  as path formula)

$$= \forall \pi. \text{Path } R s \pi \Rightarrow \llbracket \psi \rrbracket_M((\pi \downarrow 1)(0))$$

( $\psi$  as state formula)

$$= \forall \pi. \text{Path } R s \pi \Rightarrow \llbracket \psi \rrbracket_M(\pi(1))$$

$$\llbracket \mathbf{A}\mathbf{X}\psi \rrbracket_M(s)$$

$$= \forall s'. R s s' \Rightarrow \llbracket \psi \rrbracket_M(s')$$

$$= \forall s'. (\exists \pi. \text{Path } R s \pi \wedge (\pi(1) = s')) \Rightarrow \llbracket \psi \rrbracket_M(s')$$

$$= \forall s'. \forall \pi. \text{Path } R s \pi \wedge (\pi(1) = s') \Rightarrow \llbracket \psi \rrbracket_M(s')$$

$$= \forall \pi. \text{Path } R s \pi \Rightarrow \llbracket \psi \rrbracket_M(\pi(1))$$

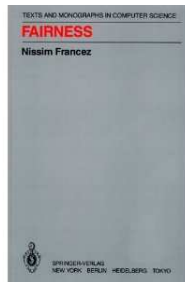
Exercise: do similar proofs for other CTL formulae

# Fairness

- ▶ May want to assume system or environment is 'fair'
- ▶ Example 1: fair arbiter  
the arbiter doesn't ignore one of its requests forever
  - ▶ not every request need be granted
  - ▶ want to exclude infinite number of requests and no grant
- ▶ Example 2: reliable channel  
no message continuously transmitted but never received
  - ▶ not every message need be received
  - ▶ want to exclude an infinite number of sends and no receive

# Handling fairness in CTL and LTL

- ▶ Consider:
  - $p$  holds infinitely often along a path then so does  $q$
- ▶ In LTL is expressible as  $\mathbf{G(F\ } p) \Rightarrow \mathbf{G(F\ } q)$
- ▶ Can't say this in CTL
  - ▶ why not – what's wrong with  $\mathbf{AG(AF\ } p) \Rightarrow \mathbf{AG(AF\ } q)$ ?
  - ▶ in CTL\* expressible as  $\mathbf{A(G(F\ } p) \Rightarrow \mathbf{G(F\ } q))$
  - ▶ fair CTL model checking implemented in checking algorithm
  - ▶ fair LTL just a fairness assumption like  $\mathbf{G(F\ } p) \Rightarrow \dots$
- ▶ Fairness is a tricky and subtle subject
  - ▶ many kinds of fairness:  
'weak fairness', 'strong fairness' etc
  - ▶ exist whole books on fairness



# Propositional modal $\mu$ -calculus

- ▶ You may learn this in *Topics in Concurrency*
- ▶  $\mu$ -calculus is an even more powerful property language
  - ▶ has fixed-point operators
  - ▶ both maximal and minimal fixed points
  - ▶ model checking consists of calculating fixed points
  - ▶ many logics (e.g. CTL\*) can be translated into  $\mu$ -calculus
- ▶ Strictly stronger than CTL\*
  - ▶ expressibility strictly increases as allowed nesting increases
  - ▶ need fixed point operators nested 2 deep for CTL\*
- ▶ The  $\mu$ -calculus is **very** non-intuitive to use!
  - ▶ intermediate code rather than a practical property language
  - ▶ nice meta-theory and algorithms, but terrible usability!