WARNING

These are preliminary slides and may differ from what is actually presented in the lectures.

Additional material may be added and topics in these slides may not be covered.

Introduction

Specification and Verification I

- This course is on the specification and verification of software
- It is a prerequisite for the course entitled:
 - Specification and Verification II
 - which concerns hardware
- The two courses are really a single course

Program Specification and Verification

- This course is about *formal* ways of specifying and validating software
- This contrasts with informal methods:
 - natural language specifications
 - testing
- Formal methods are *not* a panacea
 - formally verified designs may still not work
 - can give a false sense of security
- Assurance versus debugging
 - formal verification (FV) can reveal hard-to-find bugs
 - can also be used for assurance e.g. "proof of correctness"
 - Microsoft use FV for debugging, NSA use FV for assurance

• Goals of course:

- enable you to understand and criticise formal methods
- provide a stepping stone to current research

Testing

- Testing can quickly find obvious bugs
 - only trivial programs can be tested exhaustively
 - the cases you do not test can still hide bugs
 - coverage tools can help
- How do you know what the correct test results should be?
- Many industries' standards specify maximum failure rates
 - e.g. fewer than 10^{-6} failures per second
 - assurance that such rates have been achieved cannot be obtained by testing

Formal Methods

- Formal Specification using mathematical notation to give a precise description of what a program should do
- Formal Verification using precise rules to mathematically prove that a program satisfies a formal specification
- Formal Development (Refinement) developing programs in a way that ensures mathematically they meet their formal specifications
- Formal Methods should be used in conjunction with testing, *not* as a replacement

Should we always use formal methods?

- They can be expensive
 - though can be applied in varying degrees of effort
- There is a trade-off between expense and the need for correctness
- It may be better to have something that works most of the time than nothing at all
- For some applications, correctness is especially important
 - nuclear reactor controllers
 - car braking systems
 - fly-by-wire aircraft
 - software controlled medical equipment
 - voting machines
 - cryptographic code
- Formal proof of correctness provides a way of establishing the absence of bugs when exhaustive testing is impossible

Floyd-Hoare Logic

• This course is concerned with Floyd-Hoare Logic

• also known just as Hoare Logic

- Floyd-Hoare Logic is a method of reasoning mathematically about *imperative* programs
- It is the basis of mechanized program verification systems
 the architecture of these will be described later
- Industrial program development methods like SPARK use ideas from Floyd-Hoare Logic to obtain high assurance
- Developments to the logic still under active development

• e.g. separation logic (reasoning about pointers) – google if curious

Syllabus

- Program specification: • partial and total correctness
- Hoare notation
- Axioms and rules of Floyd-Hoare Logic . • discussion of soundness and completeness
- Mechanised program verification • verification conditions
- Program refinement •
- Higher order logic
- Semantic embedding in higher order logic .
- Related notions •
 - weakest preconditions and strongest postconditions
 - VDM • dynamic logic
 - . . .

A Little Programming Language

Expressions:

 $E{::=} N \mid V \mid E_1 + E_2 \mid E_1 - E_2 \mid E_1 \times E_2 \mid \ldots$

Boolean expressions:

 $B{::=} \quad \mathbf{T} \ \mid \ \mathbf{F} \ \mid \ E_1{=}E_2 \ \mid \ E_1{\leq}E_2 \ \mid \ \ldots$

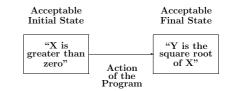
Commands: $C{::=}\ \mathtt{SKIP}$

V := E $V(E_1) := E_2$ C_1 ; C_2 IF B THEN C(redundant) IF B THEN ${\cal C}_1$ ELSE ${\cal C}_2$ BEGIN VAR \boldsymbol{V}_1 ; . . VAR \boldsymbol{V}_n ; C END WHILE B DO CFOR $V := E_1$ UNTIL E_2 DO C

Some Notation

- Programs are built out of *commands* like assignments, conditionals, while-loops etc
- The terms 'program' and 'command' are synonymous
 - the former generally used for commands representing complete algorithms
- The term 'statement' is used for conditions on program variables • that occur in correctness specifications
 - potential for confusion as some writers use this word for commands
 - e.g. 'FOR-statement' wrong here, use 'FOR-command'

Specification of Imperative Programs



Hoare's notation

C.A.R. Hoare introduced the following notation called a partial correctness specification for specifying what a program does:
 {P} C {Q}

) ~ (%

- where:
- C is a command
- P and Q are conditions on the program variables used in C
- Conditions on program variables will be written using standard mathematical notations together with *logical operators* like:
 - \wedge ('and'), $\,\vee$ ('or'), $\,\neg$ ('not'), $\,\Rightarrow$ ('implies')
- Hoare's original notation was $P \{C\} Q$ not $\{P\} C \{Q\}$, but the latter form is now more widely used

Meaning of Hoare's Notation

- $\{P\} \subset \{Q\}$ is true if
 - whenever C is executed in a state satisfying P
 - and if the execution of C terminates
 - then the state in which C terminates satisfies Q
- Example: ${X = 1} X := X+1 {X = 2}$
 - P is the condition that the value of X is 1
 - Q is the condition that the value of X is 2
 - C is the assignment command X:=X+1

• i.e. 'X becomes X+1'

- {X = 1} X:=X+1 {X = 2} is true
- ${X = 1} X := X+1 {X = 3}$ is false

Specifications as the Basis of Contracts

- A formal specification can be used as the basis for requirements analysis and procurement
 - is this what the customer intended?
 - see link Design by Contract on course web page
- "I want a program that swaps the values in X and Y"
- { $X=x \land Y=y$ } C { $X=y \land Y=x$ }
- The command BEGIN R:=X; X:=Y; Y:=R END would fulfil the specification and so the contract
- The command BEGIN X:=Y; Y:=X END would not
- How do we determine whether a program fulfils the contract?

Formal versus Informal Proof

- Mathematics text books give informal proofs
- English arguments are used
 - proof of $(X + 1)^2 = X^2 + 2 \times X + 1$
 - "follows by the definition of squaring and distributivity laws"
- Formal verification uses formal proof
 - the rules used are described and followed very precisely
 - formal proof has been used to discover errors in published informal ones
- Here is an example formal proof

1.	$(X + 1)^2$	$= (X + 1) \times (X + 1)$	Definition of () ² .
2.	$(X + 1) \times (X + 1)$	$= (X + 1) \times X + (X + 1) \times 1$	Left distributive law of \times over +.
3.	$(X + 1)^2$	$= (\mathtt{X} + \mathtt{1}) \times \mathtt{X} + (\mathtt{X} + \mathtt{1}) \times \mathtt{1}$	Substituting line 2 into line 1.
4.	$(X + 1) \times 1$	= X + 1	Identity law for 1.
5.	$(X + 1) \times X$	$= X \times X + 1 \times X$	Right distributive law of \times over +.
6.	$(X + 1)^2$	$= \texttt{X} \times \texttt{X} + \texttt{1} \times \texttt{X} + \texttt{X} + \texttt{1}$	Substituting lines 4 and 5 into line 3.
7.	$1 \times X$	= X	Identity law for 1.
8.	$(X + 1)^2$	$= X \times X + X + X + 1$	Substituting line 7 into line 6.
9.	$X \times X$	$= X^2$	Definition of () ² .
10.	X + X	$= 2 \times X$	2=1+1, distributive law.
11.	$(X + 1)^2$	$= X^2 + 2 \times X + 1$	Substituting lines 9 and 10 into line 8.

The Structure of Proofs

- A proof consists of a sequence of lines
- Each line is an instance of an *axiom* • like the definition of ()²
- or follows from previous lines by a *rule of inference*
 - like the substitution of equals for equals
- The statement occurring on the last line of a proof is the statement proved by it
 - thus $(X + 1)^2 = X^2 + 2 \times X + 1$ is proved by the proof on the previous slide
- These are 'Hilbert style' formal proofs
 - can use a tree structure rather than a linear one
 - choice is a matter of convenience

Formal proof is syntactic 'symbol pushing'

- Formal Systems reduce verification and proof to symbol pushing
- The rules say...
 - if you have a string of characters of this form
 - you can obtain a new string of characters of this other form
- Even if you don't know what the strings are intended to mean, provided the rules are designed properly and you apply them correctly, you will get correct results • though not necessarily the desired result
- Thus computers can do formal verification
- Formal verification by hand generally not feasible • maybe hand verify high-level design, but not code
- Famous paper that's worth reading: "Social processes and the proofs of theorems and programs". R. A. DeMillo, R. J. Lipton, and A. J. Perlis. CACM, May 1979
- Also see the book "Mechanizing Proof" by Donald MacKenzie

Hoare's Verification Grand Challenge

• Bill Gates, keynote address at WinHec 2002

... software verification ... has been the Holy Grail of computer science for many decades but now in some very key areas, for example, driver verification we are building tools that can do actual proof about the software and how it works in order to guarantee the reliability."

• Hoare has posed a challenge

The verification challenge is to achieve a significant body of verified programs that have precise external specifications, complete internal specifications, machine-checked proofs of correctness with respect to a sound theory of programming.

The Deliverables

A comprehensive theory of programming that covers the features needed to build practical and reliable programs. A coherent toolset that automates the theory and scales up to the analysis of large codes. A collection of verified programs that replace existing unverified ones, and continue to evolve in a verified state.

"You can't say anymore it can't be done! Here, we have done it."

Exercise: debug the proof of "1=2" below

Reflexivity of equality

Adding the fractions

Negate both sides

- 1. 1/1 = 1/12. -(1/1) = -(1/1)
- 3. -1/1 = 1/-1
- 4. $\sqrt{-1/1} = \sqrt{1/-1}$
- 5. $\sqrt{-1}/\sqrt{1} = \sqrt{1}/\sqrt{-1}$
- 6. i/1 = 1/i7. i/2 = 1/2i

- 10. -1/2 + 3/2 = 1/2 + 3/2 Using $i^2 = -1$ and cancelling
- 11. 1 = 2
- Square root of both sides Use $\sqrt{m/n} = \sqrt{m}/\sqrt{n}$ (since $(m/n)^2 = m^2/n^2$) As $i = \sqrt{-1}$ and $1 = \sqrt{1}$ Halving both sides 8. i/2 + 3/2i = 1/2i + 3/2i Adding same thing to both sides 9. $i^2/2 + 3i/2i = i/2i + 3i/2i$ Multiplying both sides by i

Use -(n/m)=(-n)/m=n/(-m)

Hoare Logic and Verification Conditions

- Hoare Logic is a deductive proof system for Hoare triples $\{P\} \ C \ \{Q\}$
- Can use Hoare Logic directly to verify programs
 - original proposal by Hoare
 - tedious and error prone
 - impractical for large programs
- Can 'compile' proving $\{P\} \ C \ \{Q\}$ to verification conditions
 - more natural
 - basis for computer assisted verification
- Proof of verification conditions equivalent to proof with Hoare Logic
 - Hoare Logic can be used to explain verification conditions

Formal Specification

Partial Correctness Specification

- An expression {P} C {Q} is called a partial correctness specification
 P is called its precondition
 - Q its postcondition
- {*P*} *C* {*Q*} is true if
 - whenever C is executed in a state satisfying P
 - and *if* the execution of *C* terminates
 - then the state in which $C\sp{s}$ execution terminates satisfies Q
- These specifications are 'partial' because for $\{P\} C \{Q\}$ to be true it is *not* necessary for the execution of C to terminate when started in a state satisfying P
- It is only required that if the execution terminates, then ${\boldsymbol{Q}}$ holds
- {X = 1} WHILE T DO SKIP {Y = 2} this specification is true!

Total Correctness Specification

- A stronger kind of specification is a total correctness specification
 - there is no standard notation for such specifications
 - we shall use $[P] \ C \ [Q]$
- A total correctness specification $[P] \ C \ [Q]$ is true if and only if
 - whenever C is executed in a state satisfying P the execution of C terminates
 after C terminates Q holds
- [X = 1] Y:=X; WHILE T DO SKIP [Y = 1]
 - \bullet this says that the execution of Y:=X;WHILE T DO SKIP terminates when started in a state satisfying X = 1
 - after which Y = 1 will hold
 - this is clearly false

Total Correctness

• Informally:

 $Total\ correctness = Termination + Partial\ correctness$

- Total correctness is the ultimate goal
 usually easier to show partial correctness and termination separately
- $\bullet\,$ Termination is usually straightforward to show, but there are examples where it is not: no one knows whether the program below terminates for all values of X

WHILE X>1 DO

- IF ODD(X) THEN X := $(3 \times X)+1$ ELSE X := X DIV 2
- + $\tt X$ DIV 2 evaluates to the result of rounding down $\tt X/2$ to a whole number
- the Collatz conjecture is that this terminates with X=1

Auxiliary Variables

- { $X=x \land Y=y$ } R:=X; X:=Y; Y:=R { $X=y \land Y=x$ }
 - this says that if the execution of
 R:=X; X:=Y; Y:=R
 - terminates (which it does)
 - \bullet then the values of X and Y are exchanged
- The variables x and y, which don't occur in the command and are used to name the initial values of program variables X and Y
- They are called *auxiliary* variables or *ghost* variables
- Informal convention:
 - program variable are upper case
 - auxiliary variable are lower case

More simple examples

- {X=x \land Y=y} BEGIN X:=Y; Y:=X END {X=y \land Y=x}
 - \bullet this says that BEGIN X:=Y; Y:=X END exchanges the values of X and Y
 - this is not true
- $\{\mathbf{T}\} \subset \{Q\}$
 - this says that whenever C halts, Q holds
- {P} C {T}
 - this specification is true for every condition \boldsymbol{P} and every command \boldsymbol{C}
 - because T is always true
- [P] C [T]
 - this says that C terminates if initially P holds
 - it says nothing about the final state
- [T] C [P]
 - this says that C always terminates and ends in a state where P holds

A More Complicated Example

- $\begin{cases} T \\ BEGIN \\ R:=X; \\ Q:=0; \\ WHILE \ Y \leq R \ DO \\ BEGIN \ R:=R-Y; \ Q:=Q+1 \ END \\ \{R < Y \ \land \ X = R + (Y \times Q) \} \end{cases} \\ \end{bmatrix} C$
- This is $\{T\} \subset \{R < Y \land X = R + (Y \times Q)\}$
 - where C is the command indicated by the braces above
 - the specification is true if whenever the execution of C halts, then Q is quotient and R is the remainder resulting from dividing Y into X
 - it is true (even if X is initially negative!)
 - \bullet in this example ${\mathbb Q}$ is a program variable
 - don't confuse Q with the metavariable Q used in previous examples to range over postconditions (Sorry: my bad notation!)

Some Easy Exercises

- When is [T] C [T] true?
- Write a partial correctness specification which is true if and only if the command C has the effect of multiplying the values of X and Y and storing the result in X
- Write a specification which is true if the execution of C always halts when execution is started in a state satisfying P

Specification can be Tricky

- "The program must set Y to the maximum of X and Y"
 - [T] C [Y = max(X,Y)]
- A suitable program:
 - IF X >= Y THEN Y := X ELSE SKIP
- Another?
 - IF X >= Y THEN X := Y ELSE SKIP
- Or even?
- Y := X
- Later you will be able to prove that these programs are "correct"
- The postcondition "Y=max(X,Y)" says "Y is the maximum of X and Y in the final state"

Specification can be Tricky (ii)

- The intended specification was probably *not* properly captured by
 - $\vdash \ \{\mathtt{T}\} \ \mathtt{C} \ \{\mathtt{Y}=\mathtt{max}(\mathtt{X},\mathtt{Y})\}$
- The correct formalisation of what was intended is probably
 - \vdash {X=x \land Y=y} C {Y=max(x,y)}
- The lesson
 - it is easy to write the wrong specification!
 - a proof system will not help since the incorrect programs could have been proved "correct"
 - testing would have helped!

Sorting

- \bullet Suppose \mathtt{C}_{sort} is a command that is intended to sort the first N elements of an array
- To specify this formally, let SORTED(A, N) mean

 $A(1) \le A(2) \le \ldots \le A(N)$

• A first attempt to specify that $\ensuremath{\mathtt{C}_{\textit{sort}}}$ sorts is

 $\{1 \leq N\} C_{sort} \{SORTED(A,N)\}$

- Not enough:
 - \bullet SORTED(A,N) can be achieved by simply zeroing the first N elements of A

Permutation Required

- It is necessary to require that the sorted array is a rearrangement, or permutation, of the original array
- To formalise this, let PERM(A, A', N) mean that

$$\begin{split} A(1), A(2), \dots, A(N) \\ \text{is a rearrangement of} \end{split}$$

 $A'(1), A'(2), \ldots, A'(N)$

• An improved specification that C_{sort} sorts:

 $\{1 \leq N \land A=a\} C_{sort} \{SORTED(A,N) \land PERM(A,a,N)\}$

Still Not Correct ...

• The following specification is true

 $\begin{array}{l} \{1 \leq \! N\} \\ N \! : = \! 1 \\ \{ \texttt{SORTED(A,N)} \ \land \ \texttt{PERM(A,a,N)} \} \end{array}$

- Must say explicitly that ${\tt N}$ is unchanged
- A better specification is thus:

 $\begin{array}{l} \{1 \leq \!\! \mathbb{N} \land A \!\! = \!\! a \land N \!\! = \!\! n \} \\ \mathbb{C}_{sort} \\ \{ \texttt{SORTED}(A, N) \land \texttt{PERM}(A, a, N) \land N \!\! = \!\! n \} \end{array}$

• Is this the correct specification?

Summary

- We have given a notation for specifying
 - the partial correctness of programs
 - the total correctness of programs
- Specifications can still be incorrect
 - however, their meaning is precise
- We next describe the predicate calculus:
 - the precise language upon which they are based

Review of Predicate Calculus

- Program states are specified with first-order logic (FOL)
- Knowledge of this is assumed (brief review given now)
- Later higher-order logic (HOL) will be:
 - used to semantically embed Floyd-Hoare logic
 - used for hardware specification
- In first-order logic there are two separate syntactic classes
 - Terms (or expressions): these denote values (e.g. numbers)
 - Statements (or formulae): these are either true or false
- In higher-order logic statements are a special case of terms
 because truth-values are values

Terms (Expressions)

- Statements are built out of *terms* which denote *values* such as numbers, strings and arrays
- Terms, like 1 and 4+5, denote a fixed value, and are called ground
- Other terms contain variables like x, X, y, X, z, Z etc
- We use conventional notation, e.g. here are some terms:

X, y, Z,
1, 2, 325,
-X, -(X+1),
$$(x \times y)+Z$$
,
 $\sqrt{(1+x^2)}$, X!, $\sin(x)$, $rem(X,Y)$

• Convention:

- program variables are uppercase
- auxiliary (i.e. logical) variables are lowercase

Atomic Statements

• Examples of atomic statements are

 $\label{eq:tau} T, \qquad F, \qquad X=1, \qquad R < Y, \qquad X=R\text{+}(Y{\times}Q)$

- T and F are atomic statements that are always true and false
- Other atomic statements are built from terms using *predicates*, e.g.

ODD(X), PRIME(3), X = 1, $(X+1)^2 \ge x^2$

- ODD and PRIME are examples of predicates
- $\bullet \ = and \geq are \ examples \ of \ infixed \ predicates$
- X, 1, 3, X+1, (X+1)², x² are terms in above atomic statements

Compound statements

• Compound statements are built up from atomic statements using:

 \neg (not)

V

- \land (and)
 - (or)
- $\Rightarrow \quad (\text{implies})$
- \Leftrightarrow (if and only if)
- The single arrow \rightarrow is commonly used for implication instead of \Rightarrow

• Suppose P and Q are statements, then

- $\neg P$ is true if P is false, and false if P is true
- $P \wedge Q$ is true whenever both P and Q are true
- $P \lor Q$ is true if either P or Q (or both) are true
- $P \Rightarrow Q$ is true if whenever P is true, then Q is true
- P ⇔ Q is true if P and Q are either both true or both false

More on Implication

- By convention we regard $P \Rightarrow Q$ as being true if P is false
- In fact, it is common to regard $P \Rightarrow Q$ as equivalent to $\neg P \lor Q$
- Some philosophers disagree with this treatment of implication
 - since any implication $A \Rightarrow B$ is true if A is false
 - e.g. (1 < 0) ⇒ (2 + 2 = 3)
 - search web for "paradoxes of implication"
- $P \Leftrightarrow Q$ is equivalent to $(P \Rightarrow Q) \land (Q \Rightarrow P)$
- Sometimes write P = Q or $P \equiv Q$ for $P \Leftrightarrow Q$
 - P = Q used in higher-order logic
 - $P \equiv Q$ used for definitions
 - also $P =_{def} Q$ used for definitions

Precedence

- To reduce the need for brackets it is assumed that
 - $\bullet \ \neg \ is \ more \ binding \ than \ \land \ and \ \lor$
 - $\bullet~\wedge$ and \lor are more binding than \Rightarrow and \Leftrightarrow

• For example

$\neg P \land Q$	is equivalent to	$(\neg P) \land Q$
$P \land Q \Rightarrow R$	is equivalent to	$(P \land Q) \Rightarrow R$
$P \wedge Q \Leftrightarrow \neg R \vee S$	is equivalent to	$(P \land Q) \Leftrightarrow ((\neg R) \lor S)$

Universal quantification

- If S is a statement and x a variable
- Then $\forall x. S$ means:

'for all values of x, the statement S is true'

- The statement abbreviates
- $\forall x_1 \ x_2 \ \dots \ x_n. \ S$

 $\forall x_1. \ \forall x_2. \ \dots \ \forall x_n. \ S$

- It is usual to adopt the convention that any unbound (i.e. *free*) variables in a statement are to be regarded as implicitly universally quantified
- For example, if *n* is a variable then the statement *n*+0 = *n* is regarded as meaning the same as *∀n*. *n* + 0 = *n*

Example

• Let us abbreviate

 $x_1 \le x_2 \land x_2 \le x_3 \land \ldots \land x_{n-1} \le x_n$

 $\mathbf{b}\mathbf{y}$

 $x_1 \le x_2 \le x_3 \le \ldots \le x_{n-1} \le x_n$

• Recall that SORTED(A, N) means that

 $A(1) \le A(2) \le \ldots \le A(N)$

 $\bullet~$ The definition of SORTED can now be given formally

 $\begin{array}{ll} \text{SORTED}(A,N) &\equiv \\ \forall I \ J. \ 1 \leq I \leq J \leq N \ \Rightarrow \ A(I) \leq A(J) \end{array}$

- Comment on Definition of SORTED
- The symbol ≡ is synonymous with ⇔ and means 'if and only if'
 it is used to introduce the definitions of constants
- Notice that A and N are unbound variables in

$$\begin{array}{ll} \text{SORTED}(A,N) &\equiv \\ \forall I \ J. \ 1 \leq I \leq J \leq N \ \Rightarrow \ A(I) \leq A(J) \end{array}$$

 $\forall A$

- Unbound variables are regarded as implicitly universally quantified
- The definition of SORTED could thus have been written as

$$\begin{array}{ll} N. \ {\rm SORTED}(A,N) & \equiv \\ \forall I \ J. \ 1 \leq I \leq J \leq N \ \Rightarrow \ A(I) \leq A(J) \end{array}$$

Existential quantification

- If S is a statement and x a variable
- Then $\exists x. S$ means

'for some value of x, the statement S is true'

• The statement

abbreviates

 $\exists x_1 \ x_2 \ \dots \ x_n. \ S$ $\exists x_1. \ \exists x_2. \ \dots \ \exists x_n. \ S$

PERM(A, a, N)

• PERM(A, a, N) easy to define if one can quantify over functions

 $\begin{array}{l} PERM(A,a,N) = \\ \exists f. \quad (\forall n. \ n \le N \Rightarrow f(n) \le N) \land \\ (\forall m \ n. \ m \le N \land n \le N \land f(m) = f(n) \Rightarrow m = n) \land \\ (\forall n. \ n \le N \Rightarrow a(n) = A(f(n))) \end{array}$

• Exercise: specify PERM(A, a, N) in first-order logic

Summary

- Predicate calculus forms the basis for program specification
- It is used to describe the acceptable initial states, and intended final states of programs
- We will next look at how to prove programs meet their specifications
- Proof of theorems within predicate calculus assumed known!

Floyd-Hoare Logic

- To construct formal proofs of partial correctness specifications, axioms and rules of inference are needed
- This is what Floyd-Hoare logic provides
 - the formulation of the deductive system is due to Hoare
 - some of the underlying ideas originated with Floyd
- A proof in Floyd-Hoare logic is a sequence of lines, each of which is either an *axiom* of the logic or follows from earlier lines by a *rule of inference* of the logic
 - proofs can also be trees, if you prefer
- A formal proof makes explicit what axioms and rules of inference are used to arrive at a conclusion

Notation for Axioms and Rules

- If S is a statement, $\vdash S$ means S has a proof
 - statements that have proofs are called theorems
- The axioms of Floyd-Hoare logic are specified by schemas
 - these can be instantiated to get particular partial correctness specifications
- The inference rules of Floyd-Hoare logic will be specified with a notation of the form

- this means the $\mathit{conclusion} \vdash S$ may be deduced from the hypotheses $\vdash S_1, \ldots, \vdash S_n$
- the hypotheses can either all be theorems of Floyd-Hoare logic
- or a mixture of theorems of Floyd-Hoare logic and theorems of mathematics

An example rule

The sequencing rule

$$\vdash \{P\} C_1 \{Q\}, \quad \vdash \{Q\} C_2 \{R\} \\ \vdash \{P\} C_1; C_2 \{R\}$$

- If a proof has lines matching $\vdash \{P\} C_1 \{Q\}$ and $\vdash \{Q\} C_2 \{R\}$
- One may deduce a new line $\vdash \{P\} C_1; C_2 \{R\}$
- For example if one has deduced: ⊢ {X=1} X:=X+1 {X=2}
- $\vdash {\tt X=2} \tt X:=X+1 \tt \{X=3\}$ • One may then deduce:
 - $\vdash \ {\tt X=1} \ {\tt X:=X+1} \ {\tt X:=X+1} \ {\tt X=3} \\$
- Method of verification conditions (VCs) generates proof obligation \vdash X=1 \Rightarrow X+(X+1)=3
 - VCs are handed to a theorem prover
 - "Extended Static Checking" (ESC) is an industrial example

Invalid 'Proofs'

- It is quite easy to come up with plausible rules for reasoning about programs that are actually unsound
 - some examples for FOR-commands are given later
- Proofs of correctness of computer programs are often very intricate and formal methods are needed to ensure that they are valid
- It is thus important to make fully explicit the reasoning principles • being used, so that their soundness can be analysed
- Soundness and completeness will be discussed informally later
- Here is a bogus proof

5.

 $\begin{array}{ll} 1. & \sqrt{-1 \times -1} & = \sqrt{-1 \times -1} & \text{Reflexivity of } =. \\ 2. & \sqrt{-1 \times -1} & = (\sqrt{-1}) \times (\sqrt{-1}) & \text{Distributive law of } \sqrt{-} \text{ over } \times. \\ 3. & \sqrt{-1 \times -1} & = (\sqrt{-1})^2 & \text{Definition of } ()^2. \end{array}$ $\begin{array}{rcl}
0. & \sqrt{-1 \times -1} & = -(\sqrt{-1} \times -1) \\
4. & \sqrt{-1 \times -1} & = -1 \\
5. & \sqrt{1} & = -1
\end{array}$ definition of $\sqrt{}$. As $-1 \times -1 = 1$. As $\sqrt{1} = 1$. = -1= -1 6.1

• See link Some classic fallacies on course web page

Proof Rules For Partial Correctness

Overview

• The proof rules that follow constitute an *axiomatic semantics* of our programming language (more on "axiomatic semantics" later)

- Arrays and FOR-commands are tricky and discussed in a later lecture
- One-armed conditionals will be used to illustrate derived semantics

Judgements

- Three kinds of things that could be true or false:
 - statements of mathematics, e.g. $(\mathtt{X}+\mathtt{1})^2=\mathtt{X}^2+2\times\mathtt{X}+\mathtt{1}$
 - partial correctness specifications $\{P\}\ C\ \{Q\}$
 - total correctness specifications $[P] \ C \ [Q]$
- These three kinds of things are examples of *judgements*
 - a logical system gives rules for proving judgements
 - Floyd-Hoare logic provides rules for proving partial correctness specifications
 - the laws of arithmetic provide ways of proving statements about integers
- $\vdash S$ means statement S can be proved
 - how to prove predicate calculus statements assumed known
 - this course covers axioms and rules for proving program correctness statements

Syntactic Conventions

- Symbols V, V₁, ..., V_n stand for arbitrary variables
 examples of particular variables are X, R, Q etc
- Symbols E, E_1, \ldots, E_n stand for arbitrary expressions (or terms)
 - \bullet these are things like $X+1,\,\sqrt{2}$ etc. which denote values (usually numbers)
- Symbols S, S_1, \ldots, S_n stand for arbitrary statements
 - these are conditions like X < Y, X² = 1 etc. which are either true or false
 will also use P, Q, R to range over pre and postconditions
- Symbols C, C_1, \ldots, C_n stand for arbitrary commands

Skip

- Syntax: SKIP
- Semantics: the state is unchanged

The Skip Axiom

 $\vdash \{P\}$ SKIP $\{P\}$

- It is an axiom schema
 - $\bullet~P$ can be instantiated with arbitrary predicate calculus formulae (statements)
- Instances of the skip axiom are:
 - $\vdash \{Y = 2\}$ SKIP $\{Y = 2\}$
 - \vdash {T} SKIP {T}
 - $\vdash \{ R=X+(Y \times Q) \} \text{ SKIP } \{ R=X+(Y \times Q) \}$

Substitution Notation

- Q[E/V] is the result of replacing all occurrences of V in Q by E
 - read Q[E/V] as 'Q with E for V'
 - for example: (X+1 > X)[Y+Z/X] = ((Y+Z)+1 > Y+Z)
 - ignoring issues with bound variables for now (e.g. variable capture)
- Same notation for substituting into terms, e.g. $E_1[E_2/V]$
- Think of this notation as the 'cancellation law'

V[E/V] = E

which is analogous to the cancellation property of fractions

 $v \times (e/v) ~=~ e$

• Note that Q[x/V] doesn't contain V (if $V \neq x$)

The Assignment Axiom (Hoare)

- Syntax: V := E
- Semantics: value of V in final state is value of E in initial state
- Example: X:=X+1 (adds one to the value of the variable X)

The Assignment Axiom

 $\vdash \{Q[E/V]\} V := E \{Q\}$

Where V is any variable, ${\cal E}$ is any expression, Q is any statement.

• Instances of the assignment axiom are

- $\bullet \hspace{0.2cm} \vdash \hspace{0.2cm} \{E=x\} \hspace{0.2cm} V:=E \hspace{0.2cm} \{V=x\}$
- $\bullet \hspace{0.2cm} \vdash \hspace{0.2cm} \{Y=2\} \hspace{0.2cm} X:=2 \hspace{0.2cm} \{Y=X\}$
- $\bullet \ \vdash \ \{X+1=n+1\} \ X:=X+1 \ \{X=n+1\}$
- $\vdash \{E = E\} X := E \{X = E\}$ (if X does not occur in E)

The Backwards Fallacy

- Many people feel the assignment axiom is 'backwards'
- One common erroneous intuition is that it should be

 $\vdash \{P\} V := E \{P[V/E]\}$

- where P[V/E] denotes the result of substituting V for E in P
- this has the false consequence $\vdash {X=0} X:=1 {X=0}$ (since (X=0)[X/1] is equal to (X=0) as 1 doesn't occur in (X=0))
- Another erroneous intuition is that it should be

 $\vdash \{P\} V := E \{P[E/V]\}$

 this has the false consequence ⊢ {X=0} X:=1 {1=0} (which follows by taking P to be X=0, V to be X and E to be 1)

A Forwards Assignment Axiom (Floyd)

• This is the original semantics of assignment due to Floyd

 $\vdash \{P\} V := E \{\exists v. V = E[v/V] \land P[v/V]\}$

- where v is a new variable (i.e. doesn't equal V or occur in P or E)
- Example instance

 $\vdash \hspace{0.1 cm} \{ \texttt{X=1} \} \hspace{0.1 cm} \texttt{X:=X+1} \hspace{0.1 cm} \{ \exists v. \hspace{0.1 cm} \texttt{X} = \texttt{X+1} \hspace{0.1 cm} [v/\texttt{X}] \hspace{0.1 cm} \land \hspace{0.1 cm} \texttt{X=1} \hspace{0.1 cm} [v/\texttt{X}] \hspace{0.1 cm} \}$

• Simplifying the postcondition

 $\vdash \{X=1\} X:=X+1 \{ \exists v. X = X+1[v/X] \land X=1[v/X] \}$

- $\vdash \hspace{0.1 cm} \{ \texttt{X=1} \} \hspace{0.1 cm} \texttt{X:=X+1} \hspace{0.1 cm} \{ \exists v. \hspace{0.1 cm} \texttt{X} = v+1 \hspace{0.1 cm} \land \hspace{0.1 cm} v=1 \}$
- $\vdash \{X=1\} X := X+1 \{ \exists v. X = 1+1 \land v = 1 \}$
- $\vdash \{X=1\} X := X+1 \{X = 1 + 1 \land \exists v. v = 1\} \\ \vdash \{X=1\} X := X+1 \{X = 2 \land T\}$
- $\vdash \{X=1\} X := X+1 \{X=2\}$
- Forwards Axiom equivalent to standard one but harder to use

Precondition Strengthening

• Recall that

$$\begin{array}{cccc} \vdash S_1, \ \dots, \ \vdash \ S_n \\ \hline \vdash \ S \end{array}$$

means $\vdash S$ can be deduced from $\vdash S_1, \ldots, \vdash S_n$

• Using this notation, the rule of precondition strengthening is

Precondition strengthening

$$\frac{\vdash P \Rightarrow P', \quad \vdash \{P'\} C \{Q\}}{\vdash \{P\} C \{Q\}}$$

• Note the two hypotheses are different kinds of judgements

Example

```
• From
```

 $\bullet \hspace{0.1in} \vdash \hspace{0.1in} \texttt{X=n} \hspace{0.1in} \Rightarrow \hspace{0.1in} \texttt{X+1=n+1}$

```
• trivial arithmetical fact
```

 $\bullet \ \vdash \ \{X+1=n+1\} \ X:=X+1 \ \{X=n+1\}$

• from earlier slide

• It follows by precondition strengthening that

 $\vdash \ \{ X = n \} \ X := X + 1 \ \{ X = n + 1 \}$

• Note that n is an *auxiliary* (or *ghost*) variable

Postcondition weakening

• Just as the previous rule allows the precondition of a partial correctness specification to be strengthened, the following one allows us to weaken the postcondition

Postcondition weakening

$$\frac{\vdash \ \{P\} \ C \ \{Q'\}, \qquad \vdash \ Q' \Rightarrow Q}{\vdash \ \{P\} \ C \ \{Q\}}$$

Validity

- Important to establish the validity of axioms and rules
- Can give a *formal semantics* of our little programming language
 - then prove axioms and rules of inference of Floyd-Hoare logic are sound
 - this will only increase our confidence in the axioms and rules to the extent that we believe the correctness of the formal semantics!
- Won't go into this topic here (some discussion later)
- The Assignment Axiom is not valid for 'real' programming languages
 - In an early PhD on Hoare Logic G. Ligler showed that the assignment axiom can fail to hold in six different ways for the language Algol 60

Expressions with Side-effects

- The validity of the assignment axiom depends on expressions not having side effects
- Suppose that our language were extended so that it contained the 'block expression'

BEGIN Y:=1; 2 END

- this expression has value 2, but its evaluation also 'side effects' the variable Y by storing 1 in it
- If the assignment axiom applied to block expressions, then it could be used to deduce

⊢ {Y=0} X:=BEGIN Y:=1; 2 END {Y=0}

- since (Y=0)[E/X] = (Y=0) (because X does not occur in (Y=0))
- this is clearly false; after the assignment Y will have the value 1

An Example Formal Proof

• Here is a little formal proof

5

- 1. $\vdash \ \{\texttt{R=X} \land \texttt{0=0}\} \ \texttt{Q:=0} \ \{\texttt{R=X} \land \texttt{Q=0}\}$ By the assignment axiom
- $2 \vdash \mathbf{R} = \mathbf{X} \implies \mathbf{R} = \mathbf{X} \land \mathbf{0} = \mathbf{0}$ By pure logic 3. \vdash {R=X} Q:=0 {R=X \land Q=0}
 - By precondition strengthening $\vdash \texttt{R=X} \land \texttt{Q=0} \ \Rightarrow \ \texttt{R=X+(Y \times Q)}$ By laws of arithmetic
 - $\vdash \ {\tt R=X} \ {\tt Q:=O} \ {\tt R=X+(Y\times Q)} \ {\tt Q}$ By postcondition weakening
- The rules precondition strengthening and postcondition weakening are sometimes called the rules of consequence

The sequencing rule

- Syntax: C_1 ; \cdots ; C_n
- Semantics: the commands C_1, \dots, C_n are executed in that order
- Example: R:=X; X:=Y; Y:=R
 - \bullet the values of X and Y are swapped using R as a temporary variable
 - note side effect: value of R changed to the old value of X

The sequencing rule

 $\frac{\vdash \{P\} C_1 \{Q\}, \quad \vdash \{Q\} C_2 \{R\}}{\vdash \{P\} C_1; C_2 \{R\}}$

Example Proof

Example: By the assignment axiom:

- (i) \vdash {X=x \land Y=y} R:=X {R=x \land Y=y}
- (ii) \vdash {R=x \land Y=y} X:=Y {R=x \land X=y}
- (iii) \vdash {R=x \land X=y} Y:=R {Y=x \land X=y}

Hence by (i), (ii) and the sequencing rule

(iv) ⊢ {X=x∧Y=y} R:=X; X:=Y {R=x∧X=y}

Hence by (iv) and (iii) and the sequencing rule

 $(v) \ \vdash \ \{\texttt{X=x} \land \texttt{Y=y}\} \ \texttt{R:=X}; \ \texttt{X:=Y}; \ \texttt{Y:=R} \ \{\texttt{Y=x} \land \texttt{X=y}\}$

Blocks

- Syntax: BEGIN VAR V_1 ; · · · VAR V_n ; C END
- Semantics: command C is executed, then the values of V_1, \cdots, V_n are restored to the values they had before the block was entered

• the initial values of V_1, \cdots, V_n inside the block are unspecified

- Example: BEGIN VAR R; R:=X; X:=Y; Y:=R END
 - \bullet the values of X and Y are swapped using R as a temporary variable
 - this command does not have a side effect on the variable R

The Block Rule

• The block rule takes care of local variables

The block rule

$$\begin{array}{c|c} & \vdash \ \{P\} \ C \ \{Q\} \\ \hline & \vdash \ \{P\} \ \text{Begin var} \ V_1; \ \dots; \ \text{var} \ V_n; \ C \ \text{end} \ \{Q\} \end{array}$$

where none of the variables V_1, \ldots, V_n occur in P or Q.

• Note that the block rule is regarded as including the case when there are no local variables (the 'n = 0' case)

The Side Condition

• The syntactic condition that none of the variables V_1, \ldots, V_n occur in P or Q is an example of a *side condition*

• From

 $\begin{array}{l} \vdash \{X{=}x \ \land \ Y{=}y\} \ R{:=}X; \ X{:=}Y; \ Y{:=}R \ \{Y{=}x \ \land \ X{=}y\} \\ \text{it follows by the block rule that} \\ \vdash \{X{=}x \ \land \ Y{=}y\} \ BEGIN \ VAR \ R; \ R{:=}X; \ X{:=}Y; \ Y{:=}R \ END \quad \{Y{=}x \ \land \ X{=}y\} \\ \text{since } R \ does \ not \ occur \ in \ X{=}x \ \land \ Y{=}y \ or \ X{=}y \ \land \ Y{=}x \end{array}$

• However from

 $\label{eq:rescaled} \begin{array}{l} \vdash \{X{=}x \ \land \ Y{=}y\} \ R{:=}X; \ X{:=}Y \ \{R{=}x \ \land \ X{=}y\} \\ \textbf{one cannot deduce} \\ \vdash \{X{=}x \ \land \ Y{=}y\} \ BEGIN \ VAR \ R; \ R{:=}X; \ X{:=}Y \ END \ \{R{=}x \ \land \ X{=}y\} \\ \textbf{since } R \ occurs \ in \ R{=}x \ \land \ X{=}y \end{array}$

Exercises

• Consider the specification

{X=x} BEGIN VAR X; X:=1 END {X=x}

Can this be deduced from the rules given so far? (i) if so, give a proof of it

(ii) if not, explain why not and suggest additional rules and/or axioms to enable it to be deduced

- Is the following true?
 - $\vdash \{X=x \land Y=y\} X:=X+Y; Y:=X-Y; X:=X-Y \{Y=x \land X=y\}$
 - if so prove it
 - if not, give the circumstances when it fails
- Show
 - \vdash {X=R+(Y×Q)} BEGIN R:=R-Y; Q:=Q+1 END {X=R+(Y×Q)}

Two-armed conditionals

- Syntax: IF S THEN C₁ ELSE C₂
- Semantics:
 - if the statement S is true in the current state, then C_1 is executed
 - if S is false, then C₂ is executed
- Example: IF X<Y THEN MAX:=Y ELSE MAX:=X
 - \bullet the value of the variable MAX it set to the maximum of the values of X and Y
- One-armed conditional is defined by:
 - IF S then $C =_{define}$ IF S then C else skip

The Conditional Rule

The conditional rule

 $\vdash \{P \land S\} C_1 \{Q\}, \qquad \vdash \{P \land \neg S\} C_2 \{Q\} \\ \vdash \{P\} \text{ IF } S \text{ THEN } C_1 \text{ ELSE } C_2 \{Q\}$

• From Assignment Axiom + Precondition Strengthening and

 $\vdash (X{\geq}Y \ \Rightarrow \ X \ = \ \max(X,Y)) \ \land \ (\neg(X{\geq}Y) \ \Rightarrow \ Y \ = \ \max(X,Y))$ it follows that

 $\vdash \ \{\texttt{T} \ \land \ \texttt{X}{\geq}\texttt{Y}\} \ \texttt{MAX}{:=}\texttt{X} \ \{\texttt{MAX}{=}\texttt{max}(\texttt{X},\texttt{Y})\}$

- and
- $\vdash \ \left\{ \texttt{T} \ \land \ \neg(\texttt{X}{\geq}\texttt{Y}) \right\} \ \texttt{MAX}{:=}\texttt{Y} \ \left\{ \texttt{MAX}{=}\texttt{max}(\texttt{X},\texttt{Y}) \right\}$
- Then by the conditional rule it follows that
 - $\ \ \vdash \ \{T\} \ \ IF \ X \geq Y \ \ THEN \ \ MAX:=X \ ELSE \ MAX:=Y \ \{MAX=max(X,Y)\}$
- A one-armed conditional rule is derived later

WHILE-commands

- Syntax: WHILE S DO C
- Semantics:
 - if the statement S is true in the current state, then C is executed and the <code>WHILE-command</code> is repeated
 - if S is false, then nothing is done
 - thus ${\cal C}$ is repeatedly executed until the value of ${\cal S}$ becomes false
 - if ${\boldsymbol{S}}$ never becomes false, then the execution of the command never terminates
- Example: WHILE ¬(X=0) DO X:= X-2
 - $\bullet\,$ if the value of X is non-zero, then its value is decreased by 2 and then the process is repeated
- This <code>WHILE-command</code> will terminate (with X having value 0) if the value of X is an even non-negative number
 - in all other states it will not terminate

Invariants

- Suppose $\vdash \{P \land S\} \subset \{P\}$
- P is said to be an *invariant* of C whenever S holds
- The WHILE-rule says that
 - **if** *P* is an invariant of the body of a WHILE-command whenever the test condition holds
 - then P is an invariant of the whole WHILE-command
- In other words
 - \bullet if executing C once preserves the truth of P
 - then executing C any number of times also preserves the truth of P
- The WHILE-rule also expresses the fact that after a WHILE-command has terminated, the test must be false
 - otherwise, it wouldn't have terminated

The WHILE-Rule

The WHILE-rule

 $\vdash \{P \land S\} C \{P\}$ $\vdash \{P\} \text{ WHILE } S \text{ DO } C \{P \land \neg S\}$

• It is easy to show

 $\vdash \{X=R+(Y\times Q) \land Y \leq R\} \text{ BEGIN } R:=R-Y; Q:=Q+1 \text{ END } \{X=R+(Y\times Q)\}$

- Hence by the WHILE-rule with $P = 'X=R+(Y \times Q)'$ and $S = 'Y \leq R'$
 - $\label{eq:constraint} \begin{array}{l} \vdash \left\{ X{=}R{+}(Y{\times}\mathbb{Q}) \right\} \\ & \text{WHILE } Y{\leq}R \text{ DO} \\ & \text{BEGIN } R{:}{=}R{-}Y; \ \mathbb{Q}{:}{=}\mathbb{Q}{+}1 \text{ END} \\ & \left\{ X{=}R{+}(Y{\times}\mathbb{Q}) \ \land \ \neg(Y{\leq}R) \right\} \end{array}$

Example

• From the previous slide

```
\begin{array}{l} \vdash \begin{array}{l} \left\{ \texttt{X=R+(Y\times Q)} \right\} \\ & \texttt{WHILE } Y {\leq} \texttt{R} \texttt{ DO} \\ & \texttt{BEGIN } \texttt{R:=R-Y; } \texttt{Q:=Q+1 } \texttt{END} \\ & \left\{ \texttt{X=R+(Y\times Q)} \ \land \ \neg (Y {\leq} \texttt{R}) \right\} \end{array}
```

• It is easy to deduce that

 \vdash {T} R:=X; Q:=O {X=R+(Y \times Q)}

- Hence by the sequencing rule and postcondition weakening
 - $\begin{array}{l} \vdash \{T\} \\ & R:=X; \\ & Q:=0; \\ & WHILE \; Y \leq R \; DO \\ & BEGIN \; R:=R-Y; \; Q:=Q+1 \; END \\ & \{R < Y \; \land \; X = R + (Y \times Q)\} \end{array}$

Summary

- We have given:
 - a notation for specifying what a program does
 - a way of proving that it meets its specification
- Now we look at ways of finding proofs and organising them:
 - finding invariants
 - derived rules
 - backwards proofs
 - annotating programs prior to proof
- Then we see how to automate program verification
 - the automation mechanises some of these ideas

How does one find an invariant?

$\mathbf{The} \ \mathtt{WHILE}\textbf{-rule}$

- Look at the facts:
 - invariant P must hold initially
 - with the negated test $\neg S$ the invariant P must establish the result
 - \bullet when the test S holds, the body must leave the invariant P unchanged
- Think about how the loop works the invariant should say that:
 - what has been done so far together with what remains to be done
 - holds at each iteration of the loop
 - and gives the desired result when the loop terminates

Example

• Consider a factorial program

 $\begin{array}{ll} \{X=n \ \land \ Y=1\} \\ & \mbox{ while } X \neq 0 \ \ DO \\ & \mbox{ BEGIN } Y:=Y \times X; \ X:=X-1 \ \ END \\ & \ \{X=0 \ \land \ Y=n\,!\,\} \end{array}$

- Look at the facts
 - initially X=n and Y=1
 - finally X=0 and Y=n!
 - \bullet on each loop Y is increased and, X is decreased
- Think how the loop works
 - Y holds the result so far
 - X! is what remains to be computed
 - n! is the desired result
- The invariant is X!×Y = n!
 - 'stuff to be done' \times 'result so far' = 'desired result'
 - decrease in X combines with increase in Y to make invariant

Related example

```
{X=0 ^ Y=1}
WHILE X<N DO
BEGIN X:=X+1; Y:=Y×X END
{Y=N!}
```

- Look at the Facts
 - \bullet initially X=0 and Y=1
 - finally X=N and Y=N!
 - \bullet on each iteration both X an Y increase: X by 1 and Y by X
- An invariant is Y = X!
- At end need Y = N!, but WHILE-rule only gives $\neg(X < N)$
- Ah Ha! Invariant needed: $Y = X! \land X \leq N$
- At end $X \leq N \land \neg(X < N) \Rightarrow X=N$
- Often need to strenthen invariants to get them to work
 typical to add stuff to 'carry along' like X≤N

Conjunction and Disjunction

Specification conjunction

$$\frac{\vdash \{P_1\} C \{Q_1\}, \vdash \{P_2\} C \{Q_2\}}{\vdash \{P_1 \land P_2\} C \{Q_1 \land Q_2\}}$$

Specification disjunction

 $\frac{\vdash \{P_1\} C \{Q_1\}, \quad \vdash \{P_2\} C \{Q_2\}}{\vdash \{P_1 \lor P_2\} C \{Q_1 \lor Q_2\}}$

• These rules are useful for splitting a proof into independent bits

• they enable \vdash {P} C {Q₁ \land Q₂} to be proved by proving separately that both \vdash {P} C {Q₁} and also that \vdash {P} C {Q₂}

• Any proof with these rules could be done without using them

- i.e. they are theoretically redundant (proof omitted)
- however, useful in practice

Combining Multiple Steps

- Proofs involve lots of tedious fiddly small steps
 - similar sequences are used over and over again
- It is tempting to take short cuts and apply several rules at once
 - this increases the chance of making mistakes
- Example:
 - by assignment axiom & precondition strengthening
 - $\bullet \hspace{0.1in} \vdash \hspace{0.1in} \{\mathtt{T}\} \hspace{0.1in} \mathtt{R} := \mathtt{X} \hspace{0.1in} \{\mathtt{R} = \mathtt{X}\}$
- Rather than:
 - by the assignment axiom
 - $\bullet \hspace{0.1in} \vdash \hspace{0.1in} \{{\tt X}={\tt X}\} \hspace{0.1in} {\tt R}:={\tt X} \hspace{0.1in} \{{\tt R}={\tt X}\}$

```
• by precondition strengthening with \ \vdash \ \mathtt{T} \ \Rightarrow \ \mathtt{X=X}
```

```
\bullet \hspace{0.1in} \vdash \hspace{0.1in} \{T\} \hspace{0.1in} R := X \hspace{0.1in} \{R = X\}
```

Derived rules for finding proofs

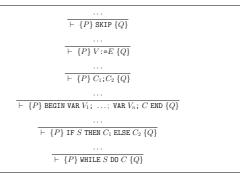
- Suppose the goal is to prove {*Precondition*} Command {*Postcondition*}
- If there were a rule of the form

$$\frac{\vdash H_1, \ \cdots, \ \vdash \ H_n}{\vdash \ \{P\} \ C \ \{Q\}}$$

- then we could instantiate $P \mapsto \textit{Precondition}, \ C \mapsto \textit{Command}, \ Q \mapsto \textit{Postcondition}$ to get instances of H_1, \dots, H_n as subgoals
- Some of the rules are already in this form e.g. the sequencing rule
- We will derive rules of this form for all commands
- Then we use these derived rules for mechanising Hoare Logic proofs

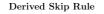
Derived Rules

• We will establish derived rules for all commands



• These support 'backwards proof' starting from a goal $\{P\} \ C \ \{Q\}$

The Derived Skip Rule



$\vdash P \Rightarrow Q$ \vdash {P} SKIP {Q}

• Justifying proof schema:

- $\vdash P \Rightarrow Q \qquad \text{By assumption.} \\ \vdash \{Q\} \text{ SKIP } \{Q\} \qquad \text{By the skip axiom.} \end{cases}$
- 2
- 3. \vdash {P} SKIP {Q} By precondition strengthening with 1 and 2.
- This schematic proof shows that any inference with the Derived Skip Rule can be replaced by three inferences using primitive rules
- Derived rules are 'proof subroutines'
 - the schema metavariables (P, Q above) are the parameters of the subroutine
 - the derivation schema is the body of the subroutine

- The Derived Assignment Rule
- An example proof
- 1. \vdash {R=X \land 0=0} Q:=0 {R=X \land Q=0} By the assignment axiom.
- \vdash R=X \Rightarrow R=X \land 0=0 By pure logic.
- 3. \vdash {R=X} Q:=0 {R=X \land Q=0} By precondition strengthening.
- Can generalise this proof to a proof schema:
- By precondition strengthening.
- This proof schema justifies:

Derived Assignment Rule

 $\vdash P \Rightarrow Q[E/V]$ $\vdash \{P\} V := E \{Q\}$

- Note: Q[E/V] is the weakest liberal precondition wlp(V:=E,Q)
- Example proof above can now be done in one less step
- $1. \quad \vdash \ \mathtt{R=X} \ \Rightarrow \ \mathtt{R=X} \land \mathtt{0=0}$ By pure logic
- 2. \vdash {R=X} Q:=0 {R=X \land Q=0} By derived assignment.

Derived Sequenced Assignment Rule

• The following rule will be useful later

Derived Sequenced Assignment Rule

 $\begin{array}{c} \vdash \ \{P\} \ C \ \{Q\llbracket E/V\rrbracket\} \\ \hline \vdash \ \{P\} \ C; V := E \ \{Q\} \end{array}$

- Exercise: give a proof schema to justify this
- Intuitively work backwards:

- push Q 'through' $V{:=}E,$ changing it to Q[E/V]

• Example: By the assignment axiom:

 $\vdash \ \{\texttt{X=x}{\wedge}\texttt{Y=y}\} \ \texttt{R:=X} \ \{\texttt{R=x}{\wedge}\texttt{Y=y}\}$

• Hence by the sequenced assignment rule

 $\vdash \ \{\texttt{X=x} \land \texttt{Y=y}\} \ \texttt{R:=X}; \ \texttt{X:=Y} \ \{\texttt{R=x} \land \texttt{X=y}\}$

Backward Hoare & forward Floyd assignment axioms

• Recall Hoare (backward) and Floyd (forward) assignment axioms

Hoare axiom: $\vdash \{P[E/V]\} V := E\{P\}$

Floyd axiom: $\vdash \{P\} V := E \{\exists v. V = E[v/V] \land P[v/V]\}$

- Exercise 1 (easy): derive forward axiom from Hoare axiom
 hint: P ⇒ ∃v. E = E[v/V] ∧ P[v/V]
- Exercise 2 (a bit harder): derive Hoare axiom from forward axiom
 hint: if v is a new variable then P[E/V][v/V] = P[E[v/V]/V]
- Exercise 3: devise and justify a derived assignment rule based on the Floyd assignment axiom

The Derived While Rule

Derived While Rule

$$\label{eq:response} \begin{array}{c|c} \vdash \ P \Rightarrow R & \vdash \ \{R \ \land \ S\} \ {\tt C} \ \{R\} & \vdash \ R \land \ \neg S \ \Rightarrow Q \\ \hline & \vdash \ \{P\} \ {\tt WHILE} \ {\tt S} \ {\tt DO} \ {\tt C} \ \{Q\} \end{array}$$

- This follows from the While Rule and the rules of consequence
- Example: it is easy to show
 - $\vdash \quad \texttt{R=X} \ \land \ \texttt{Q=0} \ \Rightarrow \ \texttt{X=R+(Y\times Q)}$
 - $\vdash \hspace{0.1 in} \left\{ \texttt{X=R+(Y \times \texttt{Q}) \land Y \leq R} \right\} \hspace{0.1 in} \texttt{R}:=\texttt{R-Y}; \hspace{0.1 in} \texttt{Q}:=\texttt{Q+1} \hspace{0.1 in} \left\{ \texttt{X=R+(Y \times \texttt{Q})} \right\}$
 - $\vdash \quad \texttt{X=R+(Y \times Q)} \land \neg (\texttt{Y} \leq \texttt{R}) \ \Rightarrow \ \texttt{X=R+(Y \times Q)} \land \neg (\texttt{Y} \leq \texttt{R})$
- Then, by the derived While rule
 - $\label{eq:constraint} \begin{array}{l} \vdash & \{\text{R=X} \ \land \ \text{Q=0} \} \\ & \text{WHILE} \ \text{Y} {\leq} \text{R} \ \text{DO} \\ & \text{R:=R-Y;} \ \ \text{Q:=Q+1} \\ & \{\text{X=R+(Y \times Q)} \ \land \ \neg (Y {\leq} \text{R}) \} \end{array}$

The Derived Sequencing Rule

• The rule below follows from the sequencing and consequence rules

The Derived Sequencing Rule $\vdash P \Rightarrow P_1$ $\vdash \{P_1\} C_1 \{Q_1\} \vdash Q_1 \Rightarrow P_2$ $\vdash \{P_2\} C_2 \{Q_2\} \vdash Q_2 \Rightarrow P_3$ \vdots \vdots $\vdash \{P_n\} C_n \{Q_n\} \vdash Q_n \Rightarrow Q$ $\vdash \{P\} C_1; \ldots; C_n \{Q\}$

• Exercise: why no derived conditional rule?

Example

• By the assignment axiom

(i) \vdash {X=x \land Y=y} R:=X {R=x \land Y=y} (ii) \vdash {R=x \land Y=y} X:=Y {R=x \land X=y} (iii) \vdash {R=x \land X=y} Y:=R {Y=x \land X=y}

- Using the derived sequencing rule, it can be deduced in one step from (i), (ii), (iii) and the fact that for any $P: \vdash P \Rightarrow P$
 - $\vdash \{X=x \land Y=y\} R:=X; X:=Y; Y:=R \{Y=x \land X=y\}$

Derived Block Rule

wh

• From the derived sequencing rule and the block rule the following rule for blocks can be derived

The Derived Block Rule	
$ \begin{array}{ccc} \vdash & P \Rightarrow P_1 \\ \vdash & \{P_1\} & C_1 & \{Q_1\} & \vdash & Q_1 \Rightarrow P_2 \\ \vdash & \{P_2\} & C_2 & \{Q_2\} & \vdash & Q_2 \Rightarrow P_3 \end{array} $	
$\begin{array}{c} 1 \\ 1 \\ 2 \\ 1 \\ 2 \\ 1 \\ 2 \\ 1 \\ 2 \\ 1 \\ 2 \\ 2$	
$\begin{array}{cccc} & & & \\ & & \vdash & \{P_n\} \ C_n \ \{Q_n\} & \vdash & Q_n \Rightarrow Q \\ & & \vdash & \{P\} \ \texttt{BEGIN VAR} \ V_1; \ \dots \ \texttt{VAR} \ V_m; C_1; \ \dots \ ; \ C_n \ \{Q\} \end{array}$	
ere none of the variables V_1, \ldots, V_m occur in P or Q .	

Example

- By the assignment axiom
 - (i) \vdash {X=x \land Y=y} R:=X {R=x \land Y=y} (ii) \vdash {R=x \land Y=y} X:=Y {R=x \land X=y}
- (iii) \vdash {R=x \land X=y} Y:=R {Y=x \land X=y}
- Using the derived block rule, it can be deduced in one step from (i), (ii) and (iii) that

 $\vdash \ \{\texttt{X=x} \land \texttt{Y=y}\}$ BEGIN VAR R; R:=X; X:=Y; Y:=R END $\{\texttt{Y=x} \land \texttt{X=y}\}$

- Deriving Rules for New Commands
- Suppose we define a one-armed conditional by: IF S THEN $C \equiv$ IF S THEN C ELSE SKIP
- We can derive the following rule:

⊢

The One-Armed Conditional Rule

$$\begin{array}{c|c} \{P \land S\} \ C \ \{Q\} & \vdash \ P \land \neg S \Rightarrow Q \\ \hline & \vdash \ \{P\} \ \text{IF } S \ \text{THEN } C \ \{Q\} \end{array}$$

• Derivation

- $1. \ \vdash \ P \land \neg S \ \Rightarrow \ Q$

- 5. $\vdash \{P\}$ IF S THEN C $\{Q\}$

Hypothesis

 1. $+ P \land \neg S \Rightarrow Q$ Hypothesis

 2. $+ \{P \land \neg S\}$ SKIP $\{Q\}$ By derived SKIP rule

 3. $+ \{P \land S\} C \{Q\}$ Hypothesis

 4. $+ \{P\}$ IF S THEN C ELSE SKIP $\{Q\}$ By conditional rule

 5. $+ \{P\}$ IF S THEN C (Q)
 By conditional rule

 By derived SKIP rule By definition of one-armed conditional

Example

• From

- Then by the derived one-armed conditional rule it follows that
 - \vdash {T} IF X \geq Y THEN Y:=X {Y=max(X,Y)}

Aside: linear versus tree structured proofs

- Tree structured proofs are fine (e.g. for exams)
 - advantages: familiar, maybe easier to construct
 - disadvantage: harder to present large proofs
- Examples (proof schemas, not concrete proofs)

 $\begin{array}{c|c} \vdash P \Rightarrow Q[E/V] & \overline{\vdash \{Q[E/V]\} V := E \{Q\}} \\ \hline \vdash \{P\} V := E \{Q\} \end{array} \begin{array}{c} ASS \\ PRE \end{array}$

 $\frac{\vdash P \Rightarrow Q \quad \overline{\vdash \{Q\} \text{ SKIP } \{Q\}}}{\vdash \{P\} \text{ SKIP } \{Q\}} \frac{SKP}{PRE}$

 $\begin{array}{c|c} \vdash \ \{P\}C\{Q[E/V]\} & \overline{\vdash} \ \{Q[E/V]\} \ V := E \ \{Q\} \\ \hline \quad \vdash \ \{P\} \ C; V := E \ \{Q\} \end{array} \begin{array}{c} ASS \\ SEQ \end{array}$

 $\begin{array}{c|c} & \vdash P \land \neg S \Rightarrow Q \\ \hline & \vdash \{P \land S\} C \{Q\} \end{array} \begin{array}{c} & \vdash P \land \neg S \Rightarrow Q \\ \hline & \vdash \{P \land \neg S\} SKIP \{Q\} \\ \hline & \vdash \{P\} \mbox{ IF } S \mbox{ THEN } C \mbox{ ELSE } SKIP \{Q\} \\ \hline & \vdash \{P\} \mbox{ IF } S \mbox{ THEN } C \mbox{ Q} \end{array} DEF$

Forwards and backwards proof

- Previously it was shown how to prove $\{P\}C\{Q\}$ by
 - \bullet proving properties of the components of C
 - and then putting these together, with the appropriate proof rule, to get the desired property of ${\cal C}$
- For example, to prove $\vdash \{P\}C_1; C_2\{Q\}$
- First prove $\vdash \{P\}C_1\{R\}$ and $\vdash \{R\}C_2\{Q\}$
- then deduce $\vdash \{P\}C_1; C_2\{Q\}$ by sequencing rule
- This method is called *forward proof*
 - move forward from axioms via rules to conclusion
- The problem with forwards proof is that it is not always easy to see what you need to prove to get where you want to be
- It is more natural to work backwards
 - starting from the goal of showing $\{P\}C\{Q\}$
 - generate subgoals until problem solved

Example

• Suppose one wants to show

 $\{\texttt{X=x} ~\land~ \texttt{Y=y}\} ~\texttt{R:=X}; ~\texttt{X:=Y}; ~\texttt{Y:=R} ~\{\texttt{Y=x} ~\land~ \texttt{X=y}\}$

• By the assignment axiom and derived sequenced assignment rule it is sufficient to show the subgoal

 $\{\texttt{X=x} ~\land~ \texttt{Y=y}\} ~\texttt{R:=X}; ~\texttt{X:=Y} ~\{\texttt{R=x} ~\land~ \texttt{X=y}\}$

• Similarly this subgoal can be reduced to

 $\{\texttt{X=x} \ \land \ \texttt{Y=y}\} \ \texttt{R:=X} \ \{\texttt{R=x} \ \land \ \texttt{Y=y}\}$

• This clearly follows from the assignment axiom

Backwards versus Forwards Proof

- Backwards proof just involves using the rules backwards
- Given the rule

- Forwards proof says:
 - if we have proved $\vdash S_1 \ldots \vdash S_n$ we can deduce $\vdash S$
- Backwards proof says:
 - to prove $\vdash S$ it is sufficient to prove $\vdash S_1 \ldots \vdash S_n$
- Having proved a theorem by backwards proof, it is simple to extract a forwards proof

Example Backwards Proof

```
• To prove
```

```
 \begin{array}{l} \vdash \ \{T\} \\ R:=X; \\ Q:=0; \\ WHILE \ Y \leq R \ DO \\ BEGIN \ R:=R-Y; \ Q:=Q+1 \ END \\ \left\{X=R+(Y \times Q) \ \land \ R < Y\right\} \end{array}
```

- By the sequencing rule, it is sufficient to prove
 - (i) \vdash {T} R:=X; Q:=O {R=X \land Q=O}
- Where does {R=X \land Q=0} come from? (Answer later)

Example Continued (1)

- From previous slide:
 - (i) \vdash {T} R:=X; Q:=O {R=X \land Q=O}
- $\bullet\,$ To prove (i), by the sequenced assignment axiom, we must prove:
 - (iii) \vdash {T} R:=X {R=X \land 0=0}
- To prove (iii), by the derived assignment rule, we must prove:
 - $\vdash \quad \mathtt{T} \ \Rightarrow \ \mathtt{X=X} \ \land \ \mathtt{0=0}$
- This is true by pure logic

Example continued (2)

• From an earlier slide:

• To prove (ii), by the derived while rule, we must prove:

(iv) R=X \land Q=0 \Rightarrow (X = R+(Y×Q))

(v) X = R+Y×Q $\land \neg$ (Y \leq R) \Rightarrow (X = R+(Y×Q) \land R<Y)

and

 $\begin{array}{l} \left\{ \begin{array}{ll} X = R+(Y \times \mathbb{Q}) \land (Y \leq R) \right\} \\ (\mathbf{vi}) & \text{BEGIN } R:=R-Y; \ \mathbb{Q}:=\mathbb{Q}+1 \ \text{END} \\ \left\{ X=R+(Y \times \mathbb{Q}) \right\} \end{array}$

• (iv) and (v) are proved by pure arithmetic

Example Continued (3)

• To prove (vi), by the block rule, we must prove

```
 \{ X = R+(Y \times Q) \land (Y \le R) \} 
 (vii) \quad \begin{array}{l} R:=R-Y; \ Q:=Q+1 \\ \{X=R+(Y \times Q) \} \end{array}
```

 $\bullet~$ To prove (vii), by the sequenced assignment rule, we must prove

```
 \begin{array}{l} \{X=R+(Y\times \mathbb{Q}) \land (Y\leq R)\} \\ (viii) \quad R:=R-Y \\ \{X=R+(Y\times (\mathbb{Q}+1))\} \end{array}
```

- To prove (viii), by the derived assignment rule, we must prove
 - (ix) $X=R+(Y \times Q) \land Y \leq R \Rightarrow (X = (R-Y)+(Y \times (Q+1)))$
- This is true by arithmetic
- Exercise: Construct the forwards proof that corresponds to this backwards proof

Annotations

• The sequencing rule introduces a new statement ${\it R}$

$$\frac{\vdash \{P\} C_1 \{R\} \vdash \{R\} C_2 \{Q\}}{\vdash \{P\} C_1; C_2 \{Q\}}$$

- To apply this backwards, one needs to find a suitable statement ${\it R}$
- If C_2 is V := E then sequenced assignment gives Q[E/V] for R
- If C_2 isn't an assignment then need some other way to choose R
- Similarly, to use the derived While rule, must invent an invariant

Annotate First

- It is helpful to think up these statements before you start the proof and then annotate the program with them
 - the information is then available when you need it in the proof
 - this can help avoid you being bogged down in details
 - the annotation should be true whenever control reaches that point
- Example, the following program could be annotated at the points P_1 and P_2 indicated by the arrows

```
\begin{array}{l} \{T\} \\ & \text{BEGIN} \\ & \text{R}:=X; \\ & \mathbb{Q}:=0; \ \{\text{R}=X \ \land \ \text{Q}=0\} \ \longleftarrow P_1 \\ & \text{WHILE} \ Y \leq \text{R} \ \text{DO} \ \{X \ = \ \text{R}+Y \times \mathbb{Q}\} \ \longleftarrow P_2 \\ & \text{BEGIN} \ \text{R}:=\text{R}-Y; \ \ \text{Q}:=\mathbb{Q}+1 \ \ \text{END} \\ & \text{END} \\ \{X \ = \ \text{R}+Y \times \mathbb{Q} \ \land \ \text{R}<Y\} \end{array}
```

Summary

- We have looked at three ways of organizing proofs that make it easier for humans to apply them:
 - deriving "bigger step" rules
 - backwards proof
 - annotating programs
- Next we see how these techniques can be used to mechanize program verification

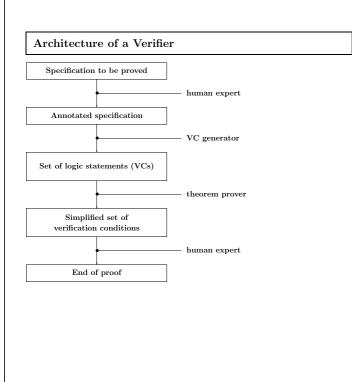
NEW TOPIC: Mechanizing Program Verification

- The architecture of a simple program verifier will be described
- Justified with respect to the rules of Floyd-Hoare logic
- It is clear that
 - proofs are long and boring, even if the program being verified is quite simple
 - lots of fiddly little details to get right, many of which are trivial, e.g.

 $\ \ \vdash \ (R{=}X \ \ \wedge \ \ Q{=}0) \ \Rightarrow \ (X=R+Y{\times}Q)$

Mechanization

- Goal: automate the routine bits of proofs in Floyd-Hoare logic
- Unfortunately, logicians have shown that it is impossible in principle to design a *decision procedure* to decide automatically the truth or falsehood of an arbitrary mathematical statement
- This does not mean that one cannot have procedures that will prove many *useful* theorems
 - \bullet the non-existence of a general decision procedure merely shows that one cannot hope to prove everything automatically
 - in practice, it is quite possible to build a system that will mechanize the boring and routine aspects of verification
- The standard approach to this will be described in the course
 - ideas very old (JC King's 1969 CMU PhD, Stanford verifier in 1970s)
 - used by program verifiers (e.g. Gypsy and SPARK verifier)
 - used to validate proof carrying code (PCC)
 - provides a verification front end to different provers (see *Why* system)



Commentary

• Input: a Hoare triple annotated with mathematical statements

• these annotations describe relationships between variables

- The system generates a set of purely mathematical statements called *verification conditions* (or VCs)
- If the verification conditions are provable, then the original specification can be deduced from the axioms and rules of Hoare logic
- The verification conditions are passed to a *theorem prover* program which attempts to prove them automatically
 - if it fails, advice is sought from the user

Verification conditions

- The three steps in proving $\{P\}C\{Q\}$ with a verifier
- [1] The program C is annotated by inserting statements (assertions) expressing conditions that are meant to hold at intermediate points
 - this step is tricky and needs intelligence and a good understanding of how the program works
 - automating it is an artificial intelligence problem
- 2 A set of logic statements called *verification conditions* (VCs) is then generated from the annotated specification
 - this is purely mechanical and easily done by a program
- 3 The verification conditions are proved
 - needs automated theorem proving (i.e. more artificial intelligence)
- To improve automated verification one can try to
 - reduce the number and complexity of the annotations required
 - increase the power of the theorem prover
 - still a research area

Validity of Verification Conditions

- It will be shown that
 - if one can prove all the verification conditions generated from $\{P\}C\{Q\}$
 - then $\vdash \{P\}C\{Q\}$
- Step 2 converts a verification problem into a conventional mathematical problem
- The process will be illustrated with:
 - {T} BEGIN R:=X; Q:=0; WHILE Y≤R DO BEGIN R:=R-Y; Q:=Q+1 END END {X = R+Y×Q ∧ R<Y}

Example

• Step 1 is to insert annotations P₁ and P₂

```
\begin{array}{l} \{T\} \\ & \text{BEGIN} \\ & R:=X; \\ & \mathbb{Q}:=0; \ \{R=X \ \land \ \mathbb{Q}=0\} \ \longleftarrow P_1 \\ & \text{WHILE} \ Y \leq R \ \text{DO} \ \{X \ = \ R+Y \times \mathbb{Q}\} \ \longleftarrow P_2 \\ & \text{BEGIN} \ R:=R-Y; \ \mathbb{Q}:=\mathbb{Q}+1 \ \text{END} \\ & \text{END} \\ \{X \ = \ R+Y \times \mathbb{Q} \ \land \ R<Y\} \end{array}
```

• The annotations P_1 and P_2 state conditions which are intended to hold whenever control reaches them

Example Continued

```
\begin{array}{l} \{T\} \\ & \text{BEGIN} \\ & \text{R}:=X\,; \\ & \text{Q}:=0\,; \quad \{\text{R}=X \ \land \ \text{Q}=0\} \ \longleftarrow P_1 \\ & \text{WHILE} \ Y {\leq} \text{R} \ \text{DO} \ \left\{X \ = \ \text{R}+Y {\times} \text{Q}\right\} \ \longleftarrow P_2 \\ & \text{BEGIN} \ \text{R}:=R-Y\,; \ \text{Q}:=\text{Q}+1 \ \text{END} \\ & \text{END} \\ \left\{X \ = \ \text{R}+Y {\times} \text{Q} \ \land \ \text{R}{<}Y\right\} \end{array}
```

- Control only reaches the point at which $\ensuremath{\mathtt{P}}_1$ is placed once
- It reaches P₂ each time the WHILE body is executed
 - whenever this happens $X=R+Y\times Q$ holds, even though the values of R and Q vary
 - P2 is an invariant of the WHILE-command

Generating and Proving Verification Conditions

• Step 2 will generate the following four verification conditions

• Notice that these are statements of arithmetic

• the constructs of our programming language have been 'compiled away'

• Step 3 consists in proving the four verification conditions

easy with modern automatic theorem provers

Annotation of Commands

- An annotated command is a command with statements (assertions) embedded within it
- A command is *properly annotated* if statements have been inserted at the following places

(i) before C_2 in C_1 ; C_2 if C_2 is not an assignment command (ii) after the word DO in WHILE (and FOR) commands

- The inserted assertions should express the conditions one expects to hold *whenever* control reaches the point at which the assertion occurs
- Can reduce number of annotations using weakest preconditions (see later)

Annotation of Specifications

- A properly annotated specification is a specification $\{P\}C\{Q\}$ where C is a properly annotated command
- Example: To be properly annotated, assertions should be at points (1) and (2) of the specification below

 $\begin{array}{l} \{X=n\} \\ & \text{BEGIN} \\ & Y:=1; \quad \longleftarrow \ (1) \\ & \text{WHILE } X \neq 0 \text{ DO } \leftarrow \ (2) \\ & \text{BEGIN } Y:=Y \times X; \ X:=X-1 \text{ END} \\ & \text{END} \\ \{X=0 \ \land \ Y=n!\} \end{array}$

• Suitable statements would be

at (1): $\{Y = 1 \land X = n\}$ at (2): $\{Y \times X! = n!\}$

Verification Condition Generation

- The VCs generated from an annotated specification $\{P\}C\{Q\}$ are obtained by considering the various possibilities for C
- We will describe it command by command using rules of the form:
- The VCs for $C(C_1, C_2)$ are
 - vc_1 , ... , vc_n
 - \bullet together with the VCs for C_1 and those for C_2
- Each VC rule corresponds to either a primitive or derived rule

A VC Generation Program

- The algorithm for generating verification conditions is *recursive* on the structure of commands
- The rule just given corresponds to the recursive program clause:
 VC (C(C₁, C₂)) = [vc₁, ..., vc_n] @ (VC C₁) @ (VC C₂)
- The rules are chosen so that only one VC rule applies in each caseapplying them is then purely mechanical
 - the choice is based on the syntax
 - only one rule applies in each case so VC generation is deterministic

Justification of VCs

- This process will be justified by showing that $\vdash \{P\}C\{Q\}$ if all the verification conditions can be proved
- $\bullet~$ We will prove that for any C
 - assuming the VCs of $\{P\}C\{Q\}$ are provable
 - then $\vdash \{P\}C\{Q\}$ is a theorem of the logic

Justification of Verification Conditions

- The argument that the verification conditions are sufficient will be by induction on the structure of ${\cal C}$
- Such inductive arguments have two parts
 - show the result holds for atomic commands: skip and assignments
 - show that when C is not an atomic command, then if the result holds for the constituent commands of C (this is called the $induction\ hypothesis$), then it holds also for C
- The first of these parts is called the *basis* of the induction
- The second is called the step
- The basis and step entail that the result holds for all commands

VC for SKIP

The Skip command

The single verification condition generated by

 $\{P\} \text{ SKIP } \{Q\}$

 $P \Rightarrow Q$

• Example: The verification condition for

{X=0} SKIP {X=0}

is $X=0 \Rightarrow X=0$

is

(which is clearly true)

Justification of SKIP VC

- We must show that if the VCs of $\{P\}$ SKIP $\{Q\}$ are provable then $\vdash~\{P\}$ SKIP $\{Q\}$
- Proof:
 - Assume $P \Rightarrow Q$ is provable since it is the VC (i.e. assume $\vdash P \Rightarrow Q$)
 - From derived Skip rule it follows that $\vdash \{P\}$ SKIP $\{Q\}$ as required

VC for Assignments

Assignment commands

The single verification condition generated by

 $\{P\}\ V{:=}E\ \{Q\}$

 $P \Rightarrow Q[E/V]$

• Example: The verification condition for

{X=0} X:=X+1 {X=1}

 \mathbf{is}

is $X=0 \Rightarrow (X+1)=1$

(which is clearly true)

• Note: Q[E/V] = wlp("V:=E",Q)

Justification of Assignment VC

- We must show that if the VCs of {P} V := E {Q} are provable then ⊢ {P} V := E {Q}
- Proof:
 - Assume $\vdash P \Rightarrow Q[E/V]$ as it is the VC
 - From derived assignment rule it follows that $\vdash \{P\} V := E \{Q\}$

VCs for Two-Armed Conditional

	Two-armed conditional
	The verification conditions generated from
	$\{P\}$ IF S THEN C_1 ELSE C_2 $\{Q\}$
	are
	(i) the verification conditions generated by
	$\{P \land S\} C_1 \{Q\}$
	(ii) the verifications generated by
	$\{P \land \neg S\} C_2 \{Q\}$
L	

• Example: The verification conditions for

{T} IF X \geq THEN MAX:=X ELSE MAX:=Y {MAX=max(X,Y)} are

(i) the VCs for {T \land X ≥ Y} MAX:=X {MAX=max(X,Y)} (ii) the VCs for {T $\land \neg(X \ge Y)$ } MAX:=Y {MAX=max(X,Y)}

Justification for the Conditional VCs (1)

- Must show that if VCs of
 {P} IF S THEN C1 ELSE C2 {Q}
 are provable, then
 ⊢ {P} IF S THEN C1 ELSE C2 {Q}
- Proof:
 - Assume the VCs $\{P \land S\} C_1 \{Q\}$ and $\{P \land \neg S\} C_2 \{Q\}$
 - The inductive hypotheses tell us that if these VCs are provable then the corresponding Hoare Logic theorems are provable
 - i.e. by induction $\vdash \{P \land S\} C_1 \{Q\}$ and $\vdash \{P \land \neg S\} C_2 \{Q\}$
 - Hence by the conditional rule $\vdash \{P\}$ IF S THEN C_1 ELSE C_2 $\{Q\}$

Review of Annotated Sequences

- If C₁; C₂ is properly annotated, then either
 Case 1: it is of the form C₁; {R}C₂ and C₂ is not an assignment
 Case 2: it is of the form C; V := E
- And C, C₁ and C₂ are properly annotated

VCs for Sequences

Sequences

Example

• The verification conditions generated from

{X=x \land Y=y} R:=X; X:=Y; Y:=R {X=y \land Y=x}

• Are those generated by

 $\left\{ \texttt{X=x} ~\land~ \texttt{Y=y} \right\} ~\texttt{R:=X}; ~\texttt{X:=Y} ~\left\{ \texttt{(X=y} ~\land~ \texttt{Y=x}) ~\texttt{[R/Y]} \right\}$

• This simplifies to

{X=x \land Y=y} R:=X; X:=Y {X=y \land R=x}

• The verification conditions generated by this are those generated by

{X=x \land Y=y} R:=X {(X=y \land R=x)[Y/X]}

• Which simplifies to

 $\{\texttt{X=x} ~\land~ \texttt{Y=y}\} ~\texttt{R:=X} ~\{\texttt{Y=y} ~\land~ \texttt{R=x}\}$

Example Continued

• The only verification condition generated by

 $\{X{=}x \ \land \ Y{=}y\}$ R:=X $\{Y{=}y \ \land \ R{=}x\}$ is

X=x \land Y=y \Rightarrow (Y=y \land R=x)[X/R]

• Which simplifies to

 $\texttt{X=x} \ \land \ \texttt{Y=y} \ \Rightarrow \ \texttt{Y=y} \ \land \ \texttt{X=x}$

• Thus the single verification condition from

 $\{ X=x \ \land \ Y=y \} \ R:=X ; \ X:=Y ; \ Y:=R \ \{ X=y \ \land \ Y=x \} \\ \mathbf{is}$

 $\texttt{X=x} \ \land \ \texttt{Y=y} \ \Rightarrow \ \texttt{Y=y} \ \land \ \texttt{X=x}$

Justification of VCs for Sequences (1)

• Case 1: If the verification conditions for

 $\{P\} C_1 \ ; \ \{R\} C_2 \ \{Q\}$ are provable

• Then the verification conditions for

 $\{P\}\ C_1\ \{R\}$ and $\{R\}\ C_2\ \{Q\}$ must both be provable

• Hence by induction

 $\vdash \{P\} C_1 \{R\} \text{ and } \vdash \{R\} C_2 \{Q\}$

• Hence by the sequencing rule

 $\vdash \{P\} C_1; C_2 \{Q\}$

Justification of VCs for Sequences (2)

• Case 2: If the verification conditions for

 $\{P\} \ C; V := E \ \{Q\}$ are provable, then the verification conditions for $\{P\} \ C \ \{Q[E/V]\}$

are also provable

• Hence by induction

 $\vdash \{P\} C \{Q[E/V]\}$

• Hence by the derived sequenced assignment rule

 $\vdash \hspace{0.2cm} \{P\} \hspace{0.2cm} C \hspace{0.2cm} \text{;} \hspace{0.2cm} V := E \hspace{0.2cm} \{Q\}$

VCs for Blocks

Blocks

 $\{P\}$ BEGIN VAR V_1 ; ... ; VAR V_n ; C END $\{Q\}$

The verification conditions generated by

are

(i) the verification conditions generated by $\{P\}C\{Q\}$, and (ii) none of V_1, \ldots, V_n occur in either P or Q.

Syntactic Conditions for Blocks

• Generating verification conditions from blocks involves checking a syntactic condition

• the local variables do not occur in the precondition or postcondition

- The need for this is clear from the side condition in the block rule
- Example: the verification conditions for

• Are the verification conditions generated by

{X=x \land Y=y} R:=X; X:=Y; Y:=R {X=y \land Y=x}

and the syntactic check that R not in {X=x $~\wedge~$ Y=y} or {X=y $~\wedge~$ Y=x}

• See previous example for verification conditions generated by this

Justification of VCs for Blocks

• If the verification conditions for

 $\{P\}$ begin var $V_1; \ldots;$ var $V_n; C$ end $\{Q\}$ are provable

- Then the verification conditions for
 - $\{P\} \subset \{Q\}$

are provable and V_1, \ldots, V_n do not occur in P or Q

• By induction

 $\vdash \{P\} \ C \ \{Q\}$

- Hence by the block rule
 - $\vdash \{P\}$ BEGIN VAR V_1 ; ...; VAR V_n ; C END $\{Q\}$

VCs for WHILE-Commands

• A correctly annotated specification of a WHILE-command has the form

 $\{P\}$ while S do $\{R\}$ C $\{Q\}$

• The annotation R is called an invariant

WHILE-commands

The verification conditions generated from $\{P\} \; {\rm WHILE} \; S \; {\rm DO} \; \{R\} \; C \; \{Q\}$ are

(i) P ⇒ R
(ii) R ∧ ¬S ⇒ Q
(iii) the verification conditions generated by {R ∧ S} C{R}

Example

• The verification conditions for

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 \begin{cases} R=X \land Q=0 \\ & \text{WHILE } Y \leq R \text{ DO } \{X=R+Y \times Q \} \\ & \text{BEGIN } R:=R-Y; \ Q:=Q+1 \text{ END} \\ \{X = R+(Y \times Q) \land R < Y \} \\ & \text{are:} \\ & (i) R=X \land Q=0 \Rightarrow (X = R+(Y \times Q)) \end{cases}
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(ii) X = R+Y×Q $\land \neg$ (Y \leq R) \Rightarrow (X = R+(Y×Q) \land R<Y)

together with the verification condition for

 $\begin{aligned} & \{X = R+(Y\times Q) \ \land \ (Y\leq R)\} \\ & \text{BEGIN } R:=R-Y; \ Q:=Q+1 \ \text{END} \\ & \{X=R+(Y\times Q)\} \end{aligned}$ which consists of the single condition

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(iii) X = R+(Y \times Q) \land (Y \le R) \Rightarrow X = (R-Y)+(Y \times (Q+1))
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Example Summarised

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• By previous transparency
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if

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\vdash R=X \land Q=0 \Rightarrow (X = R+(Y \times Q))
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and

 $\vdash \ \mathtt{X} \ = \ \mathtt{R} \textbf{+} (\mathtt{Y} \times \mathtt{Q}) \ \land \ \neg (\mathtt{Y} \leq \mathtt{R}) \Rightarrow \ (\mathtt{X} \ = \ \mathtt{R} \textbf{+} (\mathtt{Y} \times \mathtt{Q}) \ \land \ \mathtt{R} \textbf{<} \mathtt{Y})$

and

 $\vdash X = R+(Y \times Q) \land (Y \leq R) \implies X = (R-Y)+(Y \times (Q+1))$

Justification of WHILE VCs

• If the verification conditions for

 $\begin{array}{l} \{P\} \text{ WHILE } S \text{ DO } \{R\} \ C \ \{Q\} \\ \text{are provable, then} \\ \vdash \ P \Rightarrow R \\ \vdash \ (R \ \land \ \neg S) \ \Rightarrow \ Q \\ \text{and the verification conditions for} \\ \{R \ \land \ S\} \ C \ \{R\} \\ \text{are provable} \end{array}$

- By induction
 - $\vdash \{R \land S\} C \{R\}$
- Hence by the derived WHILE-rule
 - \vdash {P} WHILE S DO C {Q}

Summary

- Have outlined the design of an automated program verifier
- Annotated specifications compiled to mathematical statements
 if the statements (VCs) can be proved, the program is verified
- Human help is required to give the annotations and prove the VCs
- The algorithm was justified by an inductive proof
 - it appeals to the derived rules
- All the techniques introduced earlier are used
 - backwards proof
 - derived rules
 - annotation

Dijkstra's weakest preconditions

- Weakest preconditions is a theory of refinement
 - idea is to calculate a program to achieve a postcondition
 - not a theory of post hoc verification
- Non-determinism a key idea in Dijksta's presentation
 - start with a non-deterministic high level pseudo-code
 - refine to deterministic and efficient code
- Weakest preconditions (wp) are for total correctness
- Weakest *liberal* preconditions (wlp) for partial correctness
- If C is a command and Q a predicate, then informally:
 wlp(C,Q) = 'The weakest predicate P such that {P} C {Q}'
 wp(C,Q) = 'The weakest predicate P such that [P] C [Q]'
- If P and Q are predicates then $Q \Rightarrow P$ means P is 'weaker' than Q

Rules for weakest preconditions

• Relation with Hoare specifications:

- Dijkstra gives rules for computing weakest preconditions: $\begin{array}{lll} \mathtt{wp}(\mathtt{SKIP},Q) & = & Q \\ \mathtt{wp}(\mathtt{SKIP},Q) & = & Q[E/V] \\ \mathtt{wp}(C_1;C_2,\ Q) & = & \mathtt{wp}(C_1,\mathtt{wp}(C_2,\ Q)) \\ \mathtt{wp}(\mathtt{IF}\ B\ \mathtt{THEN}\ C_1\ \mathtt{ELSE}\ C_2,\ Q) & = & (B\ \Rightarrow \mathtt{wp}(C_1,Q)) \land \ (\neg B\ \Rightarrow\ \mathtt{wp}(C_2,Q)) \\ \texttt{for deterministic loop-free code the same equations hold for wlp} \end{array}$
- Rule for WHILE-commands doesn't give a first order result
- Weakest preconditions closely related to verification conditions
- VCs for $\{P\} \ C \ \{Q\}$ are related to $P \Rightarrow wlp(C,Q)$
 - VCs use annotations to ensure first order formulas can be generated

Sequencing example

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Swapping variables:

wlp(R:=X; X:=Y; Y:=R, (Y = x ∧ X = y))

= wlp(R:=X, wlp(X:=Y, wlp(Y:=R, (Y = x ∧ X = y))))

= wlp(R:=X, wlp(X:=Y, (Y = x ∧ X = y)[R/Y]))

= wlp(R:=X, (R = x ∧ Y = y)))

= (X = x ∧ Y = y)
So since {P} C {Q} ⇔ P ⇒ wlp(C,Q)

to prove

{X = x ∧ Y = y} R:=X; X:=Y; Y:=R {Y = x ∧ X = y}

just need to prove:

(X = x ∧ Y = y) ⇒ (X = x ∧ Y = y)

which is clearly true (instance of S ⇒ S)
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Conditional example

- Compute wlp of the maximum program:
 - wlp(IF X<Y THEN MAX:=Y ELSE MAX:=X, (MAX = max(x,y))
 - $= \ (\texttt{X} < \texttt{Y} \ \Rightarrow \ \texttt{wlp}(\texttt{MAX} := \texttt{Y}, \ (\texttt{MAX} = max(x,y)))) \\$
 - $(\neg(\texttt{X<Y}) \implies \texttt{wlp}(\texttt{MAX:=X}, \ (\texttt{MAX} = max(x,y))))$
 - $= \ (\mathbf{X} \boldsymbol{<} \mathbf{Y} \ \Rightarrow \ \mathbf{Y} = max(x,y)) \ \land \ (\neg(\mathbf{X} \boldsymbol{<} \mathbf{Y}) \ \Rightarrow \ \mathbf{X} = max(x,y))$
 - = if X < Y then Y = max(x, y) else X = max(x, y)
- So to prove

 $\{{\bf X}=x \wedge {\bf Y}=y\}$ IF X<Y THEN MAX:=X ELSE MAX:=Y $\{{\rm MAX}=max(x,y)\}$ just prove:

 $(X = x \land Y = y) \Rightarrow (X < Y \Rightarrow Y = max(x, y)) \land (\neg (X < Y) \Rightarrow X = max(x, y))$ which follows from the defining property of max

 $\vdash \quad \forall x \ y. \ (x \geq y \Rightarrow x = max(x,y)) \ \land \ (\neg(x \geq y) \Rightarrow y = max(x,y))$

Using wlp to improve verification condition method

• If C is loop-free then VC for $\{P\} \ C \ \{Q\}$ is $P \Rightarrow wlp(C,Q)$

• no annotations needed in sequences!

- + Cannot in general compute a finite formula for $\mathtt{wlp}(\mathtt{WHILE}\;S\;\mathtt{DO}\;C,\;Q)$
- The following holds $\texttt{wlp}(\texttt{WHILE} \ S \ \texttt{DO} \ C, \ Q) \ = \ \textit{if} \ S \ \textit{then} \ \texttt{wlp}(C, \ \texttt{wlp}(\texttt{WHILE} \ S \ \texttt{DO} \ C, \ Q)) \ \textit{else} \ Q$
- Above doesn't define wlp(C,Q) as a finite statement
- We will describe a hybrid VC and wlp method

wlp-based verification condition method

- We define $\operatorname{awp}(C,Q)$ and $\operatorname{wvc}(C,Q)$
 - $\operatorname{awp}(C,Q)$ is a statement sort of approximating $\operatorname{wlp}(C,Q)$
 - wvc(C,Q) is a set of verification conditions
- If C is loop-free then
 - $\operatorname{awp}(C,Q) = \operatorname{wlp}(C,Q)$
 - $wvc(C,Q) = \{\}$
- Denote by $\wedge S$ the conjunction of all the statements in S
 - $\bullet \ \land \{\} = T$
 - $\wedge(S_1 \cup S_2) = (\wedge S_1) \wedge (\wedge S_2)$
- It will follow that $\land wvc(C,Q) \Rightarrow \{awp(C,Q)\} C \{Q\}$
- Hence to prove $\{P\}C\{Q\}$ it is sufficient to prove all the statements in wvc(C,Q) and $P \Rightarrow awp(C,Q)$

${\rm Definition} \,\, of \,\, {\tt awp}$

- Assume all WHILE-commands are annotated: WHILE S DO $\{R\}$ C
- Define awp recursively by:

awp(SKIP, Q)	= Q
awp(V := E, Q)	=Q[E/V]
$\mathtt{awp}(C_1 \ ; \ C_2, \ Q)$	$= \texttt{awp}(C_1, \ \texttt{awp}(C_2, \ Q))$
$\texttt{awp}(\texttt{IF} \ S \ \texttt{THEN} \ C_1 \ \texttt{ELSE} \ C_2, \ Q)$	$= (S \ \wedge \texttt{awp}(C_1, \ Q)) \lor (\neg S \land \texttt{awp}(C_2, \ Q))$
$\texttt{awp}(\texttt{WHILE} \; S \; \texttt{DO} \; \{R\} \; C, \; Q)$	= R

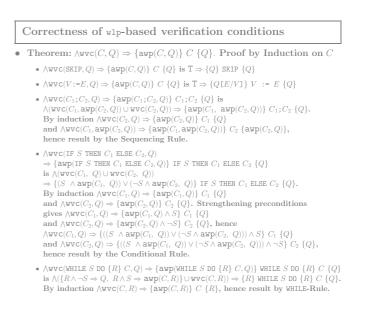
• Note: $(S \land awp(C_1, Q)) \lor (\neg S \land awp(C_2, Q) = if S then awp(C_1, Q) else awp(C_2, Q)$

Definition of wvc

• Assume all WHILE-commands are annotated: WHILE S DO $\{R\}$ C

• Define wvc recursively by:

wvc(SKIP, Q)	= {}
wvc(V := E, Q)	= {}
${\tt wvc}(C_1 \ ; \ C_2, \ Q)$	$= \texttt{wvc}(C_1,\texttt{awp}(C_2,Q)) \cup \texttt{wvc}(C_2,Q)$
$wvc(IF \ S \ THEN \ C_1 \ ELSE \ C_2, \ Q)$	$= \texttt{wvc}(C_1, \ Q) \cup \texttt{wvc}(C_2, \ Q)$
$\texttt{wvc}(\texttt{WHILE} \; S \; \texttt{DO} \; \{R\} \; C, \; Q)$	$= \{R \wedge \neg S \Rightarrow Q, \; R \wedge S \Rightarrow \texttt{awp}(C,R)\}$
	$\cup \mathtt{wvc}(C,R)$



Example

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\boxed{\texttt{wvc}(\texttt{WHILE} \ S \ \texttt{DO} \ \{R\} \ C, \ Q) \ = \ (R, \ \{R \land \neg S \Rightarrow Q, \ R \land S \Rightarrow \texttt{awp}(C, R)\} \cup \texttt{wvc}(C, R))}
   \texttt{wvc}(\texttt{R}\texttt{:=}\texttt{R}\texttt{-}\texttt{Y}\texttt{;}\texttt{Q}\texttt{:=}\texttt{Q}\texttt{+}\texttt{1}, \ \texttt{X}=\texttt{R}+\texttt{Y}\times\texttt{Q})
                                                                                                                                                                                                    (analyse body)
       = (\texttt{wlp}(\texttt{R}:=\texttt{R}-\texttt{Y};\texttt{Q}:=\texttt{Q}+\texttt{1}, \texttt{X}=\texttt{R}+\texttt{Y}\times\texttt{Q}), \{\})
         = (\mathtt{X} = \mathtt{R} - \mathtt{Y} + \mathtt{Y} \times \mathtt{Q} + \mathtt{1}, \ \{\})
  \texttt{wvc}(\texttt{WHILE Y} \leq \texttt{R DO } \{\texttt{X} = \texttt{R} + \texttt{Y} \times \texttt{Q}\} \texttt{ R} : \texttt{=R-Y} ; \texttt{Q} : \texttt{=Q+1}, \texttt{ X} = \texttt{R} + \texttt{Y} \times \texttt{Q} \land \texttt{R} < \texttt{Y})
         = (X = R + Y \times Q,
               \{\mathtt{X}=\mathtt{R}+\mathtt{Y}\times\mathtt{Q}\wedge\neg(\mathtt{Y}\leq\mathtt{R})\Rightarrow\mathtt{X}=\mathtt{R}+\mathtt{Y}\times\mathtt{Q}\wedge\mathtt{R}{<}\mathtt{Y},
                   \mathtt{X} = \mathtt{R} + \mathtt{Y} \times \mathtt{Q} \land \mathtt{Y} \leq \mathtt{R} \Rightarrow \mathtt{X} = \mathtt{R} \text{-} \mathtt{Y} + \mathtt{Y} \times \mathtt{Q} \text{+} \mathtt{1} \} \cup \{\})
   WVC(Q:=0;WHILE Y \le R DO \{X = R + Y \times Q\} R:=R-Y; Q:=Q+1, X = R+Y \times Q \land R < Y)
          = (X = R + Y \times 0,
                \begin{array}{l} \{X = R + Y \times Q, \\ \{\} \cup \{X = R + Y \times Q \land \neg (Y \le R) \Rightarrow X = R + Y \times Q \land R < Y, \\ X = R + Y \times Q \land Y \le R \Rightarrow X = R - Y + Y \times Q + 1\}) \end{array} 
  \texttt{wvc}(\texttt{R=X};\texttt{Q}:\texttt{=0};\texttt{WHILE } Y \leq \texttt{R} \texttt{ DO } \{\texttt{X} = \texttt{R} + \texttt{Y} \times \texttt{Q}\} \texttt{ R}:\texttt{=R-Y}; \texttt{ Q}:\texttt{=Q+1}, \texttt{ X} = \texttt{R} + \texttt{Y} \times \texttt{Q} \land \texttt{R} < \texttt{Y})
          = (X = X + Y \times 0,
               \{\} \cup \{ \mathtt{X} = \mathtt{R} + \mathtt{Y} \times \mathtt{Q} \land \neg (\mathtt{Y} \leq \mathtt{R}) \Rightarrow \mathtt{X} = \mathtt{R} + \mathtt{Y} \times \mathtt{Q} \land \mathtt{R} < \mathtt{Y},
                               X = R + Y \times Q \land Y \le R \Rightarrow X = R - Y + Y \times Q + 1\})
 As X = X + Y \times 0 is T the correctness theorem for wvc gives
 X = R + Y \times Q \land \neg (Y \le R) \Rightarrow X = R + Y \times Q \land R < Y \land X = R + Y \times Q \land Y \le R \Rightarrow X = R - Y + Y \times Q + 1
  \{T\} \text{ R=X; Q:=0; WHILE } Y \leq \text{R DO } \{X=\text{R}+Y\times \text{Q}\} \ \{X=\text{R}+Y\times \text{Q} \land \text{R}{<}Y\}
```

Strongest postconditions

- Define $\operatorname{sp}(C, P)$ to be 'strongest' Q such that $\{P\} \ C \ \{Q\}$
 - partial correctness: $\{P\} \ C \ \{ \mathtt{sp}(C, P) \}$
 - strongest means if $\{P\}\ C\ \{Q\}$ then $\operatorname{sp}(C,P)\Rightarrow Q$
- Note that wlp goes 'backwards', but sp goes 'forwards'
 - verification condition for $\{P\}\ C\ \{Q\}$ is: $\mathtt{sp}(C,P)\Rightarrow Q$
- By 'strongest' and Hoare logic postcondition weakening
 - $\{P\} \ C \ \{Q\}$ if and only if $\operatorname{sp}(C, P) \Rightarrow Q$

Strongest postconditions for loop-free code

- Only consider loop-free code
- $\bullet \quad \texttt{sp}(\texttt{SKIP}, \ P) \ = \ P$
- $\operatorname{sp}(V := E, P) = \exists v. V = E[v/V] \land P[v/V]$
- $\bullet \quad \operatorname{sp}(C_1 \ \text{;} \ C_2, \ P) \ = \ \operatorname{sp}(C_2, \ \operatorname{sp}(C_1, \ P))$
- $\operatorname{sp}(\operatorname{IF} S \text{ THEN } C_1 \text{ ELSE } C_2, P) = \operatorname{sp}(C_1, P \wedge S) \vee \operatorname{sp}(C_2, P \wedge \neg S)$
- sp(V:=E, P) corresponds to Floyd assignment axiom
- Can dynamically prune conditionals because sp(C, F) = F

Sequencing example

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• sp(R:=X; X:=Y; Y:=R, X = x \land Y = y)

= sp(Y:=R, sp(X:=Y, sp(R:=X, X = x \land Y = y)))

= sp(Y:=R, sp(X:=Y, (\exists v. R = X[v/R] \land (X = x \land Y = y)[v/R])))

= sp(Y:=R, sp(X:=Y, (\exists v. R = X \land (X = x \land Y = y))))

= sp(Y:=R, sp(X:=Y, (R = X \land X = x \land Y = y))))

= sp(Y:=R, (\exists v. X = Y[v/X] \land (R = x \land X = x \land Y = y)))

= sp(Y:=R, (\exists v. X = Y \land (R = x \land x = x \land Y = y)))

= sp(Y:=R, (\exists v. X = Y \land (R = x \land (z = v \land Y = y))))

= sp(Y:=R, (X = Y \land (R = x \land (Z = v = x \land Y = y))))

= sp(Y:=R, (X = Y \land (R = x \land (Z = v = x \land Y = y)))

= sp(Y:=R, (X = Y \land (R = x \land (X = y \land Y = y)))

= sp(Y:=R, (X = Y \land (R = x \land Y = y)))

= \exists v. Y = R(VY] \land (X = Y \land R = x \land Y = y) [v/Y]

= \exists v. Y = R \land (X = y \land R = x \land v = y)

= \exists v. Y = R \land (X = y \land R = x \land (Z = v = y))

= Y = R \land (X = y \land R = x \land T)

= Y = R \land (X = y \land R = x

= Y = x \land X = y \land R = x
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• So to prove {X = $x \land Y = y$ } R:=X; X:=Y; Y:=R {Y = $x \land X = y$ } just prove: (Y = $x \land X = y \land R = x$) \Rightarrow Y = $x \land X = y$

Conditional example

• Compute sp of the maximum program: • Floyd assignment formula makes computing sp messy in general $sp(IF X < Y THEN MAX := Y ELSE MAX := X, (X = x \land Y = y))$ • For a special case it becomes like symbolic execution = $sp(MAX:=Y, ((X = x \land Y = y) \land X < Y))$ • Symbolic state: $X_1 = E_1 \land \cdots \land X_i = E_i \land \cdots \land X_n = E_n \land R$ $sp(MAX:=X, ((X = x \land Y = y) \land \neg(X < Y)))$ • Suppose E_1, \ldots, E_n or R doesn't contain X_1, \ldots, X_n then $= \exists v. \text{ max} = \mathbf{Y} [v/\text{max}] \land ((\mathbf{X} = x \land \mathbf{Y} = y) \land \mathbf{X} < \mathbf{Y}) [v/\text{max}]$ $\operatorname{sp}(\mathbf{X}_i := \mathbf{E}), \ (\mathbf{X}_1 = E_1 \land \dots \land \mathbf{X}_i = E_i \land \dots \land \mathbf{X}_n = E_n \land R))$ $\exists v. \text{ MAX} = X[v/\text{MAX}] \land ((X = x \land Y = y) \land \neg (X < Y))[v/\text{MAX}]$ $= \exists v. \mathbf{X}_i = E \left[v / \mathbf{X}_i \right] \land \left(\mathbf{X}_1 = E_1 \land \dots \land \mathbf{X}_i = E_i \land \dots \land \mathbf{X}_n = E_n \land R \right) \left[v / \mathbf{X}_i \right]$ $= \exists v. \ \mathsf{MAX} = \mathsf{Y} \land ((\mathsf{X} = x \land \mathsf{Y} = y) \land \mathsf{X} < \mathsf{Y})$ $= \exists v. \mathbf{X}_i = E[v/\mathbf{X}_i] \land (\mathbf{X}_1 = E_1 \land \dots \land v = E_i \land \dots \land \mathbf{X}_n = E_n \land R)$ $\exists v. \ \mathsf{MAX} = \mathbf{X} \land \mathbf{X} = x \land \mathbf{Y} = y \land \neg (\mathbf{X} < \mathbf{Y}))$ $= \mathbf{X}_i = E \left[E_i / \mathbf{X}_i \right] \land (\mathbf{X}_1 = E_1 \land \dots \land (\exists v. \ v = E_i) \land \dots \land \mathbf{X}_n = E_n \land R)$ $= \ (\mathtt{MAX} = \mathtt{Y} \land \mathtt{X} = x \land \mathtt{Y} = y \land \mathtt{X} < \mathtt{Y}) \lor (\mathtt{MAX} = \mathtt{X} \land \mathtt{X} = x \land \mathtt{Y} = y \land \neg (\mathtt{X} < \mathtt{Y})$ $= \mathbf{X}_i = E \left[E_i / \mathbf{X}_i \right] \land \left(\mathbf{X}_1 = E_1 \land \dots \land \mathbf{T} \land \dots \land \mathbf{X}_n = E_n \land R \right)$ $= X_i = E[E_i/X_i] \land X_1 = E_1 \land \dots \land X_n = E_n \land R$ $= (\mathtt{MAX} = y \land \mathtt{X} = x \land \mathtt{Y} = y \land x < y) \lor (\mathtt{MAX} = x \land \mathtt{X} = x \land \mathtt{Y} = y \land \neg (x < y)$ $= \mathbf{X}_i = E \left[E_1 / \mathbf{X}_1 \right] \cdots \left[E_n / \mathbf{X}_n \right] \land \mathbf{X}_1 = E_1 \land \cdots \land \mathbf{X}_n = E_n \land R$ $= if x < y then (MAX = y \land X = x \land Y = y) else (MAX = x \land X = x \land Y = y)$ $= \mathbf{X}_1 = E_1 \wedge \dots \wedge \mathbf{X}_i = E[E_1/\mathbf{X}_1] \cdots [E_n/\mathbf{X}_n] \wedge \dots \wedge \mathbf{X}_n = E_n \wedge R$ = MAX = $(if \ x < y \ then \ y \ else \ x) \land X = x \land Y = y$ = MAX = max $(x, y) \land X = x \land Y = y$ • Note $E[E_1/X_1] \cdots [E_n/X_n]$ doesn't contain X_1, \ldots, X_n Computing sp as symbolic execution: assignment (2)

- Suppose $X \neq X_i$ and X doesn't occur in E_i or E for $1 \le i \le n$, then
 - $\mathbf{sp}(\mathbf{X}:=\mathbf{E}, (\mathbf{X}_1 = E_1 \wedge \cdots \wedge \mathbf{X}_n = E_n \wedge R))$
 - $= \exists v. \mathbf{X} = E[v/\mathbf{X}] \land (\mathbf{X}_1 = E_1 \land \dots \land \mathbf{X}_n = E_n \land R)[v/\mathbf{X}]$
 - $= \exists v. \mathbf{X} = E \land \mathbf{X}_1 = E_1 \land \dots \land \mathbf{X}_n = E_n \land R$
 - $= \mathbf{X} = E[E_1/\mathbf{X}_1] \cdots [E_n/\mathbf{X}_n] \land \mathbf{X}_1 = E_1 \land \cdots \land \mathbf{X}_n = E_n \land R$
- Summarising: we have two symbolic computation rules:
 - 1. if E_1, \ldots, E_n or R doesn't contain X_1, \ldots, X_n then: $sp(X_i:=E, (X_1 = E_1 \land \cdots \land X_i = E_i \land \cdots \land X_n = E_n \land R))$ $= (\mathbf{X}_1 = E_1 \wedge \dots \wedge \mathbf{X}_i = E [E_1 / \mathbf{X}_1] \cdots [E_n / \mathbf{X}_n] \wedge \dots \wedge \mathbf{X}_n = E_n \wedge R)$
- 2. if $X \neq X_i$ and X doesn't occur in E_i or E for $1 \le i \le n$, then $sp(X:=E, (X_1 = E_1 \land \cdots \land X_n = E_n \land R))$
 - $= (\mathbf{X} = E[E_1/\mathbf{X}_1] \cdots [E_n/\mathbf{X}_n] \wedge \mathbf{X}_1 = E_1 \wedge \cdots \wedge \mathbf{X}_n = E_n \wedge R)$

Computing sp as symbolic execution: conditional (1)

Computing sp as symbolic execution: assignment (1)

- Suppose if none of $E_1, \ldots, E_n, R_1, R_2$ contain X_1, \ldots, X_n then $sp(C_1, (X_1 = E_1 \land \dots \land X_n = E_n \land R_1)) = (X_1 = E_{11} \land \dots \land X_n = E_{1n} \land R_1)$ $sp(C_2, (X_1 = E_1 \land \dots \land X_n = E_n \land R_2)) = (X_1 = E_{21} \land \dots \land X_n = E_{2n} \land R_2)$
- Conditional notation: $(B \rightarrow E_1 | E_2) = if B then E_1 else E_2$
- Then for E_1, \ldots, E_n , R not containing X_1, \ldots, X_n
 - $\operatorname{sp}(\operatorname{IF} S \operatorname{THEN} C_1 \operatorname{ELSE} C_2, (X_1 = E_1 \wedge \cdots \wedge X_n = E_n \wedge R))$
 - $= \operatorname{sp}(C_1, (X_1 = E_1 \wedge \dots \wedge X_n = E_n \wedge R) \wedge S)$
 - $sp(C_2, (X_1 = E_1 \land \cdots \land X_n = E_n \land R) \land \neg S)$
 - $= \operatorname{sp}(C_1, (\mathbf{X}_1 = E_1 \land \dots \land \mathbf{X}_n = E_n \land (R \land S[E_1/\mathbf{X}_1] \cdots [E_n/\mathbf{X}_n])))$
 - $sp(C_2, (X_1 = E_1 \land \dots \land X_n = E_n \land (R \land \neg S[E_1/X_1] \cdots [E_n/X_n])))$
 - $= (\mathbf{X}_1 = E_{11} \wedge \dots \wedge \mathbf{X}_n = E_{1n} \wedge (R \wedge S [E_1/\mathbf{X}_1] \cdots [E_n/\mathbf{X}_n]))$ (by assumption) $(\mathbf{X}_1 = E_{21} \land \dots \land \mathbf{X}_n = E_{2n} \land (R \land \neg S[E_1/\mathbf{X}_1] \cdots [E_n/\mathbf{X}_n]))$
 - $= (\mathtt{X}_1 = (S \llbracket E_1 / \mathtt{X}_1 \rrbracket \cdots \llbracket E_n / \mathtt{X}_n \rrbracket \rightarrow E_{11} | E_{21})) \wedge \cdots \wedge (\mathtt{X}_n = (S \llbracket E_1 / \mathtt{X}_1 \rrbracket \cdots \llbracket E_n / \mathtt{X}_n \rrbracket \rightarrow E_{1n} | E_{2n})) \wedge R$

Computing sp as symbolic execution: conditional (2)

- From last slide if E_1, \ldots, E_n, R do not contain X_1, \ldots, X_n sp(IF S THEN C_1 ELSE $C_2, (X_1 = E_1 \land \cdots \land X_n = E_n \land R))$ $= (X_1 = (S [E_1/X_1] \cdots [E_n/X_n] \rightarrow E_{11} |E_{21})) \land \cdots \land (X_n = (S [E_1/X_1] \cdots [E_n/X_n] \rightarrow E_{1n} |E_{2n})) \land R$ where sp($C_1, (X_1 = E_1 \land \cdots \land X_n = E_n \land R_1)$) $= (X_1 = E_{11} \land \cdots \land X_n = E_{1n} \land R_1)$
- If C₁ or C₂ don't assign to X_i then E_i = E_{1i} = E_{2i} so (S[E₁/X₁] ··· [E_n/X_n] → E_{1i}|E_{2i}) = E_i so formula above can be further simplified

 $\mathbf{sp}(C_2, \ (\mathbf{X}_1 = E_1 \wedge \dots \wedge \mathbf{X}_n = E_n \wedge R_2)) \ = \ (\mathbf{X}_1 = E_{21} \wedge \dots \wedge \mathbf{X}_n = E_{2n} \wedge R_2)$

• If R determines the value of $S[E_1/X_1] \cdots [E_n/X_n]$ then can simplify $(X_i = (S[E_1/X_1] \cdots [E_n/X_n] \rightarrow E_{1i} | E_{2i}))$

Summary of sp loop-free code symbolic execution

- Symbolic state: $(X_1 = E_1 \land \dots \land X_n = E_n \land R)$
- $\mathbf{sp}(\mathbf{SKIP}, \ (\mathbf{X}_1 = E_1 \land \dots \land \mathbf{X}_n = E_n \land R)) = (\mathbf{X}_1 = E_1 \land \dots \land \mathbf{X}_n = E_n \land R))$
- If E_1, \ldots, E_n or R doesn't contain X_1, \ldots, X_n then: $\mathbf{sp}(X_i := E, (X_1 = E_1 \land \cdots \land X_i = E_i \land \cdots \land X_n = E_n \land R))$ $= (X_1 = E_1 \land \cdots \land X_i = E[E_1/X_1] \cdots [E_n/X_n] \land \cdots \land X_n = E_n \land R)$
- If $X \neq X_i$ and X doesn't occur in E_i or E for $1 \le i \le n$, then $sp(X:=E, (X_1 = E_1 \land \dots \land X_n = E_n \land R))$ $= (X = E[E_1/X_1] \cdots [E_n/X_n] \land X_1 = E_1 \land \dots \land X_n = E_n \land R)$
- If E_1, \ldots, E_n , R does not contain X_1, \ldots, X_n sp(IF S THEN C_1 ELSE C_2 , $(X_1 = E_1 \land \cdots \land X_n = E_n \land R))$ $= (X_1 = (S [E_1/X_1] \cdots [E_n/X_n] \rightarrow E_{11} | E_{21})) \land \cdots \land (X_n = (S [E_1/X_1] \cdots [E_n/X_n] \rightarrow E_{1n} | E_{2n})) \land R$ where sp(C_1 , $(X_1 = E_1 \land \cdots \land X_n = E_n \land R_1)$) $= (X_1 = E_{11} \land \cdots \land X_n = E_{1n} \land R_1)$ sp(C_2 , $(X_1 = E_1 \land \cdots \land X_n = E_n \land R_2)$) $= (X_1 = E_{21} \land \cdots \land X_n = E_{2n} \land R_2)$

Example symbolic computation using sp(1)

• $\operatorname{sp}(C_1; C_2, P) = \operatorname{sp}(C_2, \operatorname{sp}(C_1, P))$ hence

 $\begin{array}{l} {\rm sp}({\rm R}:=0; \\ {\rm K}:=0; \\ {\rm IF}\ {\rm I} < {\rm J}\ {\rm THEN}\ {\rm K}:={\rm K}+1\ {\rm ELSE}\ {\rm SKIP}; \\ {\rm IF}\ {\rm K}=1\wedge\neg({\rm I}={\rm J})\ {\rm THEN}\ {\rm R}:={\rm J}-{\rm I}\ {\rm ELSE}\ {\rm R}:={\rm I}-{\rm J}, \\ ({\rm I}=i\wedge {\rm J}=j\wedge i< j))\ = \\ {\rm sp}({\rm K}:=0; \end{array}$

 $\begin{array}{l} \text{SP}(n, -0, \\ \text{IF I} < \text{J THEN } \text{K} := \text{K} + 1 \text{ ELSE SKIP}; \\ \text{IF } \text{K} = 1 \land \neg(\text{I} = \text{J}) \text{ THEN } \text{R} := \text{J} - \text{I} \text{ ELSE } \text{R} := \text{I} - \text{J}, \\ (\text{R} = 0 \land \text{I} = i \land \text{J} = i \land i < j)) = \end{array}$

 $\begin{array}{l} \texttt{Sp}\big(\texttt{IF I} < \texttt{J THEN K} := \texttt{K} + \texttt{1} \texttt{ELSE SKIP};\\ \texttt{IF K} = \texttt{1} \land \neg(\texttt{I} = \texttt{J}) \texttt{ THEN R} := \texttt{J} - \texttt{I} \texttt{ ELSE R} := \texttt{I} - \texttt{J},\\ (\texttt{K} = \texttt{0} \land \texttt{R} = \texttt{0} \land \texttt{I} = i \land \texttt{J} = j \land i < j) \end{array}$

Example symbolic computation using sp(2)

Considering each conditional branch and merging gives something like:

 $\begin{array}{l} {\rm sp(IF \ I < J \ THEN \ K := K+1 \ ELSE \ SKIP;} \\ {\rm IF \ K = 1 \land \neg (I = J) \ THEN \ R := J-I \ ELSE \ R := I-J,} \\ {\rm (K = 0 \land R = 0 \land I = i \land J = j \land i < j)) =} \\ {\rm (K = (i < j \to E_{11} \ | \ E_{12}) \land R = (i < j \to E_{21} \ | \ E_{22}) \land I = (i < j \to E_{31} \ | \ E_{32}) \land J = (i < j \to E_{41} \ | \ E_{42}) \land i < j) \end{array}$

Noting ' $\wedge i < j$ ' it follows that this simplifies to:

 $\begin{array}{l} \texttt{sp}(\texttt{IF I} < \texttt{J THEN K} := \texttt{K} + \texttt{1} \texttt{ELSE SKIP};\\ \texttt{IF K} = \texttt{1} \land \neg(\texttt{I} = \texttt{J}) \texttt{ THEN R} := \texttt{J} - \texttt{I} \texttt{ ELSE R} := \texttt{I} - \texttt{J},\\ (\texttt{K} = \texttt{0} \land \texttt{R} = \texttt{0} \land \texttt{I} = i \land \texttt{J} = j \land i < j)) =\\ (\texttt{K} = E_{\texttt{11}} \land \texttt{R} = E_{\texttt{21}} \land \texttt{I} = E_{\texttt{31}} \land \texttt{J} = E_{\texttt{41}} \land i < j) \end{array}$

so need only consider the ${\tt I} < {\tt J}$ branch

Example symbolic computation using sp(3)Same example using wlp $\operatorname{sp}(\mathbf{R}:=\mathbf{0})$ wlp(R := 0;K := 0 K := 0: IF I < J THEN K := K + 1 ELSE SKIP; IF I < J THEN K := K + 1 ELSE SKIP; $\label{eq:integral} \text{IF } K = 1 \land \neg (I = J) \text{ Then } R := J - I \text{ Else } R := I - J,$ IF $K=1 \land \neg (I=J)$ Then R:=J-I else R:=I-J, $(\mathbb{I} = i \land \mathbb{J} = j \land i < j)) =$ (R = J - I)) = $\texttt{sp}(\texttt{IF } K = 1 \land \neg(\texttt{I} = \texttt{J}) \text{ THEN } \texttt{R} := \texttt{J} - \texttt{I} \text{ ELSE } \texttt{R} := \texttt{I} - \texttt{J},$ wlp(R := 0: $\left(\mathbf{K} = (\mathbf{K}+1)\left[\mathbf{0}/\mathbf{K}\right] \land \mathbf{R} = \mathbf{0} \land \mathbf{I} = i \land \mathbf{J} = j \land i < j\right)\right) =$ K := 0; IF I < J THEN K := K + 1 ELSE SKIP, $\texttt{sp}(\texttt{IF}\ \texttt{K}=\texttt{1} \land \neg(\texttt{I}=\texttt{J}) \ \texttt{THEN}\ \texttt{R}:=\texttt{J}-\texttt{I}$ else R:=I-J $(\mathtt{K}=1 \land \neg (\mathtt{I}=\mathtt{J}) \ \rightarrow \ \mathtt{J} - \mathtt{I} = \mathtt{J} - \mathtt{I} \ \mid \ \mathtt{J} - \mathtt{I} = \mathtt{I} - \mathtt{J}))$ $\left({\tt K} = 1 \wedge {\tt R} = 0 \wedge {\tt I} = i \wedge {\tt J} = j \wedge i < j \right) \ = \qquad {\rm (by \ a \ similar \ argument)}$ wlp(R := 0; $(\mathbf{K} = 1 \land \mathbf{R} = j - i \land \mathbf{I} = i \land \mathbf{J} = j \land i < j)$ K := 0; Hence by $\{P\} \ C \ \{Q\} = \operatorname{sp}(C, P) \Rightarrow Q$ it follows that $\{(\mathbf{I} = i \land \mathbf{J} = j \land i < j\}$ $(\mathbb{I} < \mathbb{J} \ \rightarrow \ (0+1 = 1 \land \neg (\mathbb{I} = \mathbb{J}) \rightarrow \mathbb{J} - \mathbb{I} = \mathbb{J} - \mathbb{I} \mid \mathbb{J} - \mathbb{I} = \mathbb{I} - \mathbb{J})$ $\mathbb{R}:=0;$ $\mid (0 = 1 \land \neg (I = J) \rightarrow J - I = J - I \mid J - I = I - J)) =$ K := 0: IF I < J THEN K := K + 1 ELSE SKIP; $(\mathtt{I} < \mathtt{J} \ \rightarrow \ (\neg(\mathtt{I} = \mathtt{J}) \rightarrow \mathtt{J} - \mathtt{I} = \mathtt{J} - \mathtt{I} \mid \mathtt{J} - \mathtt{I} = \mathtt{I} - \mathtt{J}) \ \mid \ \mathtt{J} - \mathtt{I} = \mathtt{I} - \mathtt{J}) \ =$ IF $K=1 \land \neg (\texttt{I}=\texttt{J})$ then R:=J-I else R:=I-J) $(\texttt{I} < \texttt{J} \ \rightarrow \ \texttt{J}-\texttt{I} = \texttt{J}-\texttt{I} \ \mid \ \texttt{J}-\texttt{I} = \texttt{I}-\texttt{J}) \ =$ $\{R=j\!-\!i\}$ $({\tt I} < {\tt J})$ Example comparing sp with wlp Computing sp versus wlp • Going forward (simplifying on-the-fly) • Computing sp is like execution sp(R := 0; can simplify as one goes along with the 'current state' K := 0; • may be able to resolve branches, so can avoid executing them IF I < J THEN K := K + 1 ELSE SKIP; IF $K = 1 \land \neg (I = J)$ then R := J - I else R := I - J, • Floyd assignment rule complicated in general $({\tt I}=i \wedge {\tt J}=j \wedge i < j)) \ =$ • Sp used for symbolically exploring 'reachable states' $(\mathbf{K} = 1 \land \mathbf{R} = j - i \land \mathbf{I} = i \land \mathbf{J} = j \land i < j)$ (see Specification and Verification II, especially model checking) • Going backwards Computing wlp is like backwards proof wlp(R := 0;• don't have 'current state', so can't simplify using it K := 0: IF I < J THEN K := K + 1 ELSE SKIP: • can't determine conditional tests, so get big if-then-else trees $\label{eq:integral} \text{IF } K = 1 \land \neg (I = J) \ \text{THEN } R := J - I \ \text{ELSE } R := I - J,$ • Hoare assignment rule simpler for arbitrary formulae (R = J - I)) = $(\mathtt{I} < \mathtt{J} \ \rightarrow \ (0+1=1 \land \neg (\mathtt{I}=\mathtt{J}) \rightarrow \mathtt{J}-\mathtt{I}=\mathtt{J}-\mathtt{I} \ | \ \mathtt{J}-\mathtt{I}=\mathtt{I}-\mathtt{J})$ wlp used for improved verification conditions (see later slides)

Exercises

• Compute

 ${\tt sp}({\tt R}:={\tt 0};$

 $\begin{array}{l} K:=0;\\ \text{IF }I < J \text{ THEN } K:=K+1 \text{ ELSE SKIP};\\ \text{IF }K=1 \wedge \neg (I=J) \text{ THEN } R:=J-I \text{ ELSE } R:=I-J,\\ (I=i \wedge J=j \wedge j \leq i)) \end{array}$

• Hence show

$$\begin{split} & \{(I=i \wedge J=j \wedge j \leq i\} \\ & R:=0; \\ & IF \ I < J \ THEN \ K:=K+1 \ ELSE \ SKIP; \\ & IF \ K=1 \wedge \neg (I=J) \ THEN \ R:=J-I \ ELSE \ R:=I-J) \\ & \{R=i-j\} \end{split}$$

• Do same example use wlp

Using sp to generate verification conditions

- If C is loop-free then VC for $\{P\} \ C \ \{Q\}$ is $sp(C, P) \Rightarrow Q$
- Cannot in general compute a finite formula for sp(WHILE S DO C, P)
- The following holds

 $\texttt{sp}(\texttt{WHILE} \ S \ \texttt{DO} \ C, \ P) \ = \texttt{sp}(\texttt{WHILE} \ S \ \texttt{DO} \ C, \ \texttt{sp}(C, \ (P \land S))) \ \lor \ (P \land \neg S)$

- Above doesn't define $\operatorname{sp}(C,P)$ to be a finite statement
- As with wlp, we will describe a hybrid VC and sp method

sp-based verification conditions

- Define asp(C, P) to be an approximate strongest postcondition
- Define svc(C, P) to be a set of verification conditions
- Idea is that if $\land svc(C, P) \Rightarrow \{P\} \ C \ \{asp(C, P)\}$
- If C is loop-free then
 - $\bullet \; \operatorname{asp}(C,P) = \operatorname{sp}(C,P)$
 - $\bullet \ \operatorname{svc}(C,P) = \{\}$

Definition of asp

• Define asp recursively by:

$$\begin{split} & \operatorname{asp}(P, \ \operatorname{SKIP}) &= P \\ & \operatorname{asp}(P, \ V := E) &= \exists v. \ V = E \left[v/V \right] \land P \left[v/V \right] \\ & \operatorname{asp}(P, \ C_1 \ ; \ C_2) &= \operatorname{asp}(\operatorname{asp}(P, C_1), C_2) \\ & \operatorname{asp}(P, \ \operatorname{IF} \ S \ \operatorname{THEN} \ C_1 \ \operatorname{ELSE} \ C_2) &= \operatorname{asp}(P \land S, \ C_1) \ \lor \ \operatorname{asp}(P \land \neg S, \ C_2) \\ & \operatorname{asp}(P, \ \operatorname{WHILE} \ S \ \operatorname{DO} \ \{R\} \ C) &= R \land \neg S \end{split}$$

Definition of svc

• Define svc recursively by: $svc(P, SKIP) = \{\}$ $svc(P, V := E) = \{\}$ $svc(P, C_1; C_2) = svc(P, C_1) \cup svc(svc_1(P, C_1), C_2)$ $svc(P, \text{ IF } S \text{ THEN } C_1 \text{ ELSE } C_2) = svc(P \land S, C_1) \cup svc(P \land \neg S, C_2)$ $svc(P, \text{ WHILE } S \text{ DO } \{R\} C) = \{P \Rightarrow R, asp(R \land S, C) \Rightarrow R\}$ $\cup svc(R \land S, C)$

- Theorem: $\land \texttt{svc}(P, C) \Rightarrow \{P\} \ C \ \{\texttt{asp}(P, C)\}$
- Proof by induction on C (exercise)

Summary

- Annotate then generate VCs is the classical method
 - practical tools: Gypsy (1970s), SPARK (current)
 - weakest preconditions are alternative explanation of VCs
 - \bullet wlp needs fewer annotations than VC method described earlier
 - \bullet wlp also used for refinement
- $\bullet~{\rm VCs}$ and wlp go backwards, sp goes forward
 - sp provides verification method based on symbolic simulation
 - widely used for loop-free code
 - current research potential for forwards full proof of correctness
 - probably need mixture of forwards and backwards methods (Hoare's view)

Range of methods for proving $\{P\}C\{Q\}$

- Bounded model checking (BMC)
 - unwind loops a finite number of times
 - then symbolically execute
 - check states reached satisfy decidable properties
- Full proof of correctness
 - add invariants to loops
 - generate verification conditions
 - prove verification conditions with a theorem prover
- Research goal: unifying framework for a spectrum of methods

decidable checking

proof of correctness

Proving Programs Terminate

Total Correctness Specification

- So far our discussion has been concerned with partial correctness
 - what about termination
- A total correctness specification [P] C [Q] is true if and only if
 - whenever C is executed in a state satisfying P, then the execution of C terminates
 - after C terminates Q holds
- Except for the WHILE-rule, all the axioms and rules described so far are sound for total correctness as well as partial correctness

Termination of WHILE-Commands

- WHILE-commands are the only commands that might not terminate
- Consider now the following proof

(SKIP axiom)	1. ⊢ {T} SKIP {T}
(precondition strengthening)	$2.\ \vdash\ \{\mathtt{T}\wedge\mathtt{T}\}\ \mathtt{SKIP}\ \{\mathtt{T}\}$
(2 and the WHILE-rule)	3. \vdash {T} while T do skip {T $\land \neg$ T}

 $\bullet~$ If the <code>WHILE-rule</code> worked for total correctness, then this would show:

 $\vdash \ [\texttt{T}] \texttt{ WHILE T DO SKIP} \ [\texttt{T} \land \neg \texttt{T}]$

• Thus the WHILE-rule is unsound for total correctness

Rules for Non-Looping Commands

- Replace { and } by [and], respectively, in:
 - Assignment axiom (see next slide for discussion)
 - Consequence rules
 - Conditional rules
 - Sequencing rule
 - Block rule
- The following is a valid derived rule

 $\begin{array}{c} \vdash \ \{P\} \ C \ \{Q\} \\ \hline \vdash \ [P] \ C \ [Q] \end{array}$

if C contains no WHILE-commands

Total Correctness Assignment Axiom

- Assignment axiom for total correctness
 - $\vdash [P[E/V]] V := E [P]$
- Note that the assignment axiom for total correctness states that assignment commands *always* terminate
- So all function applications in expressions must terminate
- This might not be the case if functions could be defined recursively
- Consider X := fact(-1), where fact(n) is defined recursively:

 $fact(n) = if n = 0 then 1 else n \times fact(n-1)$

Error Termination

- We assume erroneous expressions like 1/0 don't cause problems
- Most programming languages will cause an error stop when division by zero is encountered encountered
- In our logic it follows that

$$\vdash$$
 [T] X := 1/0 [X = 1/0]

- The assignment X := 1/0 halts in a state in which X = 1/0 holds
- This assumes that 1/0 denotes some value that \mathtt{X} can have

Two Possibilities

• There are two possibilities

(i) 1/0 denotes some number;

- (ii) 1/0 denotes some kind of 'error value'.
- It seems at first sight that adopting (ii) is the most natural choice
 - this makes it tricky to see what arithmetical laws should hold
 - is $(1/0) \times 0$ equal to 0 or to some 'error value'?
 - if the latter, then it is no longer the case that $\forall n. \ n \times 0 = 0$ is valid
- It is possible to make everything work with undefined and/or error values, but the resultant theory is a bit messy

Example

- We assume that arithmetic expressions *always* denote numbers
- In some cases exactly what the number is will be not fully specified
 - \bullet for example, we will assume that m/n denotes a number for any m and n
 - $\bullet \ {\bf only \ assume:} \ \neg(n=0) \ \ \Rightarrow \ \ (m/n) \times n = m$
 - it is not possible to deduce anything about $m/0\ {\rm from}\ {\rm this}$
 - in particular it is not possible to deduce that $(m/0)\times 0=0$
 - but $(m/0) \times 0 = 0$ does follow from $\forall n. \ n \times 0 = 0$
- People still argue about this e.g. advocate "three-valued" logics

WHILE-rule for Total Correctness (i)

- WHILE-commands are the only commands in our little language that can cause non-termination
 - they are thus the only kind of command with a non-trivial termination rule
- The idea behind the WHILE-rule for total correctness is
 - to prove WHILE S DO C terminates
 - show that some non-negative quantity decreases on each iteration of C
 - this decreasing quantity is called a variant

WHILE-Rule for Total Correctness (ii)

- In the rule below, the variant is E, and the fact that it decreases is specified with an auxiliary variable n
- The hypothesis $\vdash P \land S \Rightarrow E \ge 0$ ensures the variant is non-negative

WHILE-rule for total correctness

 $\label{eq:product} \begin{array}{c|c} \vdash & [P \land S \land (E=n)] \ C \ [P \land (E < n)], \quad \vdash \ P \land S \Rightarrow E \geq 0 \\ \hline \quad \vdash & [P] \ \texttt{WHILE} \ S \ \texttt{DO} \ C \ [P \land \neg S] \end{array}$

where E is an integer-valued expression and n is an identifier not occurring in P, C, S or E.

Example

• We show

 $\vdash~[\texttt{Y}>0]$ while <code>Y \leq R</code> do begin <code>R:=R-Y;</code> <code>Q:=Q+1</code> END <code>[T]</code>

• Take

 $\begin{array}{rcl} P & = & \mathbf{Y} > \mathbf{0} \\ S & = & \mathbf{Y} \leq \mathbf{R} \\ E & = & \mathbf{R} \\ C & = & \mathrm{BEGIN} \ \mathbf{R}{:=}\mathbf{R}{-}\mathbf{Y} \ \mathbf{Q}{:=}\mathbf{Q}{+}\mathbf{1} \ \mathrm{END} \end{array}$

- We want to show $\vdash [P]$ WHILE S DO C [T]
- By the WHILE-rule for total correctness it is sufficient to show

(i) $\vdash [P \land S \land (E = \mathbf{n})] C [P \land (E < \mathbf{n})]$ (ii) $\vdash P \land S \Rightarrow E \ge 0$

Example Continued (1)

• From previous slide:

 $\begin{array}{rcl} P & = & \mathbf{Y} > \mathbf{0} \\ S & = & \mathbf{Y} \leq \mathbf{R} \\ E & = & \mathbf{R} \\ C & = & \mathrm{BEGIN} \ \mathbf{R}{:=}\mathbf{R}{-}\mathbf{Y} \ \mathbf{Q}{:=}\mathbf{Q}{+}\mathbf{1} \ \mathrm{END} \end{array}$

• We want to show

(i) $\vdash [P \land S \land (E = \mathbf{n})] C [P \land (E < \mathbf{n})]$ (ii) $\vdash P \land S \Rightarrow E \ge 0$

• The first of these, (i), can be proved by establishing

 $\vdash \{P \land S \land (E = \mathbf{n})\} C \{P \land (E < \mathbf{n})\}$

• Then using the total correctness rule for non-looping commands

- Example Continued (2)
- From previous slide:

```
\begin{array}{rcl} P & = & \mathbf{Y} > \mathbf{0} \\ S & = & \mathbf{Y} \leq \mathbf{R} \\ E & = & \mathbf{R} \\ C & = & \mathrm{BEGIN} \ \mathbf{R}{:=}\mathbf{R}{-}\mathbf{Y} \ \mathbf{Q}{:=}\mathbf{Q}{+}\mathbf{1} \ \mathrm{END} \end{array}
```

• The verification condition for $\{P \land S \land (E = n)\} C \{P \land (E < n)\}$ is:

 $\begin{array}{lll} Y>0 & \wedge & Y \leq R & \wedge & R=n & \Rightarrow \\ & (Y>0 & \wedge & R<n) \left[Q\!+\!1/Q \right] \left[R\!-\!Y/R \right] \\ {\bf i.e.} & Y>0 & \wedge & Y \leq R & \wedge & R=n & \Rightarrow & Y>0 & \wedge & R\!-\!Y<n \end{array}$

which follows from the laws of arithmetic

• The second subgoal, (ii), is just $\vdash Y > 0 \land Y \leq R \Rightarrow R \geq 0$

Termination Specifications

• The relation between partial and total correctness is informally given by the equation

 $Total \ correctness = Termination + Partial \ correctness$

• This informal equation can be represented by the following two rules of inferences

Derived Rules

• Multiple step rules for total correctness can be derived in the same way as for partial correctness

• the rules are the same up to the brackets used

 $\bullet\,$ same derivations with total correctness rules replacing partial correctness ones

Example: The Derived Skip Rule



$$\begin{array}{c} \vdash \ P \Rightarrow Q \\ \vdash \ [P] \ \texttt{SKIP} \ [Q] \end{array}$$

• Proof:

- Derivation Tree

$$\frac{\vdash P \Rightarrow Q \quad \overline{\vdash [Q] \text{ SKIP } [Q]}}{\vdash [P] \text{ SKIP } [Q]} \frac{SKP}{PRE}$$

The Derived While Rule

• Derived WHILE-rule needs to handle the variant

Derived WHILE-rule for total correctness

 $\vdash P \Rightarrow R$ $\vdash \ R \wedge S \Rightarrow E \geq 0$ $\vdash \ R \wedge \neg S \ \Rightarrow Q$ $\vdash \ [R \wedge S \wedge (E = n)] \ C \ [R \wedge (E < n)]$ \vdash [P] WHILE S DO C [Q]

VCs for Termination

- Verification conditions are easily extended to total correctness
- To generate total correctness verification conditions for WHILEcommands, it is necessary to add a variant as an annotation in addition to an invariant
- Variant added directly after the invariant, in square brackets
- No other extra annotations are needed for total correctness
- VCs generation algorithm same as for partial correctness

WHILE Annotation

• A correctly annotated total correctness specification of a <code>WHILE-command</code> thus has the form

[P] while S do $\{R\}[E]$ C [Q]

where R is the invariant and E the variant

- Note that the variant is intended to be a non-negative expression that decreases each time around the WHILE loop
- The other annotations, which are enclosed in curly brackets, are meant to be conditions that are true whenever control reaches them (as before)

WHILE VCs

- A correctly annotated specification of a $\ensuremath{\mathtt{WHILE}}$ -command has the form

[P] while S do $\{R\}[E] \mathrel{C} [Q]$

WHILE-commands The verification conditions generated from [P] WHILE S DO $\{R\}[E] C [Q]$ are (i) $P \Rightarrow R$ (ii) $R \land \neg S \Rightarrow Q$ (iii) $R \land S \Rightarrow E \ge 0$ (iv) the verification conditions generated by $[R \land S \land (E = n)] C[R \land (E < n)]$ where n is a variable not occurring in

P, R, E, C, S or Q.

Example

• The verification conditions for

```
 \begin{split} & [R=X \land Q=0] \\ & \text{WHILE } Y \leq R \text{ DO } \{X=R+Y \times Q\}[R] \\ & \text{ BEGIN } R:=R-Y; \ Q=Q+1 \text{ END } \\ & [X = R+(Y \times Q) \land R < Y] \\ & \text{are:} \\ & (i) R=X \land Q=0 \Rightarrow (X = R+(Y \times Q)) \\ & (ii) X = R+Y \times Q \land \neg (Y \leq R) \Rightarrow (X = R+(Y \times Q) \land R < Y) \\ & (iii) X = R+Y \times Q \land Y \leq R \Rightarrow R \geq 0 \\ & \text{together with the unification condition for} \end{split}
```

together with the verification condition for

 $\begin{array}{ll} \left[X=R+(Y{\times}\mathbb{Q})\ \land\ (Y{\leq}R)\ \land\ (R{=}n)\right]\\ & \text{BEGIN }R{:}{=}R{-}Y;\ \mathbb{Q}{:}{=}\mathbb{Q}{+}1\ \text{END}\\ \left[X{=}R{+}(Y{\times}\mathbb{Q})\ \land\ (R{<}n)\right] \end{array}$

Example Continued

• The single verification condition for

 \mathbf{is}

- But this isn't true
 take Y=0
- To prove R-Y<n we need to know Y>0
- *Exercise:* Explain why one would not expect to be able to prove the verification conditions of this last example
- *Hint:* Consider the original specification

Summary

- We have given rules for total correctness
- They are similar to those for partial correctness
- The main difference is in the WHILE-rule
 because WHILE commands are the only ones that can fail to terminate
- Must prove a non-negative expression is decreased by the loop body
- Derived rules and VC generation rules for partial correctness easily extended to total correctness
- Interesting stuff on the web
 - $\bullet \ http://www.crunchgear.com/2008/12/31/zune-bug-explained-in-detail$
 - $\bullet \ http://research.microsoft.com/TERMINATOR$

Overview

- All the axioms and rules given so far were quite straightforward
 may have given a false sense of simplicity
- Hard to give rules for anything other than very simple constructs
 - an incentive for using simple languages
- We already saw with the assignment axiom that intuition over how to formulate a rule might be wrong

• the assignment axiom can seem 'backwards'

- We now look at the remaing commands in our little language
 - array assignments
 - FOR-commands

Arrays and FOR-commands Soundness and Completeness

Array assignments

- Syntax: *V*(*E*₁):=*E*₂
- Semantics: the state is changed by assigning the value of the term E_2 to the E_1 -th component of the array variable V
- Example: A(X+1) := A(X)+2
 - if the the value of X is x
 - \bullet and the value of the x-th component of A is n
 - then the value stored in the (x+1)-th component of A becomes $n\!+\!2$

Naive Array Assignment Axiom Fails

- The axiom $\vdash \{P[E_2/A(E_1)]\} A(E_1) := E_2 \{P\}$
 - doesn't work
- Take $P \equiv 'X=Y \land A(Y)=0', E_1 \equiv 'X', E_2 \equiv '1'$
 - since A(X) does not occur in P
 - it follows that P[1/A(X)] = P
 - hence the axiom yields: $\vdash \{X=Y \land A(Y)=0\} A(X):=1 \{X=Y \land A(Y)=0\}$
 - which is false since it implies: $\vdash \{\cdots\} A(X) := 1 \{A(X)=0\}$
- Must take into account possibility that changes to A(X) may change $A(Y),\,A(Z)$ etc

• since X might equal Y, Z etc (i.e. aliasing)

• Related to the Frame Problem in AI

Reasoning About Arrays

• The naive array assignment axiom

$$\vdash \{P[E_2/A(E_1)]\} A(E_1) := E_2 \{P\}$$

does not work: changes to A(X) may also change $A(Y), \ A(Z), \ \ldots$

• The solution, due to Hoare, is to treat an array assignment

 $A(E_1):=E_2$

as an ordinary assignment

$$A := A \{E_1 \leftarrow E_2$$

where the term $A\{E_1 \leftarrow E_2\}$ denotes an array identical to A, except that the E_1 -th component is changed to have the value E_2

Array Assignment axiom

• Array assignment is a special case of ordinary assignment

 $A := A \{ E_1 \leftarrow E_2 \}$

• Array assignment axiom just ordinary assignment axiom

 $\vdash \{P[A\{E_1 \leftarrow E_2\}/A]\} A := A\{E_1 \leftarrow E_2\} \{P\}$

• Thus:

The array assignment axiom

 $\vdash \{P[A\{E_1 \leftarrow E_2\}/A]\} A(E_1) := E_2 \{P\}$

Where A is an array variable, E_1 is an integer valued expression, P is any statement and the notation $A\{E_1 \leftarrow E_2\}$ denotes the array identical to A, except that $A(E_1) = E_2$. Array Axioms

• In order to reason about arrays, the following axioms, which define the meaning of the notation $A\{E_1 \leftarrow E_2\}$, are needed

The array axioms

 $\label{eq:eq:entropy} \begin{array}{rcl} \vdash & A\{E_1{\leftarrow}E_2\}(E_1) &= & E_2 \\ \\ \vdash & E_1 \neq E_3 & \Rightarrow & A\{E_1{\leftarrow}E_2\}(E_3) &= & A(E_3) \end{array}$

• Second of these is a Frame Axiom

Example

• We show

• Working backwards using the array assignment axiom

$$\begin{split} \vdash & \left\{ (\mathbb{A}\{Y \leftarrow R\})(X) = y \land (\mathbb{A}\{Y \leftarrow R\})(Y) = x \right\} \\ & \mathbb{A}(Y) := R \\ & \left\{ \mathbb{A}(X) = y \land \mathbb{A}(Y) = x \right\} \end{split}$$

- Array assignments are variable assignments of array values, so:
 - $\begin{array}{l} \vdash \left\{ (A\{Y \leftarrow R\})(X) = y \land (A\{Y \leftarrow R\})(Y) = x \right\} \\ A := A\{Y \leftarrow R\} \\ \left\{ A(X) = y \land A(Y) = x \right\} \end{array}$

Example Continued (1)

• Using

 $\vdash A{Y \leftarrow R}(Y) = R$

- It follows that
 - $\begin{array}{l} \vdash \ \left\{ (\mathbb{A}\{Y \leftarrow \mathbb{R}\}) (X) = y \land \mathbb{R} = x \right\} \\ \mathbb{A}(Y) \ := \ \mathbb{R} \\ \left\{ \mathbb{A}(X) = y \land \mathbb{A}(Y) = x \right\} \end{array}$
- Continuing backwards

 $\begin{array}{l} \displaystyle \vdash \ \left\{ \left(\left(\mathbb{A} \{ X \leftarrow \mathbb{A} (Y) \} \right) \{ Y \leftarrow \mathbb{R} \} \right) (X) = y \ \land \ \mathbb{R} = x \right\} \\ \displaystyle \mathbb{A} (X) \ := \ \mathbb{A} (Y) \\ \displaystyle \left\{ \left(\mathbb{A} \{ Y \leftarrow \mathbb{R} \} \right) (X) = y \ \land \ \mathbb{R} = x \right\} \end{array}$

• Maybe more intuitive if the assignment is rewritten

```
 \begin{array}{l} \vdash \ \left\{ \left(\left( A \{ X \leftarrow A(Y) \} \right) \{ Y \leftarrow B \} \right) (X) = y \land R = x \right\} \\ A \ := \ A \{ X \leftarrow A(Y) \} \\ \left\{ \left( A \{ Y \leftarrow B \} \right) (X) = y \land R = x \right\} \end{array}
```

Example Continued (2)

• Continuing backwards

$$\begin{split} & \vdash \left\{ ((A\{X \leftarrow A(Y)\}) \{Y \leftarrow A(X)\}) (X) = y \land A(X) = x \right\} \\ & R := A(X) \\ & \left\{ ((A\{X \leftarrow A(Y)\}) \{Y \leftarrow R\}) (X) = y \land R = x \right\} \end{split}$$

• Hence by the derived sequencing rule

 $\begin{array}{l} \displaystyle \vdash \ \left\{ \left(\left(\mathbb{A} \{ X \leftarrow \mathbb{A}(Y) \} \right) \{ Y \leftarrow \mathbb{A}(X) \} \right) (X) = y \land \mathbb{A}(X) = x \right\} \\ \displaystyle R \ := \ \mathbb{A}(X) \ ; \ \mathbb{A}(X) \ := \ \mathbb{A}(Y) \ ; \ \mathbb{A}(Y) \ := \ \mathbb{R} \\ \displaystyle \left\{ \mathbb{A}(X) = y \land \mathbb{A}(Y) = x \right\} \end{array}$

• By the array axioms (considering the cases X=Y and $X\neq Y$ separately):

 $(Y) A = (X) ({(X)} A \rightarrow Y) ({(Y)} A \rightarrow X) A \rightarrow X$

• Hence, (as desired)

```
\begin{array}{l} \vdash \; \big\{ A\,(Y) = y \; \land \; A\,(X) = x \big\} \\ R \; := \; A\,(X) \; ; \; A\,(X) \; := \; A\,(Y) \; ; \; A\,(Y) \; := \; R \\ \big\{ A\,(X) = y \; \land \; A\,(Y) = x \big\} \end{array}
```

FOR-commands

- Syntax: FOR $V := E_1$ UNTIL E_2 DO C
 - restriction: V must not occur in E₁ or E₂, or be the left hand side of an assignment in C (explained later)
- Semantics:
 - if the values of terms E_1 and E_2 are positive numbers e_1 and e_2
 - and if $e_1 \leq e_2$
 - then C is executed $(e_2-e_1)+1$ times with the variable V taking on the sequence of values $e_1,\,e_1+1,\,\ldots\,,\,e_2$ in succession
 - for any other values, the FOR-command has no effect
- Example: FOR N:=1 UNTIL M DO X:=X+N
 - if the value of the variable M is m and $m\geq$ 1, then the command X:=X+N is repeatedly executed with N taking the sequence of values 1, \ldots , m
 - if m < 1 then the FOR-command does nothing

Subtleties of FOR-commands

- There are many subtly different versions of FOR-commands
- For example
 - the expressions E_1 and E_2 could be evaluated at each iteration
 - \bullet and the controlled variable V could be treated as global rather than local
- Early languages like Algol 60 failed to notice such subtleties
- Note that with the semantics presented here FOR-commands cannot generate non termination

More on the semantics of FOR-commands

• The semantics of

FOR $V := E_1$ UNTIL E_2 DO C

is as follows

- (i) E_1 and E_2 are evaluated once to get values e_1 and e_2 , respectively.
- (ii) If either e₁ or e₂ is not a number, or if e₁ > e₂, then nothing is done.
 (iii) If e₁ ≤ e₂ the FOR-command is equivalent to:

BEGIN VAR V; V:= e_1 ; C; V:= e_1 +1; C; ...; V:= e_2 ; C END

i.e. C is executed $(e_2-e_1)+1$ times with V taking on the sequence of values $e_1, \, e_1+1, \, \ldots \, , \, e_2$

• If C doesn't modify V then FOR-command equivalent to: BEGIN VAR V; $V:=e_1$; ... C; V:=V+1; ... $V:=e_2$; C END repeated

- The Derived Frame Rule (used in motivating FOR Rule)
- The following can be derived

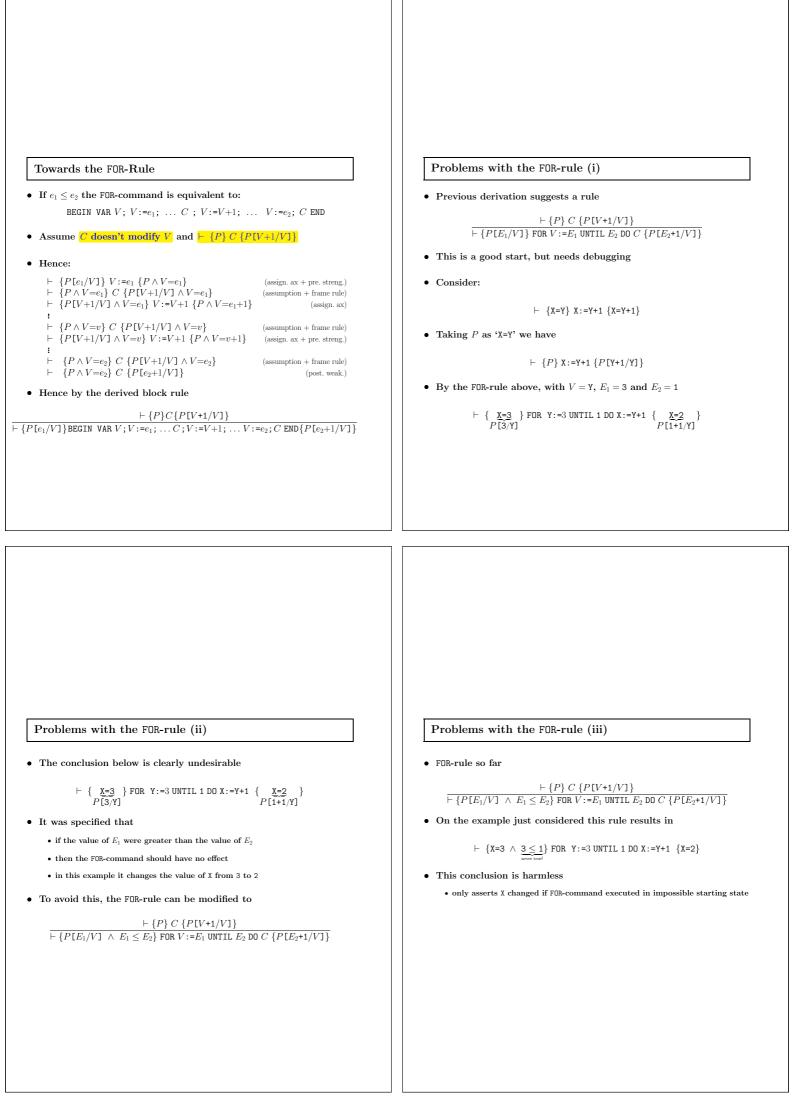
The frame rule

$$\begin{array}{c|c} \vdash & \{P\} \ C \ \{Q\} \\ \hline \vdash & \{P \land R\} \ C \ \{Q \land R\} \end{array}$$

where no variable assigned to in \boldsymbol{C} occurs in \boldsymbol{R}

• Outline of derivation

- prove $\{R\} \ C \ \{R\}$ by induction on C
- then use Specification Conjunction



Problems with the FOR-rule (iv)

• Unfortunately, there is a bug in

 $\frac{ \vdash \{P\} C \{P[V+1/V]\}}{\vdash \{P[E_1/V] \land E_1 \leq E_2\} \text{ for } V := E_1 \text{ until } E_2 \text{ do } C \{P[E_2+1/V]\}}$

• Take P to be 'Y=1' and note that

$$\vdash \{\underbrace{\underline{\mathsf{Y}=1}}_{P} \} \underbrace{\mathsf{Y}:=\mathsf{Y}-1}_{P} \{\underbrace{\underbrace{\mathsf{Y}+1=1}}_{P[\underline{\mathsf{Y}+1}/\underline{\mathsf{Y}}]} \}$$

• So by this FOR-rule

$$\vdash \begin{array}{c} \{ \begin{array}{c} \underline{1=1} \\ P\left[\overline{1}/Y\right] \end{array} \land 1 \leq 1 \} \text{ FOR } Y := 1 \text{ UNTIL 1 DO } Y := Y - 1 \end{array} \begin{cases} 2\underline{=1} \\ P\left[\overline{1+1}/Y\right] \end{array} \end{cases}$$

Problems with the FOR-rule (v)

- Whatever the command does, it doesn't lead to a state in which 2=1
- The problem is that the body of the FOR-command modifies the controlled variable
- This is why it was explicitly assumed that the body didn't modify the controlled variable

Problems with the FOR-rule (vi)

- This problem may also arise if any variables in the expressions E_1 and E_2 are modified
- For example, taking P to be Z=Y, then

$$\vdash \underbrace{\{\underline{Z}=\underline{Y}\}}_{P} \underbrace{Z:=Z+1}_{P[\underline{Y}+1/\underline{Y}]} \underbrace{\{\underline{Z}=\underline{Y+1}}_{P[\underline{Y}+1/\underline{Y}]}$$

• Thus the following can be derived

$$\label{eq:constraint} \begin{array}{l} \vdash \ \{ \begin{array}{c} \underline{Z=1} \\ P\left[1/Y\right] \end{array} \land 1 \leq Z \} \ \text{FOR} \ Y:=1 \ \text{UNTIL} \ Z \ \text{DO} \ Z:=Z+1 \ \{ \begin{array}{c} \underline{Z=Z+1} \\ P\left[Z+1/Y\right] \end{array} \}$$

• This is clearly wrong

• one can never have Z=Z+1

- Not a problem because the FOR-command doesn't terminate?
 - in some languages this might be the case
 - semantics of our language defined so that FOR-commands always terminate

The FOR-Rule

• To rule out the problems that arise when the controlled variable or variables in the bounds expressions, are changed by the body, we simply impose a side condition on the rule that stipulates that it cannot be used in these situations

The FOR-rule

 $\begin{array}{c} \displaystyle \displaystyle \vdash \{P \wedge (E_1 \leq V) \wedge (V \leq E_2)\} \ C \ \{P[V + 1/V]\} \\ \displaystyle \\ \displaystyle \overline{\vdash \{P[E_1/V] \wedge (E_1 \leq E_2)\}} \ \text{FOR} \ V := E_1 \ \text{UNTIL} \ E_2 \ \text{DO} \ C \ \{P[E_2 + 1/V]\} \\ \text{where neither } V, \ \text{nor any variable occurring in } E_1 \ \text{or } E_2, \ \text{is assigned to in the command} \ C. \end{array}$

- Note $(E_1 \leq V) \land (V \leq E_2)$ in precondition of rule hypothesis
 - added to strengthen rule to allow proofs to use facts about $V\sp{s}$ range of values
- Can be tricky to think up P

Comment on the FOR-Rule

- The FOR-rule does not enable anything to be deduced about FORcommands whose body assigns to variables in the bounds expressions
- This precludes such assignments being used if commands are to be reasoned about
- Only defining rules of inference for non-tricky uses of constructs motivates writing programs in a perspicuous manner
- It is possible to devise a rule that does cope with assignments to variables in bounds expressions
- Consider:

 $\begin{array}{c} \vdash \{P \land (E_1 \leq V) \land (V \leq E_2)\} \ C \ \{P [V + 1/V]\} \\ \vdash \{P [E_1/V] \land (E_1 \leq E_2) \land (E_2 = e_2)\} \ \text{FOR} \ V := E_1 \ \text{UNTIL} \ E_2 \ \text{DO} \ C \ \{P [e_2 + 1/V]\} \end{array}$

The FOR-axiom

• To cover the case when $E_2 < E_1$, we need the FOR-axiom below

The FOR-axiom

 $\vdash \{P \land (E_2 < E_1)\} \text{ FOR } V := E_1 \text{ UNTIL } E_2 \text{ DO } C \{P\}$

• This says that when E_2 is less than E_1 the FOR-command has no effect

Exercise: understand the example on this slide

- By the assignment axiom and precondition strengthening
 - $\vdash \ \left\{ \texttt{X} \ = \ (\texttt{(N-1)} \times \texttt{N}) \ \texttt{DIV} \ 2 \right\} \ \texttt{X} := \texttt{X} + \texttt{N} \ \left\{ \texttt{X} = (\texttt{N} \times (\texttt{N+1})) \ \texttt{DIV} \ 2 \right\}$
- Strengthening the precondition of this again yields
 - $\label{eq:linear_linear} \begin{array}{l} \vdash \left\{ (\texttt{X} = ((\texttt{N-1}) \times \texttt{N}) \ \texttt{DIV} \ \texttt{2}) \land (\texttt{1} \leq \texttt{N}) \land (\texttt{N} \leq \texttt{M}) \right\} \\ \texttt{X} := \texttt{X} + \texttt{N} \\ \left\{ \texttt{X} = (\texttt{N} \times (\texttt{N+1})) \ \texttt{DIV} \ \texttt{2} \right\} \end{array}$
- Hence by the FOR-rule
 - $\label{eq:constraint} \begin{array}{l} \vdash \left\{ (\texttt{X} = ((1{-}1){\times}1) \ \texttt{DIV} \ 2){\wedge}(1{\leq}\texttt{M}) \right\} \\ \quad \texttt{FOR } \texttt{N} := \texttt{1} \ \texttt{UNTIL } \texttt{M} \ \texttt{DO } \ \texttt{X} := \texttt{X}{+}\texttt{N} \\ \left\{ \texttt{X} = (\texttt{M}{\times}(\texttt{M}{+}1)) \ \texttt{DIV} \ 2 \right\} \end{array}$
- Hence
 - $\label{eq:constraint} \begin{array}{l} \vdash \ \left\{ (\texttt{X=0}) \land (\texttt{1}{\leq}\texttt{M}) \right\} \\ \quad \text{FOR } \texttt{N}:=\texttt{1} \text{ UNTIL } \texttt{M} \text{ DO } \texttt{X}:=\texttt{X+N} \\ \left\{ \texttt{X} = \ (\texttt{M}{\times}(\texttt{M+1})) \text{ DIV } \texttt{2} \right\} \end{array}$

Note on using the FOR-Rule

- Note that if any of the following hold
 - (i) $\vdash \{P\} C \{P[V+1/V]\}$ (ii) $\vdash \{P \land (E_1 \le V)\} C \{P[V+1/V]\}$ (iii) $\vdash \{P \land (V \le E_2)\} C \{P[V+1/V]\}$
- Then by precondition strengthening:
 - $\vdash \ \{P \ \land \ (E_1 \le V) \ \land \ (V \le E_2)\} \ C \ \{P [V+1/V] \}$
- So any of (i), (ii) or (iii) above is a sufficient hypothesis for FOR Rule

Deriving the For Rule

- The following is a command equivalent to FOR $I:=E_1$ UNTIL E_2 DO C
 - BEGIN VAR I; VAR UpperBound; I := E₁; UpperBound := E₂; WHILE I \leq UpperBound DO (C; I := I+1) END
 - UpperBound is assumed to be a 'new' variable
 - \bullet and I is not assigned to inside C
- Thus we could derive a rule from the implementation
 - we must be sure the implementation is correct
- Exercise: try deriving the FOR-rule from the WHILE-rule

Exercise: think about Wickerson's FOR-Rule (see below)

The FOR rule as presented in the notes had always seemed quite unsatisfactory to me, because it couldn't deal with the case when the lover and upper bounds on the looping variable were the wrong way around (benee the need for the FOR-axiom).

I have derived a new rule, which removes the need for the FOR-axiom completely. This rule doesn't suffer from the problems that the early incarnations of the FOR-rule suffered from in the lecture notes, and i believe the rule to be equally powerful.

It is derived, very easily, by noting that: FOR V:=E1 UNTIL E2 DO C is equivalent to:

BEGIN VAR V; V:=E1; WHILE V<=E2 DO (C; V:=V+1) END

(where the standard syntactic constraints still apply, i.e. neither V nor any variable in El or E2 may be assigned to in C). Then we simply apply the Floyd-Hoare rules of blocks, sequencing and while-commands to derive the following rules

|- P ==> R[E1/V] |- R & V>E2 ==> Q |- {R & V<=E2} C {R[V+1/V]} |- {P} FOR V:=E1 UNTIL E2 DO C {0}

This rule is similar to, but subtly different from, the FOR-rule derived in the notes. I've tried my rule on various examples in the notes, and I reckon it works fine. I'll just give one quick example here; suppose we vant to prove:

{X = 2} FOR V := 10 UNTIL 0 DO X:=1 {X=2}

Then we set R = (V=10 & X=2). The three antecedents of the (new) rule are instantiated to

(1) $X = 2 \Rightarrow 5 (0-10 \& X = 2)$ (2) V = (0 & X = 2 & Y = 0) = 3 = 2(3) |-(V=10 & X = 2 & V < = 0) X = 1 (V+1=10 & X = 2)Note that (1) and (2) are trivially true, and (3) holds because the precondition is unsatisfiable (V cannot be both equal to 10 and no greater than ().

Soundness and Completeness

- It is clear from the discussion of the FOR-rule that it is not always straightforward to devise correct rules of inference
- It is important that the axioms and rules be sound. There are two approaches to ensure this

(i) define the language by the axioms and rules of the logic(ii) prove that the logic fits the language

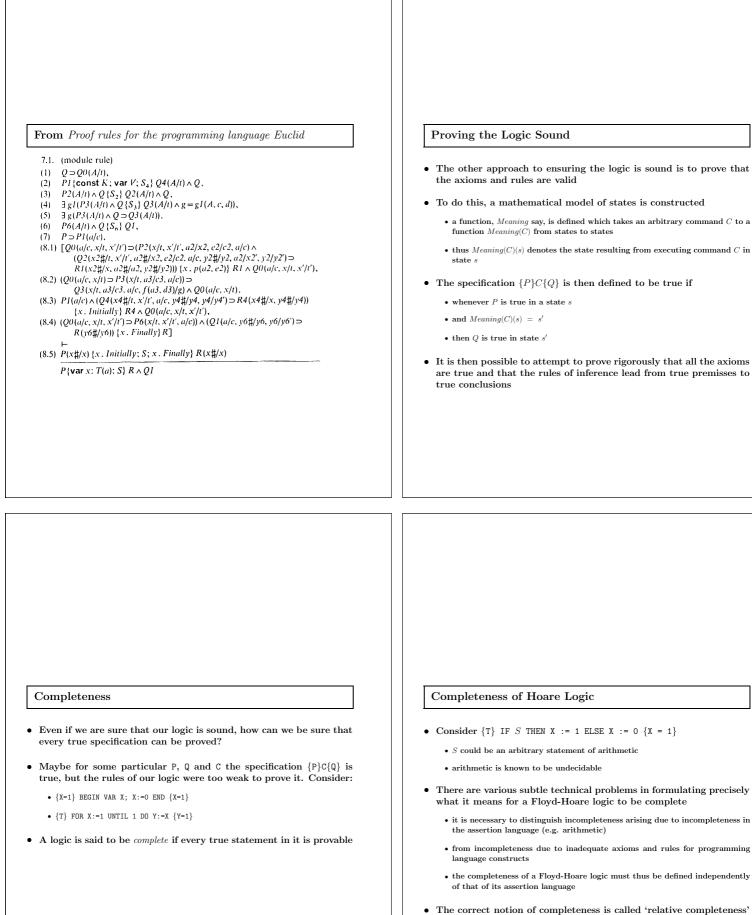
- Approach (i) is called axiomatic semantics
 - \bullet the idea is to define the semantics of the language by requiring that it make the axioms and rules of inference true
 - it is then up to implementers to ensure that the logic matches the language

Axiomatic Semantics

• One snag with axiomatic semantics is that most existing languages have already been defined in some other way

• usually by informal and ambiguous natural language statements

- The other snag with axiomatic semantics is that it is known to be impossible to devise adequate Floyd-Hoare logics for certain constructs (Clarke's Theorem)
 - it could be argued that this is not a snag at all but an advantage, because it forces programming languages to be made logically tractable
- An example of a language defined axiomatically is Euclid



roughly: complete assuming an oracle for logic and mathematical theories

Clarke's Results

- Ed Clarke (of Carnegie Mellon University) has proved the impossibility of giving complete inference systems for certain combinations of programming language constructs
- He shows it is *impossible* to give a sound and relatively complete system for any language combining:
 - procedures as parameters of procedure calls
 - recursion
 - static scopes
 - global variables
 - internal procedures as parameters of procedure calls
- These features are found in Algol 60, which thus cannot have an adequate Floyd-Hoare logic

Summary

- Devising rules for programming constructs can be tricky
 for safety critical applications logically tractable languages should be used
- Two desirable properties of the logic are:
 - soundness: only true things can be proved
 - completeness: everything that is true can be proved
- Fully automatic program verification is impossible
 - arithmetic is undecidable
 - in practice a lot of success verifying weak properties automatically (e.g. http://research.microsoft.com/en-us/um/redond/groups/rise/staticanalysis.aspx)
- User-assisted program verification is active research area

Refinement

- So far we have focused on proving programs meet specifications
- An alternative is to ensure a program is **correct by construction**
- The proof is performed in conjunction with the development
 - errors are spotted earlier in the design process
 - the reasons for design decisions are available
- Programming becomes less of a black art and more like an engineering discipline
- Rigorous development methods such as the B-Method, SPARK and the Vienna Development Method (VDM) are based on this idea
- The approach here is based on "Programming From Specifications"
 - a book by Carroll Morgan
 - simplified and with a more concrete semantics

Program Refinement

Refinement Laws

- Laws of Programming refine a specification to a program
- As each law is applied, proof obligations are generated
- The laws are derived from the Hoare logic rules
- Several laws will be applicable at a given time
 - corresponding to different design decisions
 - and thus different implementations
- The "Art" of Refinement is in choosing appropriate laws to give an efficient implementation
- For example, given a specification that an array should be sorted:
 - one sequence of laws will lead to Bubble Sort
 - a different sequence will lead to Insertion Sort
 - see Morgan's book for an example of this

Refinement Specifications

- A refinement specification has the form [P, Q]
 - P is the precondition
 - ${\boldsymbol{Q}}$ is the postcondition
- Unlike a partial or total correctness specification, a refinement specification does not include a command
- Goal: derive a command that satisfies the specification
- *P* and *Q* correspond to the pre and post condition of a total correctness specification
- A command is required which if started in a state satisfying P, will terminate in a state satisfying Q

Example

- [T, X=1]
 - \bullet this specifies that the code provided should terminate in a state where X has value 1 whatever state it is started in
- [X>0, Y=X²]
 - \bullet from a state where X is greater than zero, the program should terminate with Y the square of X

A Little Wide Spectrum Programming Language

- Let *P*, *Q* range over statements (predicate calculus formulae)
- Add specifications to commands

 $E \ ::= \ N \ \mid \ V \ \mid \ E_1 + E_2 \ \mid \ E_1 - E_2 \ \mid \ E_1 \times \ E_2 \ \mid \ \ldots$

$$B \ ::= \ \mathbf{T} \ \mid \ \mathbf{F} \ \mid \ E_1{=}E_2 \ \mid \ E_1 \leq E_2 \ \mid \ \ldots$$

Specifications as Sets of Commands

• Refinement specifications can be mixed with other commands but are not in general executable

Example
 R:=X;
 Q:=0:

[R=X \land Y>0 \land Q=0, X=R+Y×Q]

• Think of a specification as defining the set of implementations

$$[P, Q] = \{ C \mid \vdash [P] C [Q] \}$$

• For example

 $[\texttt{T}, \texttt{X=1}] = \{\texttt{"X:=1"}, \texttt{"IF} \neg(\texttt{X=1}) \texttt{ THEN } \texttt{X:=1"}, \texttt{"X:=2;X:=X-1"}, \cdots \}$

Notation for combining sets of commands

- Wide spectrum language commands are sets of ordinary commands
- Let c, c₁, c₂ etc. denote sets of commands, then define:

```
\mathcal{C}_1; \cdots; \mathcal{C}_n =
```

 $= \{ C \mid \exists C_1 \cdots C_n. C = C_1; \cdots; C_n \land$ $C_1 \in c_1 \land \cdots \land C_n \in c_n \}$ $= \{ C_1; \cdots; C_n \mid C_1 \in c_1 \land \cdots \land C_n \in c_n \}$

 $\texttt{BEGIN VAR } V_1\texttt{;} \ \cdots \ \texttt{VAR } V_n\texttt{;} \ c \ \texttt{END} \ = \{ \ \texttt{BEGIN VAR } V_1\texttt{;} \ \cdots \ \texttt{VAR } V_n\texttt{;} \ C \ \texttt{END} \ \mid \ C \in c \ \}$

Refinement based program development

- The client provides a non-executable program (the specification)
- The programmer's job is to transform it into an executable program
- It will pass through a series of stages in which some parts are executable, but others are not
- Specifications give lots of freedom about how a result is obtained
 - executable code has no freedom
 - mixed programs have some freedom
- We use the notation p₁⊇ p₂ to mean program p₂ is more refined (i.e. has less freedom) than program p₁
- N.B. The standard notation is $p_1 \sqsubseteq p_2$ (see the notes for a discussion)
- A program development takes us from the specification, through a series of mixed programs to (we hope) executable code

 $spec \supseteq \ mixed_1 \supseteq \ ... \supseteq \ mixed_n \supseteq code$

Skip Law

The Skip Law

 $[P, P] \supseteq \{ \texttt{SKIP} \}$

• Derivation:

• Examples

```
\begin{split} & [X=1, \quad X=1] \ \supseteq \ \{SKIP\} \\ & [T, \quad T] \ \supseteq \ \{SKIP\} \\ & [X=R+Y\times Q, \quad X=R+Y\times Q] \ \supseteq \ \{SKIP\} \end{split}
```

Notational Convention

- Omit { and } around individual commands
- Skip law becomes:

 $[P, P] \supseteq SKIP$

• Examples become:

 Assignment Law

The Assignment Law

 $[P[E/V], P] \supseteq \{V := E\}$

• Derivation

$$\begin{split} C &\in \{V := E\} \\ &\Leftrightarrow C = V := E \\ &\Rightarrow \vdash [P[E/V]] \ C \ [P] \ (\text{Assignment Axiom}) \\ &\Leftrightarrow C \in [P[E/V], \ P] \quad (\text{Definition of } [P[E/V], \ P]) \end{split}$$

• Examples (using bracket-omitting convention)

Laws of Consequence

Precondition Weakening

 $[P, \quad Q] \supseteq [R, \quad Q]$

provided $\vdash P \Rightarrow R$

Postcondition Strengthening

 $\begin{array}{ll} [P, & Q] \supseteq [P, & R] \\ \textbf{provided} & \vdash & R \ \Rightarrow \ Q \end{array}$

- We are now "weakening the precondition" and "strengthening the post condition"
 - this is the opposite terminology to the Hoare rules
 - refinement consequence rules are 'backwards'

Derivation of Consequence Laws

• Derivation of Precondition Weakening

 $\begin{array}{l} C \in [R, \ Q] \\ \Leftrightarrow \ \vdash \ [R] \ C \ [Q] \ (\text{Definition of } [R, \ Q]) \\ \Rightarrow \ \vdash \ [P] \ C \ [Q] \ (\text{Precondition Strengthening} \vdash P \Rightarrow R) \\ \Leftrightarrow \ C \in [P, \ Q] \ (\text{Definition of } [P, \ Q]) \end{array}$

• Derivation of Postcondition Strengthening

 $\begin{array}{l} C \in [P, \ R] \\ \Leftrightarrow \ \vdash \ [P] \ C \ [R] \ (\text{Definition of } [R, \ Q]) \\ \Rightarrow \ \vdash \ [P] \ C \ [Q] \ (\text{Postcondition Weakening} \vdash R \Rightarrow Q) \\ \Leftrightarrow \ C \in [P, \ Q] \ (\text{Definition of } [P, \ Q]) \end{array}$

A provious example: $(X-1, X-1)$ \supseteq (Sizj) Strip An alternative refinement: $(Y-1, X-1)$ \supseteq (Precondition Meakening $\vdash Y=1 \Rightarrow 1=1$) $(Y-1, X-1)$ \supseteq (Assignment) $X := 1$ Another example $(T, R\timesX)$ \supseteq (Precondition Meakening $\vdash T \Rightarrow X-X$) $(X-X, R-X)$ \supseteq (Assignment) $R := X$		
A provides example: $[2n, 1, 2n]$ $2(Rig)$ SET An alternative refinement: $[r_1, r_2]$ $[r_1, r_2]$ $2(reconstruct leadening + 1^{r_1} \rightarrow 1^{n_1})$ $[r_1, r_2]$ $[r_2, r_2]$ <		
A provides example: $[2n, 1, 2n]$ $2(Rig)$ SET An alternative refinement: $[r_1, r_2]$ $[r_1, r_2]$ $2(reconstruct leadening + 1^{r_1} \rightarrow 1^{n_1})$ $[r_1, r_2]$ $[r_2, r_2]$ <		
$\begin{array}{l} [\mathbf{r}_{1}, \mathbf{r}_{2}] \\ (Step) \\ Step $	Examples (illustrates refinement notation)	Derived Assignment Law
$\begin{array}{l} [\mathbf{r}_{1}, \mathbf{r}_{2}] \\ (Step) \\ Step $	A previous example:	· · · · · · · · · · · · · · · · · · ·
$ \begin{array}{l} 2 (\operatorname{strip}) \\ \operatorname{strip} \\ An alternative refinement: \\ (r^{+}, r^{+}, r^{+}, r^{+}) \\ (r^{+}, r^{+}, r^{+}, r^{+}) \\ (r^{+}, r^{+}, r^{+}, r^{+}, r^{+}) \\ (r^{+}, r^{+}, r^{+}, r^{+}, r^{+}, r^{+}) \\ (r^{+}, r^{+}, r^{+}, r^{+}, r^{+}, r^{+}, r^{+}) \\ (r^{+}, r^{+}, r^{+}, r^{+}, r^{+}, r^{+}, r^{+}) \\ (r^{+}, r^{+}, r^{+$		Derived Assignment Law
$fechnical Interlude: Monotonicity Technical Interlude: Monotonicity f(x_1, x_2) = \frac{1}{(x_1, x_2)} = \frac{1}{(x_1, x_2)} = \frac{1}{(x_1, x_2)} = \frac{1}{(x_2, x_2)} = $		$[P Q] \supset \{V := E\}$
[ret, r-1] 2 (Precondition Veckening + T + i = i-1) (r-t, r-1) 2 (neighbors) 3 (ret (r-t) r-1) 2 (neighbors) 3 (ret (r-t) r-1) 2 (neighbors) 3 (neighbors)		
$ \begin{array}{l} 2 \left P = condition \ Verkening \vdash Y = 1 = 1 + 1 \\ (r = 1, r = 1) \\ $		• Derivation
$Ic_{1}, r_{-1} = 1$ $I(r_{-1} = r_{-1})$ $I(r_{-1}, r_{-1})$ $I($		
$\overline{\mathbf{X}}_{i} = 1$ Another example $[T_{i} = \mathbf{R}_{i}]$ $(\mathbf{r}_{i} = \mathbf{R}_{$	· · · · · · · · · · · · · · · · · · ·	
Another example $[T, R*X] = (reconstructions Weakening \vdash T \Rightarrow T \Rightarrow T \Rightarrow (x)$ $[Point (r, R*X]) = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $R := X$ • Example $[T, R*X] = (portred Assignment \vdash T \Rightarrow X \times X)$ $[$		
[T, F, N] = (T, F, N) = (F, R, N) = (F, R)		
$ \begin{array}{l} \text{Dechnical interlude: Monotonicity} \\ \hline \text{Bechnical interlude: Monotonicity} \\ \hline \text{Sets of commands are monotonic w.r.t.} \\ \text{if } i \in \mathbb{X} \\ \hline \text{Sets of commands are monotonic w.r.t.} \\ \hline \text{if } i \in \mathbb{C}^{n}, i \in C$	-	
$ \begin{array}{llllllllllllllllllllllllllllllllllll$	-, -	• Example
Technical interlude: Monotonicity $\mathbb{R} := X$ $Previous Assignment \vdash T \Rightarrow X \times \mathbb{R}$		[T. R=X]
R := X R := X Ecchnical interlude: Monotonicity Sets of commands are monotonic w.r.t. \supseteq • if $\mathbb{C}^{C_1}, \mathbb{C}_2^{C_2}, \dots, \mathbb{C}_2^{C_n}$ • if $\mathbb{C}^{C_1}, \mathbb{C}_2^{C_2}, \dots, \mathbb{C}_n^{C_n}$ • if $\mathbb{C}^{C_n}, \mathbb{C}_n^{C_n}, \mathbb{C}_n^{C_n}, \mathbb{C}_n^{C_n}, \mathbb{C}_n^{C_n}$ • if $\mathbb{C}^{C_n}, \mathbb{C}_n^{C_n}, \mathbb{C}_n^{C_n}, \mathbb{C}_n^{C_n}, \mathbb{C}_n^{C_n}, \mathbb{C}_n^{C_n}$ • if $\mathbb{C}^{C_n}, \mathbb{C}^{C_n}, \mathbb{C}_n^{C_n}, \mathbb{C}_n^{C_n}, \mathbb{C}_n^{C_n}, \mathbb{C}_n^{C_n}$ Monotonicity shows that a command can be refined by separately refining its constituents If we definement now follow If we definement here is $\mathbb{C}^{C_n}, \mathbb{C}^{C_n}, C$		
Sets of commands are monotonic w.r.t. \supseteq • if $c \supseteq c'_1, c_1 \supseteq c'_1, \ldots, c_n \supseteq c'_n$ • then: $c_1; \cdots; c_n \supseteq c'_1; \cdots; c'_n$ EEGIN VAR $V_1; \cdots$ VAR $V_n; c \in ND \supseteq BEGIN VAR V_1; \cdots VAR V_n; c' \in NDIF S THEN c_1 \in LSE \ c_2 \supseteq IF S THEN c'_1 \in LSE \ c'_2WHILE S DD c \supseteq WHILE S DD c'Monotonicity shows that a command can be refined by separatelyrefining its constituentsLaws of refinement now followI = X \rightarrow C = [n, n] : [n, Q]I = X \rightarrow C = [n, n] : [n, Q]I = C = [n, n] : [n] \land I = [n] \land C_2 \in [n, Q] (Definition of [n, n] and [n, Q])I = C = [n] \land [n] \land$	$\mathbf{K} := \mathbf{A}$	R := X
Sets of commands are monotonic w.r.t. \supseteq • if $c \supseteq c'_1, c_1 \supseteq c'_1, \ldots, c_n \supseteq c'_n$ • then: $c_1; \cdots; c_n \supseteq c'_1; \cdots; c'_n$ EEGIN VAR $V_1; \cdots$ VAR $V_n; c \in ND \supseteq BEGIN VAR V_1; \cdots VAR V_n; c' \in NDIF S THEN c_1 \in LSE \ c_2 \supseteq IF S THEN c'_1 \in LSE \ c'_2WHILE S DD c \supseteq WHILE S DD c'Monotonicity shows that a command can be refined by separatelyrefining its constituentsLaws of refinement now followI = X \rightarrow C = [n, n] : [n, Q]I = X \rightarrow C = [n, n] : [n, Q]I = C = [n, n] : [n] \land I = [n] \land C_2 \in [n, Q] (Definition of [n, n] and [n, Q])I = C = [n] \land [n] \land$		
• if $c \supseteq c', c_1 \supseteq c'_1, \dots, c_n \supseteq c'_n$ • then: $c_1; \dots; c_n \supseteq c'_1; \dots; c'_n$ $BEGIN VAR V_1; \dots VAR V_n; c END \supseteq BEGIN VAR V_1; \dots VAR V_n; c' END$ $IF S THEN c_1 ELSE c_2 \supseteq IF S THEN c'_1 ELSE c'_2$ $WHILE S DD c \supseteq WHILE S DD c'$ • Derivation of Sequencing Law $C \in [P, R]; [R, Q]$ $\Leftrightarrow C \in \{C_1; C_2 \mid L \mid P \mid C_1 \mid R \mid A \cup L \mid R \mid C_2 \mid Q]\}$ (Definition of $c_1; c_2$) $\Leftrightarrow C \in \{C_1; C_2 \mid L \mid P \mid C_1 \mid R \mid A \cup H \mid R \mid C_2 \mid Q]\}$ (Definition of $[P, R]$ and $[R, Q]$) $\Rightarrow Laws of refinement now follow Laws of refinement now follow$	Technical interlude: Monotonicity Sets of commands are <i>monotonic</i> w.r.t. ⊇	
• then: $c_1; \dots; c_n$ $\supseteq c'_1; \dots; c'_n$ BEGIN VAR $V_1; \dots$ VAR $V_n; c \in \text{ND} \supseteq$ BEGIN VAR $V_1; \dots$ VAR $V_n; c' \in \text{ND}$ $IF S THEN c_1 ELSE c_2$ $\supseteq IF S THEN c'_1 ELSE c'_2$ $WHILE S DD c$ \supseteq WHILE S DD c' Monotonicity shows that a command can be refined by separately refining its constituents Laws of refinement now follow IT = S THEN now follow $IT = S THEN c_1 ELSE c_2$ $\supseteq IF S THEN c_1 ELSE c_2$ WHILE S DD c = Q VHILE S DD c' $IT = S THEN c_1 ELSE C_2$ $\square F = S THEN c'_1 ELSE c'_2$ VHILE S DD c' $IT = S THEN c_1 ELSE S DD c'$ $IT = S THEN c_1 ELSE $	• if $c \supseteq c'$, $c_1 \supseteq c'_1$,, $c_n \supseteq c'_n$	
$c_{1}; \dots; c_{n} \qquad \supseteq c_{1}; \dots; c_{n}$ $EGIN VAR V_{n}; c END \supseteq EGGIN VAR V_{n}; c' END$ $EGIN VAR V_{n}; c END \supseteq EGGIN VAR V_{n}; c' END$ $iF S THEN c_{1} ELSE c_{2} \qquad \supseteq IF S THEN c'_{1} ELSE c'_{2}$ $WHILE S D0 c \qquad \supseteq WHILE S D0 c'$ $C \in [P, R]; [R, Q]$ $\Leftrightarrow C \in \{C_{1}; C_{2} \mid L[P] C_{1}[R] \land L[R] C_{2}[Q]\} (Definition of c_{1}; c_{2})$ $\Leftrightarrow C \in \{C_{1}; C_{2} \mid L[P] C_{1}; C_{2}[Q]\} (Definition of [P, R] and [R, Q])$ $\Rightarrow C \in \{C_{1}; C_{2} \mid L[P] C_{1}; C_{2}[Q]\} (Definition of [P, R] and [R, Q])$ $\Rightarrow C \in \{C_{1}; C_{2} \mid L[P] C_{1}; C_{2}[Q]\} (Definition of [P, Q])$ $\Rightarrow C \in \{C_{1}; C_{2} \mid L[P] C_{1}; C_{2}[Q]\} (Definition of [P, Q])$ $\Rightarrow C \in \{C_{1}; C_{2} \mid L[P] C_{1}; C_{2}[Q]\} (Definition of [P, Q])$ $\Rightarrow C \in \{C_{1}; C_{2} \mid L[P] C_{1}; C_{2}[Q]\} (Definition of [P, Q])$ $\Rightarrow C \in \{C_{1}; C_{2} \mid L[P] C_{1}; C_{2}[Q]\} (Definition of [P, Q])$ $\Rightarrow C \in \{C_{1}; C_{2} \mid L[P] C_{1}; C_{2}[Q]\} (Definition of [P, Q])$ $\Rightarrow C \in \{C_{1}; C_{2} \mid L[P] C_{1}; C_{2}[Q]\} (Definition of [P, Q])$ $\Rightarrow C \in \{C_{1}; C_{2} \mid L[P] C_{1}; C_{2}[Q]\} (Definition of [P, Q])$ $\Rightarrow C \in \{C_{1}; C_{2} \mid L[P] C_{1}; C_{2}[Q]\} (Definition of [P, Q])$ $\Rightarrow C \in \{C_{1}; C_{2} \mid L[P] C_{1}; C_{2}[Q]\} (Definition of [P, Q])$ $\Rightarrow C \in \{C_{1}; C_{2} \mid L[P] C_{1}; C_{2}[Q]\} (Definition of [P, Q])$ $\Rightarrow C \in \{C_{1}; C_{2} \mid L[P] C_{1}; C_{2}[Q]\} (Definition of [P, Q])$ $\Rightarrow C \in \{C_{1}; C_{2} \mid L[P] C_{1}; C_{2}[Q]\} (Definition of [P, Q])$ $\Rightarrow C \in \{C_{1}; C_{2} \mid L[P] C_{1}; C_{2}[Q]\} (Definition of [P, Q])$ $\Rightarrow C \in \{C_{1}; C_{2} \mid L[P] C_{1}; C_{2}[Q]\} (Definition of [P, Q])$ $\Rightarrow C \in \{C_{1}; C_{2} \mid L[P] C_{1}; C_{2}[Q]\} (Definition of [P, Q])$ $\Rightarrow C \in \{C_{1}; C_{2} \mid L[P] C_{1}; C_{2}[Q]\} (Definition of [P, Q])$ $\Rightarrow C \in \{C_{1}; C_{2} \mid L[P] C_{1}; C_{2}[Q]\} (Definition of [P, Q])$ $\Rightarrow C \in \{C_{1}; C_{2} \mid L[P] C_{1}; C_{2}[Q]\} (Definition of [P, Q])$ $\Rightarrow C \in \{C_{1}; C_{2} \mid L[P] C_{1}; C_{2}[Q]\} (Definition of [P, Q])$ $\Rightarrow C \in \{C_{1}; C_{2} \mid L[P] C_{1}; C_{2}[Q]\} (Definition of [P, Q])$ $\Rightarrow C = C = C = C = C = C = C = C = C = C $		
$\begin{array}{c} \text{BEGIN VAR } V_1; \ \cdots \ \text{VAR } V_n; \ c \ \text{END} \ \supseteq \ \text{BEGIN VAR } V_1; \ \cdots \ \text{VAR } V_n; \ c' \ \text{END} \\ \text{IF } S \ \text{THEN } c_1 \ \text{ELSE } c_2 \ \supseteq \ \text{IF } S \ \text{THEN } c_1' \ \text{ELSE } c_2' \ \supseteq \ \text{IF } S \ \text{THEN } c_1' \ \text{ELSE } c_2' \ \supseteq \ \text{IF } S \ \text{THEN } c_1' \ \text{ELSE } c_2' \ \supseteq \ \text{WHILE } S \ \text{DO } c' \end{array} \qquad $		$C \in [P, R]$; $[R, Q]$
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$		$\Rightarrow C \in \{C_1; C_2 \mid C_1 \in [P, R] \land C_2 \in [R, Q]\} \qquad (Definition of c_1; c_2) \\ \Rightarrow C \in \{C_1; C_2 \mid F \mid P \mid C_1[R] \land F \mid R \mid C_2[Q]\} \qquad (Definition of [P, R] and [R, Q])$
WHILE S D0 c \supseteq WHILE S D0 c' $\Leftrightarrow C \in [P, Q]$ (Definition of $[P, Q]$)Monotonicity shows that a command can be refined by separately refining its constituents $[T, R=X \land Q=0]$ \supseteq (Sequencing)Laws of refinement now follow $[T, R=X]$; $[R=X]$, $R=X \land Q=0]$ \supseteq (Derived Assignment $\vdash T \Rightarrow X=X$) $R:=X; [R=X, R=X \land Q=0]$ \supseteq (Derived Assignment $\vdash R=X \Rightarrow R=X \land 0=0$)	$ \text{IF } S \text{ THEN } c_1 \text{ ELSE } c_2 \qquad \qquad \supseteq \text{ IF } S \text{ THEN } c_1' \text{ ELSE } c_2' \\$	$\Rightarrow C \in \{ C_1 ; C_2 \mid \vdash [P] C_1 ; C_2 [Q] \} $ (Sequencing Rule)
Monotonicity shows that a command can be refined by separately refining its constituents $[T, R=X \land Q=0]$ \supseteq (Sequencing)Laws of refinement now follow $[T, R=X]$; $[R=X]$, $R=X \land Q=0]$ \supseteq (Derived Assignment $\vdash T \Rightarrow X=X$) $R:=X; [R=X, R=X \land Q=0]$ \supseteq (Derived Assignment $\vdash R=X \Rightarrow R=X \land 0=0$)	WHILE S DO c \supseteq WHILE S DO c'	$\Leftrightarrow \ C \in [P, Q] $ (Definition of $[P, Q]$)
refining its constituents[1, $R=X/Q=0$]Laws of refinement now follow \bigcirc (Sequencing)[T, $R=X$]; $[R=X$, $R=X \land Q=0$] \bigcirc (Derived Assignment \vdash T \Rightarrow X=X) $R:=X$; $[R=X, R=X \land Q=0]$ \bigcirc (Derived Assignment \vdash R=X \Rightarrow R=X \land 0=0)	Monotonicity shows that a command can be refined by constately	
Laws of refinement now follow $[T, R=X]$; $[R=X, R=X \land Q=0]$ \supseteq (Derived Assignment $\vdash T \Rightarrow X=X$) $R:=X; [R=X, R=X \land Q=0]$ \supseteq (Derived Assignment $\vdash R=X \Rightarrow R=X \land 0=0$)		
$\begin{array}{c} \cong (\texttt{Derived Assignment} \vdash 1 \Rightarrow \texttt{K} \times \texttt{K}) \\ \texttt{R}:=\texttt{X}; [\texttt{R}=\texttt{X}, \texttt{R}=\texttt{X} \wedge \texttt{Q}=\texttt{O}] \\ \supseteq (\texttt{Derived Assignment} \vdash \texttt{R}=\texttt{X} \Rightarrow \texttt{R}=\texttt{X} \wedge \texttt{O}=\texttt{O}) \end{array}$	Laws of refinement now follow	[T, <mark>R=X</mark>] ; [<mark>R=X</mark> , R=X∧Q=0]
\supseteq (Derived Assignment \vdash R=X \land 0=0)	Laws of relationentenew follow	
nx, ųv		\supseteq (Derived Assignment \vdash R=X \Rightarrow R=X \land 0=0)
		nn, ųv

Creating different Programs

- By applying the laws in a different way, we obtain different programs
- Consider previous example: using a different assertion with the sequencing law creates a program with the assignments reversed

Inefficient Programs

- Refinement does not prevent you making silly coding decisions
- It does prevent you from producing incorrect executable code
- Example

```
[T, R=X∧Q=0]
⊇ (Sequencing)
[T, R=X∧Q=0]; [R=X∧Q=0, R=X∧Q=0]
⊇ (as previous example)
Q:=0; R:=X; [R=X∧Q=0, R=X∧Q=0]
⊇ (Skip)
Q:=0; R:=X; SKIP
```

Blind Alleys

- The refinement rules give the freedom to wander down blind alleys
- We may end up with an unrefinable step
 - since it will not be executable, this is safe
 - we will not get an incorrect executable program

• Example

```
[X=x∧Y=y, X=y∧Y=x]

⊇ (Sequencing)

[X=x∧Y=y, X=x∧Y=x]; [X=x∧Y=x, X=y∧Y=x]

⊇ (Derived Assignment ⊢ X=x∧Y=y⇒X=x∧X=x)

Y:=X; [X=x∧Y=x, X=y∧Y=x]

⊇ (Sequencing)

Y:=X;

[X=x∧Y=x, Y=y∧Y=x];

[X=x∧Y=x, Y=y∧Y=x];

[X=x∧Y=x, Y=y∧Y=x];

X:=Y
```

Blocks

The Block Law

 $[P, \ Q] \supseteq \texttt{BEGIN VAR} \ V_1; \ \dots \ ; \ \texttt{VAR} \ V_n; \ [P, \ Q] \ \texttt{END}$ where V_1, \dots, V_n do not occur in P or Q

- Derivation: exercise (see notes)
- Example

 $\begin{array}{ll} [X=x\wedge Y=y, & X=y\wedge Y=x]\\ \supseteq & (Block)\\ BEGIN VAR R; & [X=x\wedge Y=y, & X=y\wedge Y=x] & END\\ \supseteq & (Sequencing and Derived Assignment)\\ BEGIN VAR R; & R:=X; & X:=Y; & Y:=R & END \end{array}$

Conditional

The Conditional Law

 $[P, Q] \supseteq \text{ IF } S \text{ THEN } [P \land S, Q] \text{ ELSE } [P \land \neg S, Q]$

- The Conditional Law can be used to refine *any* specification and *any* test can be introduced
- You may not make any progress by applying the law however
 - you may need the same program on each branch!

Derivation of the Conditional Law

 $C \in \operatorname{IF}\ S \text{ THEN } [P \land S, \ Q] \text{ ELSE } [P \land \neg S, \ Q]$

- $\begin{array}{l} \Leftrightarrow \ C \in \{ \mathrm{IF} \ S \ \mathrm{THEN} \ C_1 \ \mathrm{ELSE} \ C_2 \ | \\ C_1 \in [P \land S, \ Q] \ \& \ C_2 \in [P \land \neg S, \ Q] \} & (\mathrm{Definition} \ \mathrm{of} \ \mathrm{IF} \ S \ \mathrm{THEN} \ \{\cdots\} \ \mathrm{ELSE} \ \{\cdots\}) \\ \Leftrightarrow \ C \in \{ \mathrm{IF} \ S \ \mathrm{THEN} \ C_1 \ \mathrm{THEN} \ C_2 \ | \\ \vdash \ [P \land S] \ C_1 \ [Q] \ \& \ \vdash \ [P \land \neg S] \ C_2 \ [Q] \} & (\mathrm{Definition} \ \mathrm{of} \ \mathrm{IF} \ S \ \mathrm{THEN} \ \{\cdots\} \ \mathrm{ELSE} \ \{\cdots\}) \\ \Rightarrow \ C \in \{ \mathrm{IF} \ S \ \mathrm{THEN} \ C_1 \ \mathrm{ELSE} \ C_2 \ [Q] \} & (\mathrm{Definition} \ \mathrm{of} \ [P \land S, \ Q] \ \& \ [P \land \neg S, \ Q]) \\ \Rightarrow \ C \in \{ \mathrm{IF} \ S \ \mathrm{THEN} \ C_1 \ \mathrm{ELSE} \ C_2 \ | \\ \vdash \ [P] \ \mathrm{IF} \ S \ \mathrm{THEN} \ C_1 \ \mathrm{ELSE} \ C_2 \ [Q] \} & (\mathrm{Two-armed Conditional Rule}) \\ \end{array}$
- $\Rightarrow \ \vdash \ [P] \ C \ [Q]$
- $\Leftrightarrow \ C \in [P, \ Q]$

(Definition of [P, Q])

Example

While

The While Law

$$\begin{split} [R, \quad R \wedge \neg S] \supseteq \text{ WHILE } S \text{ DO } [R \wedge S \wedge (E=n), \quad R \wedge (E < n)] \\ \mathbf{provided} \quad \vdash \quad R \wedge S \Rightarrow \quad E \geq 0 \end{split}$$

and where E is an integer-valued expression and n is an identifier not occurring in P, S, E or C.

• Example

$$\begin{split} & [\texttt{X=R+Y} \times \mathbb{Q} \ \land \ \texttt{Y>0}, \quad \texttt{X=R+Y} \times \mathbb{Q} \ \land \ \texttt{Y>0} \ \land \ \neg \ \texttt{Y\leq R}] \\ & \supseteq \ (\texttt{While} \ \vdash \ \texttt{X=R+Y} \times \mathbb{Q} \ \land \ \texttt{Y>0} \ \land \ \texttt{Y\leq R} \ \Rightarrow \ \texttt{R\geq 0}) \\ & \texttt{WHILE} \ \texttt{Y\leq R} \ \texttt{DO} \\ & [\texttt{X=R+Y} \times \mathbb{Q} \ \land \ \texttt{Y>0} \ \land \ \texttt{Y\leq R} \ \land \ \texttt{R=n}, \\ & \texttt{X=R+Y} \times \mathbb{Q} \ \land \ \texttt{Y>0} \ \land \ \texttt{R=n}] \end{split}$$

Derivation of the While Law		Example (i)
$ \begin{array}{l} \vdash \ \left[P \land S \land ({E} = n)\right] C'' \left[P \land (E < n)\right] \} \\ C \in \{ \texttt{WHILE } S \texttt{ D0 } C' \mid \\ \vdash \ \left[P\right] \texttt{WHILE } S \texttt{ D0 } C' \left[P \land \neg S\right] \} \\ \vdash \ \left[P\right] C \ \left[P \land \neg S\right] \end{array} $	(Definition of	$ \begin{bmatrix} Y > 0, & X = R + Y \times Q \land R \leq Y \end{bmatrix} $ $ \supseteq (Block) BEGIN [Y>0, & X = R + Y \times Q \land R \leq Y] END \supseteq (Sequencing) BEGIN [Y>0, & X = X \land Y>0]; [R = X \land Y>0, & X = R + Y \times Q \land R \leq Y] END \supseteq (Derived Assignment \vdash Y>0 \Rightarrow X = X \land Y>0) BEGIN R := X; [R = X \land Y>0, & X = R + Y \times Q \land R \leq Y] END END \begin{bmatrix} R = X \land Y>0, & X = R + Y \times Q \land R \leq Y] \\ END \end{bmatrix} $
Example (ii)		Example (iii) $\supseteq \begin{pmatrix} Precondition Weakening \\ \vdash R=X \land Y>0 \land Q=0 \Rightarrow X=R+Y\timesQ \land Y>0 \end{pmatrix}$ BEGIN R:=X; Q:=0;

$ \begin{split} \hline \mathbf{Example (iv)} \\ & \supseteq (Block) \\ & \text{BEGIN} \\ & \text{R}:=X; \ Q:=0; \\ & \text{WHILE } Y \leq R \text{ DO} \\ & \text{BEGIN} \\ & [X=R+Y \times Q \land Y>0 \land Y \leq R \land R=n, \\ & X=R+Y \times Q \land Y>0 \land R < n] \\ & \text{END} \\ & \text{END} \\ & \supseteq (\text{Sequence}) \\ & \text{BEGIN} \\ & \text{R}:=X; \ Q:=0; \\ & \text{WHILE } Y \leq R \text{ DO} \\ & \text{BEGIN} \\ & \text{R}:=X; \ Q:=0; \\ & \text{WHILE } Y \leq R \text{ DO} \\ & \text{BEGIN} \\ & [X=R+Y \times Q \land Y>0 \land Y \leq R \land R=n, \\ & X=(R-Y) + Y \times Q \land Y>0 \land (R-Y) < n, \\ & X=R+Y \times Q \land Y>0 \land R < n] \\ & \text{END} \\ & \text{END} \\ & \text{END} \\ & \text{END} \end{split} $	$ \begin{array}{l} \hline \textbf{Example (v)} \\ & \bigcirc (Assignment) \\ & & \text{BEGIN} \\ & & \text{R}:=X; \ Q:=0; \\ & \text{WHILE } Y \leq R \text{ DO} \\ & & \text{BEGIN} \\ & & \boxed{X=R+Y \times Q \land Y > 0 \land (Y=R \land R=n)} \\ & & \boxed{X=(R-Y)+Y \times Q \land Y > 0 \land (R-Y) < n]}; \\ & \text{R}:=R-Y \\ & \text{END} \\ & \text{END} \\ & \text{END} \\ & \text{END} \\ & & \bigcirc \begin{pmatrix} \text{Derived Assignment} \\ \bigcirc \begin{pmatrix} Derived Assignment \\ & \vdash X=R+Y \times Q \land Y > 0 \land (Y\leq R \land R=n \Rightarrow \\ & X=(R-Y)+Y \times (Q+1) \land Y > 0 \land (R-Y) < n \end{pmatrix} \\ & & \text{BEGIN} \\ & & \text{R}:=X; \ Q:=0; \\ & & \text{WHILE } Y \leq R \text{ DO} \\ & & \text{BEGIN} \\ & & & \textbf{Q}:= \ Q+1; \\ & & \text{R}:=R-Y \\ & & \text{END} \end{array} $
	END
More Notation $[P_1, P_2, P_3, \cdots, P_{n-1}, P_n]$ is used to abbreviate: $[P_1, P_2]$; $[P_2, P_3]$; \cdots ; $[P_{n-1}, P_n]$ • Brackets around specifications {C} omitted • If C is a set of commands, then $R := X$; C abbreviates $\{R := X\}$; C	Exercise: check the refinement on this slide • Let \mathcal{I} stand for $X = R + (Y \times Q)$, then: $\begin{bmatrix} Y > 0, \ I \land R \le Y \end{bmatrix}$ $\geq (Sequencing)$ $\begin{bmatrix} Y > 0, \ I \land R \le Y \end{bmatrix}$ $\geq (Sequencing)$ $R = X \land Y > 0, \ I \land R \le Y \end{bmatrix}$ $\geq (Sequencing)$ $R = X \land Y > 0, \ I \land R \le Y \end{bmatrix}$ $\geq (Sequencing)$ $R = X \land Y > 0, \ I \land R \le Y \end{bmatrix}$ $\geq (Sequencing)$ $R = X \land Y > 0, \ R = X \land Y > 0, \ Q = 0, \ I \land R \le Y \end{bmatrix}$ $\geq (Sequencing)$ $R = X \land Y > 0, \ R = X \land Y > 0, \ Q = 0, \ I \land R \le Y \end{bmatrix}$ $\geq (Sequencing)$ $R = X \land Y > 0, \ R = X \land Y > 0, \ Q = 0, \ I \land R \le Y \end{bmatrix}$ $\geq (Potocondition Westering)$ $R = X \land Y = 0, \ [R = X \land Y > 0, \ Q = 0, \ I \land R \le Y \end{bmatrix}$ $\geq (Potocondition Westering)$ $R = X \land Y = 0, \ [I \land Y > 0, \ I \land R \le Y \end{bmatrix}$ $R = X \land Y = 0, \ [I \land Y > 0, \ I \land R \le Y]$ $\geq (While)$ $R = X \land Y = 0; \ [WILE Y \in RB [I \land Y > 0 \land Y \le R \land R = n, \ I \land Y > 0 \land Q = 0; \ I \land R < Y = 0; \ [WILE Y \in RB [I \land Y > 0 \land Y \le R \land R = n, \ I \land Y > 0 \land Q < 0, \ [I \land Y > 0 \land X < Y = 0]$ $WILE Y \in RB [I \land Y > 0, \ Y \le R \land R = n, \ I \land Y > 0 \land X < X > 0 \ (R - Y) < n, \ I \land Y > 0 \land (R - Y) < n, \ I \land Y > 0 \land X < X < 0]$ $WILE Y = RB [I \land Y > 0 \land Y \le R \land R = n, \ I \land Y > 0 \land X < X < 0]$ $WILE Y = RB [I \land Y > 0 \land Y < R \land R = n, \ I \land Y > 0 \land X < X < 0]$ $WILE Y = RB [I \land Y > 0 \land Y < R \land R = n, \ I \land Y > 0 \land X < X < 0]$ $WILE Y = RB [I \land Y > 0 \land Y < R \land R = n, \ I \land Y > 0 \land X < X < 0]$ $WILE Y = RB [I \land Y > 0 \land Y < Y < R \land R = n, \ I \land Y < Y < 0 \land R < R < 0]$ $WILE Y = RB [I \land Y > 0 \land Y < Y < R \land R = n, \ I \land Y < Y < Y < 0 \land R < R < 0]$ $WILE Y = RB [I \land Y > 0 \land Y < Y < R \land R = n, \ I \land Y < Y < Y < 0 \land R < R < 0]$ $WILE Y = RB [I \land Y < Y < Y < Y < Y < Y < Y < Y < Y < Y$

Derived Laws

- Above development could be shortened by deriving appropriate laws
- $\bullet\,$ For example, a derived <code>WHILE</code> law could be derived
- Exercise: Develop a factorial program from the specification:

$[X=n, \quad Y=n!]$

• Exercise: devise refinement laws for arrays, one-armed conditionals, and FOR-commands

Data Refinement

- So far we have given laws to refine commands
- This is termed Operation Refinement
- It is also useful to be able to refine the representation of data
 - replacing an abstract data representation by a more concrete one
 - e.g. replacing numbers by binary representations
- This is termed Data Refinement
- Data Refinement Laws allow us to make refinements of this form
- The details are beyond the scope of this course
 - they can be found in Morgan's book

Summary

- Refinement 'laws' based on the Hoare logic can be used to develop programs formally
- A program is gradually converted from an unexecutable specification to executable code
- By applying different laws, different programs are obtained
 - may reach unrefinable specifications (blind alleys)
 - but will never get incorrect code
- A program developed in this way will meet its formal specification
 - one approach to 'Correct by Construction' (CbC) software engineering



Higher-Order Logic

Introduction

- Specifications in first order logic can be clumsy
- Higher-Order Logic is widely used since
 - it is more expressive than first-order logic
 - specifications are often more natural
 - they are less likely to contain mistakes and are easier to understand
- The main differences between first and higher-order logic are
 - no distinction is made between terms and statements
 - functions and predicates are treated as first class objects
- Higher-order logic is a foundational system like set theory
 - can develop mathematics inside higher-order logic

Overview

- Basic notation
- Types
- Special syntax to make notation user-friendly
- Definitions

Higher-Order Logic

• Familiar notation:

Term	Meaning
P(x)	x has property P
$\neg t$	not t
$t_1 \wedge t_2$	t_1 and t_2
$t_1 \lor t_2$	t_1 or t_2
$t_1 \Rightarrow t_2$	$t_1 \text{ implies } t_2$
$\forall x. t[x]$	for all x it is the case that $t[x]$
$\exists x. t[x]$	for some x it is the case that $t[x]$

• Higher-order logic is also called:

- higher-order predicate calculus
- simple type theory

Formulae Become Terms

• In higher-order logic statements (formulae) are boolean terms

 \bullet i.e. terms whose value is one of the two truth values (or booleans) T or F

- There are only four kinds of primitive terms in higher-order logic
 - Variables x, y, P etc
 - Constants stand for fixed values (e.g. numerals 0, 1 etc)
 - Function applications have the general form $t_1 t_2$ where t_1 and t_2 are terms, an example is $P \ 0$
 - Lambda-terms denote functions and have the form $\lambda x. t$ (where x is a variable and t a term)
- Notation on previous slide is 'syntactic sugar' (explained later)

Statements

- Statements are just terms in higher-order logic
 - $\neg t$ is the application of constant \neg to term t
 - + $t_1 \Rightarrow t_2$ is the infixed application of constant \Rightarrow to terms t_1 and t_2
- Only a single variable binding mechanism: λ -abstraction
 - quantifiers \forall and \exists are regarded as constants
 - quantification syntax $\forall x. t$ and $\exists x. t$ abbreviates $\forall (\lambda x. t)$ and $\exists (\lambda x. t)$

• Example: the term

 $\forall n. \ P(n) \Rightarrow P(n+1)$

is written instead of

 $\forall (\lambda n. \Rightarrow (P(n))(P(+\ n \ 1)))$

Higher-Order Variables

• Higher-order logic generalises first order logic by allowing higher-order variables

• i.e. variables ranging over functions and predicates

- The induction axiom for natural numbers can be written as: $\forall P. P(0) \land (\forall n. P(n) \Rightarrow P(n+1)) \Rightarrow \forall n. P(n)$
- The legitimacy of simple recursive definitions can be expressed by:
 ∀n₀. ∀f. ∃s. (s(0) = n₀) ∧ (∀n. s(n + 1) = f(s(n)))
- Sentences like these are not allowed in first order logic
 - in the first example above ${\cal P}$ ranges over predicates
 - \bullet in the second example f and s range over functions

Floyd-Hoare Logic

- Correctness specifications can be expressed in higher-order logic
- A predicate Spec is defined by

 $\operatorname{Spec}(p,c,q) \ = \ \forall s_1 \ s_2. \ p \ s_1 \ \land \ c(s_1,s_2) \Rightarrow q \ s_2$

- Spec is a predicate on triples (p, c, q) where p and q are unary predicates and c is a binary predicate
- Spec can't be defined in first order logic

Constants

Examples of constants are:

- the equals sign (=), the equivalence symbol (\equiv),
- \bullet the negation symbol (¬),
- the conjunction symbol (\land), the disjunction symbol (\lor), the implication symbol (\Rightarrow),
- \bullet the universal quantifier ($\forall),$ the existential quantifier ($\exists),$
- \bullet the pairing symbol (comma: ,),
- \bullet the numerals 0, 1, 2 etc.,
- \bullet the arithmetic functions +, –, \times and /, and
- \bullet the arithmetic relations <, >, < and $\geq.$

Function applications

• Terms of the form $t_1 t_2$ are called applications or *combinations*

• can write f(x) instead of f(x)

- The subterm t_1 is called the **operator** (or **rator**)
- The term t_2 is called the operand (or rand or argument)
- The result of such a function application can itself be a function and thus terms like $(t_1(t_2))(t_3)$ are allowed
- Functions that take functions as arguments or return functions as results are called higher-order
- Function applications can be written as f x instead of f(x)
 - $t_1 t_2 t_3 \cdots t_n$ abbreviates $(\cdots ((t_1 t_2) t_3) \cdots t_n)$
 - i.e. application associates to the left

Lambda-terms

- An abstraction is a term of the form $\lambda x. t$ (where t is a term)
- $\lambda x. t$ denotes the function f defined by:

 $f(x) \ = \ t$

- Example: λn . factorial(square(n)) denotes function f where: f(n) = factorial(square(n))
- The variable x and term t are called respectively the bound variable and body of the λ -expression λx . t

Types

• Consider the predicate P defined by:

 $\mathbf{P} \ x \ = \ \neg(x \ x)$

• From this definition it follows that:

 $P P = \neg (P P)$

- This is a version of Russell's paradox
- Russell invented types to prevent such inconsistencies

The Structure of Types

- Types denote sets of values: they are **atomic** or **compound**
- Two kinds of atomic types:
 - type constants, e.g. *num* or *bool*
 - type variables: α , β , γ etc
- Compound types are built using type operators
 - $\bullet \rightarrow {\rm and} \times {\rm are}$ infixed binary type operators
- If σ , σ_1 and σ_2 are types then so are $\sigma_1 \rightarrow \sigma_2$ and $\sigma_1 \times \sigma_2$
 - $\sigma_1{\rightarrow}\sigma_2$ denotes the set of functions with domain σ_1 and range σ_2
 - $f: \sigma_1 \rightarrow \sigma_2$ means f a function from σ_1 to σ_2
 - $\sigma_1 \times \sigma_2$ denotes the Cartesian product type
 - $p: \sigma_1 \times \sigma_2$ means p a pair (x, y) where $x: \sigma_1$ and $y: \sigma_2$

Well-Typed Terms

- Terms must be well-typed
- Typing rules are essentially those of ML
- Must be possible to assign a type to each subterm so 1 and 2 hold:
 - 1. For every subterm $t_1 t_2$ there are types σ and σ' such that:
 - (a) t_1 is assigned $\sigma' \rightarrow \sigma$
 - (b) t_2 is assigned σ'
 - (c) $t_1 t_2$ is assigned the type σ .
 - 2. Every subterm of the form λx . t is assigned a type $\sigma_1 \rightarrow \sigma_2$ where:
 - (a) \underline{x} is assigned $\underline{\sigma}_1$
 - (b) t is assigned $\sigma_2.$

Notation

- Writing $t:\sigma$ indicates that a term t has type σ
- $\sigma_1 \rightarrow \sigma_2 \rightarrow \sigma_3 \rightarrow \cdots \ \sigma_n \rightarrow \sigma$ abbreviates $\sigma_1 \rightarrow (\sigma_2 \rightarrow (\sigma_3 \rightarrow \cdots \ (\sigma_n \rightarrow \sigma) \ \cdots \))$ • i.e. \rightarrow associates to the right
- $\lambda x_1 x_2 \cdots x_n$. t abbreviates λx_1 . λx_2 . $\cdots \lambda x_n$. t
- The scope of the "." after a λ extends as far to the right as possible
 for example, λb. b = λx. T means λb. (b = (λx. T)) not (λb. b) = (λx. T)

Types of Constants

- All constants are assumed to have a fixed type
- If this type is polymorphic (i.e. contains type variables) then for the purposes of type checking the constant behaves as though it is assigned every instance of the type
- For example, if twice had type $(\alpha \rightarrow \alpha) \rightarrow (\alpha \rightarrow \alpha)$, then the terms twice(sqrt) and twice(not) would be well-typed

Special Syntactic Forms

- Certain applications are conventionally written in special ways, for example:
 - + $t_1 t_2$ is written $t_1 + t_2$
 - •, t_1 t_2 is written (t_1, t_2)
 - $\forall (\lambda x. t)$ is written $\forall x. t$
- + and , are examples of infixes
- \forall is an example of a binder
- Some other *ad hoc* syntactic forms are also used (e.g. conditionals)

Infixes

- If f is an infixed constant then applications are written as $t_1 \neq t_2$ rather than as f $t_1 t_2$
- Standard examples of infixes are the arithmetic functions +, \times etc.
- Whether a constant is an infix or not has no logical significance, it is merely syntactic
- Examples of infixes are the following constants:
 - \land : bool \rightarrow bool \rightarrow bool (Conjunction)
 - \lor : bool \rightarrow bool \rightarrow bool (Disjunction)
 - $\Rightarrow: bool \rightarrow bool \rightarrow bool$ (Implication)
 - $\equiv: bool \rightarrow bool \rightarrow bool$ (Equivalence)
- Equality is also an infixed constant; it is polymorphic: =: $\alpha \rightarrow \alpha \rightarrow bool$

Equivalence (\equiv) is equality (=) restricted to booleans

Binders

- It is sometimes more readable to write f(x, t) instead of $f(\lambda x, t)$
- For example, the quantifiers ∀ and ∃ are polymorphic constants:
 ∀: (α→bool)→bool
 ∃: (α→bool)→bool
- The idea is that if $P: \sigma \rightarrow bool$, then $\forall (P)$ is true if P(x) is true for all x and $\exists (P)$ is true if P(x) is true for some x
- Instead of writing $\forall (\lambda x. t)$ and $\exists (\lambda x. t)$ it is nice to be able to use the more conventional forms $\forall x. t$ and $\exists x. t$
- Example: recall the statement of mathematical induction: $\forall P. \ P(0) \land (\forall n. \ P(n) \Rightarrow P(n+1)) \Rightarrow \forall n. \ P(n)$

This is a term of type **bool**

• Without infix and binder notation terms are less readable $\forall (\lambda P. \Rightarrow (\land (P \ 0)(\forall (\lambda n. \Rightarrow (P \ n)(P(+ \ n \ 1)))))(\forall (\lambda n. \ Pn)))$

Pairs and Tuples

- A function of n arguments can be represented as a higher-order function of 1 argument that returns a function of n-1 arguments
- Thus λm , λn , $m^2 + n^2$ represents the 2 argument function that sums the squares of its arguments
- Functions of this form are called curried
- An alternative way of representing multiple argument functions is as single argument functions taking tuples as arguments
- If $t_1:\sigma_1$ and $t_2:\sigma_2$ then (t_1,t_2) has type $\sigma_1 \times \sigma_2$
 - (t_1, t_2) denotes a pair

Paired Functions

- Another representation of the sum-squares function would be as a constant, sumsq say, of type $(num \times num) \rightarrow num$ defined by: $sumsq(m,n) = m^2 + n^2$
- A term of the form (t_1, t_2) is equivalent to the term , $t_1 t_2$ where "," is a polymorphic infixed constant of type $\alpha \rightarrow \beta \rightarrow (\alpha \times \beta)$
- Instead of having tuples as primitive, they will be treated as iterated pairs. Thus the term:

$$(t_1,t_2,\ldots,t_{n-1},t_n)$$

is an abbreviation for:
$$(t_1,(t_2,\ \dots\ ,(t_{n-1},t_n)\ \dots\))$$

i.e. "," associates to the right

• To match this, the infixed type operator \times also associates to the right so that if $t_1:\sigma_1, \ldots, t_n:\sigma_n$ then:

 $(t_1, \ldots, t_n): \sigma_1 \times \cdots \times \sigma_n$

Definitions

- Definitions have the form ⊢ c = t where c is a new constant and t is a closed term that doesn't contain c
- Such a definition is a particular kind of axiom that introduces the constant **c** as an abbreviation for the term t
- The requirement that **c** may not occur in t prevents definitions from being recursive, this is to rule out inconsistent 'definitions' like

 $\vdash \ \mathsf{c} = \mathsf{c} + 1$

- Example: a constant Cond can be defined (see the notes) so that Cond t t_1 t_2 means "if t then t_1 else t_2 "
 - the special syntax $(t \rightarrow t_1 \mid t_2)$ is used for such terms

Function Definitions

• A function definition:

can be written as:

 $\vdash \mathbf{f} = \lambda x_1 \cdots x_n \cdot t$ $\vdash \mathbf{f} x_1 \cdots x_n = t$

- Definitions have the property that adding a new definition to the set of existing ones cannot introduce any inconsistencies
- As was shown by Russell and Whitehead, with suitable definitions, all of classical mathematics can be constructed from logic
- See notes for how recursive definitions are handled

Type Definitions

- New types can be defined
- For example, can define a new type three with values ONE, TWO and $\overset{\mbox{\scriptsize THREE}}{\mbox{\scriptsize HREE}}$
- Can also add recursive type definitions
- For example, could define a new type α list with constructors NIL and CONS
- Such definitions correspond closely to datatype definitions in ML
- Recursion theorems that allow ML style recursive definitions over such recursive types can then be proved
- Details of type definitions not given here

Summary

- Primitive notions
 - variables, constants, function applications, $\lambda\text{-abstractions}$
- Types
 - statements (formulae) are just boolean terms
- Special syntax to make notation user-friendly
 infixes, binders, conditional notation
- Definitions
 - introduces new constants consistently

Semantic embedding in a general logic

- Program verification involves the proof of mathematical statements
- A program verifier will need a theorem prover
- One approach: verification condition generation
- Another approach: embed program logic in logic of a general prover
 - programming logic rules can then be derived
 - the full power of the theorem prover will be available for proofs
 - the implementation of the rules can be guaranteed to be sound
 - easy to soundly extend the logic
- Embedding Hoare Logic and other programming logics outlined
- First a trivial pedagogical example to illustrate concepts

Deep Semantic Embedding – a preliminary example

• Consider the propositional language:

wff ::= True | N wff | C wff wff | D wff wff

- Can represent wffs inside higher order logic
 - \bullet by values of some type, $w\!f\!f$ say
 - we haven't described type definitions
- Can define a semantic function, *M* say, by recursion:

 $\begin{array}{lll} \mathcal{M}(\texttt{True}) &= T\\ \mathcal{M}(\texttt{N} \ w) &= \neg \mathcal{M}(w)\\ \mathcal{M}(\texttt{C} \ w_1 \ w_2) &= \mathcal{M}(w_1) \wedge \mathcal{M}(w_2)\\ \mathcal{M}(\texttt{D} \ w_1 \ w_2) &= \mathcal{M}(w_1) \vee \mathcal{M}(w_2) \end{array}$

- $\mathcal M$ is a constant of higher order logic of type wff \rightarrow bool
- defined via a recursion theorem details omitted

Shallow Embedding

- wff ::= True | N wff | C wff wff | D wff wff
- Translate wffs in higher order logic terms
- Suppose [w] is the translation of w into higher order logic
- Translation mapping w → [w] not defined inside higher order logic
 corresponds to informal 'parsing and pretty-printing' conventions
- Let → mean "is translated to"
- A shallow embedding: is a set of translation rules:

[True]	\sim	" <i>T</i> "
$[N \ w]$	\rightsquigarrow	"¬" \frown [w]
$\llbracket \texttt{C} \ w_1 \ w_2 \rrbracket$	\rightsquigarrow	$\llbracket w_1 bracket \frown \llbracket w_2 bracket$
$\llbracket D \ w_1 \ w_2 \rrbracket$	$\sim \rightarrow$	$\llbracket w_1 \rrbracket \frown \llbracket \lor \lor \amalg \frown \llbracket w_2 \rrbracket$

Deep vs Shallow Embedding

- Deep and shallow embedding are two ends of a spectrum
 - some aspects of the semantics formalized inside higher order logic
 - others specified via informal notational conventions
- Deep embedding: theorems about embedded language provable
 - for example: $\forall w_1 \ w_2 \in wff. \ \mathcal{M}(\mathbb{C}w_1w_2) = \mathcal{M}(\mathbb{NDN}w_1\mathbb{N}w_2)$
 - formalizes more of the embedding, but requires expressive host logic
- Shallow embedding: only theorems in embedded language provable
 quantification over wffs is not expressible
 - less in the logic, and hence the embedding is less demanding
 - so is often easier to support complex notations
- A shallow embeddings of Hoare specifications will be described
 outline how the axioms and rules of Floyd-Hoare logic can be derived
- Homeier's Sunrise system is a deep embedding of Hoare logic

Embedding command semantics into higher order logic

- Commands translate to predicates on pairs of states
- $C \rightsquigarrow c$ where the meaning of C is given by c

 $c(s_1, s_2) = \begin{cases} \mathsf{T} \ \text{if executing } C \text{ in state } s_1 \text{ results in state } s_2 \\ \\ \mathsf{F} \ \text{otherwise} \end{cases}$

• Example: if c is the predicate denoted by WHILE T DO SKIP then:

 $\forall s_1 \ s_2. \ \mathsf{c}(s_1,s_2) = \mathsf{F}$

States

- Program variables will be represented by strings
- The type state of states that we use is defined by: $state = string \rightarrow num$
- State s has 'X', 'Y', 'Z' bound to 1, 2, 3; all other strings bound to 0
 s = λx. if x = 'X' then 1 else if x = 'Y' then 2 else if x = 'Z' then 3 else 0
- A more complex type of states is needed for arrays

Translations represent meaning (denotational semantics)

• E, B, C translate to e, b and c, respectively, where: $e : state \rightarrow num$ $b : state \rightarrow bool$

c : state × state → bool

represent meanings of expressions and commands

- The embedding translation of X + 1 is $\lambda s. s'X' + 1$
- The embedding translation of (X+Y)>10 is $\lambda s.~(s^{*}X^{*}+s^{*}Y^{*})>10$
- [E] and [B] denote the translations (meanings) of E and B
- For example:

$$\begin{split} & \llbracket X+1 \rrbracket & = \ \lambda s. \ s^{i}X^{i}+1 \\ & \llbracket (X+Y)>10 \rrbracket & = \ \lambda s. \ (s^{i}X^{i}+s^{i}Y^{i})>10 \end{split}$$

Semantics of Commands

- A command C translates to a term [C] of type $state \times state \rightarrow bool$
- Define constants as 'constructors' for each kind of command
- For example:

[SKIP] = Skip

where the constant Skip is defined by:

 $Skip(s_1, s_2) = (s_1 = s_2)$

Semantics of other programming constructs

- Define constants Assign, Seq, If, While
 - just formalise semantics of language (denotational or operational) • details of a denotational semantics in the notes
- $\llbracket V := E \rrbracket = \operatorname{Assign}(`V`, \llbracket E \rrbracket)$
 - $\texttt{Assign}: (\textit{string} \times (\textit{state} \rightarrow \textit{num})) \rightarrow (\textit{state} \times \textit{state}) \rightarrow \textit{bool}$
- $[C_1; C_2] = Seq([C_1], [C_2])$
 - Seq : ((state × state → bool) × (state × state → bool)) → (state × state) → bool
- [IF B THEN C_1 ELSE C_2] = If([B], [C_1], [C_2])
 - $\bullet \hspace{0.1 cm} \texttt{If}: ((\textit{state} \rightarrow \textit{bool}) \times (\textit{state} \times \textit{state} \rightarrow \textit{bool}) \times (\textit{state} \times \textit{state} \rightarrow \textit{bool})) \rightarrow (\textit{state} \times \textit{state}) \rightarrow \textit{bool}$
- [WHILE B DO C] = While([B], [C])
 - While : ((state \rightarrow bool) \times (state \times state \rightarrow bool)) \rightarrow (state \times state) \rightarrow bool

Example

```
The command
                R := X;
               Q := 0; WHILE Y \leq R DO (R := R-Y; \; Q := Q+1)
```

translates to (means)

 $\underbrace{(\texttt{Assign}(`R`, \llbracket X \rrbracket))}_{(\texttt{Assign}(`R`, \llbracket X \rrbracket)),$ Seq (Assign('Q',[0]), While

- $\begin{array}{l} ([Y \leq R]], \\ \texttt{Seq}(\texttt{Assign}(`R`, [R-Y]], \texttt{Assign}(`Q`, [Q+1])))) \end{array}$
- Expanding $\left[\cdots \right]$ notation results in:

 $\begin{array}{c} \mathbf{Seq} \\ (\underline{\mathbf{Assign}}(^{\circ}R^{\circ},\lambda s.\ s^{\circ}X^{\circ}), \\ \widehat{\mathbf{C}} := \end{array}$ $\begin{array}{l} & \texttt{Assign}(\cdot x, \ldots \\ & \texttt{Seq} \\ (\texttt{Assign}(Q, \lambda s, 0), \\ & \texttt{While} \\ & ((\lambda s, sY) \leq s'R'), \\ & \texttt{Seq}(\texttt{Assign}(^{\circ}R', \lambda s, s'R' - s'Y'), \\ & \texttt{Assign}(^{\circ}Q, \lambda s, s'Q' + 1))))) \end{array}$

Semantics of Partial Correctness

- A partial correctness specification $\{P\} \subset \{Q\}$ translates to: $\forall s_1 \ s_2. \ \llbracket P \rrbracket \ s_1 \ \land \ \llbracket C \rrbracket (s_1, s_2) \Rightarrow \llbracket Q \rrbracket \ s_2$
- To abbreviate this formula, define a constant Spec by:

$$\operatorname{Spec}(p,c,q) = \forall s_1 \ s_2. \ p \ s_1 \ \land \ c(s_1,s_2) \Rightarrow q \ s_2$$

- The pre and postconditions P and Q are not just the logical formulae themselves, but are the translations [P] and [Q]
- Thus:

 ${X = 1} X := X + 1 {X = 2}$

translates to

 ${\tt Spec}([\![X=1]\!],\;{\tt Assign}(`X`,[\![X+1]\!]),\;[\![X=2]\!])$

which is

 $\mathtt{Spec}((\lambda s. s'X' = 1), \mathtt{Assign}(X', (\lambda s. s'X' + 1), (\lambda s. s'X' = 2))$

- Floyd-Hoare Logic
- Floyd-Hoare logic can be embedded in higher order logic by regarding the concrete syntax of partial correctness specifications as an abbreviation for the corresponding semantic statements
- For example:

$${X = x} X := X + 1 {X = x + 1}$$

- Spec([X = x]], Assign(X, [X + 1]]), [X = x + 1])
- The translation between the syntactic 'surface structure' and the semantic 'deep structure' is straightforward; it can easily be mechanized with a simple parser and pretty-printer
- If partial correctness specifications are interpreted this way then the axioms and rules of Hoare logic can be derived in higher order logic

Example: SKIP-axiom

• To derive the SKIP-axiom it must be shown for arbitrary P that: $\vdash \{P\}$ SKIP $\{P\}$

which abbreviates:

 $\vdash ~\texttt{Spec}(\llbracket P \rrbracket,\texttt{Skip},\llbracket P \rrbracket)$

- Expanding the definition of Spec, we must show, $\vdash \ \forall s_1 \ s_2. \ [P] \ s_1 \ \land \ \texttt{Skip}(s_1, s_2) \Rightarrow [P] \ s_2$
- Expanding the definition of Skip, we must show, $\vdash \forall s_1 \ s_2. \ [P] \ s_1 \land (s_1 = s_2) \Rightarrow [P] \ s_2$
- Using properties of equality:

 $\vdash \forall s_1 \ s_2. \ \llbracket P \rrbracket \ s_1 \Rightarrow \llbracket P \rrbracket \ s_1$

Rules proved as implications

- Lift \neg and \land to predicates: $\neg p, p \land q$ mean $\lambda s. \neg p(s), \lambda s. p(s) \land q(s)$
- To derive the sequencing rule prove:
 - $\label{eq:product} \begin{array}{rcl} \vdash & \forall p \ q \ r \ c_1 \ c_2. \\ & \mathbf{Spec}(p, c_1, q) \ \land \ \mathbf{Spec}(q, c_2, r) \ \Rightarrow \ \mathbf{Spec}(p, \mathbf{Seq}(c_1, c_2), r) \end{array}$
- To derive the IF-rule prove:

 $\label{eq:spectrum} \begin{array}{lll} \vdash & p \ q \ b \ c_1 \ c_2. \\ & \mbox{Spec}(p \wedge b, c_1, q) \ \wedge \ \mbox{Spec}(p \wedge \neg b, c_2, q) \ \Rightarrow \ \mbox{Spec}(p, \mbox{If}(b, c_1, c_2), q) \end{array}$

- To derive the WHILE-rule prove:
 - $\vdash \ \forall p \ b \ c. \ \texttt{Spec}(p \land b, c, p) \ \Rightarrow \ \texttt{Spec}(p, \texttt{While}(b, c), p \land \neg b)$
- By deriving the Hoare logic rules, we guarantee their soundness

Other programming logic constructs

- Variants on Hoare logic:
 - VDM-style specifications
 - strongest and weakest preconditions
 - Dynamic logic
- Originally separate programming logics
- We will define them in higher order logic
- Illustrates benefits of using a general host logic

VDM-style specifications

• Used in the Vienna Development Method (VDM)

introduced a variation on Hoare-style specifications

- VDM notation reduces the need for auxiliary logical variables by providing a way of refering to the initial values of variables in postconditions using 'hooked' variables like X
- Here's a Hoare-style example:
 {X = x ∧ Y = y} R:= X; X:= Y; Y:= R {Y = x ∧ X = y}
- VDM-style version is:

 $\{\mathtt{T}\} \ R := X \ ; \ X := Y \ ; \ Y := R \ \{Y = \overleftarrow{X} \ \land \ X = \overleftarrow{Y} \}$

• $\overline{X}, \overline{Y}$ denote values of X, Y in precondition state

Aczel's semantics of VDM

- Postcondition is a binary relation on initial and final states
- Regard

 $\{P[X_1,\ldots,X_n]\} C \{Q[X_1,\ldots,X_n,\overleftarrow{X_1},\ldots,\overleftarrow{X_n}]\}$

as an abbreviation for

 $\texttt{VDM_Spec}(\llbracket P[X_1,\ldots,X_n]\rrbracket, \llbracket C\rrbracket, \llbracket Q[X_1,\ldots,X_n,\overleftarrow{X_1},\ldots,\overleftarrow{X_n}]\rrbracket_2)$

where $\texttt{VDM_Spec}$ is defined by:

 $\texttt{VDM_Spec}(p,c,r) = \forall s_1 \ s_2. \ p \ s_1 \ \land \ c(s_1,s_2) \Rightarrow r(s_1,s_2)$

and the notation $[\![\cdots]\!]_2$ is defined by:

 $\llbracket Q[X_1, \dots, X_n, \overleftarrow{X_1}, \dots, \overleftarrow{X_n}] \rrbracket_2 \ = \ \lambda(s_1, s_2). \ Q[s_2^{\circ}X_1^{\circ}, \dots, s_2^{\circ}X_n^{\circ}, s_1^{\circ}X_1^{\circ}, \dots, s_1^{\circ}X_n^{\circ}]$

Aczel's WHILE-rule for total correctness

• Following rule due to Peter Aczel:

• Transitive and Well-Founded easily defined in higher order logic

• cannot be defined in first order logic

Dijkstra's weakest preconditions

- Idea is to calculate a program to achieve a postcondition
 not a theory of post hoc verification
- Non-determinism a key idea in Dijksta's presentation
 - start with a non-deterministic high level pseudo-coderefine to deterministic and efficient code
- $\bullet\,$ Weakest preconditions (wp) are for total correctness
- Weakest *liberal* preconditions (wlp) for partial correctness
- If C is a command and Q a predicate, then informally:
 - $wlp(C,Q) = `The weakest predicate P such that \{P\} C \{Q\}'$
 - wp(C,Q) = `The weakest predicate P such that [P] C [Q]'
- If P and Q are predicates then $Q \Rightarrow P$ means P is 'weaker' than Q, i.e. everything satisfying Q also satisfies P

Meaning of weakest preconditions

- If C is a command and Q a predicate, then informally:
 wlp(C,Q) = 'The weakest predicate P such that {P} Q {Q}'
- What is the 'weakest predicate' satisfying a condition
- Easy definition in higher order logic: $\vdash \ \texttt{wlp}(c,q) = \ \lambda s. \ \forall s'. \ c(s,s') \Rightarrow q \ s'$
- wlp(c,q)(s) holds if s always leads via c to a state satisfying q
- The relationship with Hoare's notation is given by: $\vdash \text{ Spec}(p,c,q) = \quad \forall s. \ p \ s \Rightarrow \texttt{wlp}(c,q) \ s$

Strongest postconditions

- Define $\operatorname{sp}(C, P)$ to be 'strongest' Q such that $\{P\} \subset \{Q\}$
 - partial correctness: $\{P\} \ C \ \{\operatorname{sp}(C, P)\}$
 - {P} C {Q} equivalent to $\operatorname{sp}(C, P) \Rightarrow Q$
- $\bullet\,$ Note that wlp goes 'backwards', but sp goes 'forwards'
 - backwards: $\{P\} \ C \ \{Q\}$ if and only if $P \Rightarrow \texttt{wlp}(C, Q)$
 - forwards: $\{P\} \ C \ \{Q\}$ if and only if $\operatorname{sp}(C, P) \Rightarrow Q$
- Strongest postcondition calculation related to symbolic execution

Meaning of strongest postconditions

- If C is a command and P a predicate, then informally: $sp(C, P) = `The strongest predicate Q such that \{P\} Q \{Q\}'$
- Easy definition in higher order logic: $\vdash \ \, \mathfrak{sp}(c,p) = \ \, \lambda s'. \ \, \exists s. \ \, p(s) \wedge c(s,s')$
- The relationship with Hoare's notation is given by: $\vdash \text{ Spec}(p,c,q) = \quad \forall s'. \text{ sp}(c,p)(s') \Rightarrow q(s')$
- $\bullet\,$ Exercise: prove this from the definitions of Spec and sp

Dynamic logic

- Dynamic logic relates Hoare logic to modal logic
- Invented by V.R. Pratt based on an idea of R.C. Moore (MIT)
- States of computation are thought of as *possible worlds*
 - if a command C transforms an initial state s to a final state s'
 - then s' is thought of as accessible from s (a concept from modal logic)
- Modal logic has modal formulae $\Box q$ and $\Diamond q$ where:
 - $\Box q$ is true in *s* if *q* is true in all states accessible from *s*
 - $\Diamond q$ is true in *s* if if *q* is true in *some state* accessible from *s*
- Exercise: convince yourself that $\Diamond q \Leftrightarrow \neg \Box \neg q$ and $\Box q \Leftrightarrow \neg \Diamond \neg q$

Modal operators of Dynamic Logic

- Dynamic logic has operators [C] and <C> for each command C
 [C] is analogous to □
 - <*C*> is analogous to ◊
- These can be defined on the relation c denotated by C as follows:

$$\begin{array}{lll} \llbracket c \rrbracket q & = & \lambda s. \ \forall s'. \ c(s,s') \Rightarrow q \ s' \\ <\!\!c\!\!>\!\!q & = & \neg(\llbracket c \rrbracket(\neg q)) \end{array}$$

- where ¬ is negation lifted pointwise to predicates
- Relation to weakest preconditions

 $\vdash \ \mathtt{wlp}(c,q) \ = \ \llbracket c \rrbracket q$

Conclusion

- Hoare, VDM, Dijskstra, Dynamic Logic, ... ?
- From a semantic embedding perspective its just packaging!
- Don't need separate logics, just definitions in a general host logic
- Current research in the Lab (not exhaustive!)
 - derive Hoare Logic from processor models (Fox, Myreen)
 - extend Hoare logic to pointers, concurrency and more (Parkinson et al. $\ldots)$
 - \bullet semantically embed separation logic in higher order logic (Tuerk)
- Wednesday: guest lecture by Joe Hurd of Galois (www.galois.com)