# Complexity Theory Lecture 2

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Easter Term 2017

http://www.cl.cam.ac.uk/teaching/1617/Complexity/

### **Formalising Algorithms**

To prove a lower bound on the complexity of a problem, rather than a specific algorithm, we need to prove a statement about all algorithms for solving it.

In order to prove facts about all algorithms, we need a mathematically precise definition of algorithm.

We will use the *Turing machine*.

The simplicity of the Turing machine means it's not useful for actually expressing algorithms, but very well suited for proofs about all algorithms.

# **Turing Machines**

For our purposes, a Turing Machine consists of:

- Q a finite set of states;
- $\Sigma$  a finite set of symbols, including  $\sqcup$  and  $\triangleright$ .
- $s \in Q$  an initial state;
- $\delta: (Q \times \Sigma) \to (Q \cup \{\text{acc}, \text{rej}\}) \times \Sigma \times \{L, R, S\}$

A transition function that specifies, for each state and symbol a next state (or accept acc or reject rej), a symbol to overwrite the current symbol, and a direction for the tape head to move (L - left, R - right, or S - stationary)

# **Configurations**

A complete description of the configuration of a machine can be given if we know what state it is in, what are the contents of its tape, and what is the position of its head. This can be summed up in a simple triple:

#### Definition

A configuration is a triple (q, w, u), where  $q \in Q$  and  $w, u \in \Sigma^*$ 

The intuition is that (q, w, u) represents a machine in state q with the string wu on its tape, and the head pointing at the last symbol in w.

The configuration of a machine completely determines the future behaviour of the machine.

### **Computations**

Given a machine  $M = (Q, \Sigma, s, \delta)$  we say that a configuration (q, w, u) yields in one step (q', w', u'), written

$$(q, w, u) \rightarrow_M (q', w', u')$$

if

- $\bullet \ w = va$ ;
- $\delta(q, a) = (q', b, D)$ ; and
- either D = L and w' = v u' = buor D = S and w' = vb and u' = uor D = R and w' = vbc and u' = x, where u = cx. If u is empty, then  $w' = vb \sqcup$  and u' is empty.

#### **Computations**

The relation  $\to_M^*$  is the reflexive and transitive closure of  $\to_M$ .

A sequence of configurations  $c_1, \ldots, c_n$ , where for each i,  $c_i \to_M c_{i+1}$ , is called a *computation* of M.

The language  $L(M) \subseteq \Sigma^*$  accepted by the machine M is the set of strings

$$\{x \mid (s, \triangleright, x) \to_M^{\star} (\mathrm{acc}, w, u) \text{ for some } w \text{ and } u\}$$

A machine M is said to *halt on input* x if for some w and u, either  $(s, \triangleright, x) \to_M^{\star} (\operatorname{acc}, w, u)$  or  $(s, \triangleright, x) \to_M^{\star} (\operatorname{rej}, w, u)$ 

### **Decidability**

A language  $L \subseteq \Sigma^*$  is recursively enumerable if it is L(M) for some M.

A language L is decidable if it is L(M) for some machine M which halts on every input.

A language L is semi-decidable if it is recursively enumerable.

A function  $f: \Sigma^* \to \Sigma^*$  is *computable*, if there is a machine M, such that for all x,  $(s, \triangleright, x) \to_M^* (\operatorname{acc}, \triangleright f(x), \varepsilon)$ 

# **Example**

Consider the machine with  $\delta$  given by:

	$\triangleright$	0	1	Ш
s	$s, \triangleright, R$	$\mathrm{rej},0,S$	$\mathrm{rej}, 1, S$	$q,\sqcup,R$
q	$\operatorname{rej}, \triangleright, R$	q, 1, R	q, 1, R	q', 0, R
q'	$\operatorname{rej}, \triangleright, R$	$\mathrm{rej},0,S$	q',1,L	$\mathrm{acc}, \sqcup, S$

This machine, when started in configuration  $(s, \triangleright, \sqcup 1^n 0)$  eventually halts in configuration  $(\operatorname{acc}, \triangleright \sqcup 1^{n+1} 0 \sqcup, \varepsilon)$ .

# **Multi-Tape Machines**

The formalisation of Turing machines extends in a natural way to multi-tape machines. For instance a machine with k tapes is specified by:

- $Q, \Sigma, s$ ; and
- $\delta: (Q \times \Sigma^k) \to Q \cup \{\text{acc}, \text{rej}\} \times (\Sigma \times \{L, R, S\})^k$

Similarly, a configuration is of the form:

$$(q, w_1, u_1, \ldots, w_k, u_k)$$

# **Running Time**

With any Turing machine M, we associate a function  $r: \mathbb{N} \to \mathbb{N}$  called the *running time* of M.

r(n) is defined to be the largest value R such that there is a string x of length n so that the computation of M starting with configuration  $(s, \triangleright, x)$  is of length R (i.e. has R successive configurations in it) and ends with an accepting configuration.

In short, r(n) is the length of the *longest accepting computation* of M on an input of length n.

# Complexity

For any function  $f: \mathbb{N} \to \mathbb{N}$ , we say that a language L is in  $\mathsf{TIME}(f)$  if there is a machine  $M = (Q, \Sigma, s, \delta)$ , such that:

- L = L(M); and
- The running time of M is O(f).

Similarly, we define SPACE(f) to be the languages accepted by a machine which uses O(f(n)) tape cells on inputs of length n.

In defining space complexity, we assume a machine M, which has a read-only input tape, and a separate work tape. We only count cells on the work tape towards the complexity.

# **Decidability and Complexity**

For every decidable language L, there is a computable function f such that

$$L \in \mathsf{TIME}(f)$$

If L is a semi-decidable (but not decidable) language accepted by M, then there is no computable function f such that every accepting computation of M, on input of length n is of length at most f(n).