CST Part IB/II(G)/Diploma Computation Theory List of corrections to the 2013/14 lecture notes

31 March 2014

Page 100: see the attached page.

Proof sketch, cont.

 $R_0 = 0, R_1 = x_1, \dots, R_n = x_n$. It's in **PRIM** because: configuration after t steps, starting with initial register values Writing \vec{x} for x_1, \ldots, x_n , let $config_M(\vec{x}, t)$ be the code of M's

$$\begin{cases} config_M(\vec{x}, 0) &= \lceil [0, 0, \vec{x}] \rceil \\ config_M(\vec{x}, t+1) &= next_M(config_M(\vec{x}, t)) \end{cases}$$

erroneous halts). Let $halt_M(\vec{x})$ be the number of steps M takes to halt). It satisfies halt when started with initial register values $ec{x}$ (undefined if M does not Can assume M has a single HALT as last instruction, Ith say (and no

$$halt_M(\vec{x}) \equiv \text{least } t \text{ such that } I - lab(config_M(\vec{x},t)) = 0$$

and hence is in PR (because lab, $config_M$, $I-() \in PRIM$).

So
$$f \in \mathbf{PR}$$
, because $f(\vec{x}) \equiv val_0(config_M(\vec{x}, halt_M(\vec{x})))$.