```
C and C++
6. Operators — Inheritance — Virtual
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Alan Mycroft

University of Cambridge (heavily based on previous years' notes - thanks to Alastair Beresford and Andrew Moore)

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```
1 class Complex {
   double re,im;
   public:
    Complex(double r=0.0L, double i=0.0L);
5 };
7 Complex::Complex(double r,double i) {
   re=r,im=i; // deprecated initialisation-by-assignment
11 int main() {
12 Complex c(2.0), d(), e(1,5.0L);
   return 0;
```

Operators

- ▶ C++ allows the programmer to overload the built-in operators
- ▶ For example, a new test for equality:

```
1 bool operator==(Complex a, Complex b) {
   return a.real()==b.real() && a.imag()==b.imag();
   // presume real() is an accessor for field 're', etc.
4 }
```

► An operator can be defined or declared within the body of a class, and in this case one fewer argument is required; for example:

```
1 bool Complex::operator==(Complex b) {
   return re==b.real() && im==b.imag();
```

Almost all operators can be overloaded

Streams

From last lecture . . .

- Overloaded operators also work with built-in types
- Overloading is used to define << (C++'s "printf"); for example:</p>

```
1 #include <iostream>
3 int main() {
    const char* s = "char array";
    std::cout << s << std::endl:
    //Unexpected output; prints &s[0]
    std::cout.operator<<(s).operator<<(std::endl);</pre>
    //Expected output; prints s
    std::operator<<(std::cout,s);
12
13
    std::cout.operator<<(std::endl);</pre>
14
    return 0;
15 }
```

▶ Note std::cin, std::cout, std::cerr

The 'this' pointer

- ▶ If an operator is defined in the body of a class, it may need to return a reference to the current object
 - ▶ The keyword this can be used
- ► For example:

```
1 Complex& Complex::operator+=(Complex b) {
   re += b.real();
   this->im += b.imag();
   return *this;
```

▶ In C (or assembler) terms this is an implicit argument to a method when seen as a function.

Class instances as member variables

- A class can have an instance of another class as a member variable
- ▶ How can we pass arguments to the class constructor?
- ▶ New notation for a constructor:

```
1 class X {
   Complex c;
   Complex d;
   X(double a, double b): c(a,b), d(b) {
```

- ▶ This notation must be used to initialise const and reference members
- It can also be more efficient

Temporary objects

- ► Temporary objects are often created during execution
- A temporary which is not bound to a reference or named object exists only during evaluation of a full expression (BUGS BUGS BUGS!)
- Example: the string class has a function c_str() which returns a pointer to a C representation of a string:

```
1 string a("A "), b("string");
2 const char *s1 = a.c_str(); //Okay
3 const char *s2 = (a+b).c_str(); //Wrong
_{\rm 5} //s still in scope here, but the temporary holding
6 //"a+b" has been deallocated
8 string tmp = a+b;
9 const char *s3 = tmp.c_str(); //Okay
```

Friends

- ▶ A (non-member) friend function can access the private members of a class instance it befriends
- ▶ This can be done by placing the function declaration inside the class definition and prefixing it with the keyword friend; for example:

```
1 class Matrix {
   friend Vector operator*(const Matrix&, \
                           const Vector&);
  };
```

Inheritance

► C++ allows a class to inherit features of another:

```
1 class vehicle {
2   int wheels;
3 public:
4   vehicle(int w=4):wheels(w) {}
5 };
6
7 class bicycle : public vehicle {
8   bool panniers;
9 public:
10   bicycle(bool p):vehicle(2),panniers(p) {}
11 };
12
13 int main() {
14   bicycle(false);
15 }
```

Derived member function call

I.e. when we call a function overriden in a subclass.

▶ Default derived member function call semantics differ from Java:

```
1 class vehicle {
2   int wheels;
3 public:
4   vehicle(int w=4):wheels(w) {}
5   int maxSpeed() {return 60;}
6 };
7
8 class bicycle : public vehicle {
9   int panniers;
10 public:
11  bicycle(bool p=true):vehicle(2),panniers(p) {}
12   int maxSpeed() {return panniers ? 12 : 15;}
13 };
```

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Example

```
1 #include <iostream>
2 #include "example13.hh"
3
4 void print_speed(vehicle &v, bicycle &b) {
5   std::cout << v.maxSpeed() << " ";
6   std::cout << b.maxSpeed() << std::endl;
7 }
8
9 int main() {
10   bicycle b = bicycle(true);
11   print_speed(b,b); //prints "60 12"
12 }</pre>
```

Virtual functions

- ► Non-virtual member functions are called depending on the <u>static type</u> of the variable, pointer or reference
- Since a pointer to aderived class can be cast to a pointer to a base class, calls at base class do not see the overriden function.
- ➤ To get polymorphic behaviour, declare the function virtual in the superclass:

```
1 class vehicle {
2   int wheels;
3  public:
4  vehicle(int w=4):wheels(w) {}
5   virtual int maxSpeed() {return 60;}
6 };
```

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Virtual functions

▶ In general, for a virtual function, selecting the right function has to be run-time decision; for example:

```
1 bicycle b(true);
2 vehicle v;
3 vehicle* pv;
4
5 user_input() ? pv = &b : pv = &v;
6
7 std::cout << pv->maxSpeed() << std::endl;
8 }</pre>
```

Enabling virtual functions

- ► To enable virtual functions, the compiler generates a <u>virtual function</u> table or <u>vtable</u>
- ► A vtable contains a pointer to the correct function for each object instance
- ▶ The vtable is an example of indirection
- ➤ The vtable introduces run-time overhead (this is compulsory in Java; contemplate whether C++'s additional choice is good for efficiency or bad for being an additional source of bugs)

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Abstract classes

- Sometimes a base class is an un-implementable concept
- In this case we can create an abstract class:

```
1 class shape {
2  public:
3   virtual void draw() = 0;
4 }
```

- It is not possible to instantiate an abstract class: shape s; //Wrong
- A derived class can provide an implementation for some (or all) the abstract functions
- A derived class with no abstract functions can be instantiated

Example

```
1 class shape {
2 public:
3  virtual void draw() = 0;
4 };
5  class circle : public shape {
7 public:
8  //...
9  void draw() { /* impl */ }
10 };
```

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Multiple inheritance

▶ It is possible to inherit from multiple base classes; for example:

```
_{\mbox{\scriptsize 1}} class ShapelyVehicle: public vehicle, public shape {
3 }
```

- \blacktriangleright Members from \underline{both} base classes exist in the derived class
- ▶ If there is a name clash, explicit naming is required
- ► This is done by specifying the class name; for example: ShapelyVehicle sv; sv.vehicle::maxSpeed();

```
class A {};
2 class B : public A {};
3 class C : public A {};
4 class D : public B, public C {};
```

▶ With multiple inheritance, we can build:

Multiple instances of a base class

- ▶ This means we have two instances of A even though we only have a single instance of ${\tt D}$
- ▶ This is legal C++, but means all references to A must be stated explicitly:

```
2 d.B::var=3;
```

3 d.C::var=4;

Virtual base classes

- ▶ Alternatively, we can have a single instance of the base class
- ▶ Such a "virtual" base class is shared amongst all those deriving from it

```
1 class Vehicle {int VIN;};
2 class Boat : public virtual Vehicle { ... };
3 class Car : public virtual Vehicle { ... };
4 class JamesBondCar : public Boat, public Car { \dots };
```

Exercises

- 1. If a function f has a static instance of a class as a local variable, when might the class constructor be called?
- 2. Write a class ${\tt Matrix}$ which allows a programmer to define 2×2 matrices. Overload the common operators (e.g. +, -, *, and /)
- 3. Write a class Vector which allows a programmer to define a vector of length two. Modify your ${\tt Matrix}$ and ${\tt Vector}$ classes so that they interoperate correctly (e.g. v2 = m*v1 should work as expected)
- 4. Why should destructors in an abstract class almost always be declared virtual?