## Universal Register Machine, U

## High-level specification

Universal RM U carries out the following computation, starting with $R_{0}=0, R_{1}=e$ (code of a program), $\mathrm{R}_{2}=\boldsymbol{a}$ (code of a list of arguments) and all other registers zeroed:

- decode $\boldsymbol{e}$ as a RM program $\boldsymbol{P}$
- decode $a$ as a list of register values $a_{1}, \ldots, a_{n}$
- carry out the computation of the RM program $P$ starting with $\mathrm{R}_{0}=0, \mathrm{R}_{1}=a_{1}, \ldots, \mathrm{R}_{n}=a_{n}$ (and any other registers occurring in $\boldsymbol{P}$ set to 0 ).

Mnemonics for the registers of $U$ and the role they play in its program:
$R_{1} \equiv P$ code of the $R M$ to be simulated
$\mathrm{R}_{2} \equiv \mathrm{~A}$ code of current register contents of simulated RM
$R_{3} \equiv$ PC program counter-number of the current instruction (counting from 0)
$\mathrm{R}_{4} \equiv \mathrm{~N}$ code of the current instruction body
$\mathrm{R}_{5} \equiv \mathrm{C}$ type of the current instruction body
$\mathrm{R}_{6} \equiv \mathrm{R}$ current value of the register to be incremented or decremented by current instruction (if not HALT)
$\mathrm{R}_{7} \equiv \mathrm{~S}, \mathrm{R}_{8} \equiv \mathrm{~T}$ and $\mathrm{R}_{9} \equiv \mathrm{Z}$ are auxiliary registers.
$R_{0}$ result of the simulated RM computation (if any).

## Overall structure of $\boldsymbol{U}^{\prime}$ 's program

1 copy PCth item of list in P to $N$ (halting if PC > length of list); goto 2

2 if $N=0$ then halt, else decode $N$ as $\langle\langle y, z\rangle ; \mathrm{C}::=y$; $\mathrm{N}::=z$; goto 3
\{at this point either $\mathrm{C}=2 \boldsymbol{i}$ is even and current instruction is $\mathrm{R}_{i}^{+} \rightarrow \mathrm{L}_{z}$, or $\mathrm{C}=2 i+1$ is odd and current instruction is $\mathrm{R}_{i}^{-} \rightarrow \mathrm{L}_{j}, \mathrm{~L}_{k}$ where $\left.z=\langle j, k\rangle\right\}$
3 copy $i$ th item of list in A to R; goto 4
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To implement this, we need RMs for manipulating (codes of) lists of numbers...

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to copy the contents of $R$ to $S$ can be implemented by


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precondition:
$\mathrm{R}=x$
$\mathrm{S}=y$
$Z=0$
postcondition:
$\mathrm{R}=x$
$\mathrm{S}=x$
$Z=0$

The program START $\rightarrow$| $\begin{array}{c}\text { push } \mathrm{X} \\ \text { to } \mathrm{L}\end{array}$ |
| :---: |$\rightarrow$ HALT $\quad 2^{\mathrm{X}(2 \mathrm{~L}+1)}$ to carry out the assignment $(\mathrm{X}, \mathrm{L})::=(0, \mathrm{X}:: \mathrm{L})$ can be implemented by



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The program START $\longrightarrow \begin{gathered}\text { push } \mathrm{X} \\ \text { to } \mathrm{L}\end{gathered} \rightarrow$ HALT
to carry out the assignment $(\mathrm{X}, \mathrm{L})::=(0, \mathrm{X}:: \mathrm{L})$ can be implemented by

$$
\begin{aligned}
& \text { START } \rightarrow \mathrm{Z}^{+} \longrightarrow \mathrm{L}^{-} \rightarrow \mathrm{Z}^{-} \xrightarrow{( } \mathrm{X}^{-} \rightarrow \text { HALT } \\
& ((L, Z):=2 L+Z, 0)
\end{aligned}
$$

The program START $\rightarrow \underset{\substack{\text { push } \mathrm{x} \\ \text { to } \mathrm{L}}}{ } \rightarrow$ HALT
to carry out the assignment $(\mathrm{X}, \mathrm{L})::=(0, \mathrm{X}:: \mathrm{L})$ can be implemented by

precondition:
$\mathrm{X}=x$
$\mathrm{L}=\ell$
$Z=0$
postcondition:
$\mathrm{x}=0$
$\mathrm{L}=\left\langle\langle x, \ell\rangle=2^{x}(2 \ell+1)\right.$
$\mathrm{Z}=0$

The program START $\rightarrow \begin{array}{|cc|}p_{0 \text { o } \mathrm{L}} & \rightarrow \text { HALT } \\ \text { to } \mathrm{X}\end{array} \rightarrow$ EXIT specified by "if $\mathrm{L}=0$ then ( $\mathrm{X}::=0$; goto EXIT) else let $\mathrm{L}=\langle\langle x, \ell\rangle$ in $(\mathrm{X}::=x ; \mathrm{L}::=\ell$; goto HALT $)$ "
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