# MetiTarski's Menagerie of Cooperating Systems 

Lawrence C Paulson

Computer laboratory
University of: Gambridge

1. On Combining Systems

## Combining Systems is Hard!

- Example 1: Integrating decision procedures into heuristic theorem provers. A case study of linear arithmetic" (Boyer and Moore, 1988)
- Example 2: Beachability programming in HOL98 using BDDs" (MJC Gordon, 2000)
- Example 3. Isabelle's Sledgehammer (2007)
- Example 4: Resolution + RCF = MetiTarski (2008)


# Adding Linear Arithmetic to the Boyer/Moore Prover 

* Simply adding their (custom-made!) decision procedure to the Boyer/Moore prover had little effect.
- Deep integration with the rewriter was necessary: their decision procedure was ho black box.
" Final version like the software for the space shuttle"


## Adding BDDs to HOL98

* What's the point of BDDs here? Proof assistants don't need to check huge tautologies. But.
- Mike Gordon added the BDD data stricture to HOL.
* assertions relating formulas to their BDDS
- BDD.level operations directly available
- This package was general enough to implement model checking in HOL!


## Adding ATPs to Isabelle

- Similar integrations were attempted before, but how to make it usable for novices - and useful to experts?
- Sledgehammer provides automatic...
- problem translation (into FO or whatever)
- lemma selection (out of the entire lemma library)
- process management (remote invocations, etc.)
- ATPs are invoked as black boxes - and are not trusted!


# Combining Clause Methods with Decision Procedures 

* SMT: propositional over approximation
- DPLL $(\Gamma+\mathcal{T})$ : a calculus for DPL + superposition
- MetiTarskl a modified resolution prover
- using decision procedures to simplify clauses...
$\checkmark$ and to delete redundant ones

2. MetiTarski

## MetiTarski: the Key Ideas

* proving statements about exp, In, sin, cos, $\tan ^{-1}$ - via
- axioms bounding the functions by rational functions
- heuristics to isolate and remove function occurrences
- decision procedures for real arithmetic (RCF)
(Real polynomial arit thmetic is decidable!
-though doubly exponential...)


## Some Upper/Lower Bounds

$$
\begin{aligned}
& \exp (x) \geqslant 1+x+\quad+x^{n} / n! \\
& \text { (nodd) } \\
& \exp (x) \leqslant 1+x+\quad+\quad x / n! \\
& \exp (x)-1 /\left(1+x+x^{2} / 21-x / 3!\right)(x+1.596)
\end{aligned}
$$

Taylor series,

## continued fractions, ...

$$
\begin{aligned}
& x-1,<\ln x<x-1 \\
& \frac{(1+5 x)(x-1)}{2 x(2+x)} \leqslant \ln x \leqslant \frac{(x+5)(x-1)}{2(2 x+1)}
\end{aligned}
$$

## Division Laws, abs, etc...

$$
\begin{aligned}
& 7(x \leqslant y-z) \vee x / z \leqslant y \mid z \leqslant 0 \\
& 7(x<y / z) \vee x<z \leqslant y y z \leqslant 0 \\
& 1 x+z \leqslant y) \vee x \leqslant y / z \vee z \leqslant 0 \\
& n(x / z \leqslant y) y x \leqslant y<z \vee z \leqslant 0 \\
& x \geqslant 0-x=x \\
& x<0 \Rightarrow|x|=-x
\end{aligned}
$$

## Analysing A Simple Problem


$*$ isolate occurrences of functions

* replace them by the bounds

How do we bring about these transformations?

- replace division by multiplication
- call decision procedure


## Architectural Alternatives

Roll your own tableau prover?
Analytica (1993)
Weierstrass (2001)
we have full control - must micromanage the proof search

Hack an existing resolution prover?
no calculus-it's ad-hoc (what is "the algorithm"?)

## 3. Details of the Integration

## Resolution Refresher Course

- Resolution operates on clauses: disjunctions of literals.
- Resolving two clauses yields a new one
*The aim is to contradict the negation of the goal - by deriving the empty clause.


## Algebraic Literal Deletion

- Retain a list of the ground polynomial clauses (no variables):
- Delete any literal that is inconsistent with them.....
- by calling an RGF decision procedure.
- Deleting iterals helps to derive the empty clause.
-This process yields a fine graine d integration between resolution and a decision procedure.


## Literal Deletion Examples

- Unsatisfiable literals such as $p^{2}<0$ are deleted
* If $x(y+1)>1$ is known, then $x=0$ will be deleted.
- The context includes the negations of adjacent literals in the clause $z^{2}>3$. - -
the decision procedure reduces 3z $\left[z^{2}<3 \wedge z>5\right]$ to false.


## A Tiny Proof: $\forall x\left|e^{x}-1\right| \leqslant e^{|x|}-1$



## To Summarise...

Replace functions by rational function upper or lower bounds,
and then get rid of division.
We obtain conjunctions of polynomial inequalities,

## ... which are decidable.

## Resolution theorem proving applies these steps "in its own way".

## A Few Easy Examples...

$$
\begin{aligned}
& 0<t \wedge 0<\nu_{f} \rightarrow\left(\left(1.565+313 v_{f}\right) \cos (116 t)\right. \\
& \left.\left.+01340+00268 v_{f}\right) \sin (116 t)\right) e^{1 / 34 t} \\
& \left(6.55+1.31 v_{f}\right) \text { e } v_{f}+10 \geqslant 0 \\
& 0 \leqslant x \wedge x \leqslant 289 \wedge s^{2}+c^{2}=1 / \\
& 1.51-023 e^{019 x} \quad(2.35 c+42 s) e^{00024 x}>-2 \\
& 0 \leqslant x \wedge 0 \leqslant y \Rightarrow y \tanh (x) \leqslant \sinh (y x)
\end{aligned}
$$

## Our Decision Procedures

QEPCAD (Hoon Hong, C. W. Brown et al.)
venerable - very fast for univariate problems

## Mathematica (Wolfram research) much faster than QEPCAD for 3-4 variables

Z3 (de Moura et al., Microsoft Research) an SMT solver with non-linear reasoning

## Integration Issues

- QEPCAD was purposely designed for human use
- not as a back end.
- With Z3 we go beyond black box integration. feeding back models to speed later execution.
- Machinelearning can help identify the best decision procedure for a given problem.
- Many integration issues are trivial (e.g, buffer blocking) but vexing.


## 4. Applications

## MetiTarski's Applications

* Analogue circuit verifí cation (Denman et al.; 2009)
- Linear hybrid systems (Akbarpour \& LGP, 2009)
- Abstracting nonpolynomial dynamical systems: (Denman, 2012)
- KeYmaeralinkup nonlinear hybrid systems (Sogokon et al)
- PVS linkup. NASA collision-avoidance projects (Muñoz \& Denman)


## (What are Hybrid Systems?)

* dynamical systems where the state space has
- discrete modes (with transitions to other modes)
- continuous dynamics in each mode
- simple examples bouncing ball, water tank
- any computer controlled physical process
- autopilots, driverless trains, automated factories, ...


## The Theromstat (sorn)

off
(cooling down)
on
(warming up)

## KeYmaera

* a verification tool for hy brid systems (Platzer)
- extends the KeY interactive prover with a dynamic logic
- a free-variable tableau calculus
" "differential induction"
- integration with RGF decision procedures
- MetiTarski extends its language from polynomials to allow transcendental functions.


## KeYmaera + MetiTarski



## Some KeYmaera Examples

- Damped penduluin, described by the second order differential equation $x+2 d \omega x+\omega^{2} x=0$
- Ultimately, MetiTarski has to prove (his takes $1 / 4$ sec) $t \geqslant 010-1 \times 1 \times-1-\operatorname{xe}-\left(4 \cos \left(\frac{8 t}{5}\right)+3 \sin \left(\frac{8 t}{5}\right)\right) \leqslant 4$
- Stability proofs using Lyapunov functions


## MetiTarski + PVS

* Trusted interface, complementing PVS support of interval methods for polynomial estimation
- It's being tried within NASAS ACCORD project.
- MetiTarski has been effective in early experiments
- .... but there's much more to do.


## Future Possibilities

- Refinements to the RGF decision process
- Integration with lsabelle?
- Formal proofs of all upper/lower bounds
- Can decision procedures return certificates?
- Machine learning within the decision procedures


## The Cambridge Team



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